

LLC Circuit for High-Voltage Generation

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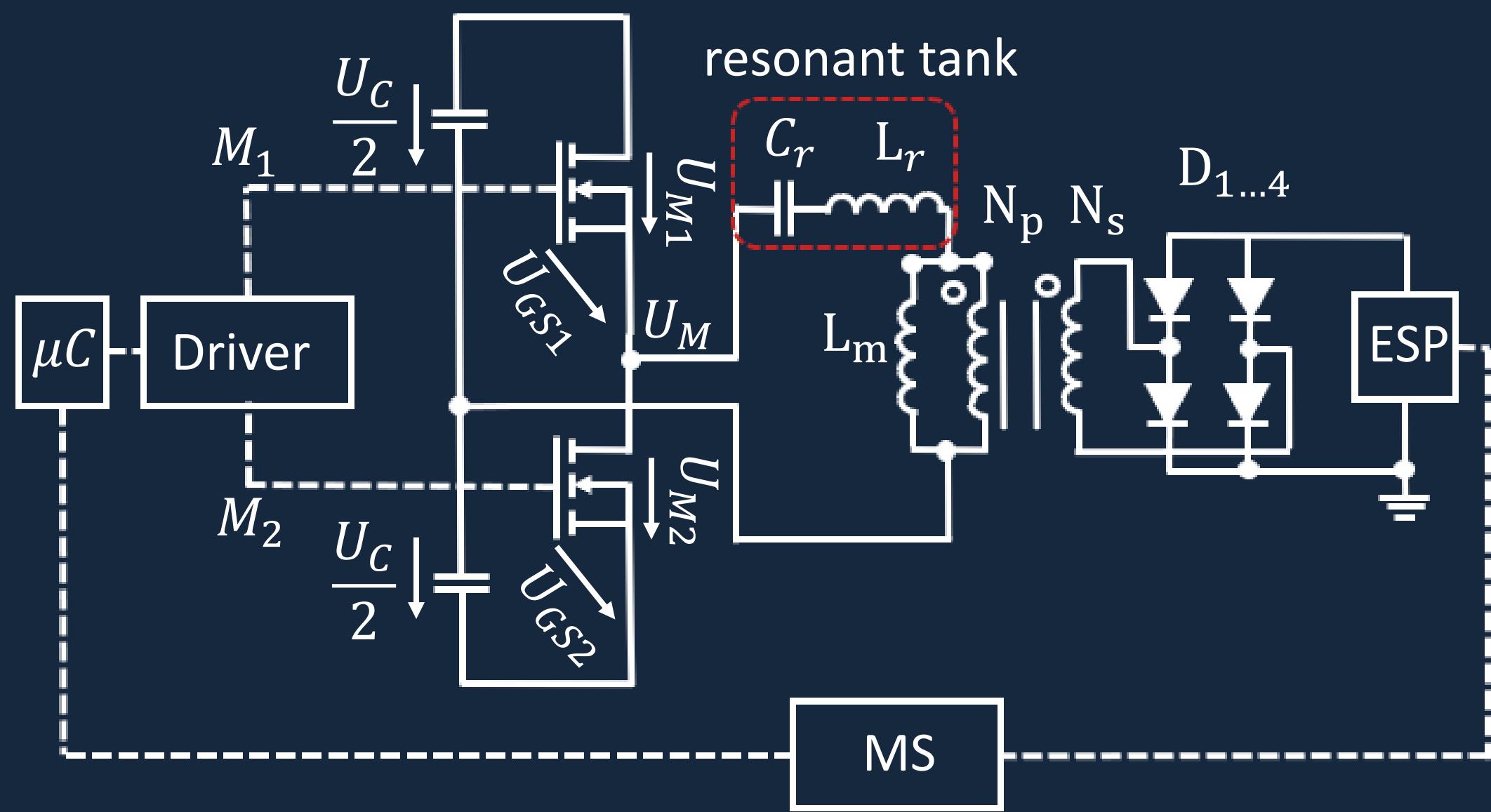


Fig. 1. Own illustration of the LLC circuit topology, based on [1]

- ESP (= electrostatic precipitator) requires negative high voltage ($-35 \text{ kV} < U_{out} < -25 \text{ kV}$)
- ESP filters combustion gases from an oven
- Half-bridge drives the LLC-Circuit
- Rectangular voltage excites the LLC tank
- First harmonic of the rectangular voltage controls the input voltage of the primary winding
- High-frequency harmonics are filtered out by the lowpass-characteristic of the LC-Circuit above the resonant frequency
- Software implementation on a low-cost 8-bit microcontroller (PIC18-F57Q84)

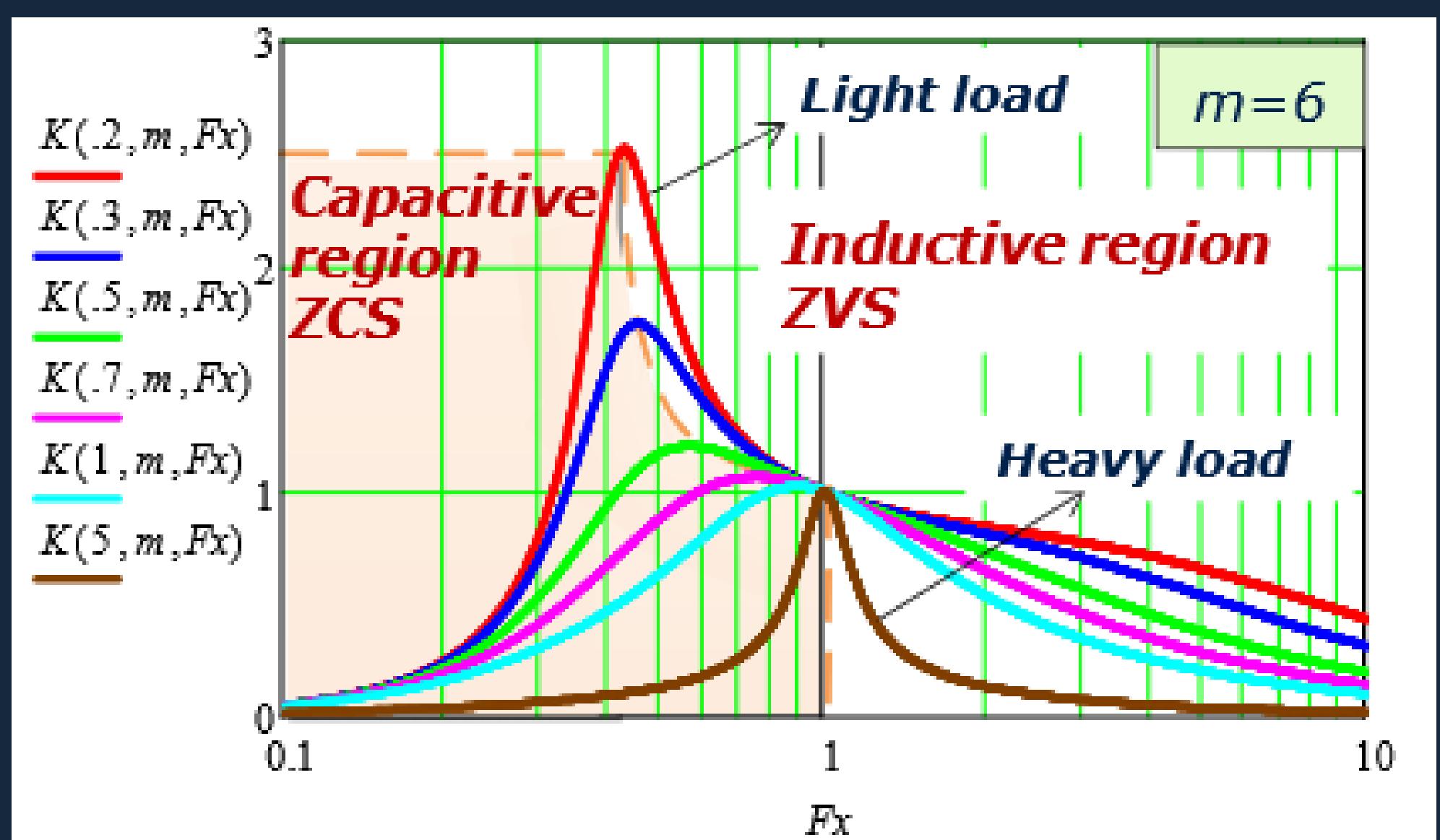


Fig. 2. [1] infineon, "magnitude response LLC-Circuit ", www.infineon.com, 16.01.2025

Control and regulation strategy

1. Resonant Tank

- Resonant frequency $f_r = \frac{1}{2\pi\sqrt{L_r \cdot C_r}} \approx 100 \text{ kHz}$
- $F_{x,\text{normalised}} = \frac{f_{\text{first harmonic}}}{f_r}$
- $m = \frac{L_R + L_m}{L_m} \quad Q = \frac{\sqrt{L_R/C_R}}{R_{LOAD}}$
- $K(Q, m, F_{x,\text{normalised}}) = \frac{|U_{out}|}{|U_{in}|}$
- Capacitive region \cong current leads voltage \rightarrow switch-off losses \uparrow
- Inductive region \cong voltage leads current \rightarrow switch-off losses \downarrow

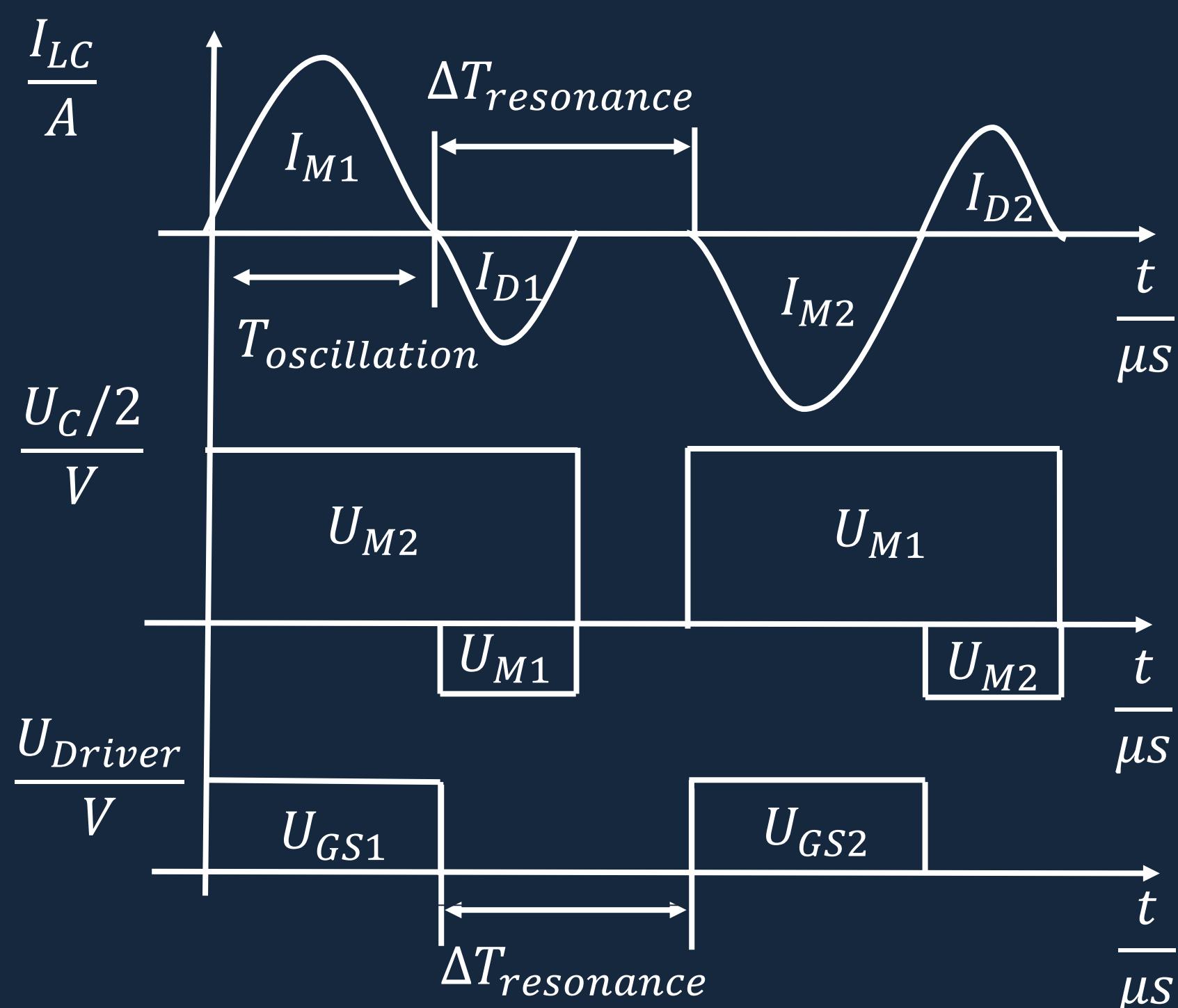


Fig. 3. Switching and output waveforms of the LLC converter (own illustration)

2. MOSFET switching strategy

- Transistor M_1 conducts the positive half-wave of the current
- After approximately $T_{\text{oscillation}} \approx \frac{1}{2} \cdot \frac{1}{f_r}$, the current reaches zero – inductance of the resonant tank causes overvoltage ($U_C < U_M$), the body diode M_{D1} conducts the negative half-wave
- While M_{D1} conducting the current, M_1 can be turned off without switching losses
- Transistor M_2 is controlled identically to M_1
- The input voltage of the primary winding controlled by the time interval between the conduction phases of M_1 and M_2
- As $\Delta T_{\text{resonance}}$ decreases, the LC-Circuit approaches resonance more closely



3. Measurement System (=MS)

- I_{ESP} is the rectified resonant tank current, transformed by the transformer
- If operating point is near the resonance – the current frequency is about $f_r = 100 \text{ kHz}$
- High switching frequency prevents direct current sampling \rightarrow a differential amplifier with low-pass filtering yields the average ESP current
- To detect electric arcs in the ESP, the operating voltage is measured via an amplifier
- The measured analog signals will be digitalized and transferred by an optocoupler to the μC

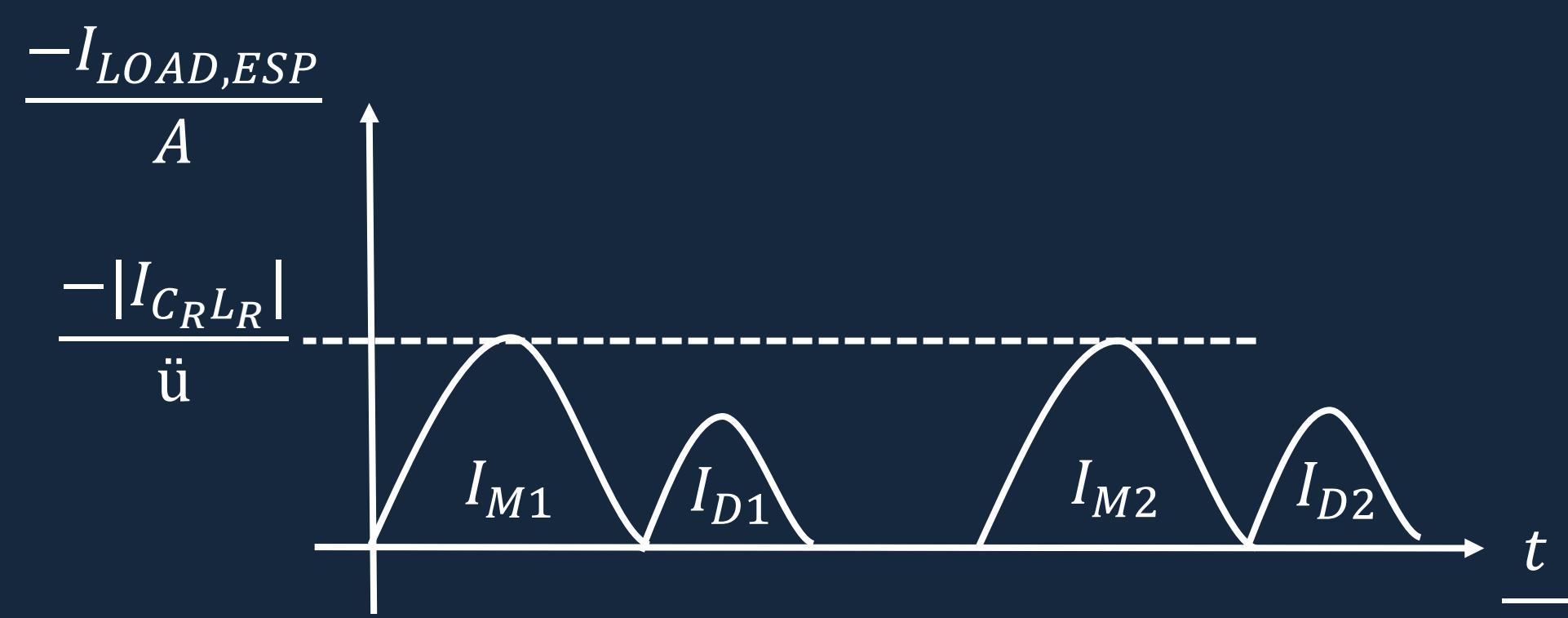


Fig. 4. output waveforms of the rectifier (own illustration)