

# Fundamental Statistical Theory

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# Statistical Theory Review: WLLN and CLT

Assuming that we have independent and identically distributed (iid) data  $Z_1, \dots, Z_n$ , then

- ①  $\frac{1}{n} \sum_{i=1}^n g(Z_i)$  converges in probability to  $E\{g(Z)\}$  by the weak law of large numbers. Note that  $Z_i$  can be a vector
- ②  $\sqrt{n} \left[ \frac{1}{n} \sum_{i=1}^n g(Z_i) - E\{g(Z)\} \right]$  converges in distribution to a normal random variable with mean 0 and variance  $\text{var}\{g(Z)\}$  by the central limit theorem. Another way of saying this is that  $\frac{1}{n} \sum_{i=1}^n g(Z_i)$  is asymptotically normal with mean  $E\{g(Z)\}$  and variance  $\text{var}\{g(Z)\}/n$ .

# Statistical Theory Review: Double expectation/variance theorem

Let  $X$  and  $Y$  be random variables. Then

- ①  $E(Y) = E\{E(Y|X)\}$
- ②  $var(Y) = var\{E(Y|X)\} + E\{var(Y|X)\}$

# Statistical Theory Review: Slutsky's theorem

From Wikipedia

Let  $X_n, Y_n$  be sequences of scalar/vector/matrix random elements. If  $X_n$  converges in distribution to a random element  $X$  and  $Y_n$  converges in probability to a constant  $c$ , then

$X_n + Y_n \xrightarrow{d} X + c; X_n Y_n \xrightarrow{d} Xc; \} X_n/Y_n \xrightarrow{d} X/c$ , provided that  $c$  is invertible, where  $\xrightarrow{d}$  denotes convergence in distribution.

Note: that in statistics,  $X$  is frequently a mean-zero normally distributed r.v.

# Statistical Theory Review: Taylor Expansion

Typically in statistics, we take Taylor expansions about parameters (say  $\theta$ ). Let  $g(Z_i; \theta)$  be any continuous and differentiable function of data  $Z_i$  and parameter  $\theta$ . Then a first-order Taylor expansion of  $g(Z_i; \theta)$  about  $\theta = \theta_0$  is

$g(Z_i; \theta) = g(Z_i; \theta_0) + \frac{\partial}{\partial \theta} g(Z_i; \theta^*)(\theta - \theta_0)$ , where  $\theta^*$  is between  $\theta$  and  $\theta_0$ .

A second-order Taylor expansion of  $g(Z_i; \theta)$  about  $\theta = \theta_0$  is

$g(Z_i; \theta) = g(Z_i; \theta_0) + \frac{\partial}{\partial \theta} g(Z_i; \theta_0)(\theta - \theta_0) + \frac{\partial^2}{\partial \theta^2} g(Z_i; \theta^*)(\theta - \theta_0)^2$

# Statistical Theory Review: M-estimation

- Assume that we want to estimate a vector of parameters  $\beta$  using independent and identically distributed data  $Z_i, i = 1, \dots, n$
- Let  $\hat{\theta}$  be given by the solution to  $\sum_{i=1}^n \Psi(Z_i; \theta) = 0$ . Note that  $\Psi(Z_i; \theta)$  is referred to as the estimating function and  $\sum_{i=1}^n \Psi(Z_i; \theta) = 0$  is the estimating equation
- $\hat{\theta}$  is referred to as an M-estimator and under certain regularity conditions,  $\hat{\theta}$  is consistent and asymptotically normal with limiting variance  $A(\theta_0)^{-1}B(\theta_0)A(\theta_0)^{-T}$  where  $A(\theta_0) = -E \left\{ \frac{\partial}{\partial \theta} \Psi(Z_i; \theta_0) \right\}$  and  $B(\theta_0) = \text{var}\{\Psi(Z_i; \theta_0)\} = E \left\{ \Psi(Z_i; \theta_0) \Psi(Z_i; \theta_0)^T \right\}$
- We can estimate these matrices as  $\hat{A}(\theta_0) = \frac{1}{n} \sum_{i=1}^n -\frac{\partial}{\partial \theta} \Psi(Z_i; \hat{\theta})$  and  $\hat{B}(\theta_0) = \frac{1}{n} \sum_{i=1}^n \Psi(Z_i; \hat{\theta}) \Psi(Z_i; \hat{\theta})^T$