

Deep Generative Models

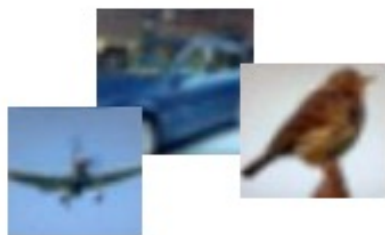
Some images are from Fei-fei Li's course @Stanford <http://cs231n.stanford.edu/> and Towards Data Science <https://towardsdatascience.com>

Outline

- Generative models
- Variational Autoencoder (VAE)
- Generative Adversarial Network (GAN)

Generative Models

Given training data, generate new samples from the same distribution



Training data $\sim p_{\text{data}}(x)$



Generated samples $\sim p_{\text{model}}(x)$

Want to learn $p_{\text{model}}(x)$ similar to $p_{\text{data}}(x)$

- Explicit density estimation: explicitly define and solve for $p_{\text{model}}(x)$
- Implicit density estimation: learn model that can sample from $p_{\text{model}}(x)$ w/o explicitly defining it

Discriminative Model vs Generative Model

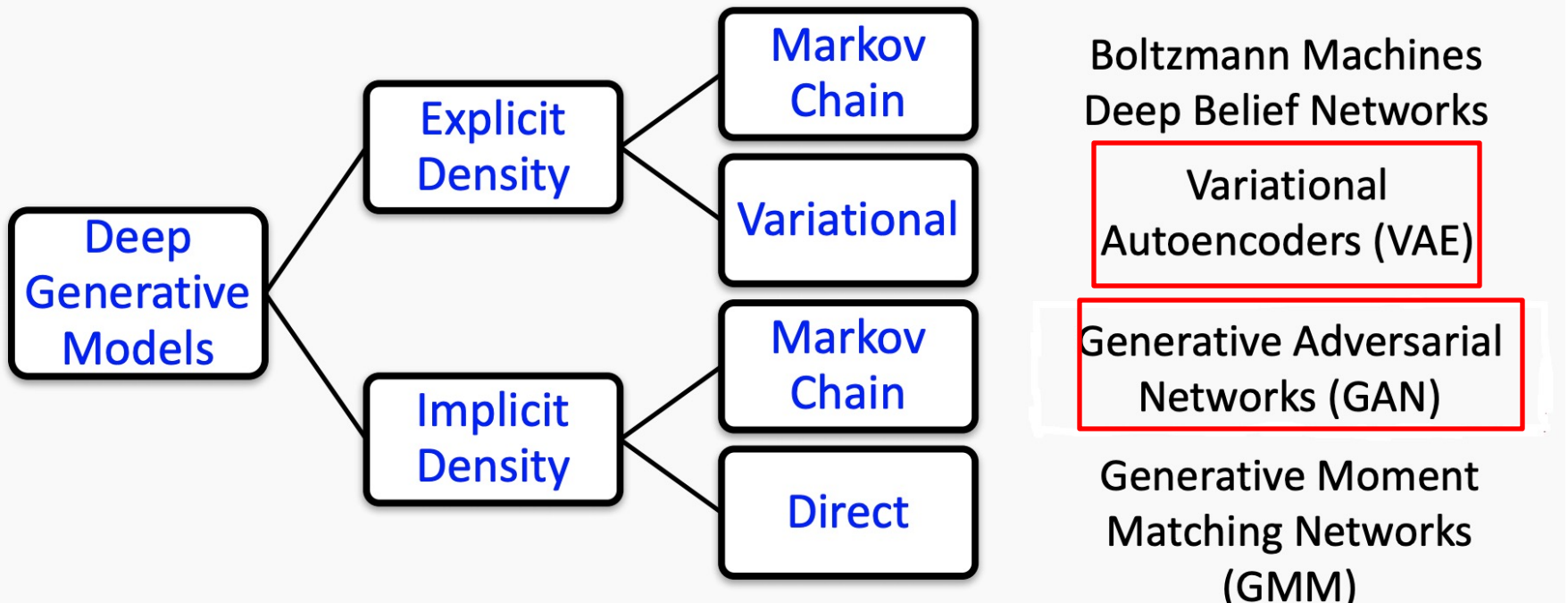
Discriminative Model

- Given an image \mathbf{X} , predict a label Y
- Estimates $P(Y|\mathbf{X})$

Generative Model

- Model $P(\mathbf{X})$
- Can generate new images

Deep Generative Models



Generative Models



Generate examples in image datasets



Generate realistic photos



Image inpainting



Image-to-image translation

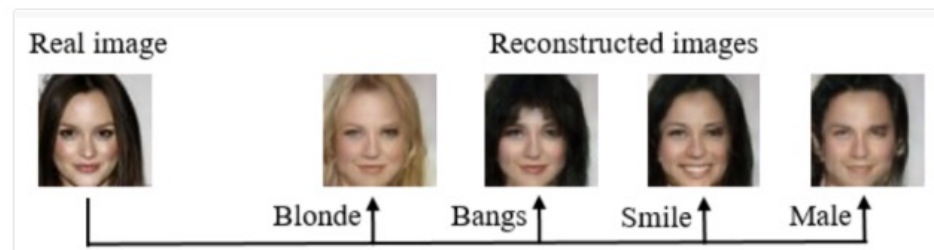
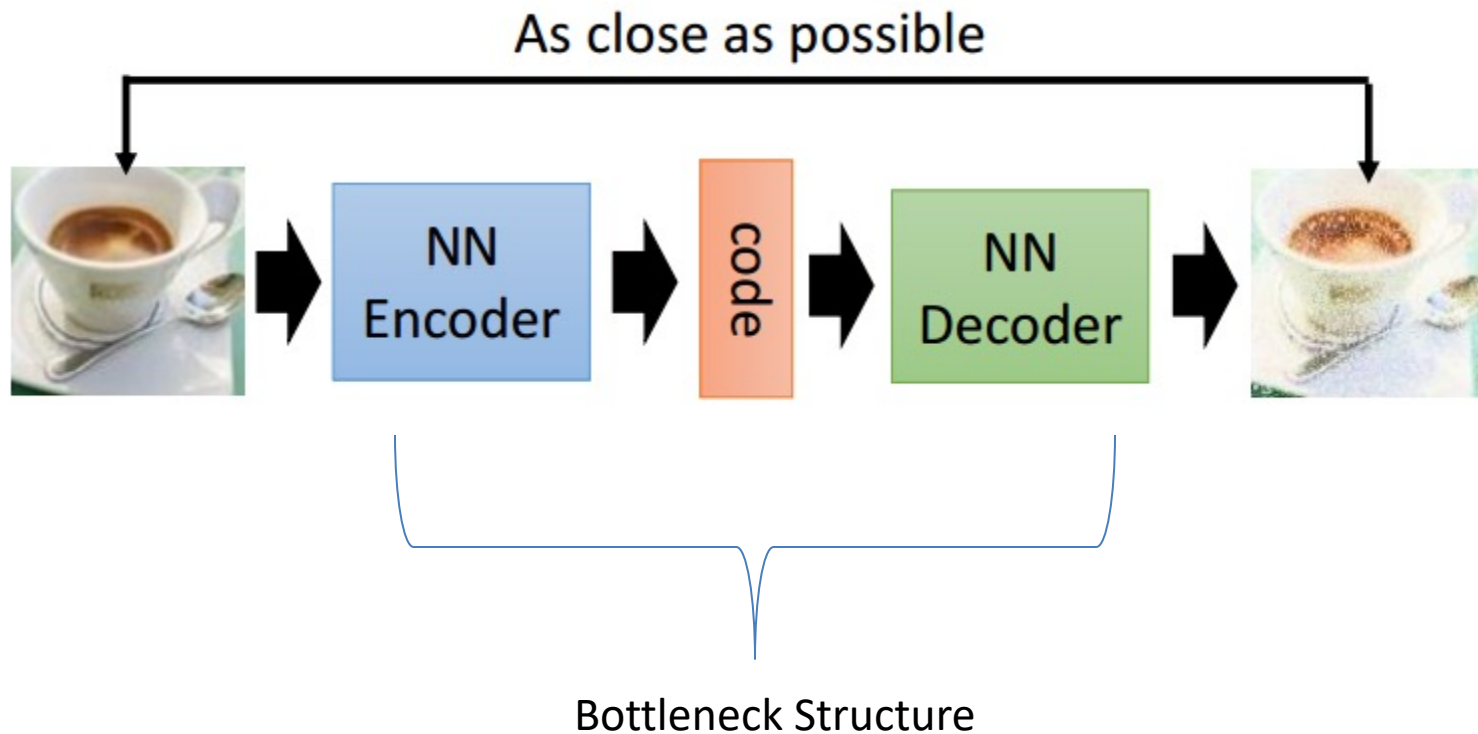


Photo editing

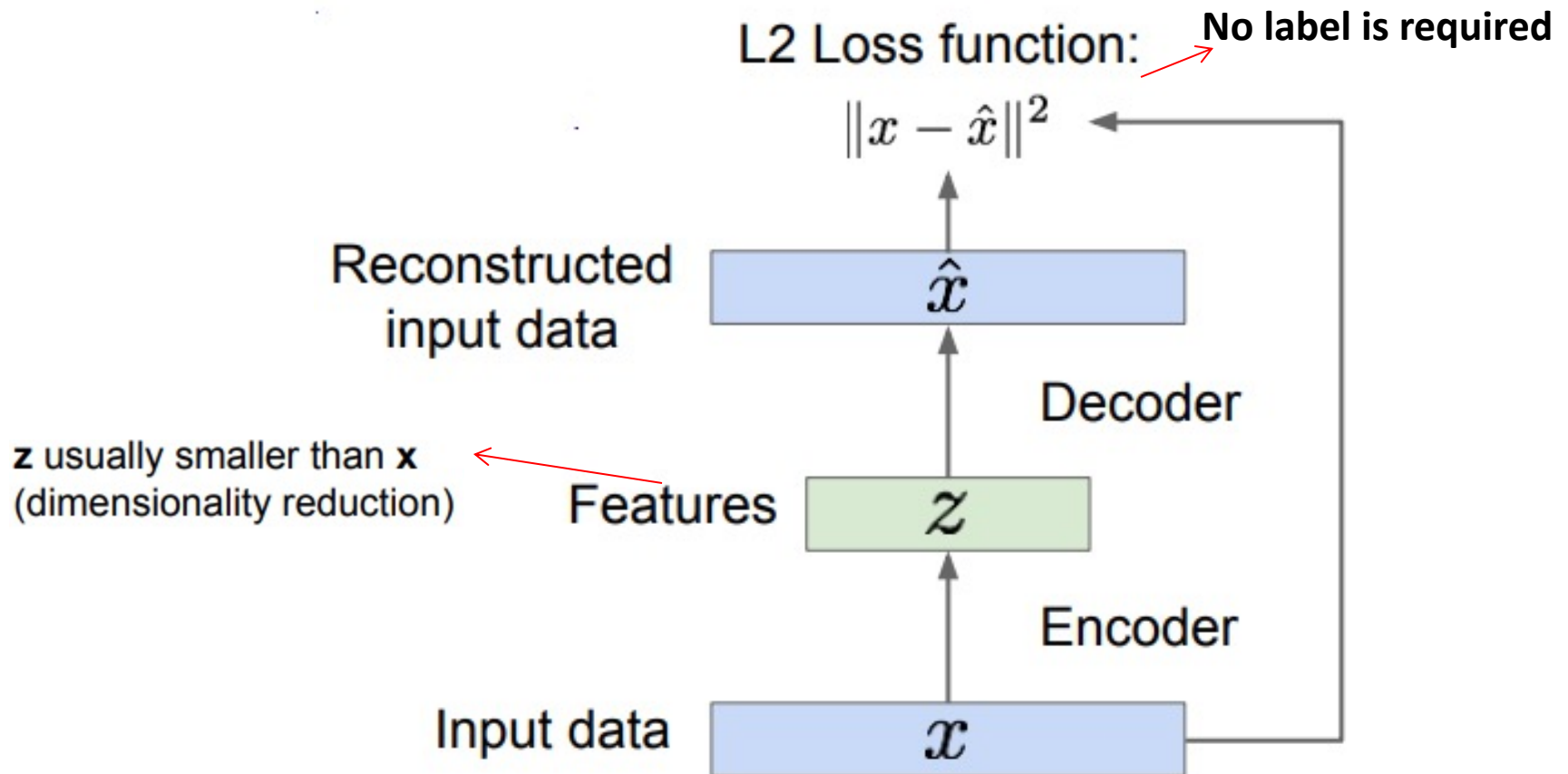
Outline

- Generative models
- **Variational Autoencoder (VAE)**
- Generative Adversarial Network (GAN)

Auto-encoder (AE): original model



Auto-encoder (AE): original model



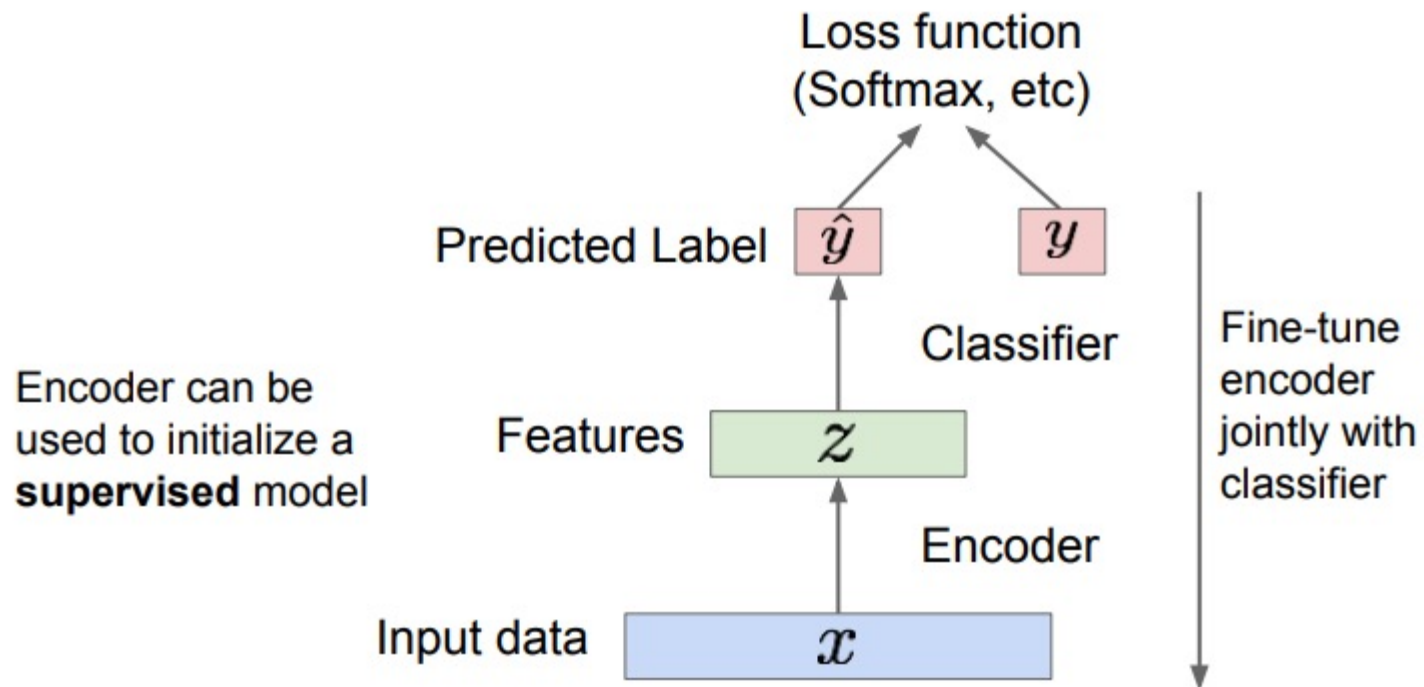
z is a latent variable that has smaller dimension than x

Autoencoder (AE): original model

- Autoencoder is a multi-layer neural network. The only difference is that the size of its output layer is the same as the input layer.
- The reconstruction objective does not involve any label.
- The generated latent representation z could be used as features extracted in an unsupervised way.
- The feature z could also be used to initialize a supervised model.

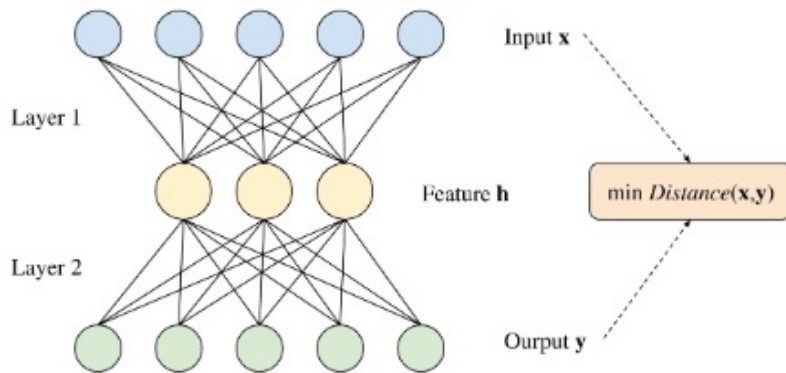
Auto-encoder (AE): original model

Autoencoder could be trained as a good initialization in a supervised model.

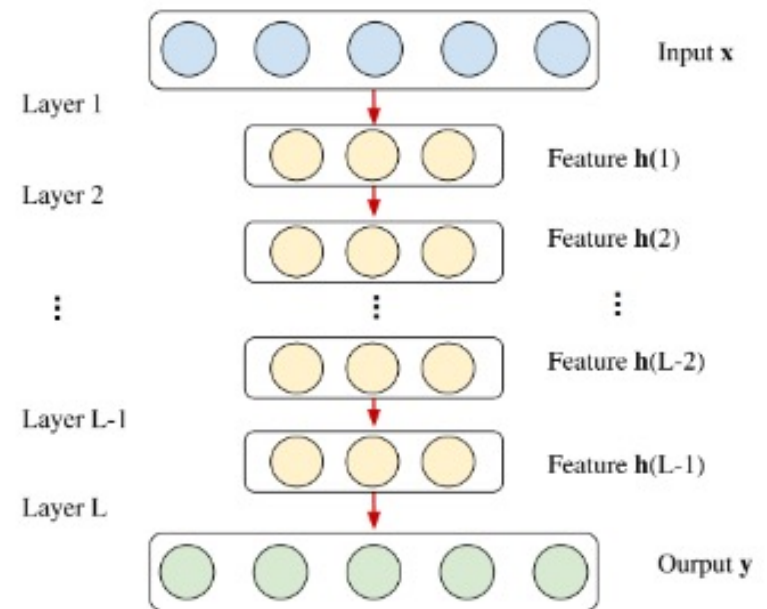


Autoencoder (AE): stacked autoencoder

Autoencoder could be stacked to form a deep model and generate a hierarchy of latent features.



Original AE

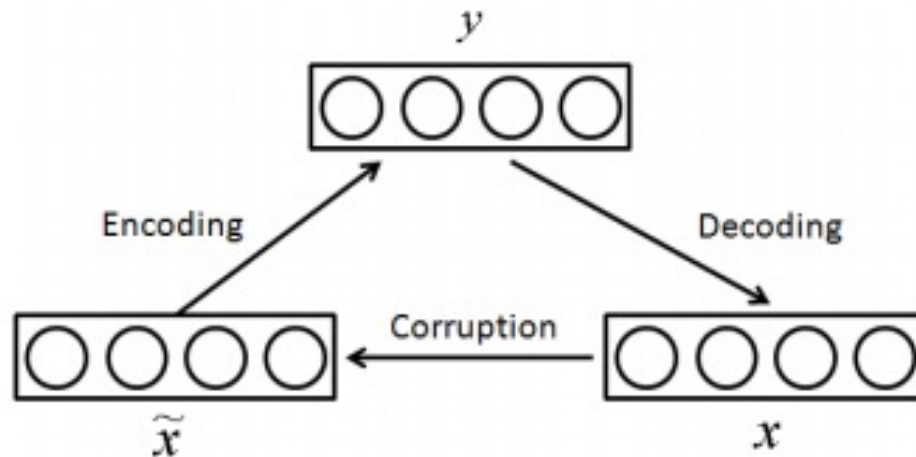


Stacked AE

Auto-encoder (AE): denoising autoencoder

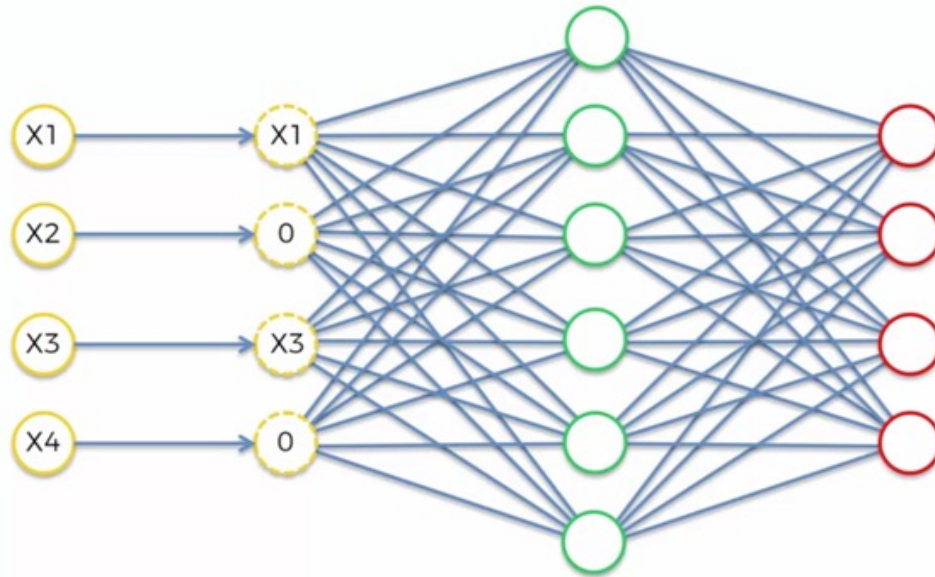
Denoising autoencoder:

In order to force the hidden layer to discover robust features and prevent it from simply learning the identity function, we want to train the autoencoder to reconstruct the input from a corrupted version of it



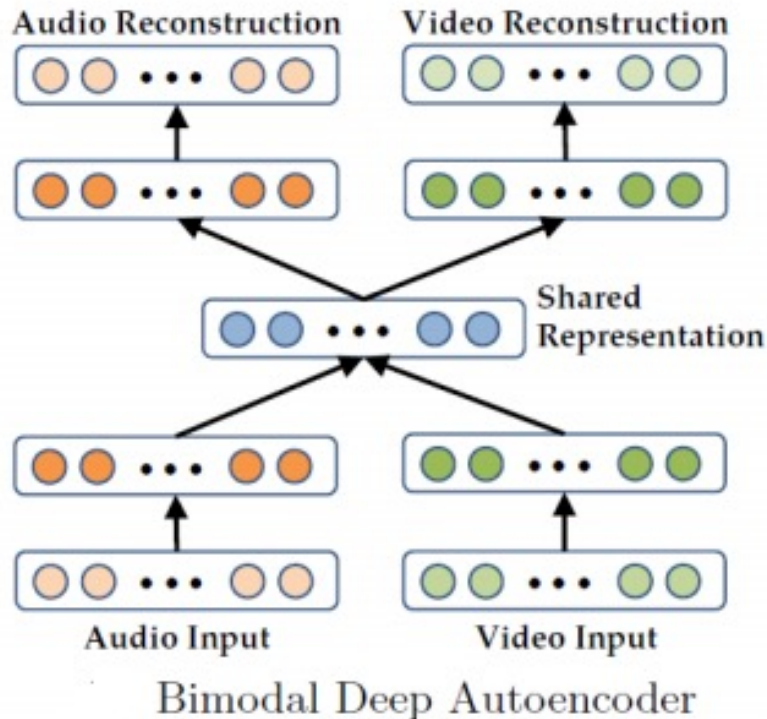
Auto-encoder (AE): denoising autoencoder

- To convert the autoencoder to a denoising autoencoder, we can randomly set some of the inputs (as many as half of them) to zero.



- The input can be corrupted in other ways

Auto-encoder (AE): multimodal autoencoder



Example:

One third of training data has only video

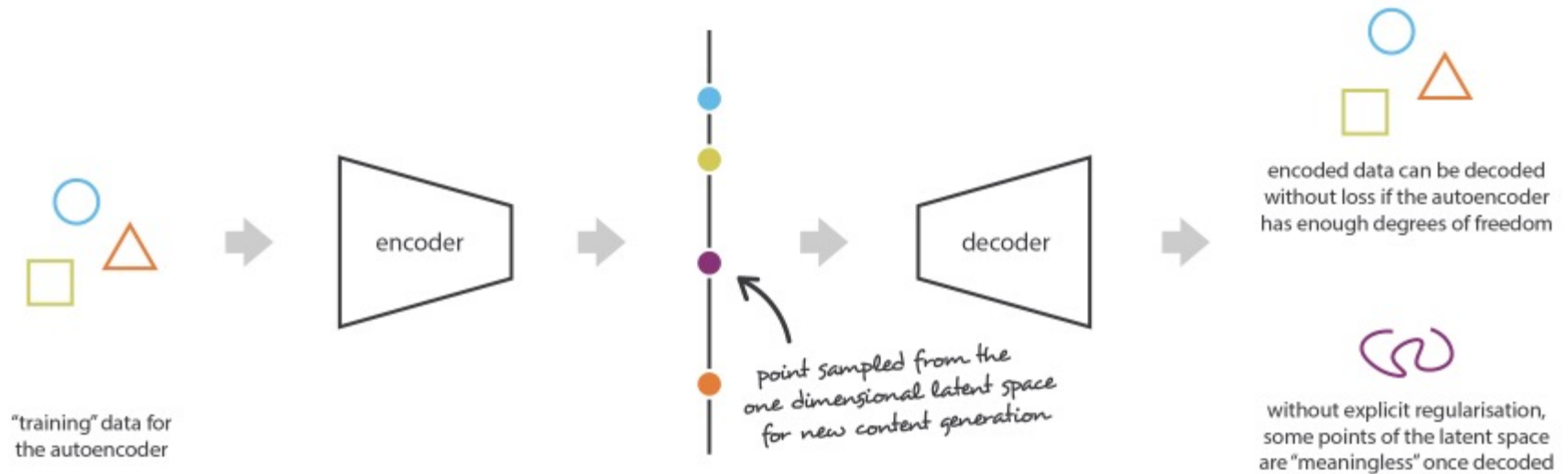
One third of training data has only audio

One third of training data has both video and audio

Variational Auto-encoder (VAE)

- Autoencoder gives low reconstruction error on test examples from the same distribution as the training examples, but generally high reconstruction error on samples randomly chosen from the input space.
- Variational auto-encoder:
 - Probabilistic spin on autoencoders - enable sampling from the model to generate data

Variational Auto-encoder (VAE)



Irregular latent space prevent us from using autoencoder for new content generation.

Variational Auto-encoder (VAE)

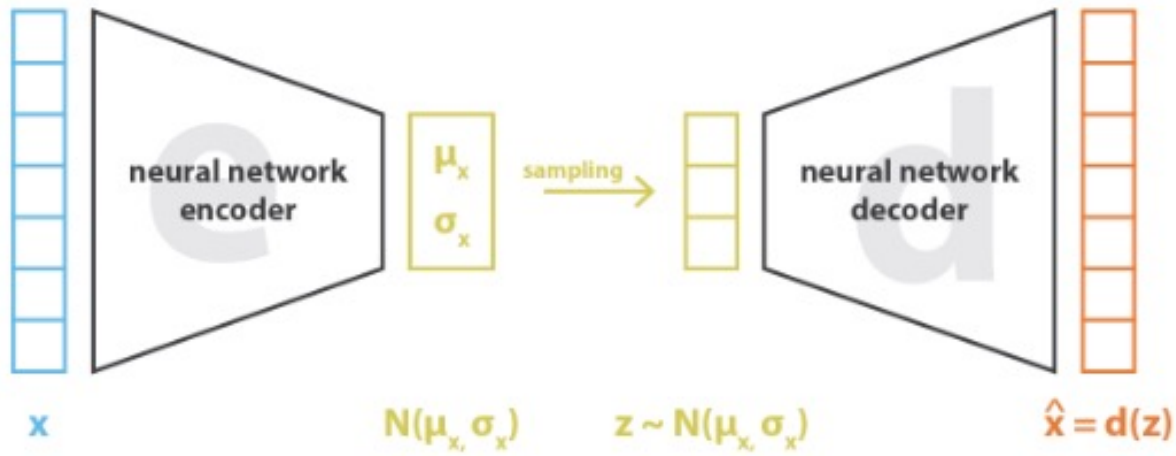


Difference between autoencoder (deterministic) and variational autoencoder (probabilistic).

Instead of encoding an input as a single point, VAE encodes it as a distribution over the latent space.

Variational Auto-encoder (VAE)

VAE could be treated as “regularized” autoencoder.



$$\text{loss} = ||x - \hat{x}||^2 - \text{KL}[N(\mu_x, \sigma_x), N(0, I)] = ||x - d(z)||^2 - \text{KL}[N(\mu_x, \sigma_x), N(0, I)]$$

Reconstruction term

Regularization term

Variational Auto-encoder (VAE)

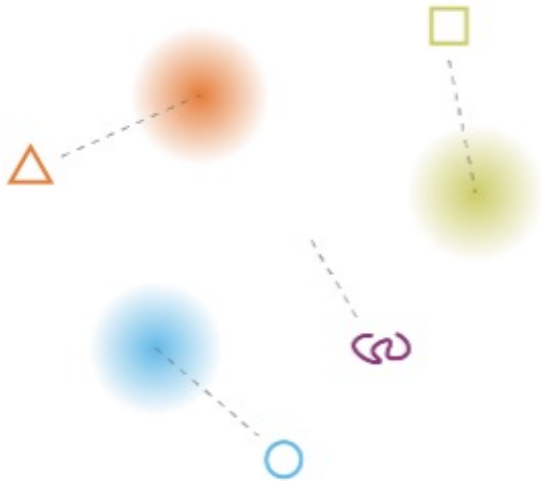


Difference between a "regular" and an "irregular" latent space.

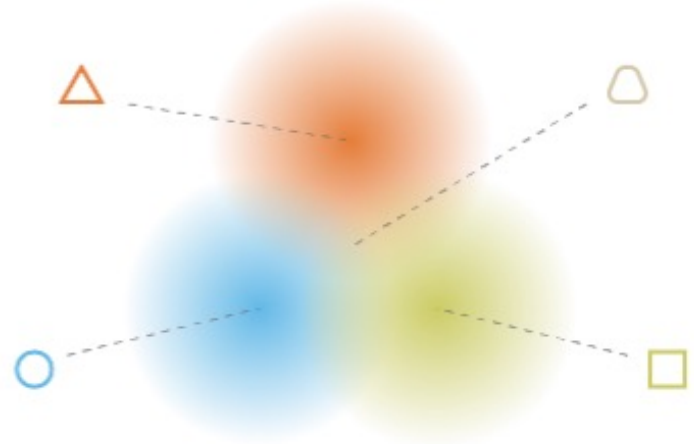
A "regular" latent space requires :

- (1) continuity** : wo close points should not give two completely different contents once decoded
- (2) completeness** : a point sampled from the latent space should give "meaningful" content once decoded

Variational Auto-encoder (VAE)

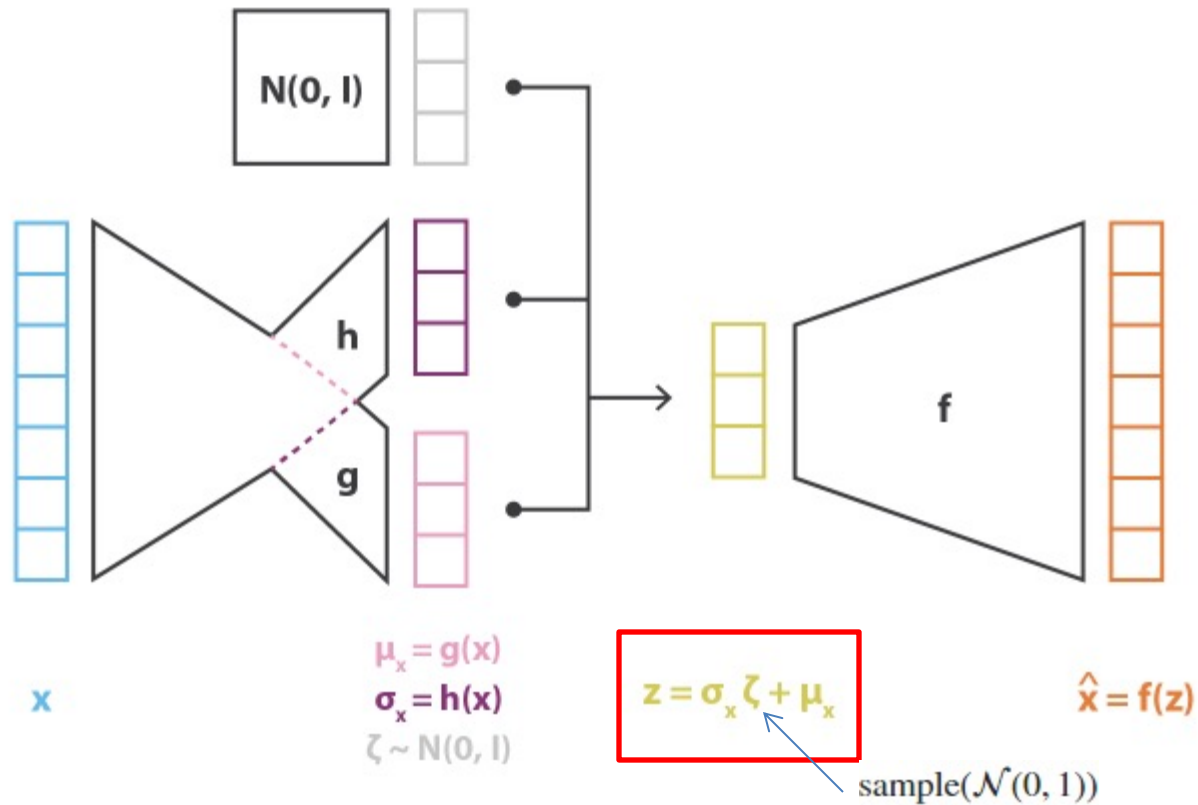


what can happen without regularisation



what we want to obtain with regularisation

Variational Auto-encoder (VAE)



$$\text{loss} = C \|x - \hat{x}\|^2 - \text{KL}[N(\mu_x, \sigma_x), N(0, I)] = C \|x - f(z)\|^2 - \text{KL}[N(g(x), h(x)), N(0, I)]$$

Variational Auto-encoder (VAE)



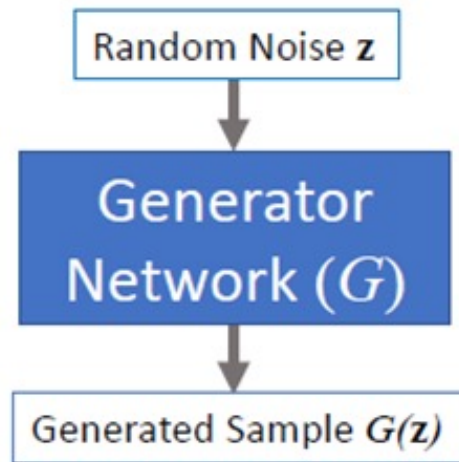
Generating celebrity-look like photos

Outline

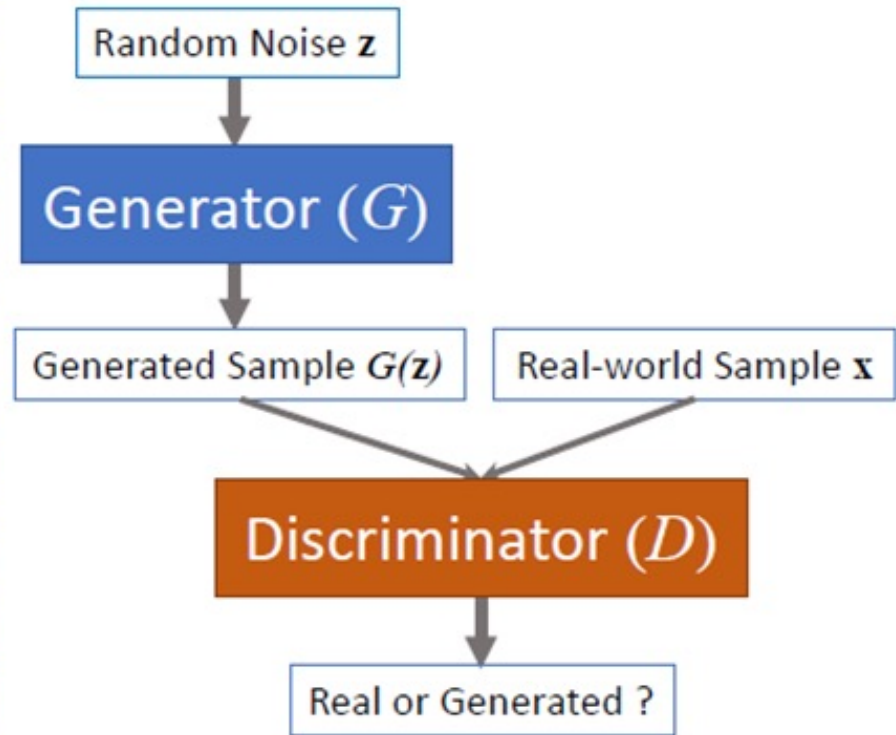
- Generative models
- Variational Autoencoder (VAE)
- **Generative Adversarial Network (GAN)**

Generative Adversarial Network (GAN)

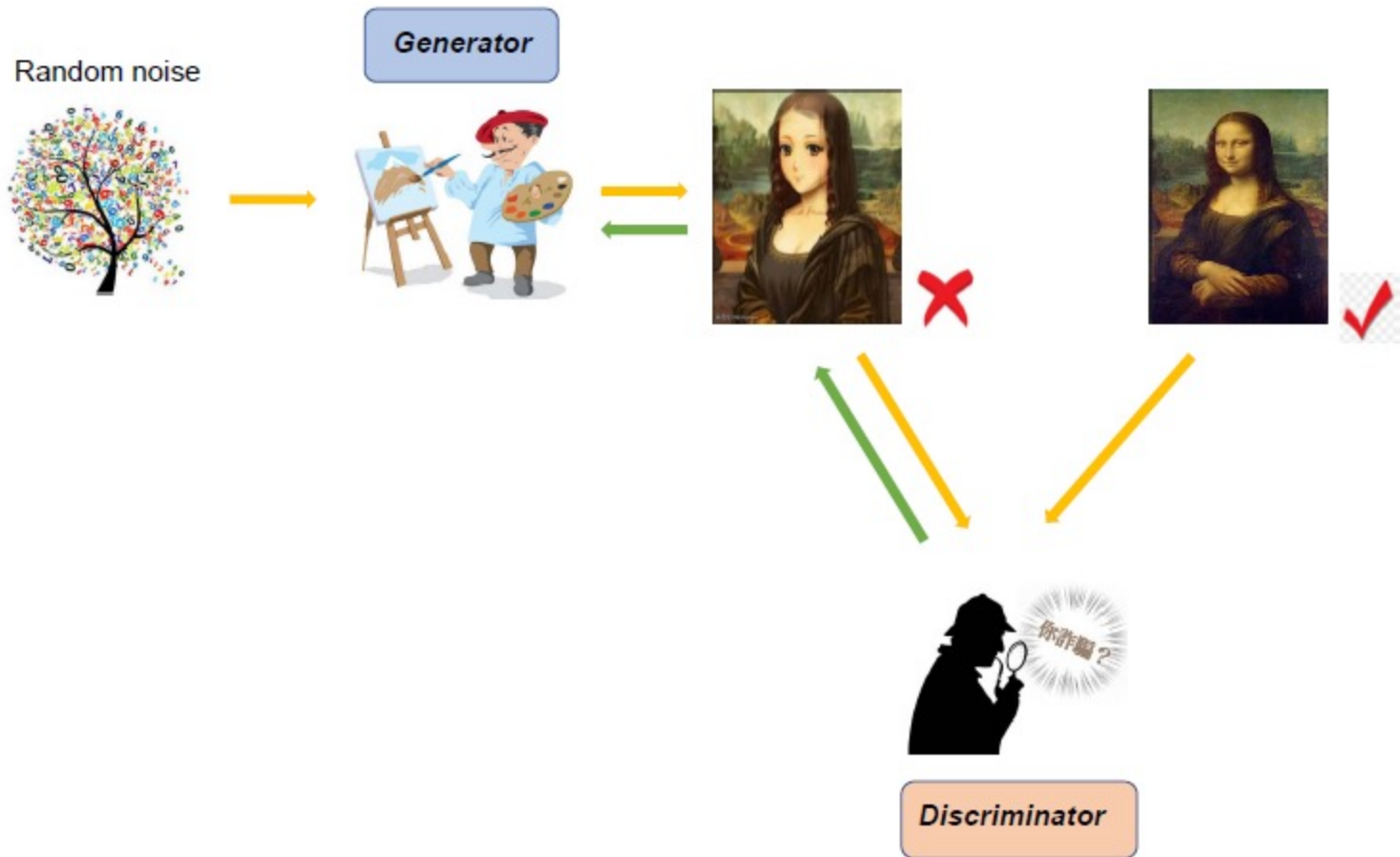
Traditional Generative Network



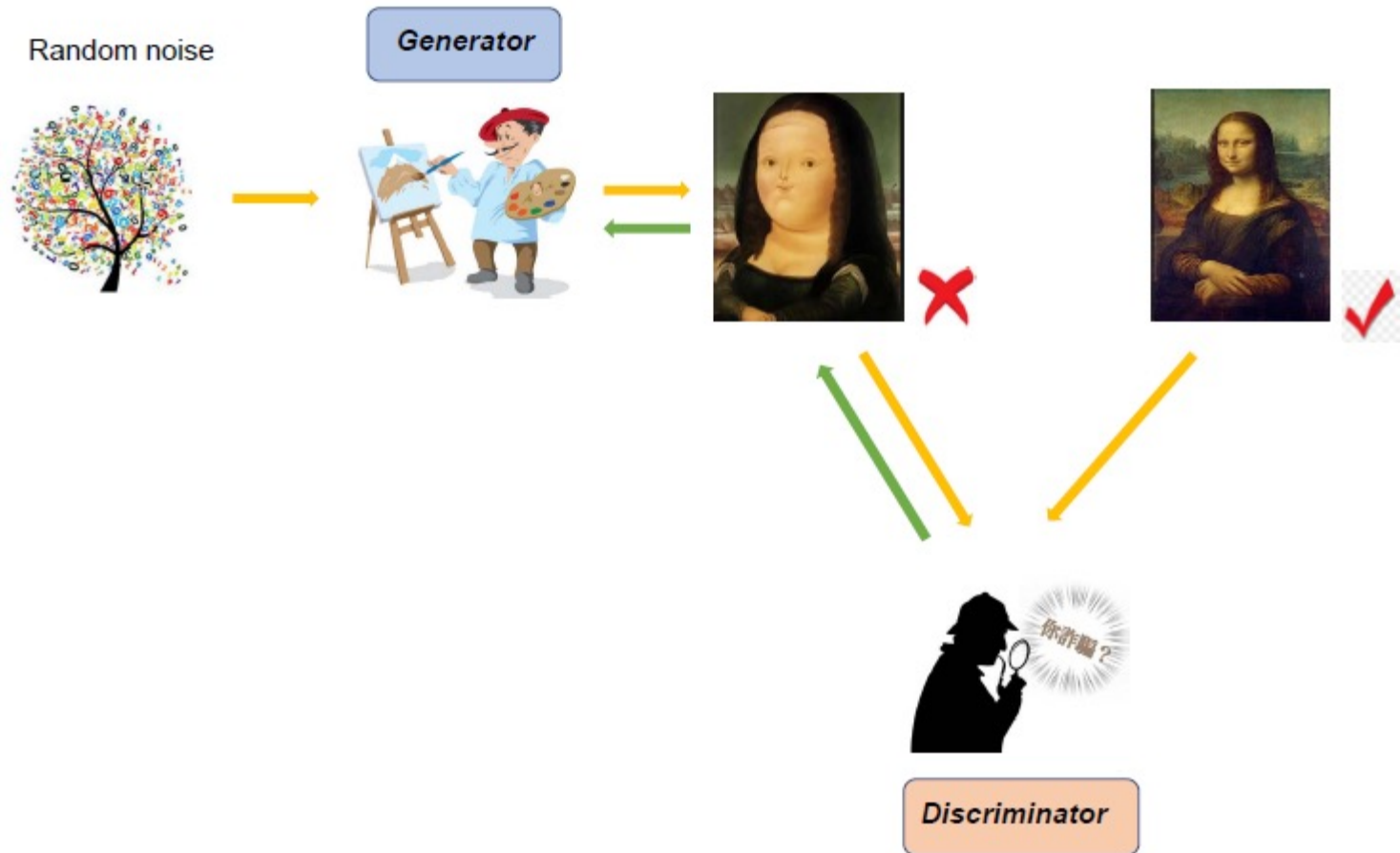
Generative Adversarial Network



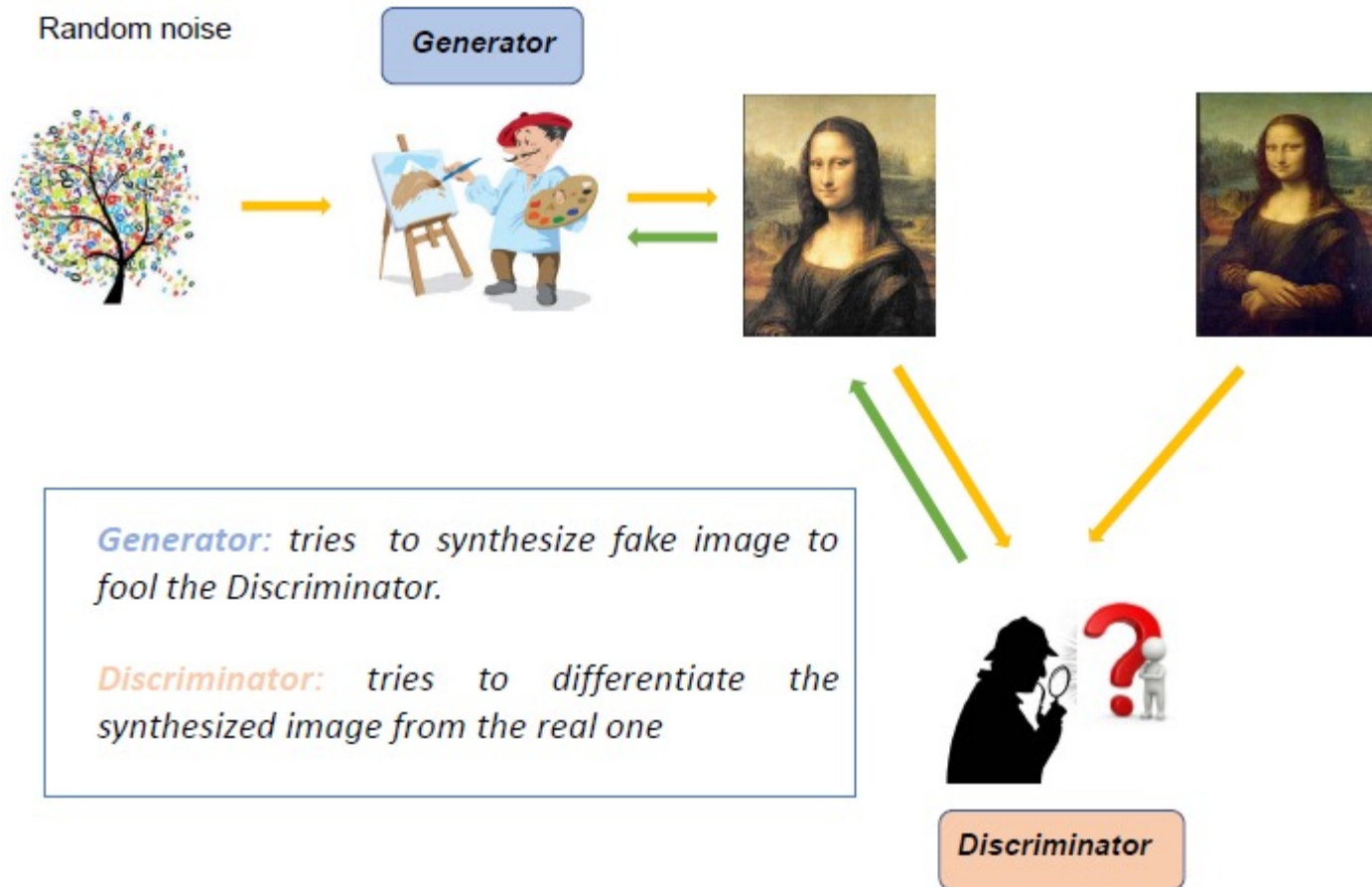
Generative Adversarial Network (GAN)



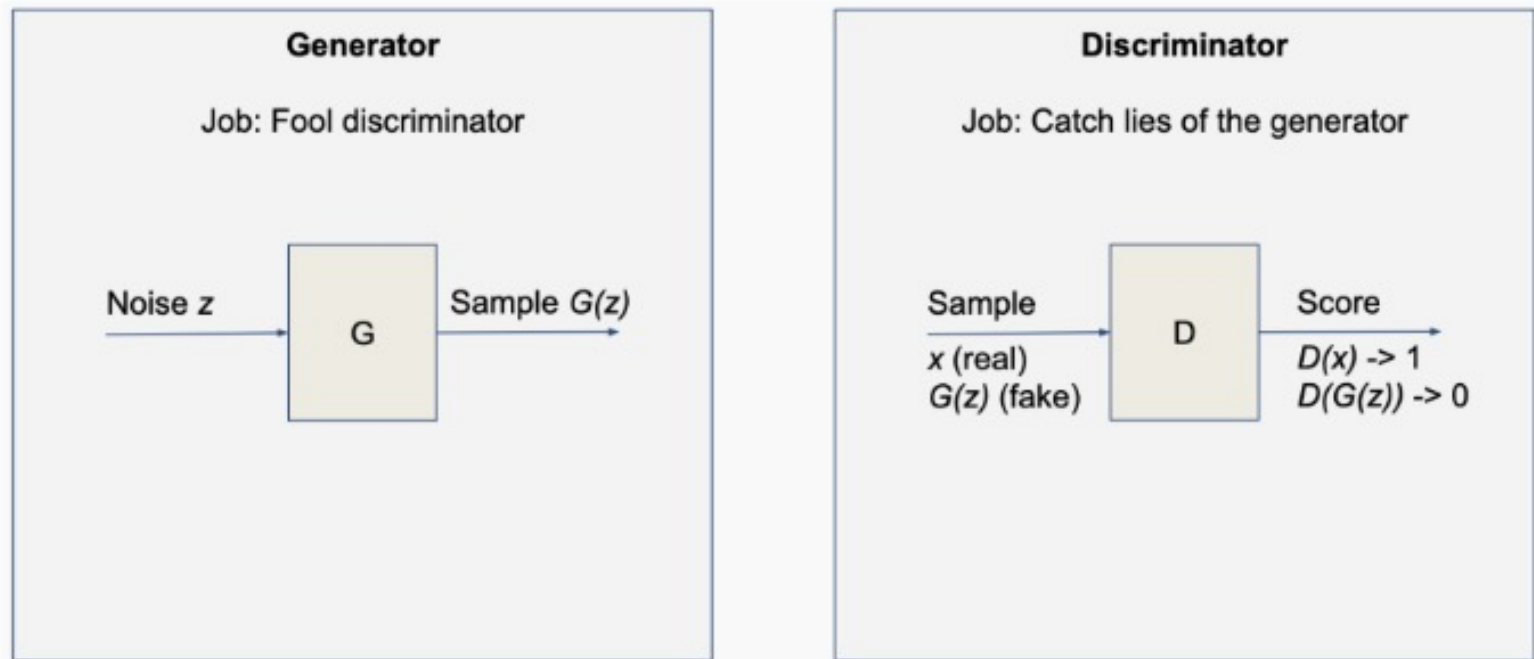
Generative Adversarial Network (GAN)



Generative Adversarial Network (GAN)



Generative Adversarial Network (GAN)



Generative Adversarial Network (GAN)

- The Discriminator is trying to maximize its reward $V(D, G)$
- The Generator is trying to minimize Discriminator's reward (or maximize its loss)

$$V(D, G) = \mathbb{E}_{x \sim p(x)} [\log D(x)] + \mathbb{E}_{z \sim q(z)} [\log(1 - D(G(z)))]$$

The overall objective of GAN is:

$$\min_G \max_D V(D, G) = \min_G \max_D \mathbb{E}_{x \sim p(x)} [\log D(x)] + \mathbb{E}_{z \sim q(z)} [\log(1 - D(G(z)))]$$

Generative Adversarial Network (GAN)

Conditional GAN:

GANs could be extended to conditional model if both the generator and the discriminator are conditioned on extra information y

$$\min_G \max_D V(D, G) = \min_G \max_D \mathbb{E}_{x \sim p(x)} [\log D(x|y)] + \mathbb{E}_{z \sim q(z)} [\log(1 - D(G(z|y)))]$$

Generative Adversarial Network (GAN)

Pix2Pix GAN:

Translation between image pairs:

The input image x and the target image y has one-to-one correspondence

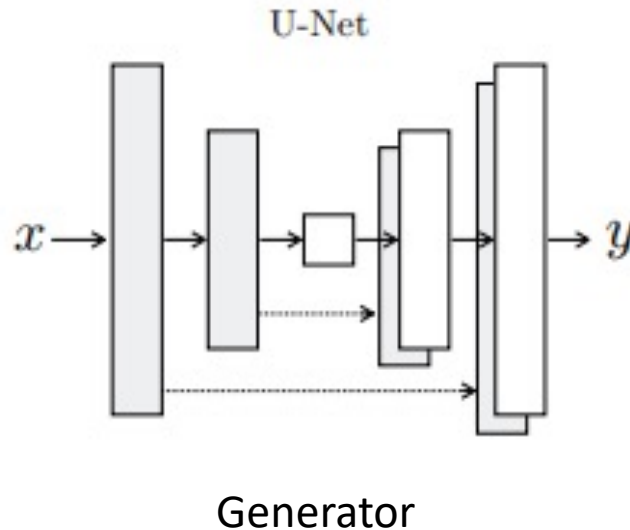


Generative Adversarial Network (GAN)

Generator loss:

$$\mathcal{L}_{cGAN}^G = \mathbb{E}_{\mathbf{x} \sim P_{data}(\mathbf{x})} [\log (1 - D(\mathbf{x}, G(\mathbf{x}))) + \lambda_{l1} \mathbb{E}_{\mathbf{x}, \mathbf{y} \sim P_{data}(\mathbf{x}, \mathbf{y})} [\|\mathbf{y} - G(\mathbf{x})\|_1]$$

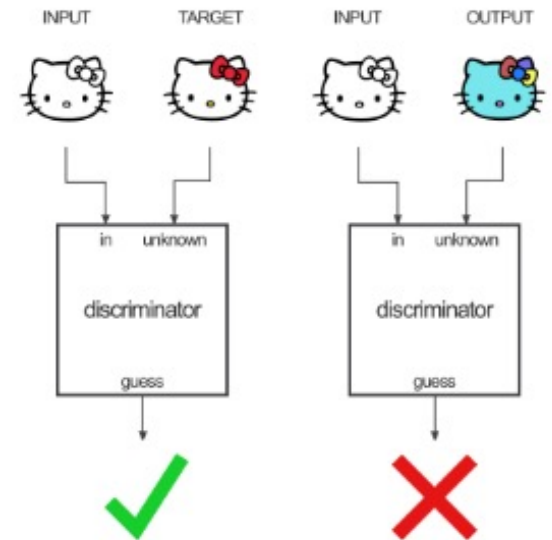
Pixel-to-pixel
intensity loss



Generative Adversarial Network (GAN)

Discriminator loss:

$$\mathcal{L}_{cGAN}^D = -\mathbb{E}_{\mathbf{x}, \mathbf{y} \sim P_{data}(\mathbf{x}, \mathbf{y})} [\log D(\mathbf{x}, \mathbf{y})] \\ - \mathbb{E}_{\mathbf{x} \sim P_{data}(\mathbf{x})} [\log (1 - D(\mathbf{x}, G(\mathbf{x})))] .$$



Overall loss:

$$\mathcal{L}_{cGAN} = \mathcal{L}_{cGAN}^G + \mathcal{L}_{cGAN}^D$$

Generative Adversarial Network (GAN)

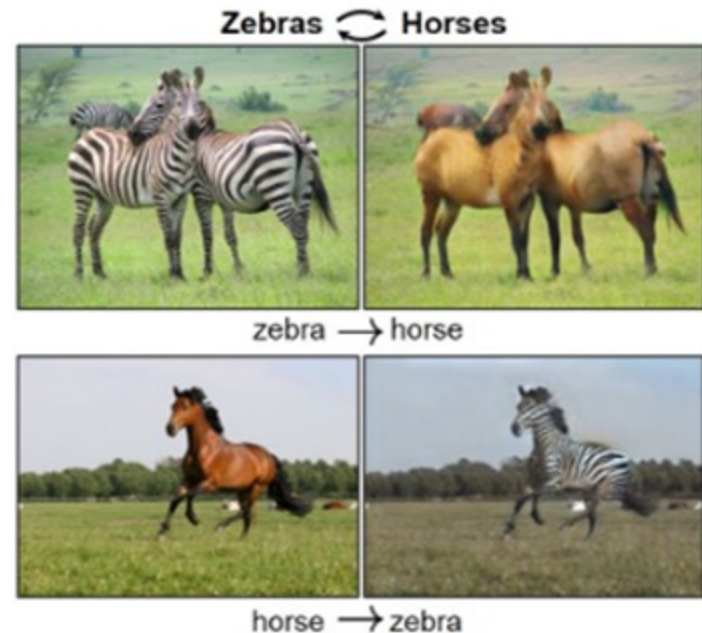
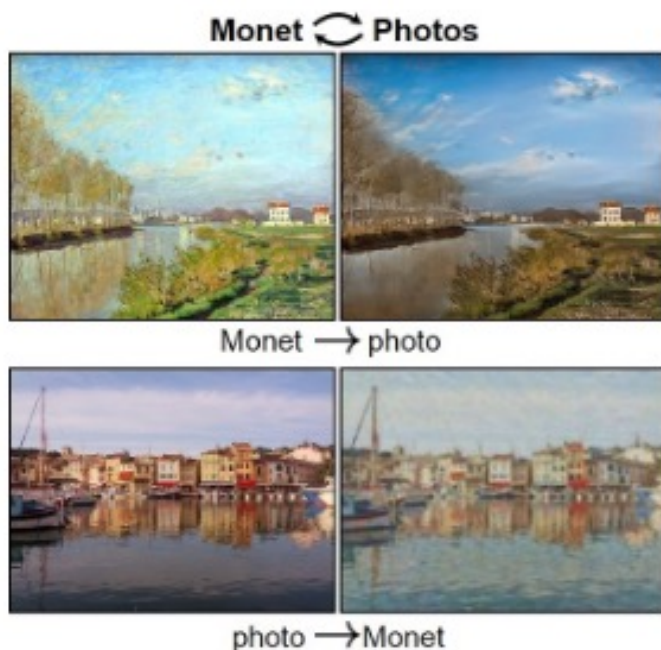


Generative Adversarial Network (GAN)

CycleGAN:

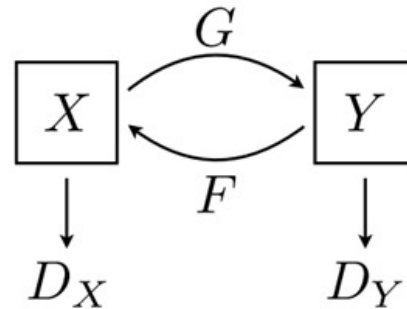
Translation between **unpaired** images:

The input image **x** and the target image **y** do **not** have correspondence

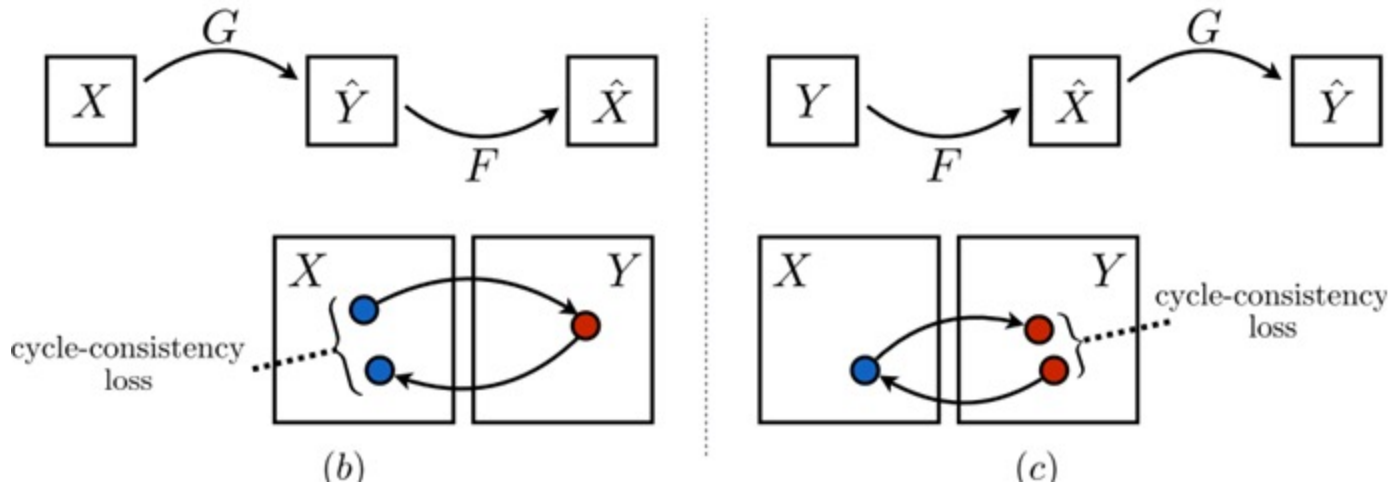


Generative Adversarial Network (GAN)

CycleGAN:



(a)



(b)

(c)

Generative Adversarial Network (GAN)

CycleGAN:

- Two generators,

G learns the mapping $\mathbf{X} \rightarrow \mathbf{Y}$

F learns the mapping $\mathbf{Y} \rightarrow \mathbf{X}$

- Two discriminators

D_X differentiates $\hat{\mathbf{x}} = F(G(\mathbf{x}))$ from \mathbf{x}

D_Y differentiates $\hat{\mathbf{y}} = G(F(\mathbf{y}))$ from \mathbf{y}

Generative Adversarial Network (GAN)

CycleGAN

Loss function:

$$\mathcal{L}(G, F, D_X, D_Y) = \mathcal{L}_{GAN}^{G, D_Y, X, Y} + \mathcal{L}_{GAN}^{G, D_X, Y, X} + \lambda \mathcal{L}_{cycle}^{G, F}$$

Common GAN loss

Cycle consistency

Cycle consistency term:

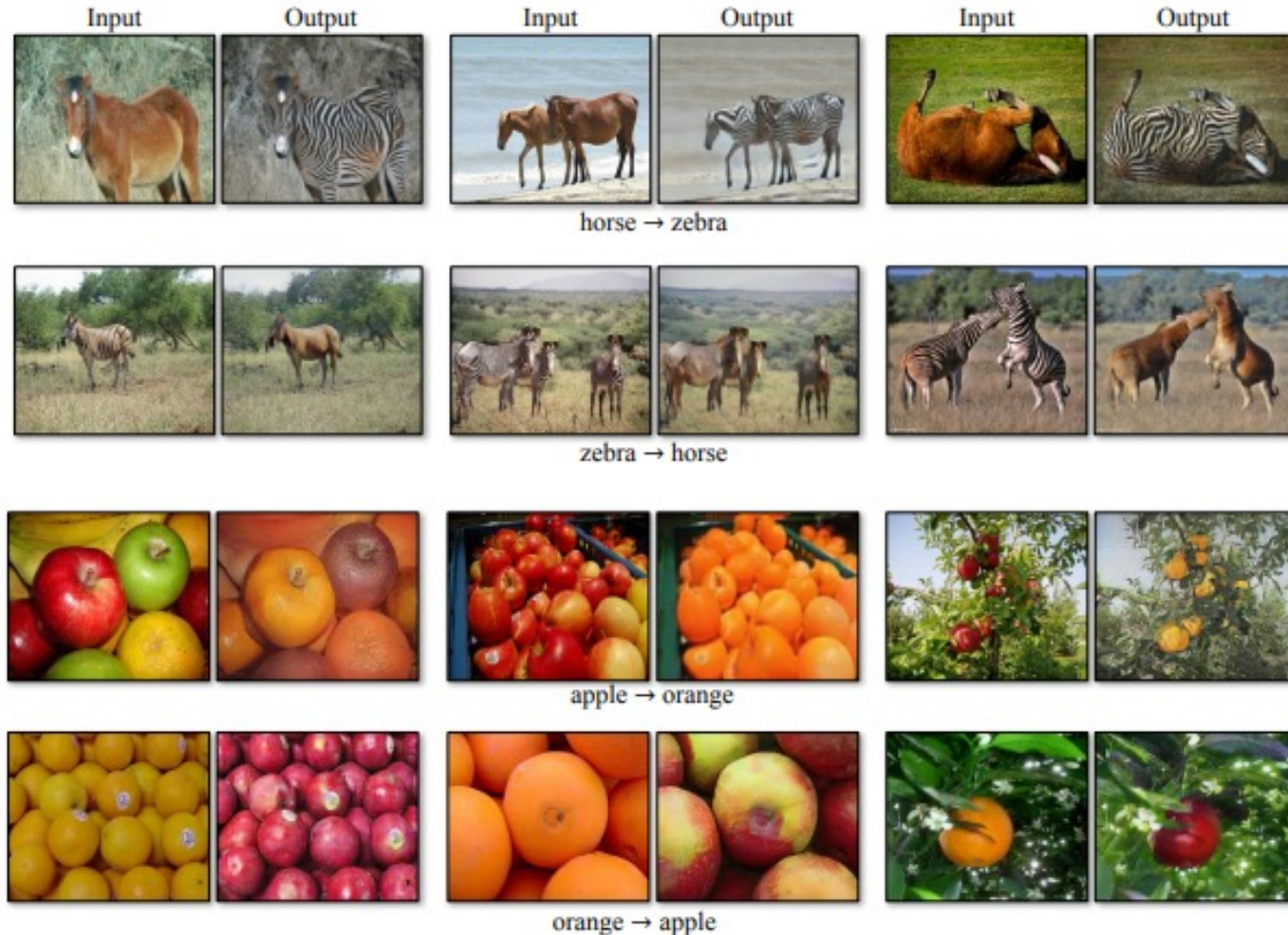
$$\mathcal{L}_{cycle}^{G, F} = \mathbb{E}_{\mathbf{x} \sim P_{data}(\mathbf{x})} [\|F(G(\mathbf{x})) - \mathbf{x}\|_1] + \mathbb{E}_{\mathbf{y} \sim P_{data}(\mathbf{y})} [\|G(F(\mathbf{y})) - \mathbf{y}\|_1]$$

Generative Adversarial Network (GAN)



Jun-Yan Zhu*, Taesung Park*, Phillip Isola, Alexei A. Efros. Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks, ICCV2017

Generative Adversarial Network (GAN)



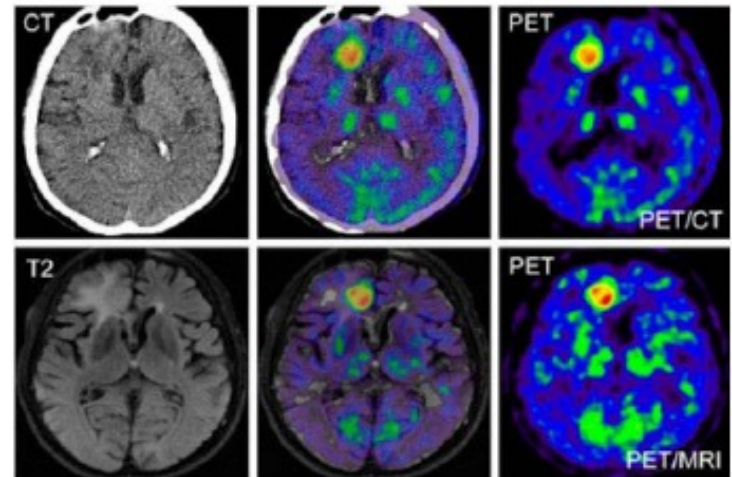
Jun-Yan Zhu*, Taesung Park*, Phillip Isola, Alexei A. Efros. Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks, ICCV2017

A Case Study

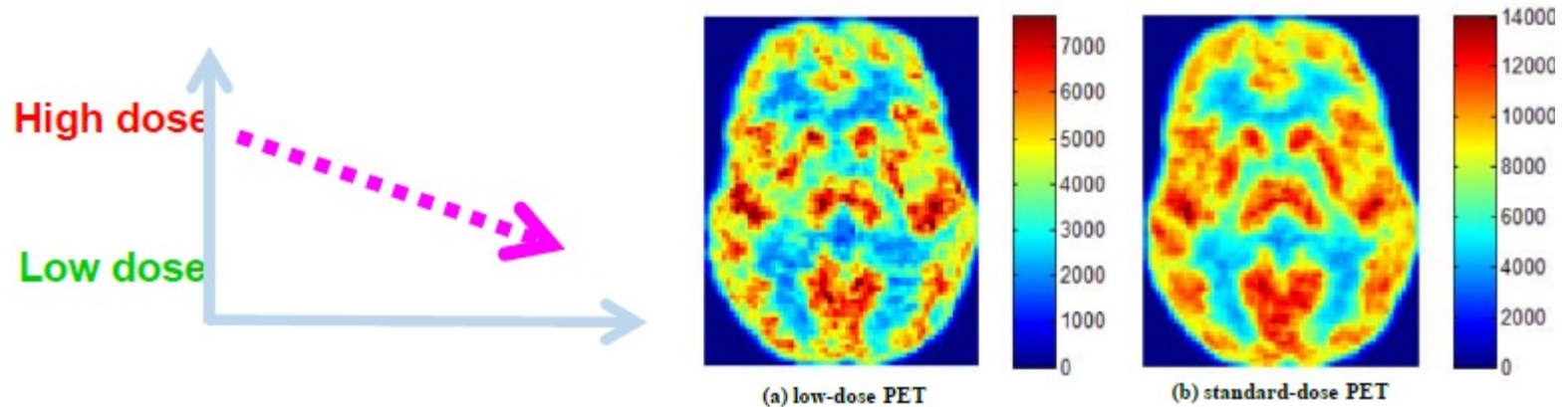
Y. Wang, B. Yu, L. Wang, C. Zu, D.S. Lalush, W. Lin, X. Wu, J. Zhou, D. Shen*, and **L. Zhou***, "**3D Conditional Generative Adversarial Networks for High-quality PET Image Estimation at Low Dose**", Neuroimage, 2018

Estimating PET images from low dose

- Positron emission tomography (PET) can produce a 3D image of the functional processes in the body, i.e., using PET/CT.
→ Widely used in various clinical applications, such as cancer diagnosis.



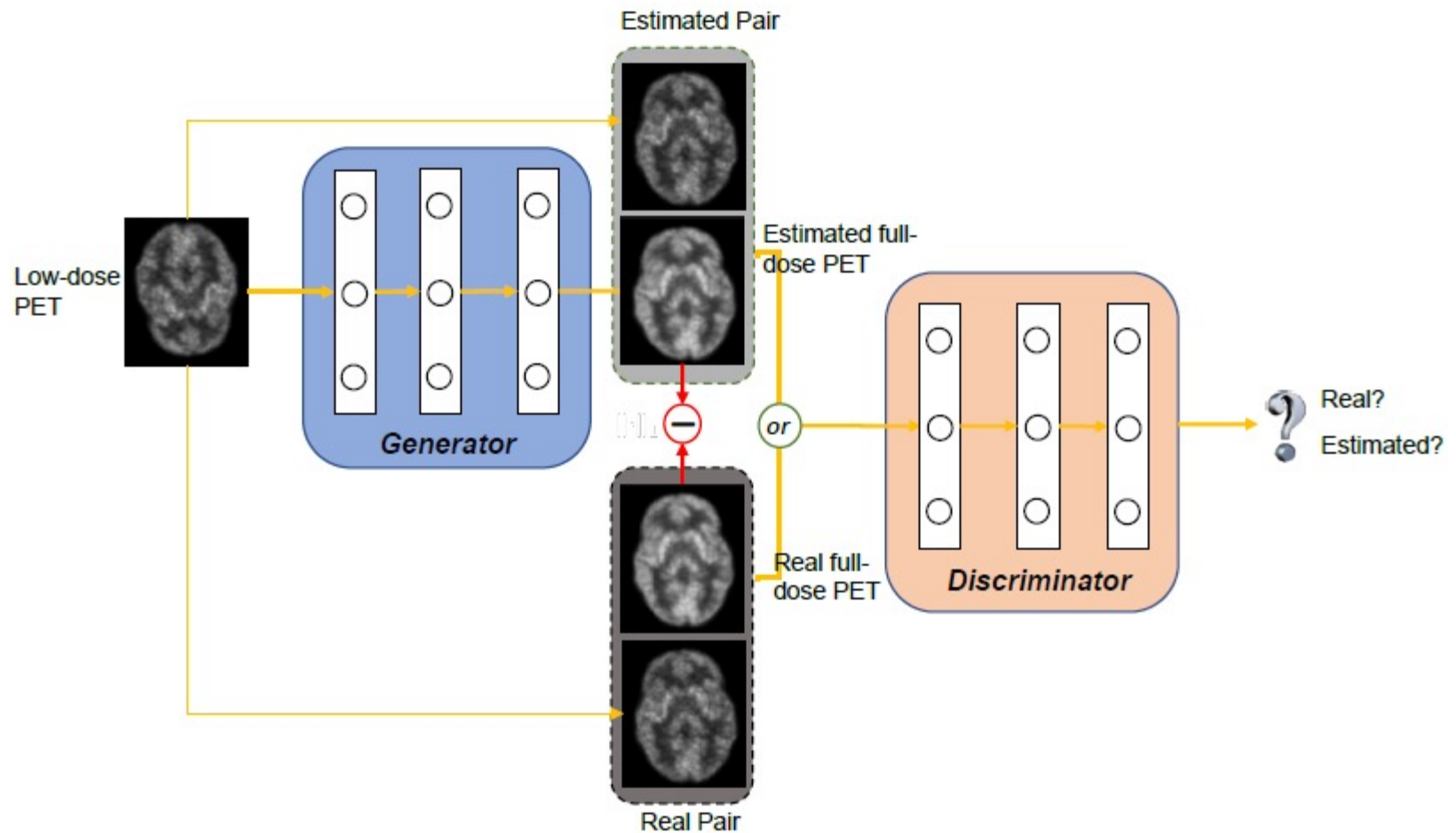
Estimating PET images from low dose



Comparison between low-dose (L-PET) and full-dose PET (F-PET) images

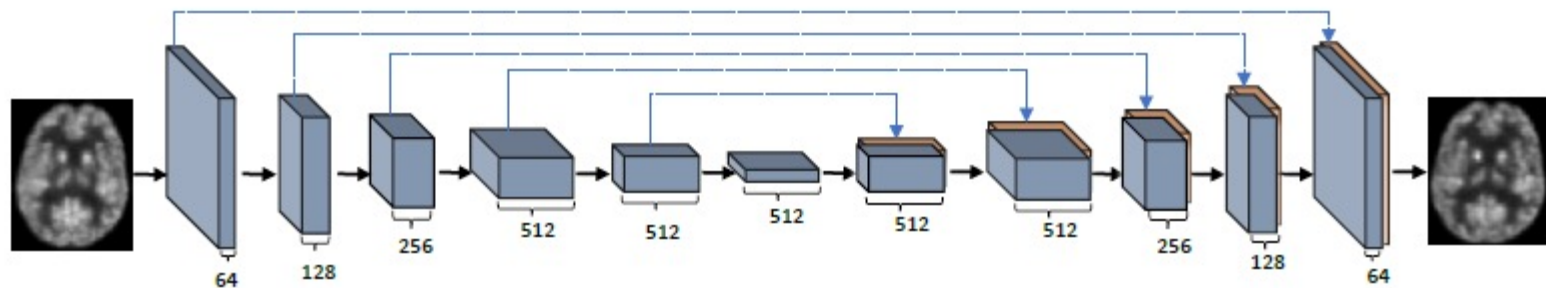
High quality PET image plays an essential role in accurately diagnosing diseases/ disorders and in assessing the response to therapy.

3D c-GAN based method

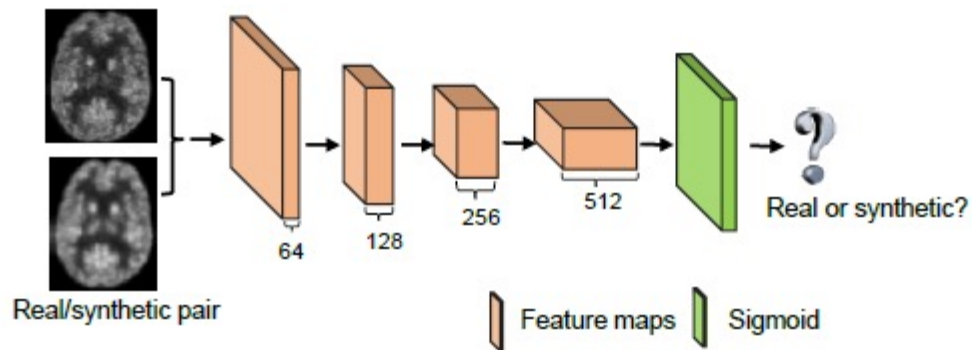


Estimating PET images from low dose

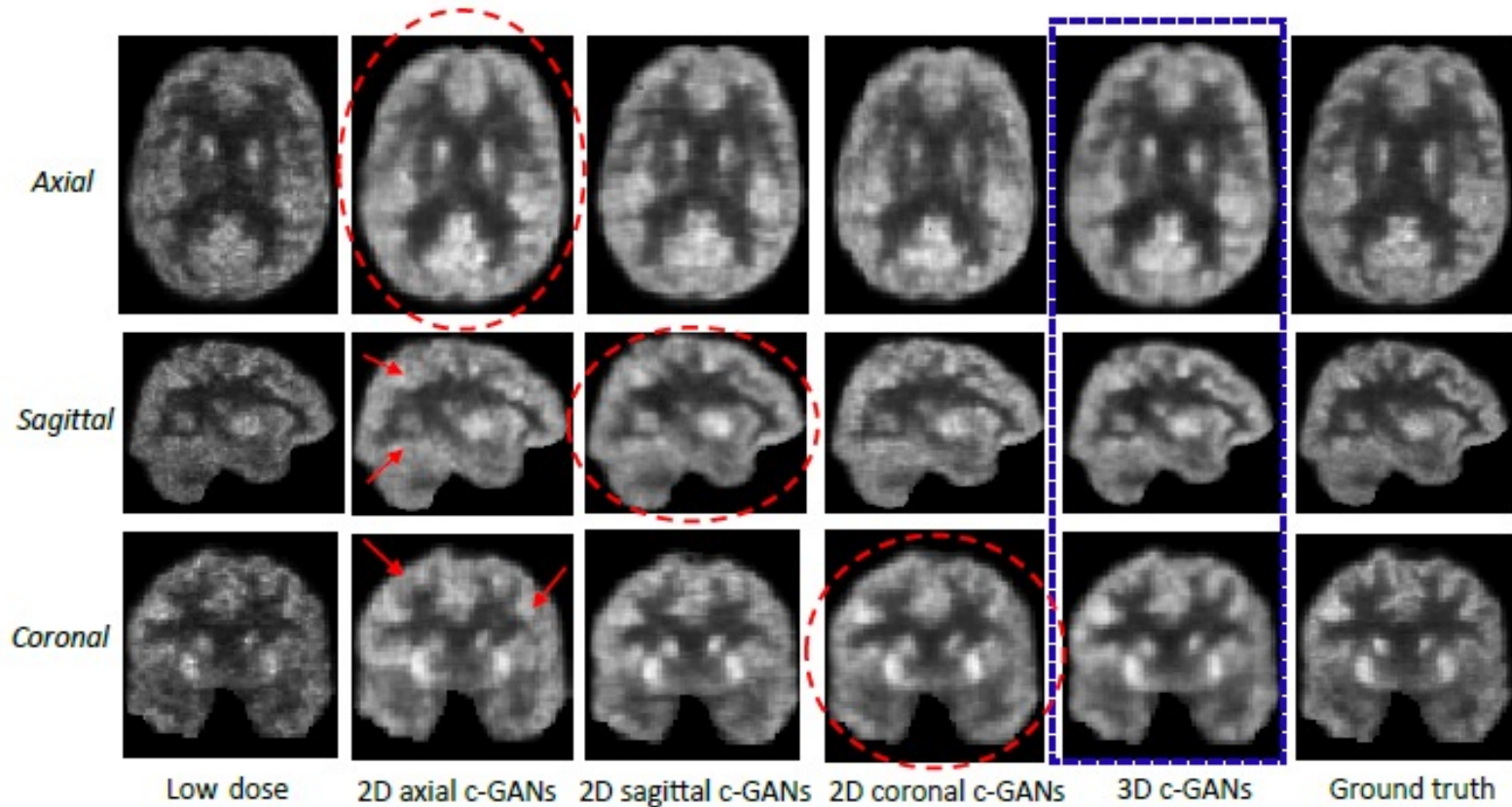
Generator:



Discriminator:



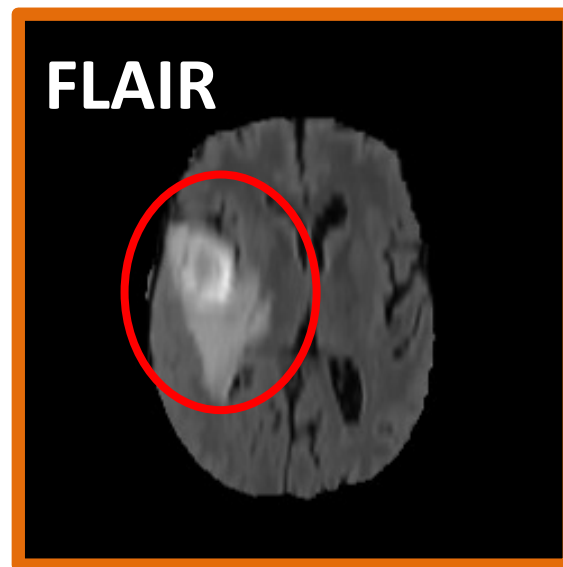
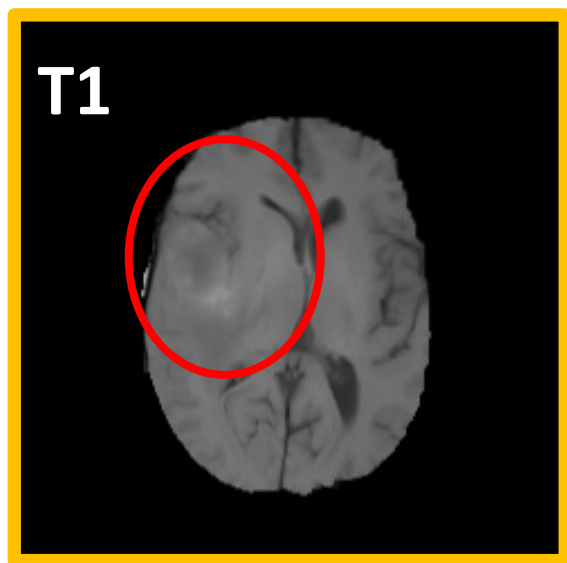
Estimating PET images from low dose



A Case Study II

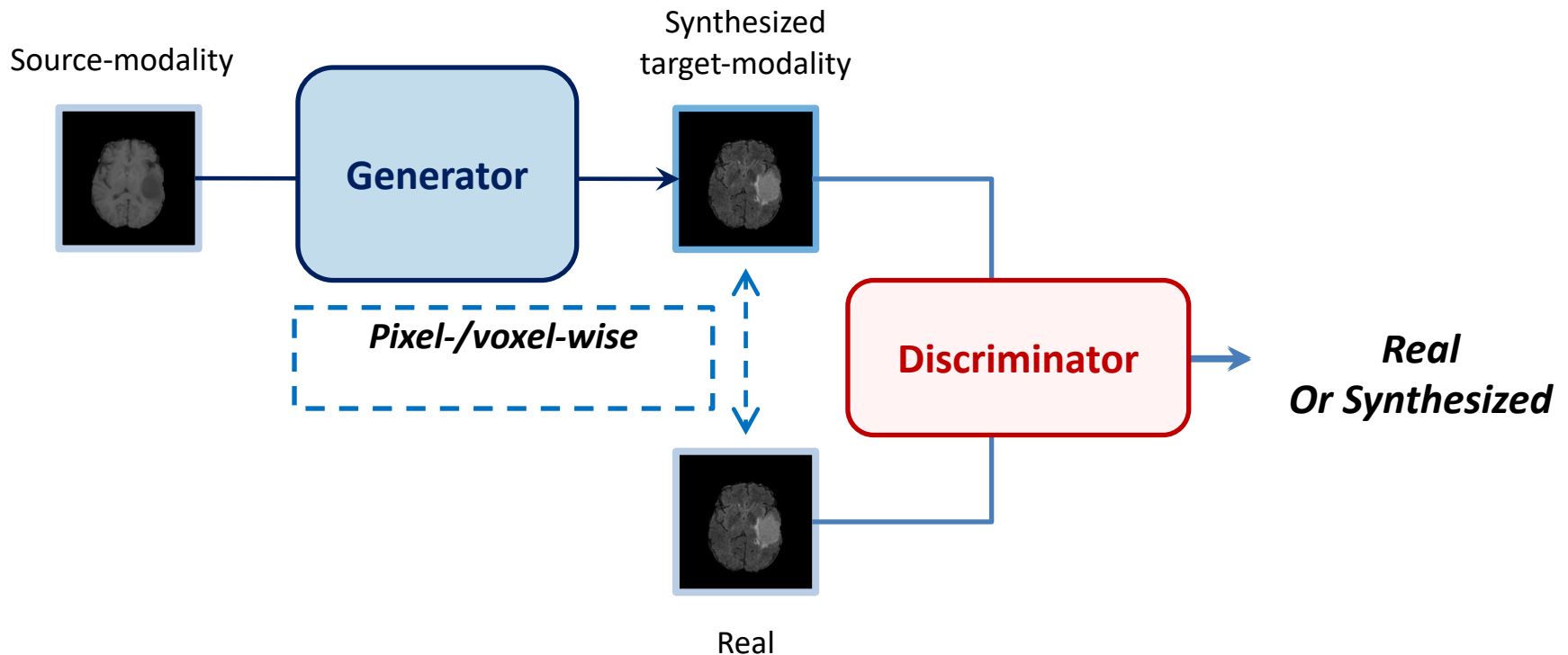
B. Yu, **L. Zhou**, L. Wang, Y. Shi, J. Fripp, and P. Bourgeat, “**Ea-GANs: Edge-aware Generative Adversarial Networks for Cross-modality MR Image Synthesis**”, IEEE Transactions on Medical Imaging (IEEE T-MI), 2019

Cross MR modality synthesis



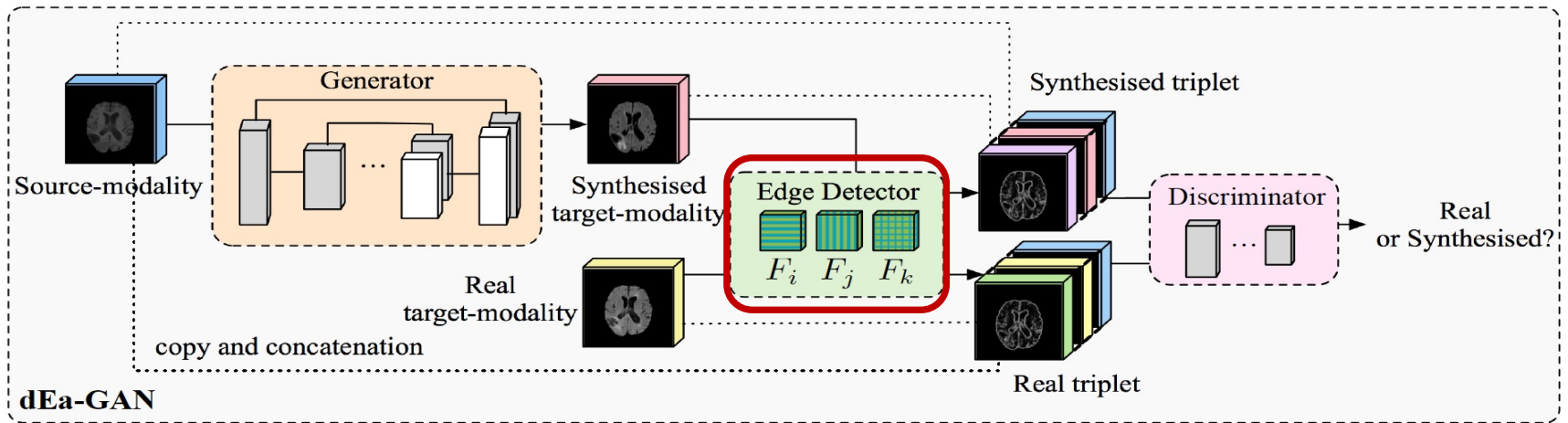
Cross MR modality synthesis

Existing Methods



Cross MR modality synthesis

- ***Discriminator-induced Ea-GAN (dEa-GAN)***
 - incorporate edge information into training both the **generator** and the **discriminator**



Cross MR modality synthesis

