

MACHINE LEARNING

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ABSTRACT. Everything about Machine Learning.

Part 1. Introduction

0.0.1. *Terminology.*

inputs \equiv independent variables \equiv predictors (cf. statistics) \equiv features (cf. pattern recognition)

outputs \equiv dependent variables \equiv responses

cf. Chapter 2 Overview of Supervised Learning, Section 2.1 Introduction of Hastie, Tibshirani, and Friedman (2009) [1]

cf. Chapter 2 Overview of Supervised Learning, Section 2.2 Variable Types and Terminology of Hastie, Tibshirani, and Friedman (2009) [1]

0.0.2. *FinSet.*

The category $\mathbf{FinSet} \in \mathbf{Cat}$ is the category of all finite sets (i.e. $\mathbf{Obj}(\mathbf{FinSet}) \equiv$ all finite sets) and all functions in between them;

note that $\mathbf{FinSet} \subset \mathbf{Set}$ ¹

Recall that the \mathbf{FinSet} *skeletal* is

0.1. **Supervised Learning.** cf. <http://cs229.stanford.edu/notes/cs229-notes1.pdf>

Consider data to belong to the category of all possible data:

$$\mathbf{Data} \equiv \mathbf{Dat} = (\mathbf{Obj}(\mathbf{Dat}), \mathbf{MorDat}, 1, \circ), \quad \mathbf{Dat} \in \mathbf{Cat}$$

Consider the **training set**:

$$\text{training set} := \{(x^{(i)}, y^{(i)}) | i = 1 \dots m, x^{(i)} \in \mathcal{X}, y^{(i)} \in \mathcal{Y}\}$$

where \mathcal{X} is a manifold (it can be topological or smooth, EY:20160502 I don’t know exactly because I need to check the topological and/or differential structure); $\mathcal{Y} \in \mathbf{Obj}(\mathbf{FinSet})$, or ($\mathcal{Y} \in \mathbf{Obj}(\mathbf{Top})$ (or $\mathcal{Y} \in \mathbf{Obj}(\mathbf{Man})$)).

So training set $\subset \mathcal{X} \times \mathcal{Y} \in \mathbf{Obj}(\mathbf{Dat})$.

I propose that there should be a functor H that represents the “learning algorithm”:

$$\mathbf{Dat} \xrightarrow{H} \mathbf{ML}$$

s.t.

$$H : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbf{Hom}(\mathcal{X}, \mathcal{Y})$$

$$H(\text{training set}) = H(\{(x^{(i)}, y^{(i)}) | i = 1 \dots m\}) = h$$

When $\mathcal{Y} \in \mathbf{Obj}(\mathbf{FinSet})$, *classification*.

When $\mathcal{Y} \in \mathbf{Obj}(\mathbf{Top})$ (or $\mathbf{Obj}(\mathbf{Man})$), *regression*.

0.1.1. *Linear Regression.* Keeping in mind

$$\mathbf{Dat} \xrightarrow{H} \mathbf{ML}$$

Consider

$$h : \mathbb{R}^p \rightarrow \mathbf{Hom}(\mathcal{X}, \mathcal{Y})$$

$$h : \theta \mapsto h_\theta$$

s.t.

$$h_\theta : \mathcal{X} \rightarrow \mathcal{Y}$$

so (possibly) $h \in \mathbf{ObjML}$ (or is h part of the functor H ?)

Consider the cost function J

$$J : \mathbb{R}^p \rightarrow \mathbf{Hom}(\mathfrak{X} \times \mathfrak{Y}, \mathbb{R}) = C^\infty(\mathcal{X} \times \mathcal{Y})$$

$$J(\theta) = \frac{1}{2} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)})^2$$

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¹nlab \mathbf{FinSet} <https://ncatlab.org/nlab/show/FinSet>

0.1.2. *LMS algorithm (least mean square (or Widrow-Hoff learning rule))*. Define **gradient descent** algorithm:

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta)$$

with $:=$ being assignment (I'll use $:=$ for “define”, in mathematical terms, use context to distinguish the 2), where α is the *learning rate*.

Rewriting the above,

$$\theta := \theta - \alpha \text{grad} J(\theta)$$

where $\text{grad} : C^\infty(M) \rightarrow \mathfrak{X}(M)$, with M being a smooth manifold.

This is *batch gradient descent*:

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta) = \theta_j - \alpha \frac{\partial}{\partial \theta_j} \frac{1}{2} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)})^2 = \theta_j - \alpha \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) \left(\frac{\partial h_\theta(x^{(i)})}{\partial \theta} \right)$$

Simply notice how the entire training set of m rows is used.

I will expound on the so-called distinguished object $1 \xrightarrow{P} X$ on pp. 8, in Section 2 The Category of Conditional Probabilities of Culbertson and Sturtz (2013) [2] because it wasn't clear to me in the first place (the fault is mine; the authors wrote a very lucid and very fathomable, pedagogically-friendly exposition).

$\forall Y$ with indiscrete σ -algebra $\Sigma_Y = \{Y, \emptyset\}$
(remember, $((Y, \Sigma_Y), \mu_Y)$, $\mu_Y(\phi) = 0$, $\mu_Y(Y) = 1$),

$\exists!$ unique morphism in $\text{Mor}\mathcal{P}$, $X \rightarrow Y$, since

$\forall P : X \rightarrow Y$, $P \in \text{Mor}\mathcal{P}$, P_x must be a probability measure on Y , because

$$\begin{aligned} (X, \Sigma_X) &\xrightarrow{P} (Y, \Sigma_Y) \\ P : \Sigma_Y \times X &\rightarrow [0, 1] \\ P(\cdot|x) : \Sigma_Y &\rightarrow [0, 1] \equiv P_x : \Sigma_Y \rightarrow [0, 1] \text{ s.t.} \\ P(\cdot|x) : \Sigma_Y &\rightarrow [0, 1] \equiv P_x(\emptyset) = 0, P_x(Y) = 1 \end{aligned}$$

i.e. EY: 20160503, Given $x \in X$ occurs, Y must occur.

By def. of terminal object ($\forall (X, \Sigma_X) \in \text{Obj}\mathcal{P}$, $\exists!$ morphism P s.t. $(X, \Sigma_X) \xrightarrow{P} (Y, \Sigma_Y)$, Y *terminal* object, and denote unique morphism $!_X : X \rightarrow Y$, $!_X \in \text{Mor}\mathcal{P}$).

Up to isomorphism, canonical terminal object is 1-element set denoted by $1 = \{*\}$, with the only possible σ -algebra ($\mu(*) = 1$, $\mu(\emptyset) = 0$),

$$\forall P : 1 \rightarrow X, P \in \text{Mor}\mathcal{P}, P \in \text{Hom}_{\mathcal{P}}(1, X), \forall X \in \text{Mor}\mathcal{P}$$

P is an “absolute” probability measure on X because “there’s no variability (conditioning) possible within singleton set $1 = \{*\}$.” [2]

Now

$$\begin{aligned} P : \Sigma_X \times 1 &\rightarrow [0, 1] \\ P(\cdot|*) : \Sigma_X &\rightarrow [0, 1] \end{aligned}$$

where $P(\cdot|*) : \Sigma_X \rightarrow [0, 1]$ perfect probability measure on X , $P(\cdot|*) : \Sigma_X \rightarrow [0, 1] \equiv P_*$, i.e. $P(\cdot|*) = p(\cdot)$ (usual probability on X).

$\forall A \in \Sigma_X$, $P(A|\cdot) : 1 \rightarrow [0, 1]$, but $P(A|*) = P(A)$, $P(A|\emptyset) = 0$.

Refer to

$$1 \xrightarrow{P} X$$

morphism $P : 1 \rightarrow X \in \text{Mor}\mathcal{P}$ as probability measure or distribution on X .

REFERENCES

[1] Trevor Hastie, Robert Tibshirani, Jerome Friedman. **The Elements of Statistical Learning: Data Mining, Inference, and Prediction**, Second Edition (Springer Series in Statistics) 2nd ed. 2009. Corr. 7th printing 2013 Edition. ISBN-13: 978-0387848570. https://web.stanford.edu/~hastie/local.ftp/Springer/OLD/ESLII_print4.pdf

[2] Jared Culbertson, Kirk Sturtz. *Bayesian machine learning via category theory*. [arXiv:1312.1445](https://arxiv.org/abs/1312.1445) [math.CT]
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[3] CS229 Stanford University. <http://cs229.stanford.edu/materials.html>