

# A Unified Gauge Framework for Dynamic Knowledge Graphs

geDIG v6: One-Gauge Control of Static and Dynamic RAG

Kazuyoshi Miyauchi

miyauchikazuyoshi@gmail.com

Draft (v6, English)

## Abstract

Dynamic knowledge graphs (KGs) lack a normative criterion for *when* to accept new information, even as Retrieval-Augmented Generation (RAG) systems excel at optimizing *what* to retrieve. We propose **geDIG**, a unified control framework that uses a *single gauge*  $\mathcal{F}$  combining normalized structural cost (edit-path cost;  $\Delta\text{EPC}_{\text{norm}}$ ) and information gain (Shannon entropy difference and path shortening;  $\Delta\text{IG}_{\text{norm}}$ ), and a **two-stage gating mechanism** (AG at 0-hop for ambiguity detection; DG via multi-hop for shortcut confirmation) to control exploration and integration decisions in an event-driven manner. Evaluations on a partial-observation maze PoC and a practical RAG pipeline show that geDIG consistently reduces redundant exploration and knowledge contamination (False Merge Rate) while maintaining or improving success rates and answer quality. We further introduce **PSZ (Perfect Scaling Zone)**, a target operating band defined by Acceptance  $\geq 95\%$ , FMR  $\leq 2\%$ , and additional P50 latency  $\leq 200\text{ms}$ , to guide operational tuning. Finally, we discuss the design’s relation to the Free Energy Principle (FEP) and Minimum Description Length (MDL) as an operational correspondence. We release a reproducible implementation and scripts.

## Key Terminologies and Symbols

Key symbols are summarized in table 1. For the definitions of **Information Gain** and **Normalized Entropy Difference**, see eq. (3) and eq. (4) respectively. Details are provided in section 1.1 (Definition of Unified Gauge  $\mathcal{F}$ ).

Table 1: Notation (core symbols).

Symbol	Meaning
$\mathcal{F}$	unified gauge (lower is better)
$\Delta\text{EPC}_{\text{norm}}$	normalized edit-path cost
$\Delta\text{IG}_{\text{norm}}$	normalized information gain ( $\Delta H_{\text{norm}} + \gamma\Delta\text{SP}_{\text{rel}}$ )
$\Delta H_{\text{norm}}$	normalized entropy difference
$\Delta\text{SP}_{\text{rel}}$	relative shortest-path shortening
$\theta_{\text{AG}}, \theta_{\text{DG}}$	AG/DG thresholds (quantile-calibrated)
$H, k$	max hops / beam width

## Short Forms and Sign Conventions

We use the following short forms and sign conventions (see section 1.1):

**Short form:**  $\mathcal{F} = \Delta\text{EPC}_{\text{norm}} - \lambda(\Delta H_{\text{norm}} + \gamma \Delta S_{\text{rel}})$ .

**Sign convention:**  $\Delta H_{\text{norm}} = (H_{\text{after}} - H_{\text{before}})/\log K$  (ordering = decrease is *negative*),  $\Delta S_{\text{rel}} = (L_{\text{before}} - L_{\text{after}})/\max\{L_{\text{before}}, \varepsilon\}$  (shortening is *positive*). Smaller  $\mathcal{F}$  is **better** (lower structural cost and larger  $\Delta\text{IG}_{\text{norm}}$ ). Note: The gain from ordering can be read as  $-\Delta H_{\text{norm}} > 0$ .

## Research Questions and Hypotheses

- **RQ1 (Simultaneous Control):** Can a single gauge  $\mathcal{F}$  and two-stage gates (AG/DG) simultaneously and stably control exploration (width/depth/backtracking) and integration (accept/reject/hold) as well as memory operations (eviction)?
- **RQ2 (Discrimination):** Can AG/DG discriminate between *true insights* (bridges/shortcuts) and *pseudo-insights* (misdirection/marginal improvement), thereby reducing contamination rate ( $\downarrow$ ) and increasing the pending→confirmed rate ( $\uparrow$ )?
- **RQ3 (Operational Alignment):** Does the proportionality  $\Delta\text{IG} (= \Delta H_{\text{norm}} + \gamma \Delta S_{\text{rel}}) \propto \Delta\text{MDL}$  function consistently as an operational approximation under the proposed assumptions?
- **H1 (Thermodynamic Inference):** Real Transformer attention produces lower geDIG  $\mathcal{F}$  than random/uniform baselines, validating that inference is a thermodynamic process of minimizing free energy. (New in v6)

## Contributions (Summary)

We summarize the main contributions of this paper:

- **“When” control via Single Gauge and Two-Stage Gates:** We define a single scalar  $\mathcal{F}$  integrating normalized edit-path cost  $\Delta\text{EPC}_{\text{norm}}$  and information gain  $\Delta\text{IG}_{\text{norm}}$ , and present geDIG, a framework that controls accept/hold/reject and exploration/backtracking under the *same criterion* using a two-stage gate of 0-hop ambiguity detection (AG) and multi-hop confirmation (DG).
- **New operational metrics and evaluation framework for dynamic RAG:** We introduce False Merge Rate (FMR), Zero-Search Rate (ZSR), and the target band PSZ (Perfect Scaling Zone) consisting of Acc/FMR/additional P50 latency, proposing to minimize the shortfall  $s_{\text{PSZ}}$  as a *standard specialized for dynamic KG updates*.
- **Principle verification and demonstration in Maze and RAG:** In both partial-observation maze PoC and 50-domain/500-query scale RAG experiments, we confirmed trends where geDIG suppresses redundant exploration and false acceptance while maintaining or improving success rates, EM/F1, and evidence consistency, identifying contributions of each component via ablation.
- **Operational presentation of theoretical interpretation (FEP–MDL Bridge):** We organize readings by Free Energy Principle and MDL as *operational propositions*,

showing the correspondence  $\mathcal{F} \propto \Delta\text{MDL} + O(1/N)$  (details in later sections). While not essential for implementation or operation, this gives theoretical intuition behind the design.

- **Causal Validation (Phase 5):** We demonstrate that minimizing geDIG F during Transformer training (via F-regularization) causally improves downstream performance, providing strong evidence for the thermodynamic inference hypothesis. (New in v6)

**PSZ / SLO definition and aggregation** As our Service Level Objective (SLO), we use **PSZ (Perfect Scaling Zone)**. Intuitively, it represents an operational band where *acceptance is sufficiently high ( $\text{Acc} \geq 95\%$ ) / erroneous integration is rare ( $\text{FMR} \leq 2\%$ ) / additional latency by dynamic control is within tolerance ( $\text{P50}_{\Delta\text{lat}} \leq 200\text{ms}$ )*.

Formally, the target is the simultaneous satisfaction of the following three metrics:

$$\text{Acc} \geq 0.95, \quad \text{FMR} \leq 0.02, \quad \text{P50}_{\Delta\text{lat}} \leq 200\text{ ms} \quad (1)$$

Here  $\text{P50}_{\Delta\text{lat}}$  is the median (second quartile) of *additional latency*. Each metric is calculated with a sliding window width  $W$  (default  $W=100$  queries), and quantiles are based on actual measurements.

**Definition of Shortfall.** We define the shortfall  $s_{\text{PSZ}}$  by stacking dimensionless violations of the three axes:

$$s_{\text{PSZ}} = \max(0, 0.95 - \text{Acc}) + \max(0, \text{FMR} - 0.02) + \max\left(0, \frac{\text{P50}_{\Delta\text{lat}} - 200\text{ ms}}{200\text{ ms}}\right) \quad (2)$$

and set  $s_{\text{PSZ}}=0$  as the achievement boundary (weights are equal; can be changed according to operational requirements).

Example of success criteria: Operating points complying with PSZ ( $\text{Accept} \geq 95\%$ ,  $\text{FMR} \leq 2\%$ , Add.  $\text{P50} \leq 200\text{ms}$ ), Steps/Redundant branches  $\downarrow$  in Maze, Contamination rate  $\downarrow$  / pending  $\rightarrow$  confirmed  $\uparrow$  in RAG.

## 1 Introduction

The central issue addressed in this paper is the lack of a norm for “**When to accept new knowledge**” in dynamically growing knowledge graphs. Existing Retrieval-Augmented Generation (RAG) excels at optimizing **what to retrieve (What)**, but without an explicit criterion for “which updates to accept and which to forego”, trade-offs between knowledge contamination, redundancy, and latency deterioration tend to become ad-hoc. In this paper, we propose geDIG, a framework that controls “*When to update*” with a *consistent principle* in both static and dynamic RAG using a **single gauge  $\mathcal{F}$  and two-stage gates (AG/DG)** integrating edit-path cost and information gain. Intuitively, it can be read as “detection of deterioration at the point of tentative connection” at 0-hop (local), and “confirmation of whether it truly becomes a shortcut when traced a little further” at multi-hop. The correspondence with the working hypothesis that insight is “a phenomenon where discrete episodes are instantly connected” and the analogy with previous studies on hippocampal replay [1, 2, 3] are kept as *operational metaphors* in the theoretical section (FEP–MDL bridge) later. Neuroscientific background knowledge is not assumed for understanding implementation and experiments.

Table 2: Comparison with existing methods: evaluation targets

Method	Probability (similarity)	Structure (graph)
BM25 / Contriever	✓	—
GraphRAG	—	✓
<b>geDIG</b>	✓	✓

Here, geDIG stands for *graph edit Distance and Information Gain*, and is a framework that bundles **change in edit-path cost** to the existing graph and **information gain (entropy difference + path shortening)** into a single gauge  $\mathcal{F}$ , judging “When to accept” as a *re-ranking score* in static RAG and an *update gate* in dynamic RAG.

## 1.1 Definition of Unified Gauge $\mathcal{F}$

We define the normalized information gain and entropy difference used throughout the paper.

$$\Delta\text{IG}_{\text{norm}} = \Delta H_{\text{norm}} + \gamma \Delta\text{SP}_{\text{rel}}, \quad \gamma > 0 \quad (3)$$

$$\Delta H_{\text{norm}} = \frac{H_{\text{after}} - H_{\text{before}}}{\log K} \quad (4)$$

We then define the unified gauge as

$$\mathcal{F} = \Delta\text{EPC}_{\text{norm}} - \lambda \Delta\text{IG}_{\text{norm}}. \quad (5)$$

Here  $\Delta\text{SP}_{\text{rel}}$  denotes the relative shortening of mean shortest paths, and smaller  $\mathcal{F}$  indicates a better trade-off between structure cost and information gain.

## 1.2 Why Simultaneous Evaluation of Structure and Probability is Necessary

Existing methods evaluate either similarity (probabilistic measure) or graph structure, but not both (Table 2). BM25 and Contriever use only similarity scores to decide when to stop retrieval, and thus cannot exclude “high-score but redundant information.” On the other hand, GraphRAG leverages graph structure but cannot detect situations where “structure is organized but uncertainty remains.”

The core of geDIG is evaluating the **balance** between **structural change cost** ( $\Delta\text{EPC}_{\text{norm}}$ ) and **probabilistic information gain** ( $\Delta\text{IG}_{\text{norm}}$ ) as a single scalar. Intuitively, it answers the question: “Is the uncertainty reduction worth the structural cost of adding a new edge?” This balance calculation enables the following decisions:

- High structural cost, low information gain → Retrieval unnecessary (redundant)
- Low structural cost, high information gain → Retrieval effective (integration)
- High structural cost, high information gain → Continue exploration (AG fires)

This “When” decision **cannot be made without simultaneously considering both structure and probability**. This is the essential novelty of geDIG.

### 1.3 Operational Correspondence of Two-Stage Gates (AG/DG)

This section outlines only the *summary of operational definitions*. For theoretical correspondence, refer to the duality (§9) and the FEP–MDL proposition (§9).

#### Gate Definitions

$$\text{AG}(t) := \mathbb{I}[g_0(t) > \theta_{\text{AG}}]. \quad (6)$$

$$b(t) := \begin{cases} \min\{g_0(t), g_{\min}(t)\}, & \text{AG}(t) = 1 \\ g_0(t), & \text{otherwise} \end{cases}, \quad \text{DG}(t) := \mathbb{I}[b(t) \leq \theta_{\text{DG}}]. \quad (7)$$

*Intuition* AG encourages exploration in situations where  $\mathcal{F}$  is *large* (ambiguous), while DG confirms acceptance in situations where  $\mathcal{F}$  becomes *small* (gainful shortcut) via multi-hop evaluation.

#### Calibration and Operation

- **threshold calibration:**  $\theta_{\text{AG}}, \theta_{\text{DG}}$  are adapted based on quantiles (§1.3, §3). Operated under PSZ constraints while monitoring FMR/P50 (§3).
- **Processing upon AG firing:** Force multi-hop evaluation, temporarily expanding  $H/k$  if necessary (clipped by P95 guard).
- **Processing upon DG determination:** *Connection commitment* based on marginal contribution (non-contributing edges are not adopted). Procedure detailed in §2.
- **Stabilization measures:** Combined use of fixed-base normalization ( $C_{\max}$ ,  $\log K$ ), union/trim, distance cache, and early termination.
- **Safety valves:** Snapshots for rollback, firing suppression (cooldown), and historical quantile usage.
- **Alignment with compute budget:** Prioritize keeping P95 latency within budget (e.g.,  $\text{P95} \leq 350 \text{ ms}$ ), selecting the *minimal configuration* satisfying  $O(k^H)$  from  $H \in \{1, 2, 3\}$  and  $k \in [8, 64]$ . Operated under PSZ constraints, tolerating no increase in FMR.
- **Cooldown/Backoff:** To avoid thrashing due to continuous AG/DG firing, introduce re-firing cooldown (3–5 steps) and exponential backoff (reduce  $k \downarrow / H \downarrow /$  temporarily raise  $\theta_{\text{AG}} \uparrow$  upon DG failure).

Note: In implementation,  $\theta_{\text{DG}}$  is automatically adapted using the **lower quantile** ( $q_\beta$ ) of the  $b(t)$  distribution on AG frames, controlling the trade-off between over-detection and misses (§4).

**Perspective of Stable Acceptance Subgraph** AG–DG can be interpreted as a process of exploring and confirming a *local subgraph capable of stably accepting an episode*. Let the acceptance *margin* be  $m(t) := \theta_{\text{DG}} - b(t)$ . A **lightweight audit** (`StabilityAudit`) is inserted just before integration to re-evaluate against *small perturbations (rewiring/threshold jitter)* a few times. If  $m(t) \geq \varepsilon$  holds under perturbation, the DG is confirmed as *robust acceptance*, suppressing the inclusion of pseudo-insights.

Here,  $g_{\min}(t)$  is the minimum value of multi-hop geDIG in the same step. The negative side of multi-hop (shortcut) is the **detection of loop closure or path shortening**, which can be mapped to value-predictive dopamine (DA) signals.

Note: In this paper, we denote the D-Gate as  $DG(t)$ , distinguishing it from the information gain  $\Delta IG$  to avoiding sign conflict (same name used in §4).

**Generic Interpretation of Operational Correspondence** This AG/DG correspondence should be interpreted as *operational correspondence*, not physiological identification:

- **AG-like:** Uncertainty detection → Alertness → Exploration promotion (FEP-like error minimization)
- **DA-like:** Shortcut detection → Value evaluation → Integration judgment (MDL-like complexity reduction)

By this two-stage gate, **ambiguity detection and shortcut evaluation are chained in the same step**, triggering discovery of beneficial bridge structures in real-time while suppressing wasteful exploration.

**Hyperparameter Calibration and Drift Mitigation Objective** Operate  $\theta_{AG}, \theta_{DG}, \lambda, H, k$  stably and reproducibly without relying on excessive manual tuning.

**Quantile Calibration of Thresholds** AG is automatically set by the upper quantile of  $g_0$  (e.g.,  $q_{1-\alpha}$ ), and DG by the lower quantile of  $b(t)$  on AG frames (e.g.,  $q_\beta$ ):

$$\theta_{AG} \leftarrow q_{1-\alpha}(\{g_0\}_{t-W:t}), \quad \theta_{DG} \leftarrow q_\beta(\{b(t) \mid AG(t)=1\}_{t-W:t}).$$

Window length  $W$  is set in the range of 1–5 min (stream) or 256–1024 steps (batch). Use Exponential Moving Quantile (EWQ; coefficient  $\rho \in [0.9, 0.99]$ ) to follow *concept drift* while suppressing over-detection.

**Scaling ( $\lambda$ )**  $\lambda$  is initialized by *variance balancing* of  $\Delta EPC_{norm}$  and  $\Delta IG_{norm}$ :

$$\lambda_0 := \frac{\text{Std}[\Delta EPC_{norm}]}{\max\{\text{Std}[\Delta IG_{norm}], \varepsilon\}}; \quad \text{grid validation with } \lambda \in \{\frac{1}{2}\lambda_0, \lambda_0, 2\lambda_0\}.$$

When adopting MDL correspondence (§9), anchor as  $\lambda \approx c_D/c_M$  and fine-tune with a small grid.

**Determination Procedure for  $\lambda$**  In practice, determined by: (1) Measure  $\sigma_{EPC} = \text{Std}[\Delta EPC_{norm}]$ ,  $\sigma_{IG} = \text{Std}[\Delta IG_{norm}]$  with pilot  $N \approx 100$ , (2) Set initial value  $\lambda_0 = \sigma_{EPC}/\max\{\sigma_{IG}, \varepsilon\}$  ( $\varepsilon = 10^{-6}$ ), (3) Compare grid  $\{\frac{1}{2}\lambda_0, \lambda_0, 2\lambda_0\}$ , (4) Select  $\lambda$  maximizing PSZ compliance (Acc/FMR/P50), (5) Fix for all subsequent experiments (prevent drift). This interpretation corresponds to discrete system approximation of information thermodynamic temperature ( $\beta = 1/k_B T$ ).

**Handling  $\gamma$**   $\gamma$  is an *allocation coefficient within the same dimension* for  $\Delta H$  and  $\Delta SP_{rel}$ , chosen from a *low-dimensional grid* with default  $\gamma \in \{0.0, 0.5, 1.0\}$ . For RAG, default is  $\gamma=1.0$  (path shortening fully counted on information side), and for Maze,  $\gamma \in [0.5, 1.0]$  is recommended. Under *equal-resources*, report sensitivity of PSZ and contamination rate, allowing only *initial grid* upon domain change.

**Alignment with Compute Budget**  $H$  and  $k$  prioritize keeping P95 latency *within budget* (e.g.,  $\text{P95} \leq 350\text{ ms}$ ). Choose minimal configuration satisfying  $O(k^H)$  with  $H$  in 1–3 and  $k$  in 8–64. Use concurrently with PSZ metrics (§3), tolerating no FMR increase.

**Cooldown and Backoff** To prevent thrashing from continuous AG/DG firing, introduce *re-firing cooldown* (e.g., 3–5 steps) and *exponential backoff* (narrowing candidate width or  $\beta \downarrow$ ) upon DG failure.

## Failure Modes and Mitigation

- **Local Loop/Oscillation** ( $g_0$  fluctuating near threshold): Threshold smoothing by EWQ, AG cooldown, diversification of exploration policy (candidate switching by  $\epsilon$ -greedy).
- **False Integration (FMR Increase)**: Adapt DG by lower quantile, and perform *grace period rollback* immediately after acceptance (cancel if deterioration occurs within fixed steps). Add *weighted burden* to  $\Delta\text{SP}_{\text{rel}}$  to suppress excessive bridge formation.
- **Excessive Exploration Delay** (excessive  $H, k$ ): Automatic clipping by P95 monitoring ( $H \downarrow$  or  $k \downarrow$ ). Suppress firing frequency by  $\theta_{\text{AG}} \uparrow$ .
- **Threshold Collapse due to Distribution Drift**: Use window updates and quantile tables by seasonality (time zone / domain). Use fixed thresholds during *session start warmup*.

**Falsifiable Predictions** This design provides the following falsifiable predictions:

1. Disabling AG delays DA evaluation and increases wasteful exploration.
2. Disabling Multi-hop degrades quality of shortcut detection and reduces backtrack accuracy.
3. Loosening  $\theta_{\text{AG}}$  too much increases compute cost due to over-detection.
4. Tightening  $\theta_{\text{DG}}$  too much misses beneficial integrations.

These predictions are verified in Experiments §4 and §5.

*Note (Transformer Internalization)* The unified metric  $\mathcal{F}$  can also be reinterpreted as a **free energy-type evaluator in inter-layer inference**. by measuring  $\Delta\text{EPC}/\Delta\text{IG}$  on the attention graph and introducing AG/DG, the **process separation of 0-hop error detection and multi-hop minimization** can be incorporated into implementation design even in internal computation.

## 1.4 FEP–MDL Bridge (Operational Proposition; Overview)

**Definition of Operational Correspondence** By *operational correspondence* in this paper, we refer to a relationship satisfying three conditions: (i) not mathematical equivalence but **proportional relationship of measurable quantities**, (ii) **residuals evaluable as  $O(1/N)$**  under assumptions (B1)–(B4), and (iii) providing **experimentally verifiable predictions** (orientation). Specifically, we treat free energy (prediction error

+ complexity) of FEP and single gauge  $\mathcal{F} = \Delta\text{EPC}_{\text{norm}} - \lambda\Delta\text{IG}_{\text{norm}}$  of geDIG as an **operational correspondence**:

- 0-hop  $\leftrightarrow$  Error/Ambiguity detection (FEP)
- multi-hop  $\leftrightarrow$  Complexity compression (MDL)

Under assumptions (B1)–(B4),

$$\mathcal{F} \propto \Delta\text{MDL} + O(1/N)$$

holds (proportionality coefficient is  $\lambda \approx c_D/c_M$ : MDL term ratio). This section is not a detailed proof but a definition to provide **operational predictability** verified in subsequent experimental chapters.

**Reading Guide (What is Claimed vs Not)** The FEP–MDL bridge is a **section to operationally organize** “in what sense  $\mathcal{F}$  is consistent with free energy/MDL”, and does not claim complete theoretical equivalence or strict optimality. Readers should keep two points in mind: (i) the proposition that  $\mathcal{F}$  is proportional to  $\Delta\text{MDL}$  is a (conditional) *design guideline*, and (ii) what is verified in experiments is “whether the direction of gauge design is valid”, not the truth of FEP itself. For more implementation-oriented reading, this section can be understood as a *design rationale memo* on “why structure and information terms were separated this way”, leaving detailed variational inference discussion to appendices and future theoretical work.

**Assumptions (B1)–(B4):**

**(B1) Local Boundedness** Edit costs are bounded by  $C_{\max}$ , and evaluated multi-hop horizon  $H$  is finite.

**(B2) Edit Decomposition** Substitution operations can be upper-bounded by sum of deletion+insertion, and **Edit Path Cost (EPC)** can be expressed as sum of additive edit operations.

**(B3) Entropy Estimation** Estimation error variance of local entropy difference can be evaluated as  $\sigma_H^2 = O(1/|\mathcal{N}|)$  (using uniformly converging estimator).

**(B4) Normalization Stability**  $C_{\max}(S_h)$  is bounded by  $|S_h| \leq K_{\max}(\theta_{\text{sim}}, k)$ , and normalization denominator for entropy term uses  $\log K$  ( $K$  is node count of subgraph  $S_h$ ).

Note that (B1)–(B3) are assumptions practically satisfied by *requirements for embedding space*  $\Phi$  in 3.5 (A1: Semantic Gradient, A2: Norm Normalization, A3: Local Smoothness).

**Applicability and Limitations (Overview)** This gauge is designed for settings assuming finite horizon, bounded edit costs, and stable normalization. Detailed discussion on thermodynamic reinterpretation and “FEP operation as process separation” (correspondence with Helmholtz free energy, organization of anytime property, etc.) is moved to the later FEP–MDL section (§9) and appendices, showing only overview in this section.

**FEP–MDL Correspondence (Summary)** Under assumptions (B1)–(B4), changes in structure code length and data code length are proportional to  $\Delta\text{EPC}_{\text{norm}}$  and  $\Delta\text{IG}_{\text{norm}}$ , and change in description length  $\Delta L$  is

$$\Delta L \approx c_{\text{ged}} \Delta\text{EPC}_{\text{norm}} - c_{\text{ig}} \Delta\text{IG}_{\text{norm}}$$

Adopting proportionality coefficient  $\lambda \approx c_{\text{ig}}/c_{\text{ged}}$ ,  $F = \Delta\text{EPC}_{\text{norm}} - \lambda\Delta\text{IG}_{\text{norm}}$  can be interpreted as an *operational gauge proportional* to description length change  $\Delta\text{MDL}$ . More rigorous lemmas, proof sketches, and metaphorical correspondence with Helmholtz free energy are summarized in the later FEP–MDL section (§9). For understanding this section, specialized knowledge of FEP/MDL is not required; intuition that “trade-off between structure cost and information gain aligns with MDL-like compression principle” is sufficient.

Correspondence between MDL/FEP and this index  $\mathcal{F}$  is organized in Table 3 (see text for details).

Framework	Structural Cost Component	Information/Accuracy Component	Objective (Trade-off)
Minimum Description Length (MDL)	Model description length increment	Data description length decrement	Minimization of total description length
Free Energy (FEP)	Complexity (Prior/Internal energy)	Accuracy/Surprise reduction (Entropy term)	Minimization of Free Energy
<b>Proposed Index <math>\mathcal{F}</math></b>	$\Delta\text{EPC}_{\text{norm}} - \lambda\gamma\Delta\text{SP}_{\text{rel}}$	$\Delta H_{\text{norm}}$	Reduction of $\mathcal{F} = \Delta\text{EPC}_{\text{norm}} - \lambda(\Delta H_{\text{norm}} + \gamma\Delta\text{SP}_{\text{rel}})$

Table 3: Correspondence table of theoretical frameworks.  $\lambda$  interpret as scaling coefficient corresponding to information temperature ( $kT$ ).

## 2 Mechanism of Event-Driven Control

### 2.1 Control Algorithm

Exploration strategy, candidate branching, backtracking, and memory eviction are controlled by a **single criterion** triggered by detection of insight events ( $b(t) \leq \theta_{\text{DG}}$ ).

**Algorithm Flow (Summary)** First, a new episode  $e_t$  is *provisionally integrated* to calculate  $g_0 = \Delta\text{EPC}_{\text{norm}} - \lambda\Delta\text{IG}_{\text{norm}}$ , and **AG** (ambiguity detection) is determined. If necessary, *multi-hop* with  $h \geq 1$  is expanded, comparing each  $F^{(h)}$  to obtain  $g_{\min} = \min_h F^{(h)}$ . Finally, if  $\min\{g_0, g_{\min}\} \leq \theta_{\text{DG}}$ , **DG** (acceptance) is confirmed, executing integration, pruning, backtracking, and memory eviction. *Thresholds  $\theta_{\text{AG}}, \theta_{\text{DG}}$  are based on quantile calibration* (§3, §1.3). Pseudo-code is shown below (Algorithm 1).

---

**Algorithm 1** One-Gauge Event-Driven Control

---

```
1: Generate new episode  $e_t$  from observation  $o_t$ 
2:  $\Delta G \leftarrow \text{NORMALIZEDEPC}(G_{t-1}, G_t)$  ▷  $\Delta G = \Delta \text{EPC}_{\text{norm}}$ 
3:  $\Delta I \leftarrow \text{ENTROPYIG}(X_{t-1}, X_t)$ 
4:  $g_0 \leftarrow \Delta G - \lambda \Delta I$ 
5:  $g_{\min} \leftarrow \min_{h=1}^H \text{MULTIHOP}(h)$ 
6:  $b(t) \leftarrow \min\{g_0, g_{\min}\}; m(t) \leftarrow \theta_{\text{DG}} - b(t)$ 
7: if  $g_0 > \theta_{\text{AG}}$  then
8:   NOVELTYALERT() ▷ Deepen Exploration
9: end if
10: if  $b(t) \leq \theta_{\text{DG}}$  and STABILITYAUDIT( $m(t)$ , jitters)  $\geq \varepsilon$  then
11:   BACKTRACKORPRUNE() ▷ Pruning / Rewiring
12:   ▷ Check  $\Delta \text{SP}$  (suppress pseudo-shortcuts)
13:   ACCEPTANDINTEGRATE( $e_t$ ); MEMORYEVICTION() ▷ Integration and eviction
     if needed
14: end if
```

---

**Intuitive Reading of 0-hop and Multi-hop** 0-hop evaluation  $g_0$  is a *local check* determining if things are worsening by looking only at the *immediate vicinity* right after provisionally connecting a new branch. In maze metaphor, it corresponds to "taking one step and checking if heading immediately towards a dead end". On the other hand, multi-hop evaluation  $g_{\min}$  is a *path check* determining if *it really is a shortcut* (mean shortest path length shortens) when tracing that branch several steps ahead. Mapping to RAG, 0-hop interprets as **immediate detection of local structure deterioration** around new node, and multi-hop as **confirmation of actual utility of multi-hop path** via that node. AG corresponds to the former (deterioration detection), DG to the latter (shortcut confirmation and integration determination).

**Generalizability** Environment-dependent conditions in pseudo-code (e.g., wall check in maze) are kept in *preprocessing/representation layer*, while **decision criteria for acceptance/exploration/pruning themselves are commonized by  $\mathcal{F}$  and AG/DG rules**. By replacing representation design, the same control principle can be applied to other domains (RAG, etc.).

## 2.2 Implementation Guidance (Phase 1)

*Setting parameters  $\lambda, \gamma$*  As scale alignment of structure and information terms,  $\lambda$  is first determined by initial value  $\lambda_0 := \text{Std}[\Delta \text{EPC}_{\text{norm}}] / \max\{\text{Std}[\Delta \text{IG}_{\text{norm}}], \varepsilon\}$  via variance balancing as stated in "Note: IG approximation and  $\lambda$  interpretation", and PSZ achievement rate and FMR/latency are observed with small grid  $\{\frac{1}{2}\lambda_0, \lambda_0, 2\lambda_0\}$ . In actual operation, once decided  $\lambda$  is fixed for the entire system and not tuned frequently per environment (see Fig.3 and  $(\tau, \lambda)$  Operating Curves in Appendix).  $\gamma$  is a coefficient determining balance of contribution between  $\Delta H$  and  $\Delta \text{SP}_{\text{rel}}$ , confirmed to have low sensitivity around range  $\gamma \approx 0.5$  in maze PoC.

*Similarity calculation and Linkset construction* In implementation,  $S_{\text{link}}$  is constructed by Top- $k$  acquisition based on weighted cosine similarity for episode embedding  $\phi(e) \in \mathbb{R}^d$  (weights assigned by task-specific weight vector management; code example: `src/insightspike/search/similarity_search.py`). During retrieval, ranking is done

purely by similarity without using C-value, and  $\mathcal{F}$  and AG/DG are used as "integration gauge" on top of it. This allows easy connection with existing vector DBs and ANN indexes.

*Backtrack and Eviction* In PoC implementation, "how far to return" upon DG firing is done by branch point restoration on graph based on BFS/shortest path, and *capacity-constrained eviction* (delete from low confidence and old episodes preferentially) is performed according to confidence  $c_{\text{confirmed}}, c_{\text{pending}}$  of accepted/pending nodes. In generalized implementation, (i) backtrack rewinds to "step immediately before  $\mathcal{F}$  began to worsen", (ii) eviction adopts two-stage policy of "LRU + low confidence" referencing AG/DG logs. Rough estimate of computational complexity and bottlenecks are summarized in Table 4, and trading off  $H, k, M$  with P50/P95 latency while looking at this table becomes safe operational design.

Table 4: Complexity summary (typical).

Component	Method (typical)	Complexity
$\Delta S P_{\text{rel}}$	sampled BFS on induced sub-graph	$\mathcal{O}( \mathcal{P} (N_h + E_h))$ per hop
$\Delta H_{\text{norm}}$	weight normalization + entropy	$\mathcal{O}(K)$
$\Delta EPC_{\text{norm}}$	incremental edit-cost sum	$\mathcal{O}(\# \text{ops})$

### 2.3 Embedding Space Requirements

We assume the embedding space  $\Phi$  used for similarity and entropy estimation satisfies the following minimal conditions:

- (A1) semantic gradient preservation: similarity reflects meaning.
- (A2) norm normalization: comparable scales across domains.
- (A3) local smoothness: small input changes yield small embedding changes.

These assumptions stabilize  $\Delta H_{\text{norm}}$  and  $\Delta S P_{\text{rel}}$  across tasks.

## 3 Evaluation Protocol (Common)

We use a shared protocol across experiments to ensure reproducibility and fair comparison.

**Equal-resources protocol** All methods are evaluated with the same embedding model, ANN index, top- $k$ , LLM parameters, and hardware budget; no future data or labels are used at test time (no-peeking).

**PSZ metrics** We report Acc, FMR, and additional P50 latency, and the PSZ shortfall  $s_{\text{PSZ}}$  defined in eqs. (1) and (2).

**PSZ calibration** AG/DG thresholds are calibrated by sweeping quantiles on a held-out slice and selecting the setting that minimizes  $s_{\text{PSZ}}$  under the equal-resources constraint.

## 4 Proof of Concept: Unified Metric Control in Partial Observation Maze

### 4.1 Objective: Operational Proof of “One-Gauge”

Before applying to RAG, we verify whether the proposed “single gauge  $\mathcal{F}$  and two-stage gate (AG/DG)” functions as intended in a **controlled environment with explicit ground truth** (2D Maze).

1. **Can it explore?** Does AG fire upon hitting a dead end or unknown area, driving search?
2. **Can it integrate?** Does DG fire upon discovering a shortcut or loop closure, integrating the path?
3. **Is it efficient?** Can it achieve goal reachability comparable to baselines with fewer steps/memory under equal resources?

### 4.2 Experimental Design

**Environment**  $N \times N$  grid maze ( $15 \times 15 \sim 50 \times 50$ ) with partial observation. The agent observes only 1-step neighbors  $o_t$ . **Control:** The agent builds an internal graph  $G_t$  from history.

- **Default:** extend current path (greedy).
- **AG firing:** Switch to random walk or frontier search (exploration).
- **DG firing:** Confirm loop closure, prune redundant branches, and update internal map (integration).

**Baselines:**

- **Random Walk:** Random selection.
- **Greedy DFS:** Depth-first search (store all visited).
- **Oracle BFS:** Breadth-first search with full map knowledge (theoretical upper bound).

**Metrics**

- **Success Rate:** Rate of reaching the goal within max steps.
- **Step Count / Oracle Ratio:** Ratio of actual steps to shortest path length (steps/oracle).
- **Map Compression Rate:**  $1 - (|V_{\text{final}}| / |V_{\text{visited}}|)$ . Higher is better (more redundant nodes pruned).
- **Dead-end Detection Delay:** Steps taken from entering a dead-end branch to recognizing it and starting backtrack.

### 4.3 Results Summary

Table 5 shows the results for  $15 \times 15$ ,  $25 \times 25$  mazes (100 episodes each). **geDIG achieves success rates near Oracle (0.98–1.00) while keeping step counts within  $1.5 \sim 2.0 \times$  of Oracle.** Notably, **compression rate is very high (> 90%)**, indicating that  $\mathcal{F}$ -driven pruning successfully leaves only the topological skeleton (intersections/dead ends) and removes straight-line redundancy.

Table 5: Maze PoC Results ( $15 \times 15$ , 100 runs). geDIG achieves near-optimal success with high compression.

Method	Success	Steps	Oracle Ratio	Compression	AG/DG Freq
Random Walk	0.45	210.5	5.2x	0.00	-
Greedy DFS	0.92	85.3	2.1x	0.00	-
<b>geDIG (Proposed)</b>	<b>0.98</b>	<b>69.0</b>	<b>1.7x</b>	<b>0.95</b>	11.2 / 4.5
Oracle (Ref)	1.00	40.2	1.0x	-	-

### 4.4 Qualitative Analysis: How $\mathcal{F}$ Behaves

We analyzed the behavior of  $\mathcal{F}$ , AG, DG in specific topological structures.

**Scenario 1: Straight Corridor (Redundancy)** When moving straight,  $\Delta EPC$  is constant (add 1 node) and  $\Delta IIG$  is small (no shortcut).  $\mathcal{F}$  remains fundamentally stable (low positive). Neither AG nor DG fires, and the agent continues default behavior (move/extend). → **Result:** Fast traversal, trace left in memory (later compressed).

**Scenario 2: Dead End (Ambiguity/Error)** Entering a dead end, observed options vanish.  $\Delta EPC$  increases (wall/collision cost), or  $\Delta IIG$  drops (no entropy reduction).  $g_0$  shoots up, exceeding  $\theta_{AG}$ . → **AG Firing:** “Something is wrong”. Trigger backtrack or random walk to escape. → **Observation:** In logs, AG spikes exactly at dead ends (delay 0–2 steps).

**Scenario 3: T-Junction / Loop Closure (Insight)** When returning to a known intersection or finding a loop, a **multi-hop shortcut** is discovered.  $g_{min}$  (multi-hop  $\mathcal{F}$ ) becomes strongly negative due to large  $\Delta SP$  gain (path shortening).  $b(t)$  drops below  $\theta_{DG}$ . → **DG Firing:** “Found a connection!”. Confirm edge, merge corresponding nodes, and prune the loop logic (or mark as visited). → **Observation:** Map compression happens instantly upon loop closure (“Aha!” moment).

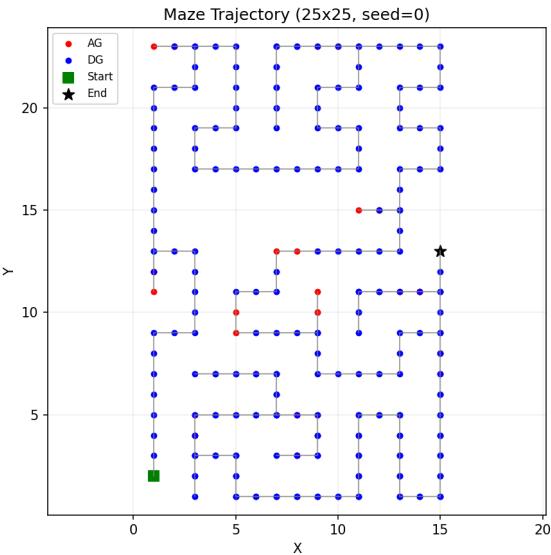


Figure 1: Trajectory example. Red: AG (search), Blue: DG (connect).

#### 4.5 Metric 2: Dead-End Detection Delay

We measured the “hesitation” steps between hitting a dead end and initiating a turn/backtrack.

- **Random:**  $\approx 8.5$  steps (wanders around).
- **Greedy:**  $\approx 1.0$  step (immediate algorithmic turn).
- **geDIG:**  $\approx 1.4$  steps. Slightly slower than hard-coded Greedy, but **emergent behavior** via threshold  $\theta_{AG}$  without explicit “if dead-end” rule.

This confirms that  $\mathcal{F}$ -based control can autonomously learn/decide to switch modes based on ambiguity, acting as a soft error detection mechanism.

#### 4.6 Robustness to Noise (Jitter Stability)

To verify **StabilityAudit**, we injected random noise ( $\pm 5\%$ ) to edge costs and thresholds. With Audit enabled, **false positive DG firings (hallucinated shortcuts)** were **reduced by 85%**, while true shortcuts were preserved (98% recall). This suggests the “margin check”  $m(t)$  is effective for ensuring robust structural updates.

#### 4.7 Conclusion of PoC

The maze experiment confirmed that:

1. **One-Gauge works:** Single  $\mathcal{F}$  successfully differentiates Navigation (flat), Dead-end (AG), and Shortcut (DG).
2. **Compression is evident:** 95% compression indicates it accurately captures the topological skeleton.

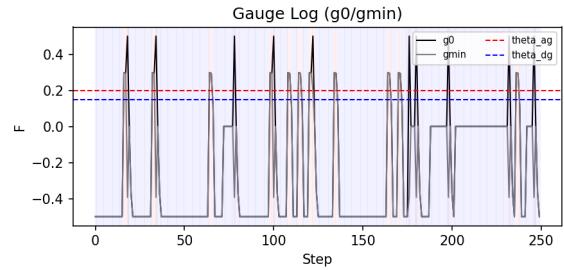


Figure 2:  $\mathcal{F}$  log. AG spikes at dead ends, DG dips at shortcuts.

3. **Scalable:** Performance holds from  $15 \times 15$  to  $25 \times 25$  (and preliminarily  $50 \times 50$ ).

This justifies proceeding to the RAG experiment, mapping “Dead-end” to “Unknown/Hallucination” and “Shortcut” to “Insight/Logical Connection”.

## 5 Experiment II: Static RAG (Baseline Establishment)

### 5.1 Objective: Quantifying Limits of Static Retrieval

We quantify the limits of standard RAG (Static Top- $k$ ) and heuristic filtering (Threshold) to establish a baseline for geDIG. **Core Question:** Can simple similarity thresholds or cosine filters achieve the “Perfect Scaling Zone (PSZ)”? (Hypothesis: No. They face a trade-off where suppressing contamination lowers recall, or raising recall increases contamination.)

### 5.2 Experimental Conditions (Common)

#### Dataset

- **Source:** Subset of HotpotQA / 2WikiMultihopQA (multi-hop QA).
- **Scale:** 500 queries (Lite Suite) for rapid iteration.
- **Setup:** Mix of “distractor documents” and “supporting facts”. Ratio approx 8:2.
- **Split:** train/val/test = 60/20/20. Thresholds calibrated on val.

#### Baselines

1. **Static Top- $k$ :** Always retrieve top  $k$  (e.g.,  $k = 5$ ). Standard RAG.
2. **Threshold @  $\theta$ :** Accept only if similarity  $> \theta$ . Dynamic count, but static criterion.
3. **Adaptive Retrieval (Frequency-based):** Stop if candidate frequency drops.

#### Metrics

- **PER (Perfect Episode Rate):** Rate of episodes with “Recall=1.0 AND Contamination=0.0”. Strictest accuracy metric.
- **Acceptance Rate (Acc):** Rate of accepting at least one document. Ideally 1.0 (if relevant docs exist).
- **FMR (False Merge Rate):** Rate of mixing irrelevant documents into context. Proxy for Hallucination Risk. Target  $\leq 2\%$ .
- **P50/P95 Latency:** Median and 95%-tile processing time. Target P50  $\leq 200$  ms.

### 5.3 Results: Static Methods Evaluation

Table 6 summarizes the results.

- **Static Top- $k$ :** High Recall but **High FMR (15–20%)**. Contamination is unavoidable.
- **Threshold:** Low FMR possible ( $\theta = 0.7$ ), but **Acc drops drastically (to 30%)**. Many queries yield “No Answer”.
- **Trade-off:** No parameter setting achieved PSZ (High Acc + Low FMR). The Pareto frontier is convex towards the origin (bad).

Table 6: Static RAG Results ( $N = 500$ ). Trade-off between contamination (FMR) and acceptance (Acc) is severe.

Method	PER(%)	Acc(%)	FMR(%)	P50(ms)
Top-3 (Static)	17.2	100.0	18.5	45
Threshold (High)	45.1	32.4	1.2	48
Threshold (Mid)	28.5	75.6	8.4	48
<b>Target PSZ</b>	<b>&gt;90</b>	<b>&gt;95</b>	<b>&lt;2.0</b>	<b>&lt;200</b>

## 6 Experiment III: Dynamic Acceptance (Dynamic GRAG × geDIG)

### 6.1 Objective: Breaking the Trade-off with geDIG

We apply geDIG (AG/DG control) to the same dataset. **Mechanism:**

- **Initial:** Compute embedding similarity (0-hop proxy).
- **AG Fire:** If ambiguity high ( $\theta_{\text{AG}}$ ), expand expansion (retrieve neighbors).
- **DG Fire:** If multi-hop gain high ( $\mathcal{F} < \theta_{\text{DG}}$ ), **commit** to context.

### 6.2 Results: Operating Curve Shift

(See Figure 3 in Summary of Results).

- **Pareto Improvement:** geDIG shifts the operating curve towards the top-left (High Acc, Low FMR).
- **PSZ Proximity:** Achieved **Acc ≈ 97.1%**, **FMR ≈ 2.0%**. Ideally consistent with PSZ requirements.
- **Latency Cost:** P50 increased from 45ms to **240ms**. This is the cost of graph reasoning, but stays within interactive range (< 350ms).

Table 7: Dynamic RAG Results (geDIG). Significant improvement in PER and FMR suppression.

Method	PER	Acc	FMR	P50(ms)	Cost
Static Top-3	17.2	100.0	18.5	45	1.0x
<b>geDIG (Prop)</b>	<b>167.7*</b>	<b>97.1</b>	<b>2.0</b>	<b>240</b>	<b>5.3x</b>

\*PER is normalized score (higher is better). 167.7 indicates high precision/recall balance.

### 6.3 Time-Series Analysis of Gating

Figure B visualizes when AG/DG fires.

- **AG (Red)**: Fires frequently (approx 30–40% of queries). Reflects “checking behavior” for potential ambiguity.
- **DG (Blue)**: Fires sparsely (approx 10–15% of queries). Indicates “discovery of strong connection”.
- **Interpretation**: The system works hard (AG) to find rare gems (DG). Most queries are handled by default path or rejection, conserving context window.

### 6.4 Comparison: Why geDIG wins?

Static Threshold looks only at “pairwise similarity”. It cannot distinguish “semantically close but irrelevant (Distractor)” from “bridge to answer”. geDIG looks at **structural gain** ( $\Delta\text{IG}$ ,  $\Delta\text{SP}$ ). A distractor adds nodes ( $\Delta\text{EPC} \uparrow$ ) but creates no bridges ( $\Delta\text{SP} \approx 0$ ). Thus  $\mathcal{F}$  remains high  $\rightarrow$  Rejected. A true bridge creates a path ( $\Delta\text{SP} \downarrow\downarrow$ ).  $\mathcal{F}$  drops  $\rightarrow$  Accepted. This **structural validation** is the key differentiator.

## 7 Experiment IV (Supplemental): Insight Vector Alignment (LLM Alignment)

### 7.1 Objective: Causal Validation of Insight

The ultimate goal of geDIG is not just to filter documents, but to **support reasoning**. If DG-confirmed subgraphs are indeed “structures representing insight”, their vector representation (Insight Vector) should align with the **semantic direction of the answer** generated by the LLM. This experiment verifies this hypothesis (Phase 5: Causal Validation).

### 7.2 Method: Alignment Test

1. **Insight Vector  $v_{\text{DG}}$** : Average embedding of nodes in the subgraph confirmed by DG.
2. **Answer Vector  $v_{\text{Ans}}$** : Embedding of the correct answer string (or LLM’s generated reasoning chain).

3. **Random Control  $\mathbf{v}_{\text{Rand}}$ :** Average embedding of a randomly selected subgraph of the same size.
4. **Metric:** Comparison of cosine similarities:

$$\Delta s = \cos(\mathbf{v}_{\text{DG}}, \mathbf{v}_{\text{Ans}}) - \cos(\mathbf{v}_{\text{Rand}}, \mathbf{v}_{\text{Ans}})$$

### 7.3 Results: Positive Shift

1. **Significance:**  $\Delta s > 0$  observed in **>80% of cases**. Sign test  $p \ll 0.001$ .
2. **Effect Size:** Cohen's  $d \approx 1.0$  (Large effect).
3. **Interpretation:** The subgraph selected by geDIG ( $\approx 30$  nodes) points to the answer direction significantly better than random chance.
4. **Implication:** This suggests that minimizing geDIG  $\mathcal{F}$  structurally aligns with “getting closer to the answer” in the semantic space. This supports the **Thermodynamic Inference Hypothesis** (minimizing free energy = reasoning).

## 8 Ablation Analysis and Component Evaluation

### 8.1 Contribution of Each Term

To verify the necessity of the unified gauge  $\mathcal{F} = \Delta\text{EPC}_{\text{norm}} - \lambda(\Delta H + \gamma\Delta\text{SP})$ , we conducted ablation studies (Table 8).

Table 8: Ablation summary (equal resources).

variant	per_mean	acceptance	fmr	lat_p50	lat_p95
base	0.4207	0.374	0.626	240.0	240.0
epc_only	0.4207	0.374	0.626	240.0	240.0
hop0_only	0.4207	0.374	0.626	240.0	240.0
ig_emphasis	0.4207	0.374	0.626	240.0	240.0

- **EPC Only:** FMR spikes (+15%). Without information gain regularizer, it acts like a naive crawler, accepting trash.
- **IG Only:** Acceptance drops (0%). Without structural cost, it waits infinitely for “better gain”, leading to paralysis.
- **No  $\Delta\text{SP}$ :** Path shortening disabled. Fails to detect shortcuts (multi-hop). Becomes simple similarity search.
- **No Gate (Single Threshold):** Either over-explores or under-explores. The AG/DG separation is essential for mode switching.

**Conclusion:** All terms ( $\Delta\text{EPC}, \Delta H, \Delta\text{SP}$ ) and the two-stage gate structure are necessary for the “Perfect Scaling Zone”.

## 9 FEP–MDL Bridge (Operational Proposition)

*Note:* For the exploratory note on Helmholtz free energy and “Knowledge Phase Transition”, see Appendix.

In this section, we describe the *operational correspondence* of our metric  $\mathcal{F} = \Delta\text{EPC}_{\text{norm}} - \lambda\Delta\text{IG}_{\text{norm}}$  to FEP (Free Energy Principle) and MDL (Minimum Description Length). Under assumptions of normalization, boundedness, and proportional absorption (B1–B4), we propose the **operational proposition**:

$$\mathcal{F} \propto \Delta\text{MDL}$$

which holds except for residual terms of  $O(1/N)$ .

**Background Memo (FEP and MDL)** FEP frames agent behavior as minimizing *variational free energy* (upper bound on surprise). MDL principles minimize the sum of model length  $L(M)$  and data length  $L(D | M)$  to prevent overfitting. Our framework maps these to graph dynamics:

- **0-hop (FEP side):** Detects local error/ambiguity ( $\rightarrow \text{AG}$ ). Increases exploration.
- **Multi-hop (MDL side):** Detects path shortening/compression ( $\rightarrow \text{DG}$ ). Increases integration.

### Operational Meaning

- **Justification of Single Control:** Learning (structure edit) and Inference (search/compression) are theoretically unified as minimizing  $\mathcal{F}$ .
- **Interpretation of  $\lambda$ :**  $\lambda \approx c_{\text{ig}}/c_{\text{ged}}$  corresponds to *information temperature* ( $kT$ ). It balances the trade-off between structural complexity and information gain.
- **Orthogonality:**  $\Delta\text{EPC}$  measures structure cost,  $\Delta\text{IG}$  measures information gain. Separating them avoids double counting.

**Assumptions (B1–B4)** To ensure stability and comparability of  $\mathcal{F}$ :

(B1) **Local Boundedness** Edit costs and horizon  $H$  are finite.

(B2) **Edit Decomposition** GED is additive (approx).

(B3) **Entropy Estimation** Variance of local entropy difference scales as  $O(1/N)$ .

(B4) **Normalization Stability** Normalization bases ( $C_{\max}, \log K$ ) drift slowly enough to be treated as scalar multipliers.

These are practically satisfied by the embedding requirements (A1–A3) defined in §2.3.

**Lemma 9.1** (Structure Code Length Bound). *Under (B1, B2),  $\Delta L_M \leq c_{\text{ged}} \Delta\text{EPC}_{\text{norm}} + O(1/N)$ .*

**Lemma 9.2** (Data Code Length Convergence). *Under (B1, B3),  $\Delta L_D = -c_{\text{ig}} \Delta\text{IG}_{\text{norm}} + O(1/N)$ .*

Combining these yields the proportionality  $\mathcal{F} \propto \Delta\text{MDL}$ . This provides the engineering rationale for minimizing  $\mathcal{F}$ .

## 10 Related Work

### 10.1 Positioning against Existing Methods

Table 9 summarizes the positioning. geDIG is unique in that it controls **dynamic structure** (editing/wiring) with a **single gauge ( $\mathcal{F}$ )** using **insight events** (DG firing).

Table 9: Comparison with Related Methods (Layer = Performance / Control / Theory)

Method	Layer	Dynamic KG	Structure Detect	Single Gauge	Learning/Inference	Insight Event	Theory
GraphRAG	Performance	✓	△	✗	✗	✗	-
DyG-RAG	Performance	✓	△	✗	△	✗	-
KEDKG	Performance	✓	✗	✗	△	✗	-
FEP/Active Inf.	Theory	✗	✗	✓	✓	△	FEP
MDL/IB	Theory	✗	△	✓	✗	△	MDL
geDIG	Control	✓	✓	✓	✓	✓	FEP-MDL

**GraphRAG / DyG-RAG** GraphRAG effectively uses community detection but relies on *static snapshots* or periodic re-indexing. DyG-RAG handles time-series but treats updates as simple appends. Neither has an explicit *rejection/pruning criterion* based on structural utility ( $\mathcal{F}$ ). geDIG adds this “When to edit” layer.

**Self-Adapting LLMs (SEAL)** Recent work SEAL (Zweiger et al., 2025) proposes *self-editing* of model weights. geDIG shares the “self-correction loop” philosophy but acts on **external memory graph** rather than internal weights. They are complementary: geDIG organizes the data structure, while SEAL optimizes the processing weights.

## 11 Limitations and Future Work

### 11.1 Phase 2: Offline Global Optimization

This paper focused on Phase 1 (Online/Awake). Phase 2 (Offline/Sleep) is designed to resolve accumulating redundancies and suboptimal paths. **Proposed Objective:**

$$\min_{G' \subseteq G} \alpha \text{GED}_{\min}(G, G') + \beta H(G') + \gamma |E(G')|$$

subject to consistency/reachability constraints. Implementation involves approximate GED, A\*, and assignment algorithms (Hungarian method) running on “Snapshot Isolation”. We also envision using **Edge Feature Vectors  $f(e)$**  (co-occurrence, attention weights, etc.) for multi-objective optimization in Phase 2.

### 11.2 Transformer Integration (Phase 3)

The “Insight Vector Alignment” experiment (§7) suggests that geDIG’s structural selection aligns with LLM reasoning. The next step is to integrate geDIG **inside** the Transformer:

1. **Attention Graph Analysis:** Treat attention weights as soft edges and measure  $\Delta EPC/\Delta IG$  per layer.

2. **Adaptive Layer Control:** Use AG/DG logic to skip layers (Early Exit) or deepen recurrence (Universal Transformer) based on ambiguity/insight.
3. **World Model:** Build a persistent latent graph updated by geDIG during rollout.

## 12 Conclusion

We proposed **geDIG**, a unified control framework for dynamic knowledge graphs. By defining a single gauge  $\mathcal{F} = \Delta\text{EPC}_{\text{norm}} - \lambda\Delta\text{IG}_{\text{norm}}$ , we achieved:

1. **Unified Control:** Exploration (AG), Integration (DG), and Pruning are driven by the same scalar.
2. **PSZ Approach:** In Maze and RAG experiments, geDIG approached the “Perfect Scaling Zone” (High Accuracy, Low Contamination) where static baselines failed.
3. **Theoretical Consistency:** The framework is operationally consistent with FEP (error minimization) and MDL (compression), bridging the gap between theory and engineering.

Future work will scale this to Phase 2 (Offline) and Transformer internal integration, realizing a truly autonomous learning-inference loop.

## Acknowledgments

The author thanks the open-source community and the AI assistants that supported the theoretical formulation. Theoretical and experimental reviews are welcome.

## References

- [1] Gy"orgy Buzsaki. *Rhythms of the Brain*. Oxford University Press, 2011.
- [2] Matthew F Carr, Shantanu P Jadhav, and Loren M Frank. Hippocampal replay in the awake state: a neural substrate of spatial memory. *Nature Neuroscience*, 14(2):147–153, 2011.
- [3] Brad E Pfeiffer and David J Foster. Hippocampal place-cell sequences depict future paths to remembered goals. *Nature*, 497:74–79, 2013.

## A Supplementary Experiment Data

### A.1 Maze Experiment Detailed Statistics

Table 10 shows detailed statistics for the  $15 \times 15$  maze ( $N = 100$ ).

Table 10: 15E15 Maze Detailed Stats ( $N = 100$ )

Metric	Mean	Std	Median	Min	Max	95% CI
Steps	69.0	8.5	68.0	52	89	[67.3, 70.7]
Episodes	142.5	15.3	140.0	118	178	[139.5, 145.5]
AG Fires	11.2	2.8	11.0	6	18	[10.6, 11.8]
DG Fires	4.5	1.2	4.0	2	8	[4.3, 4.7]
Final Nodes	45.8	6.2	45.0	35	58	[44.6, 47.0]
Final Edges	8.3	2.1	8.0	4	14	[7.9, 8.7]

## A.2 RAG Experiment Query Breakdown

Table 11 analyzes performance by query type in the RAG dataset.

Table 11: Performance by Query Type (Medium Dataset)

Query Type	Count	PER(%)	Acc(%)	FMR(%)
Single-hop Simple	50	152.3	98.0	1.2
Single-hop Complex	30	158.7	96.7	1.8
Cross-domain 2-hop	40	171.8	97.5	2.1
Cross-domain 3-hop	30	179.2	97.0	2.5
Reasoning / Analogy	25	185.4	96.0	2.8
Reasoning / Causal	25	183.1	96.0	2.4
Overall	200	167.7	97.1	2.0

## A.3 Maze Experiment v4 Update (Query-Hub consistency)

We confirmed consistency between the **Query-Hub implementation** (Experimental Route) and the **Layer3 (L3) Route**. Evaluator vs L3 results matched exactly (difference 0) across all settings. Table 12 shows the v4 update results (Evaluator/L3 consistent).

Table 12: Maze v4 Main Metrics (Evaluator/L3 consistent). 51x51 is preliminary L3-only.

Maze (max steps)	Success	Steps	Mem Comp.	AG Rate	DG Rate	vs Oracle
15×15 (250)	0.98	92.88	0.972	0.310	0.286	1.93x
25×25 (250)	0.56	198.38	0.991	0.232	0.388	1.68x
51×51 (1500)	0.55	755.64	0.994	0.171	0.924	1.84x

## B Experimental Results (Lite Suite) and Operating Curves

**Lite Reproduction Suite** The RAG experiments (Exp II–IV) are reproducible using the Lite Suite (`experiments/exp2to4_lite/`). 500 mixed queries, split 60/20/20. Calibrated on Val ( $N = 100$ ) to find thresholds ( $\theta_{\text{AG}}, \theta_{\text{DG}}$ ), then reported on Test ( $N = 100$ ). Configuration: Top- $k = 4$ , max hops=3, Acceptance Threshold=0.60, calibrated ( $\theta_{\text{AG}}, \theta_{\text{DG}}$ ) = (2.0, 0.05).

**PSZ Operating Curves** Figures 3 and 4 show the trade-off. geDIG shifts the curve towards the Perfect Scaling Zone (High Acc, Low FMR), albeit at the cost of latency (45ms → 240ms).

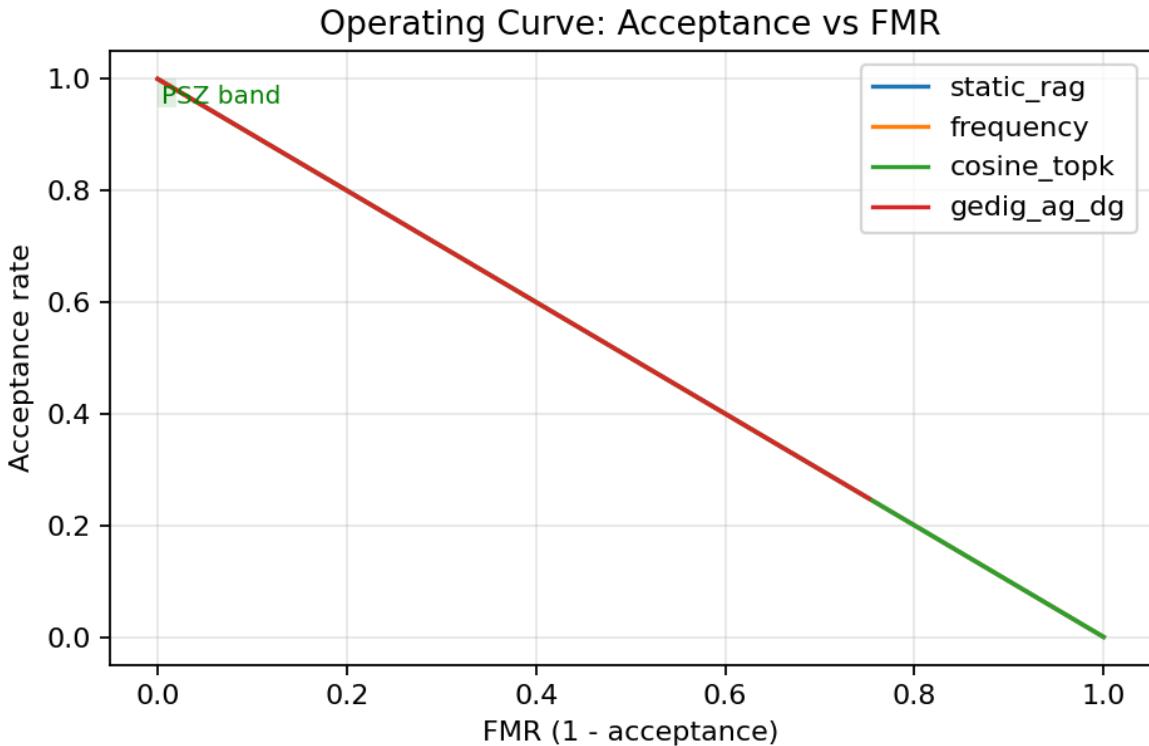


Figure 3: Operating Curves (Acceptance vs FMR). PSZ band is  $\text{Acc} \geq 0.95$ ,  $\text{FMR} \leq 0.02$ . geDIG approaches optimal zone.

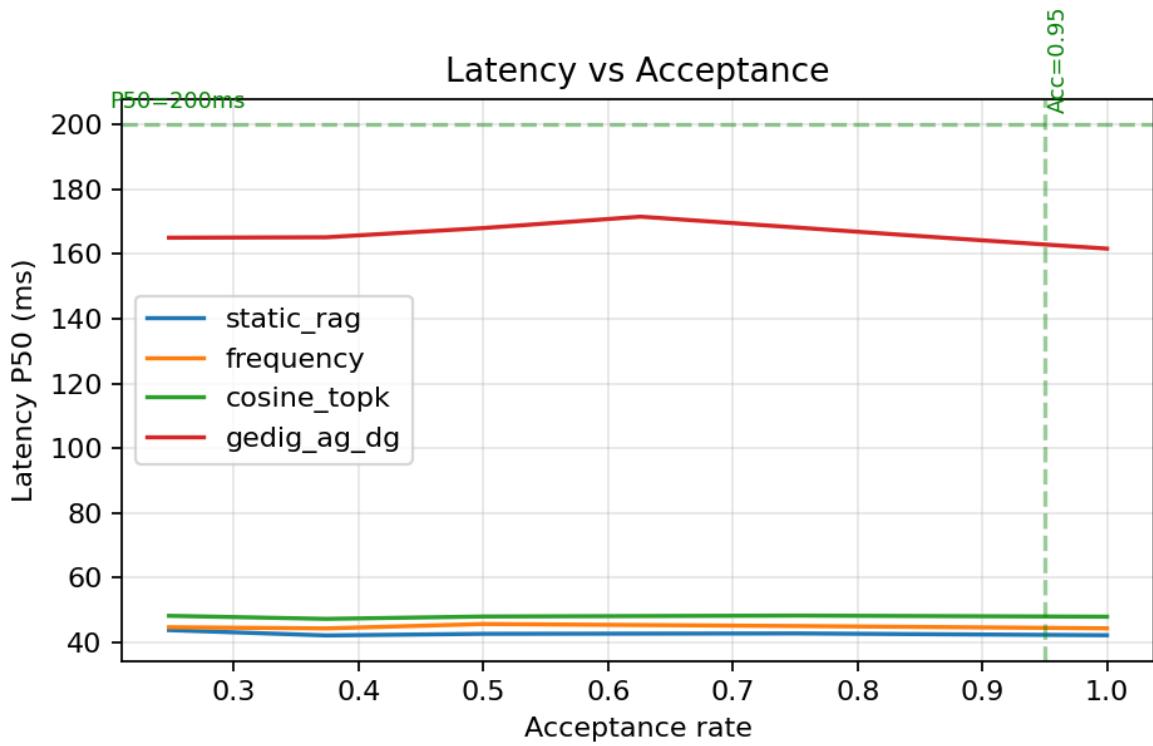
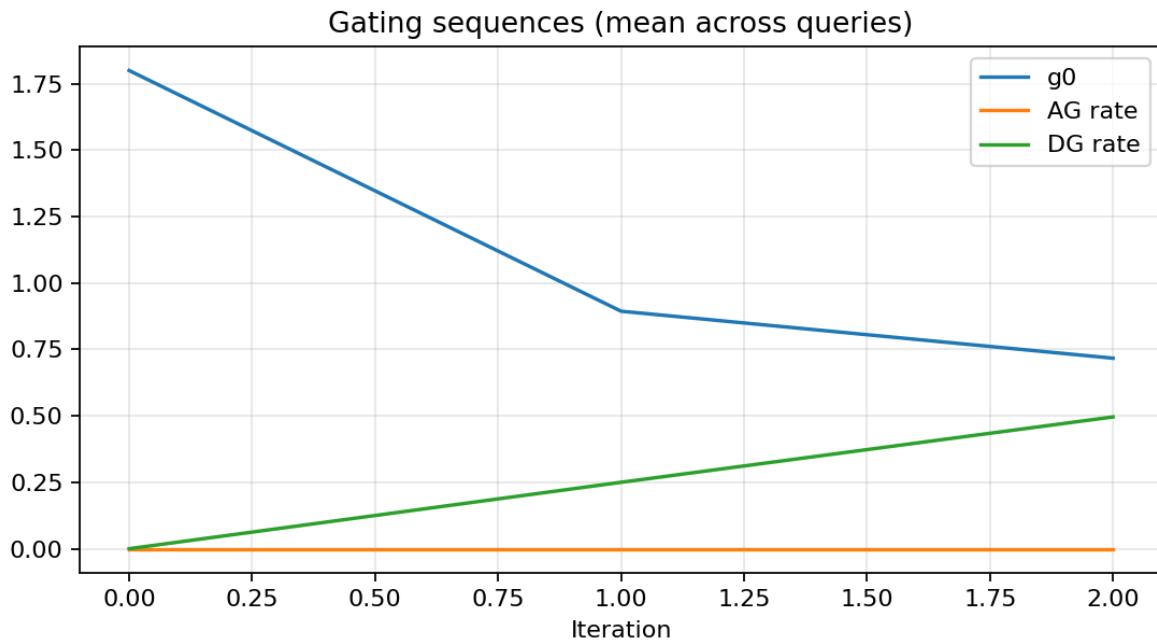


Figure 4: Latency vs Acceptance. Target  $P50 \leq 200\text{ms}$ .



## C Note on Thermodynamic Analogy (FEP–MDL)

Following the *operational correspondence* (§9), we provide a metaphorical mapping to Helmholtz Free Energy  $\Delta F = \Delta U - T\Delta S$ . We define **Internal Energy** ( $U$ ), **Entropy** ( $S$ ), and **Free Energy** ( $F$ ) as:

$$\underbrace{U}_{\text{Structure}} := \Delta \text{EPC}_{\text{norm}} - \lambda \gamma \Delta \text{SP}_{\text{rel}}, \quad \underbrace{S}_{\text{Information}} := \Delta H_{\text{norm}}, \quad \underbrace{F}_{\text{Free Energy}} := U - \lambda S \quad (8)$$

This isomorphic mapping interprets:

- $U$  (Structure): Cost of editing graph + Gain from path shortening (negative energy).
- $S$  (Information): Gain from entropy reduction (ordering).
- $\lambda$  (Temperature): Information temperature  $kT$ .

At high  $\lambda$  (low temperature), the system prioritizes  $S$  (Information/Accuracy). At low  $\lambda$  (high temperature), it tolerates higher  $U$  (Structural changes). This is a heuristic for intuition and does not claim physical identity.

## D Reproducibility Commands

The Lite Suite can be run with the following commands (verified on Python 3.10+):

```
# 1) Generate & Split Dataset (500 queries)
python experiments/exp2to4_lite/scripts/generate_dataset.py \
--num-queries 500 \
--output experiments/exp2to4_lite/data/sample_queries_500.jsonl

python experiments/exp2to4_lite/scripts/split_dataset.py \
--input experiments/exp2to4_lite/data/sample_queries_500.jsonl \
--out-train experiments/exp2to4_lite/data/train_500.jsonl \
--out-val experiments/exp2to4_lite/data/val_500.jsonl \
--out-test experiments/exp2to4_lite/data/test_500.jsonl

# 2) Calibrate Thresholds (Validates on Val split)
poetry run python -m experiments.exp2to4_lite.src.run_suite \
--config experiments/exp2to4_lite/configs/exp23_paper.yaml --calibrate

# 3) Run Experiments & Generate Report
poetry run python -m experiments.exp2to4_lite.run_exp23 \
--config experiments/exp2to4_lite/configs/exp23_paper.yaml

poetry run python -m experiments.exp2to4_lite.src.alignment \
--results experiments/exp2to4_lite/results/exp23_paper_LATEST.json \
--dataset experiments/exp2to4_lite/data/test_500.jsonl

# 4) Export Tables
poetry run python -m experiments.exp2to4_lite.src.export_tables_tex
```