

Deterministic:

$$\begin{cases} \frac{dx}{dt} = K_2 - \gamma_1 x + f z - Hxy & (1) \\ \frac{dy}{dt} = K_1 - \gamma_1 y + fz - Hxy & (2) \\ \frac{dz}{dt} = (-f - \gamma_2)z + Hxy & (3) \\ \frac{dw}{dt} = K_3 y - \gamma_3 w & (4) \end{cases}$$

(1) + (2):

$$\frac{d(x+y)}{dt} = K_1 + K_2 + 2fz - 2Hxy - \gamma_1(x+y)$$

Let $u = \frac{y}{x+y}$, i.e. fraction of coding RNA in all free/unbounded RNA

$$\begin{aligned} \frac{du}{dt} &= \frac{d(\frac{y}{x+y})}{dt} = \frac{y'(x+y) - (x+y)'y}{y^2} = \frac{(K_1 - \gamma_1 y + fz + Hxy)(x+y) - (K_4 + 2fz - 2Hxy - \gamma_1(x+y))y}{y^2} \\ &= (K_1 x - \gamma_1 y x + fz x - Hx^2 y + \cancel{x^2 y} - \cancel{x^2 y} + fz y - Hxy^2 - K_1 y - \cancel{y^2} y - \cancel{fz y} + \cancel{Hxy^2} + \cancel{rxy} + \cancel{y^2}) \frac{1}{y^2} \\ &= (K_1 x + fz x - Hx^2 y - K_1 y - fz y + Hxy^2) / y^2 \\ &= \frac{x-y}{y^2} (K_1 + fz - H(x+y)u) \end{aligned}$$

Non-dimensionalize.

$$\begin{array}{ll} K_1, K_2, K_4, & \sim NT^{-1} \\ t & \sim T \\ x, y, z, w & \sim N \\ K_3, f, \gamma_1, \gamma_2, \gamma_3 & \sim T^{-1} \\ H & \sim N^{-1} T^{-1} \end{array}$$

$$\begin{array}{l} u = \frac{y}{x+y} \\ \tau = \gamma_3 t, d\tau = \gamma_3 dt \end{array}$$

Attempt 1

WELCO

SPORTS

NO.1 COOL DOG'S

HAPPY NEW WORLD.

加油

Attempt 2

$$\frac{d(x+y)}{dt} = \frac{k_4}{r_3} + \frac{2f}{r_3} z + (x+y) \left[\frac{2H}{r_3} u(1-u) - \frac{f}{r_3} \right]$$

$$\frac{dz}{dt} = \frac{k_5}{r_3} z + (x+y) \frac{H}{r_3} u(1-u)$$

$$\frac{dw}{dt} = \frac{k_3}{r_3} (x+y) u - w$$

Here, to simplify, let's assume $f=0$, irreversible RNA interference.

Then: $\begin{cases} \frac{dl}{dt} = \frac{k_4}{r_3} + \left(-\frac{2H}{r_3} u(1-u) - \frac{f}{r_3} \right) l \\ \frac{du}{dt} = \frac{1-2u}{u^2} \frac{1}{r_3} [k_1 - Hu(1-u)l] \\ \frac{dz}{dt} = \frac{H}{r_3} u(1-u)l \\ \frac{dw}{dt} = \frac{k_3}{r_3} u l - w \end{cases}$



WELCOME TO THE COOL DOG'S HAPPY NEW WORLD

$$r = \frac{y_1}{K_1} y, dr = \frac{y_1}{K_1} dy, t = r_3 t, dt = r_3 dt$$

$$\therefore \frac{dr}{dt} = \frac{r_1}{K_1 r_3} \frac{dy}{dt} = \frac{r_1}{r_3 K_1} - \frac{y_1}{r_3} v - H \times \frac{K_1}{r_1} r \rightarrow H \frac{K_1}{r_1 r_3} v r$$

$$s = \frac{y_1 y_3}{K_1 K_3} w, ds = \frac{y_1 y_3}{K_1 K_3} dw$$

$$\therefore \frac{ds}{dt} = \frac{r_1}{K_1 K_3} \frac{dw}{dt} = r - s$$

$$v = \frac{r_1}{K_2} x, dv = \frac{r_1}{K_2} dx$$

$$\therefore \frac{dv}{dt} = \frac{r_1}{K_2 r_3} \frac{dx}{dt} = \frac{r_1}{r_3} - \frac{r_1}{r_3} v - H \frac{K_1}{r_1 r_3} v r$$

(Attempt 3)

$$q = r_2 H z, dq = r_2 H dz$$

$$\therefore \frac{dq}{dt} = \frac{r_2 H}{r_3} \frac{dz}{dt} = -\frac{r_2}{r_3} q + \frac{r_2 H^2}{r_3} \frac{K_2 K_1}{r_1^2} v r$$

To sum up:

$$\begin{cases} \frac{dr}{dt} = \epsilon_1 (1 - v - H_1 r) = f(v, r) \\ \frac{dv}{dt} = \epsilon_2 (1 - r - H_2 v) = g(v, r) \\ \frac{dq}{dt} = \epsilon_3 (-q + H_3 v) \\ \frac{ds}{dt} = M - S \end{cases}$$

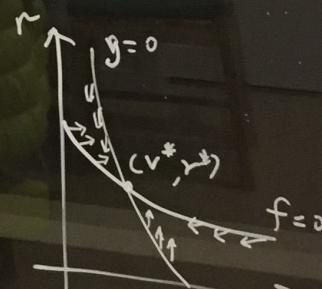
$$\text{Set } f(v^*, r^*) = g(v^*, r^*) = 0$$

$$v^* = \frac{1}{1 + H_1 r^*}, \text{ plug into } g(v, r)$$

$$r^* = \frac{1}{1 + H_2 \frac{1}{1 + H_1 r^*}} = \frac{1 + H_1 r^*}{1 + H_1 r^* + H_2}$$

$$H_1 r^{*2} + (1 + H_2 - H_1) r^* - 1 = 0$$

1 positive real s.s.
Stable (ignore negative)

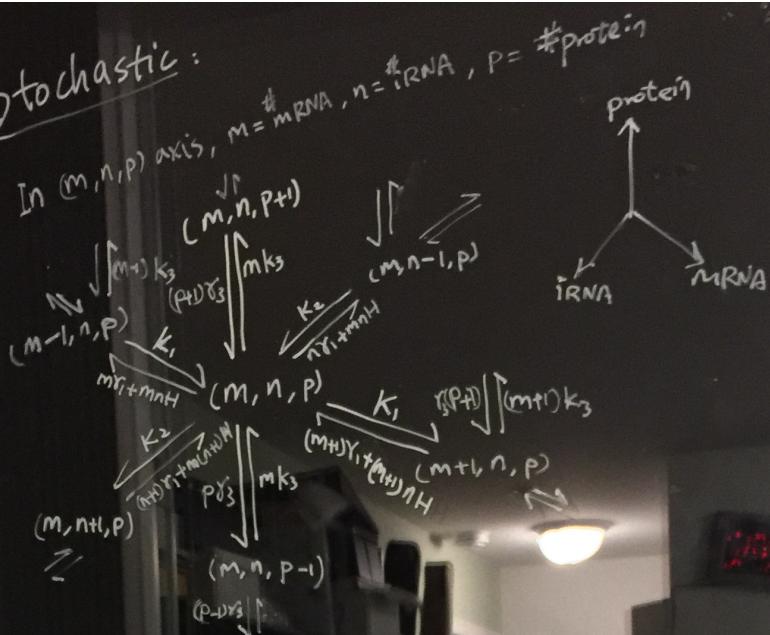


$$r^* = \frac{H_1 - H_2 - 1 + \sqrt{(-H_1 + H_2)^2 + 4H_1}}{2H_1}$$

$$v^* = \frac{H_2 - H_1 - 1 + \sqrt{(-H_2 + H_1 + 1)^2 + 4H_2}}{2H_2}$$

$$\therefore S^* = r^* + (-r^*) e^{-t}$$

Stochastic:



state-transition diagram for PGF

$$P_M(m) ?$$

$$P_N(n) ?$$

$$P_{MINIP}(m, n, p) ?$$

$$\underline{P_p(p) ?}$$

CME:

$$\frac{dP(m, n, p)}{dt} = k_2 P(m-1, n, p) + k_1 P(m+1, n, p) + m k_3 P(m, n, p-1) \\ + [(n+1)\gamma_1 + m(n+1)\gamma_H] P(m, n+1, p) + (P+D)\gamma_3 P(m, n, p+1) \\ + [(m+1)\gamma_1 + (m+1)\gamma_H] P(m+1, n, p) \\ - P(m, n, p) (k_2 + P\gamma_3 + k_1 + m k_3) \\ + n\gamma_1 + m\gamma_H + m\gamma_1 + m\gamma_H)$$

$$\frac{dP(0, n, p)}{dt} = k_2 P(0, n-1, p) + (n+1)\gamma_1 P(0, n+1, p) \\ + (P+D)\gamma_3 P(0, n, p+1) + (\gamma_1 + n\gamma_H) P(1, n, p) \\ - P(0, n, p) (k_2 + P\gamma_3 + k_1 + n\gamma_1)$$

$$\frac{dP(m, 0, p)}{dt} = k_1 P(m-1, 0, p) + m k_3 P(m, 0, p-1) \\ + (\gamma_1 + m\gamma_H) P(m, 1, p) + (P+D)\gamma_3 P(m, 0, p+1) \\ + (m\gamma_H)\gamma_1 P(m+1, 0, p) \\ - P(m, 0, p) (k_2 + P\gamma_3 + k_1 + m k_3 + m\gamma_1)$$

$$\frac{dP(m, n, 0)}{dt} = k_2 P(m, n-1, 0) + k_1 P(m+1, n, 0) \\ + [(n+1)\gamma_1 + m(n+1)\gamma_H] P(m, n+1, 0) \\ + \gamma_3(m, n, 1) + [(m+1)\gamma_1 + (m+1)\gamma_H] P(m+1, n, 0) \\ - P(m, n, 0) (k_2 + k_1 + m k_3 + n\gamma_1 + m\gamma_H \\ + m\gamma_1 + m\gamma_H)$$

$$\therefore \frac{dS}{dt} =$$

$$V = \frac{r_1}{K_2}$$

$$\therefore \frac{dV}{dt}$$

$$q =$$

$$\therefore \frac{dq}{dt}$$

To sum up

set

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