

Deep Generative Models

Some images are from Fei-fei Li's course @Standford <http://cs231n.stanford.edu/> and Towards Data Science <https://towardsdatascience.com>

Outline

- Generative models
- Variational Autoencoder (VAE)
- Generative Adversarial Network (GAN)

Generative Models

Given training data, generate new samples from the same distribution



Training data $\sim p_{\text{data}}(x)$



Generated samples $\sim p_{\text{model}}(x)$

Want to learn $p_{\text{model}}(x)$ similar to $p_{\text{data}}(x)$

-Explicit density estimation: explicitly define and solve for $p_{\text{model}}(x)$

-Implicit density estimation: learn model that can sample from $p_{\text{model}}(x)$ w/o explicitly defining it

Discriminative Model vs Generative Model

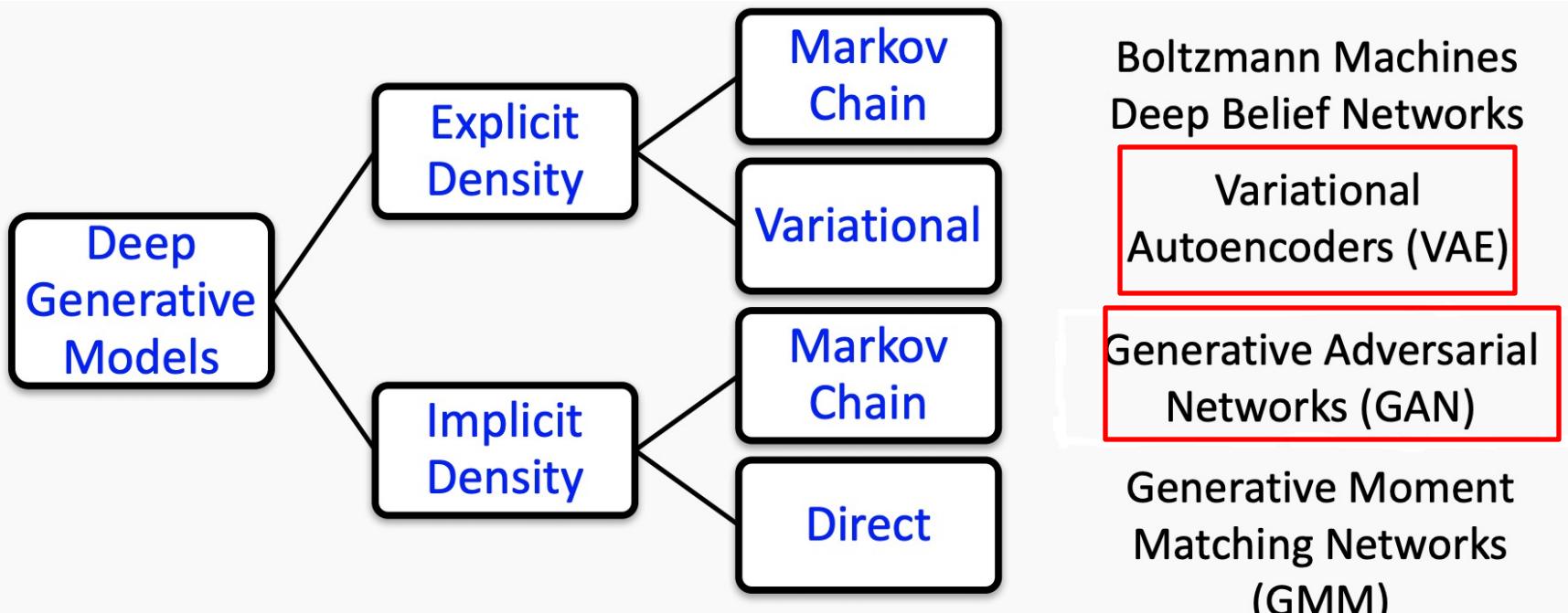
Discriminative Model

- Given an image \mathbf{X} , predict a label Y
- Estimates $P(Y|\mathbf{X})$

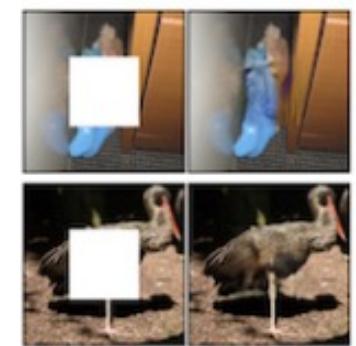
Generative Model

- Model $P(\mathbf{X})$
- Can generate new images

Deep Generative Models



Generative Models



Generate examples in image datasets

Generate realistic photos

Image inpainting



Image-to-image translation

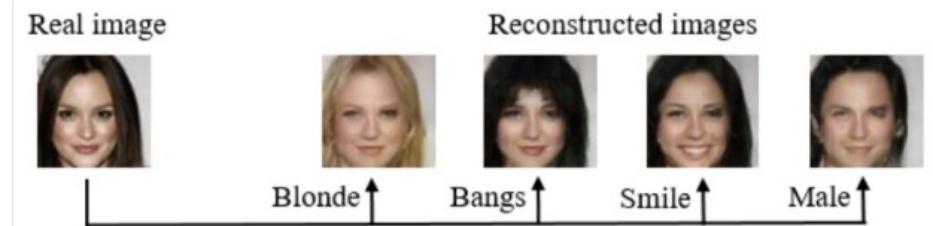
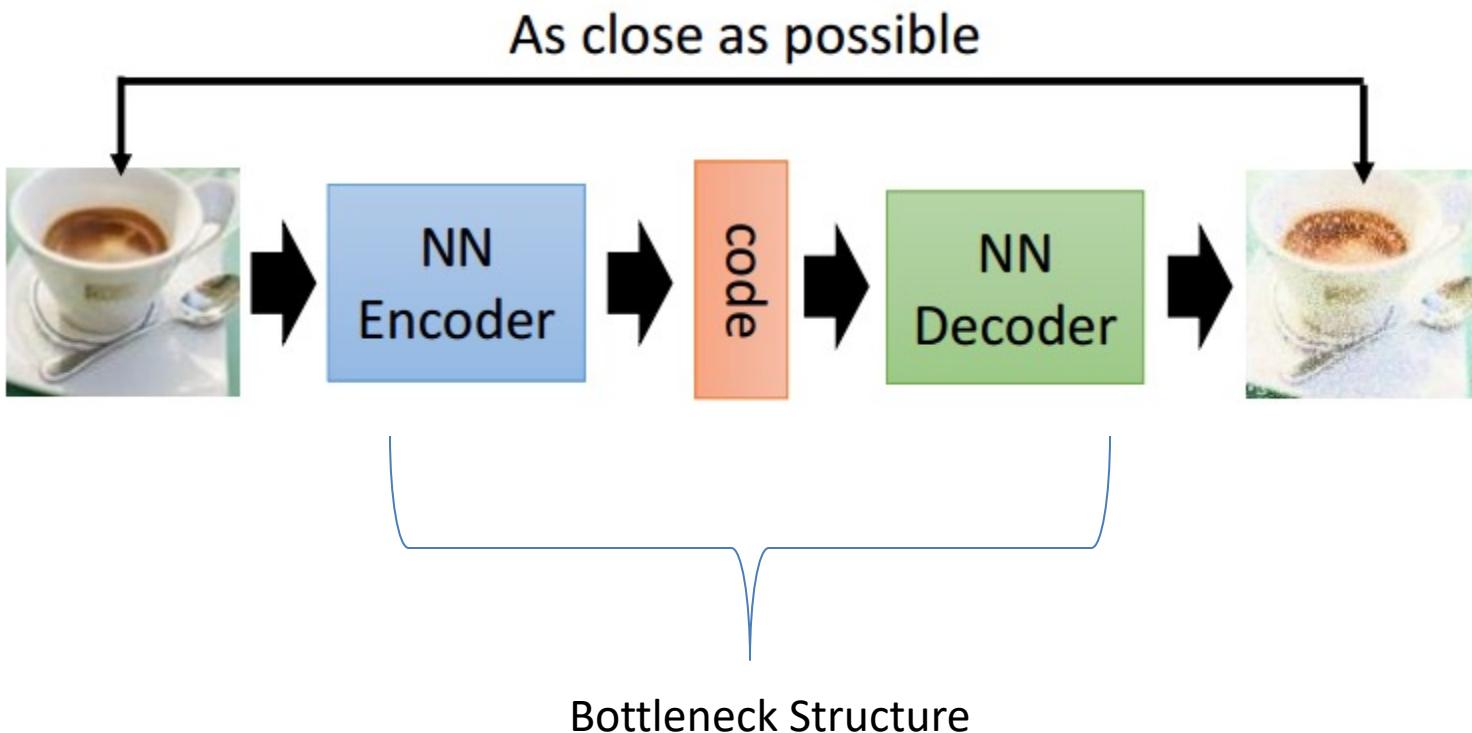


Photo editing

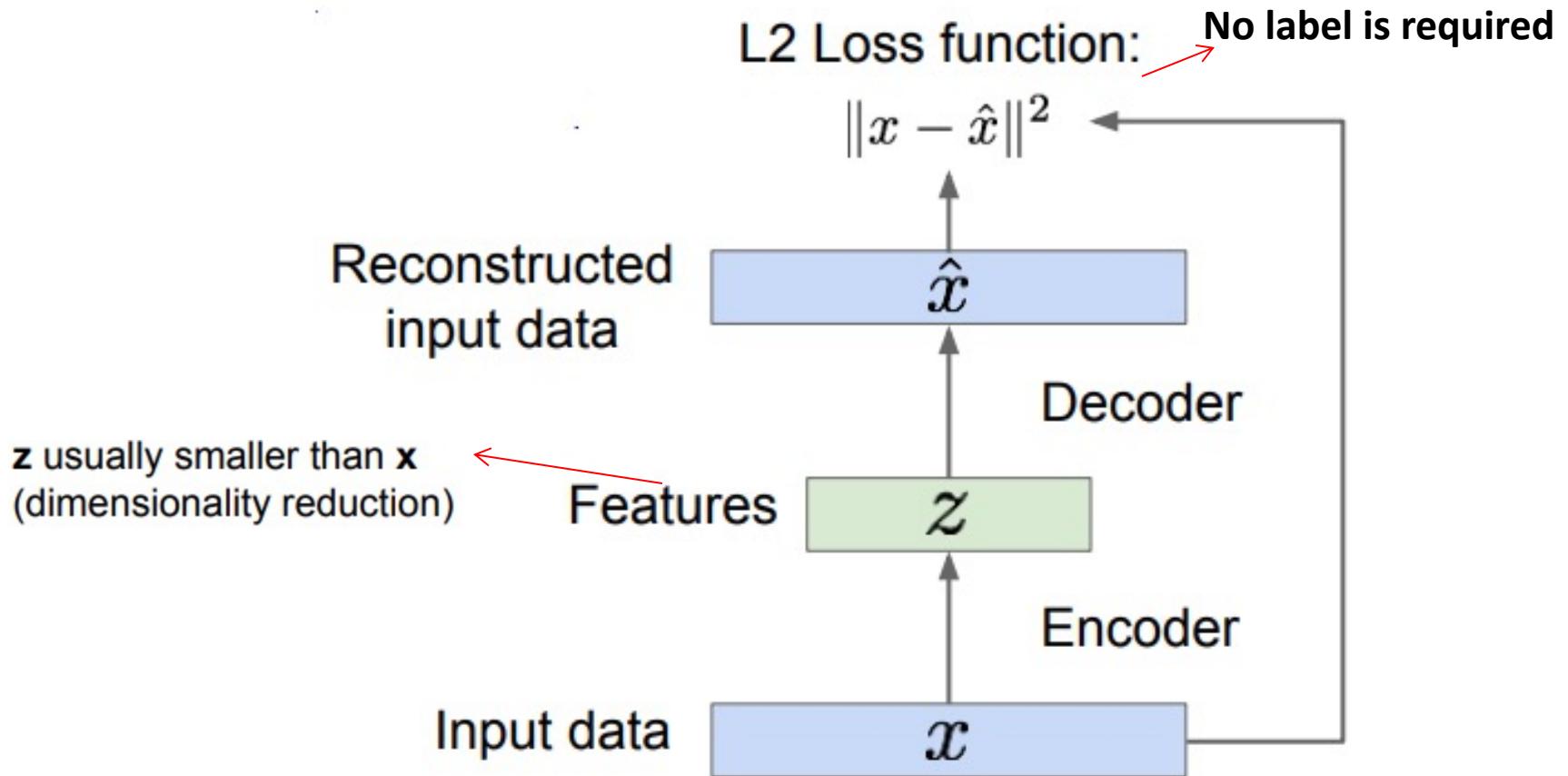
Outline

- Generative models
- **Variational Autoencoder (VAE)**
- Generative Adversarial Network (GAN)

Auto-encoder (AE): original model



Auto-encoder (AE): original model



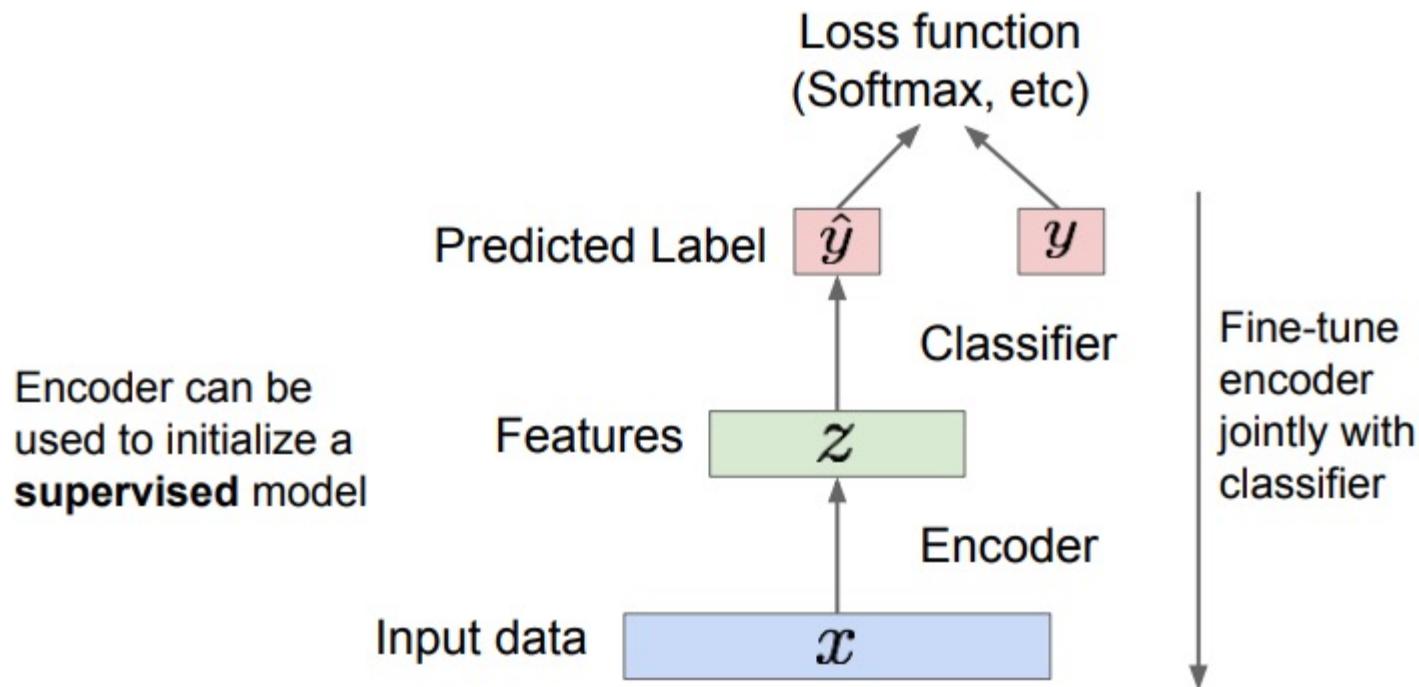
z is a latent variable that has smaller dimension than x

Autoencoder (AE): original model

- Autoencoder is a multi-layer neural network. The only difference is that the size of its output layer is the same as the input layer.
- The reconstruction objective does not involve any label.
- The generated latent representation z could be used as features extracted in an unsupervised way.
- The feature z could also be used to initialize a supervised model.

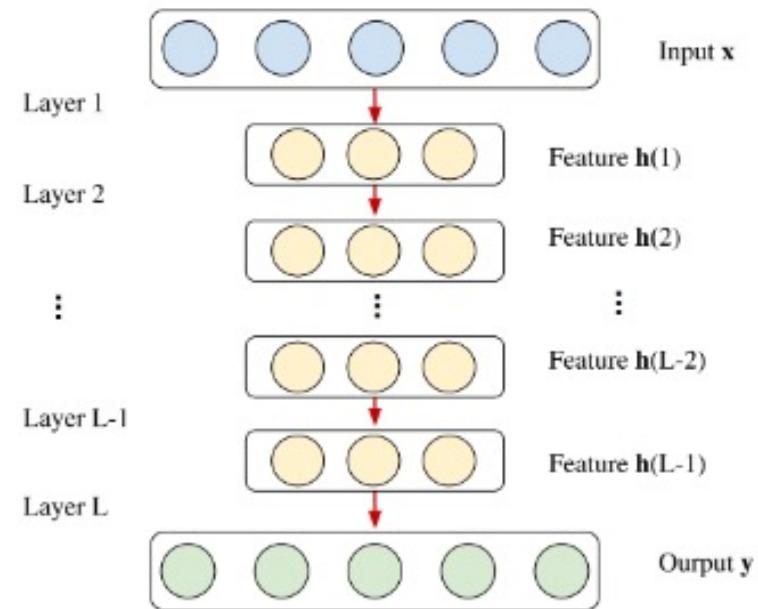
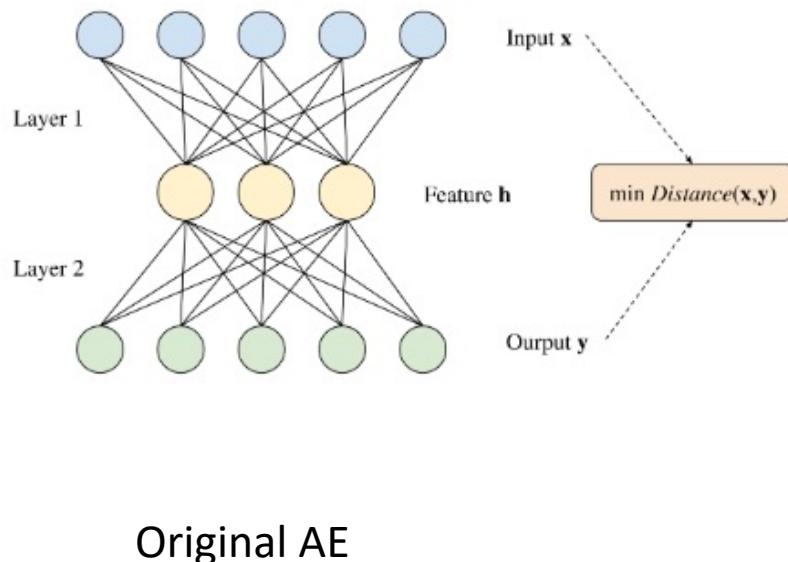
Auto-encoder (AE): original model

Autoencoder could be trained as a good initialization in a supervised model.



Autoencoder (AE): stacked autoencoder

Autoencoder could be stacked to form a deep model and generate a hierarchy of latent features.



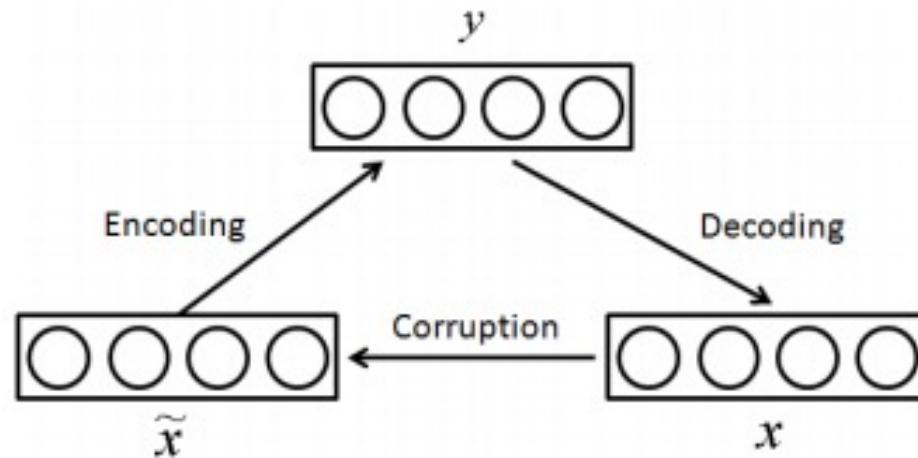
Original AE

Stacked AE

Auto-encoder (AE): denoising autoencoder

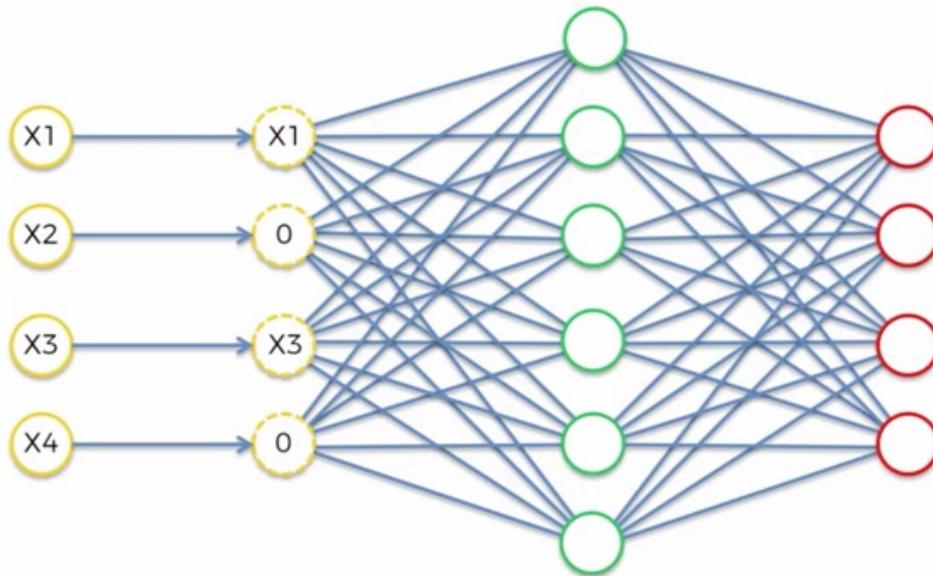
Denoising autoencoder:

In order to force the hidden layer to discover robust features and prevent it from simply learning the identity function, we want to train the autoencoder to reconstruct the input from a corrupted version of it



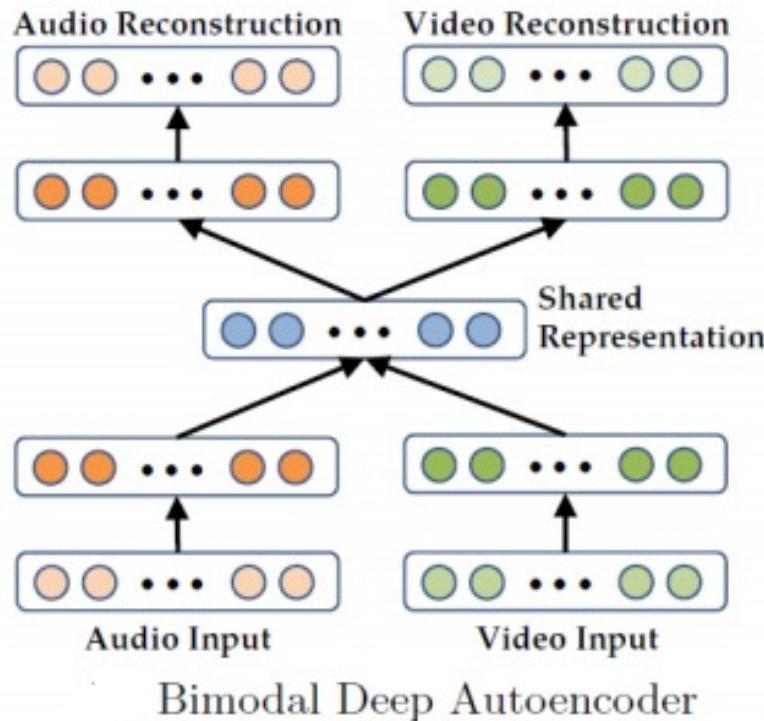
Auto-encoder (AE): denoising autoencoder

- To convert the autoencoder to a denoising autoencoder, we can randomly set some of the inputs (as many as half of them) to zero.



- The input can be corrupted in other ways

Auto-encoder (AE): multimodal autoencoder



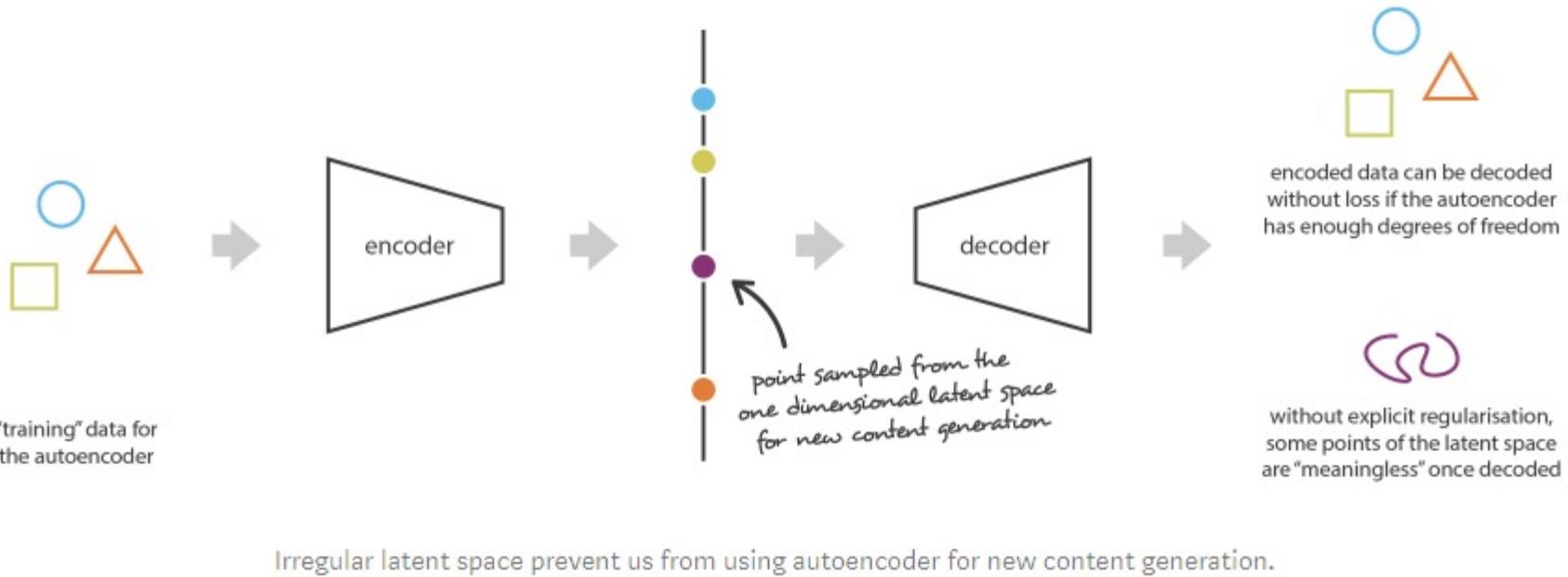
Example:

- One third of training data has only video
- One third of training data has only audio
- One third of training data has both video and audio

Variational Auto-encoder (VAE)

- Autoencoder gives low reconstruction error on test examples from the same distribution as the training examples, but generally high reconstruction error on samples randomly chosen from the input space.
- Variational auto-encoder:
 - Probabilistic spin on autoencoders - enable sampling from the model to generate data

Variational Auto-encoder (VAE)



Variational Auto-encoder (VAE)

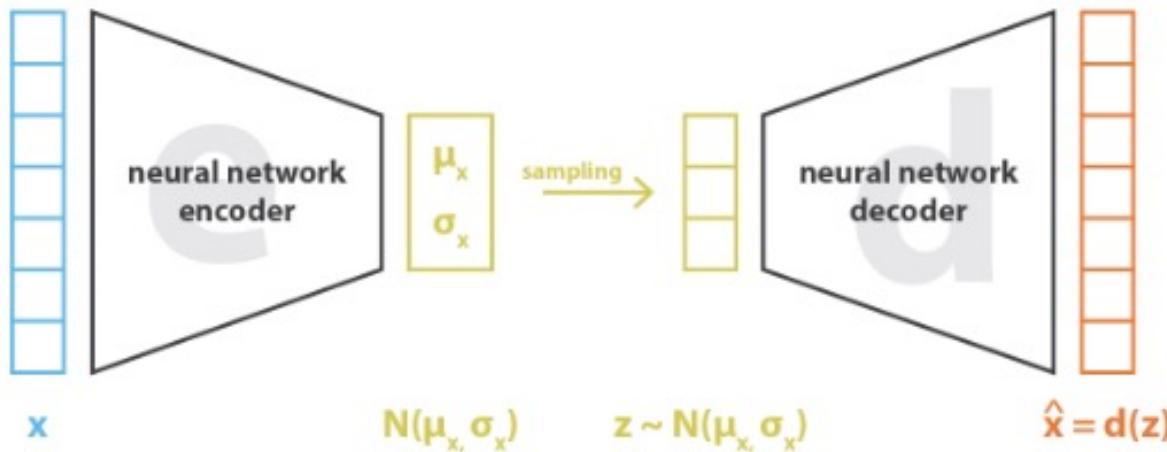


Difference between autoencoder (deterministic) and variational autoencoder (probabilistic).

Instead of encoding an input as a single point, VAE encodes it as a distribution over the latent space.

Variational Auto-encoder (VAE)

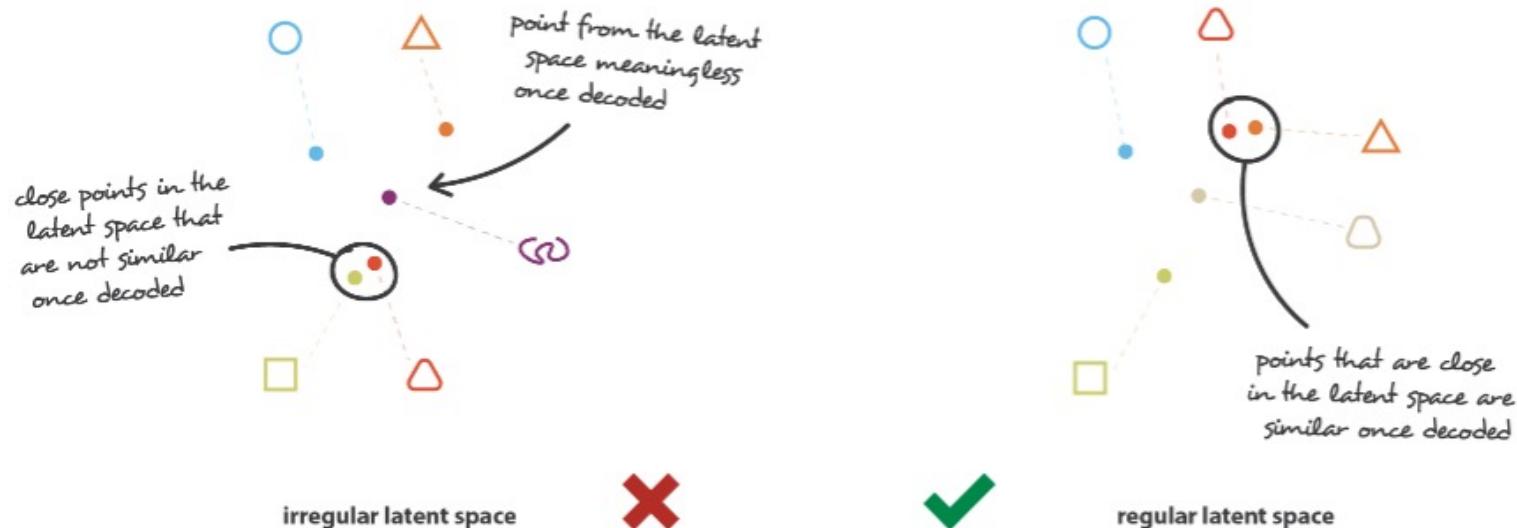
VAE could be treated as “regularized” autoencoder.



$$\text{loss} = \|x - \hat{x}\|^2 - \text{KL}[N(\mu_x, \sigma_x), N(0, I)] = \|x - d(z)\|^2 \cdot \text{KL}[N(\mu_x, \sigma_x), N(0, I)]$$

Reconstruction term Regularization term

Variational Auto-encoder (VAE)



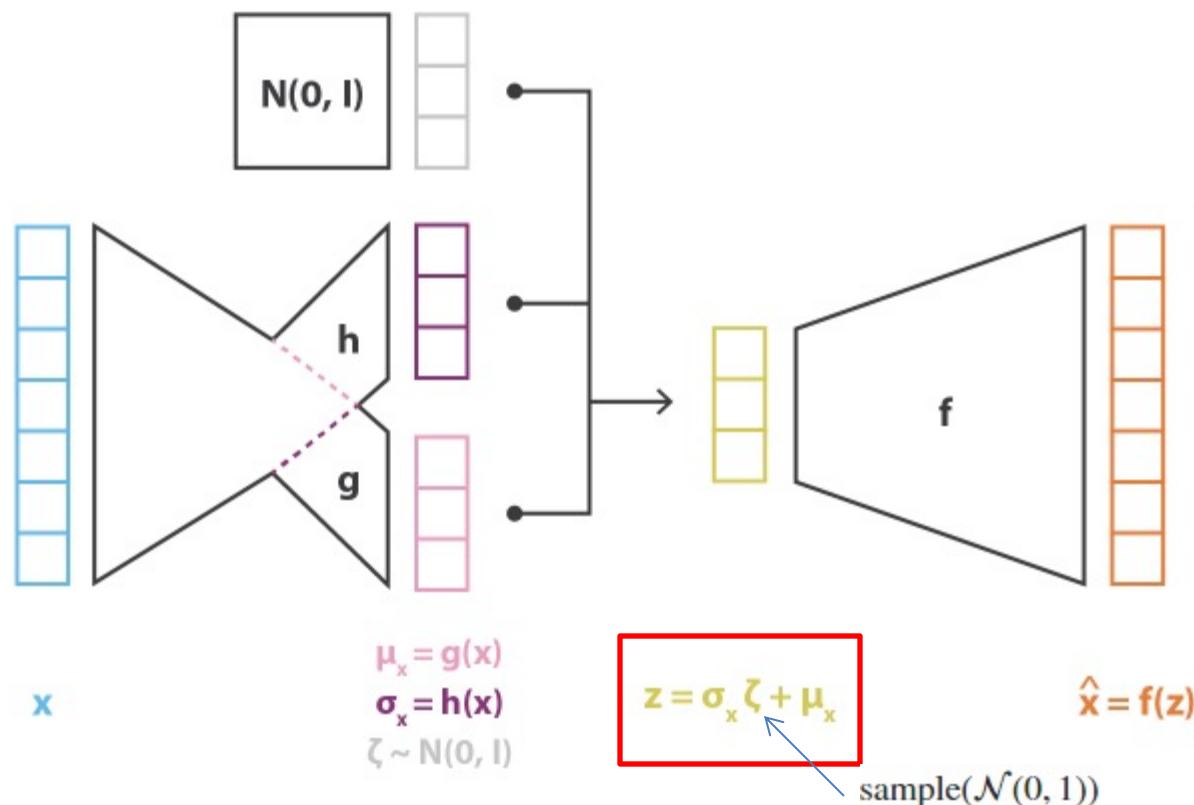
A “regular” latent space requires :

- (1) continuity :** two close points should not give two completely different contents once decoded
- (2) completeness :** a point sampled from the latent space should give “meaningful” content once decoded

Variational Auto-encoder (VAE)

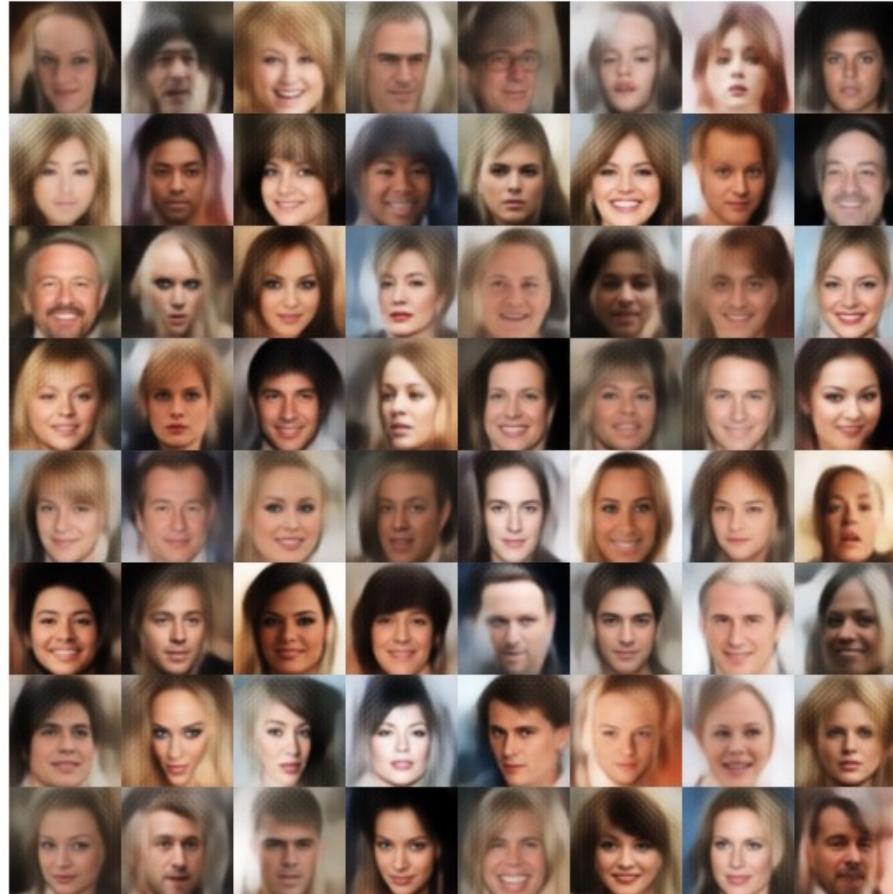


Variational Auto-encoder (VAE)



$$\text{loss} = C \| x - \hat{x} \|^2 - \text{KL}[N(\mu_x, \sigma_x), N(0, I)] = C \| x - f(z) \|^2 - \text{KL}[N(g(x), h(x)), N(0, I)]$$

Variational Auto-encoder (VAE)



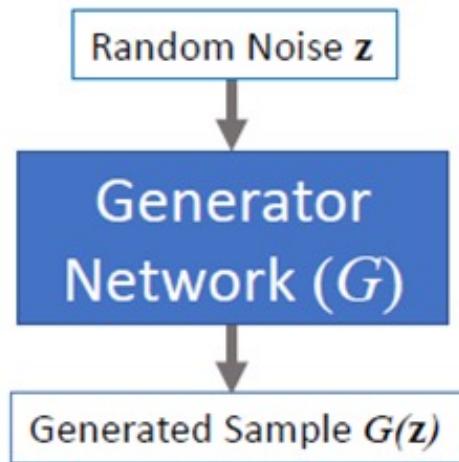
Generating celebrity-look like photos

Outline

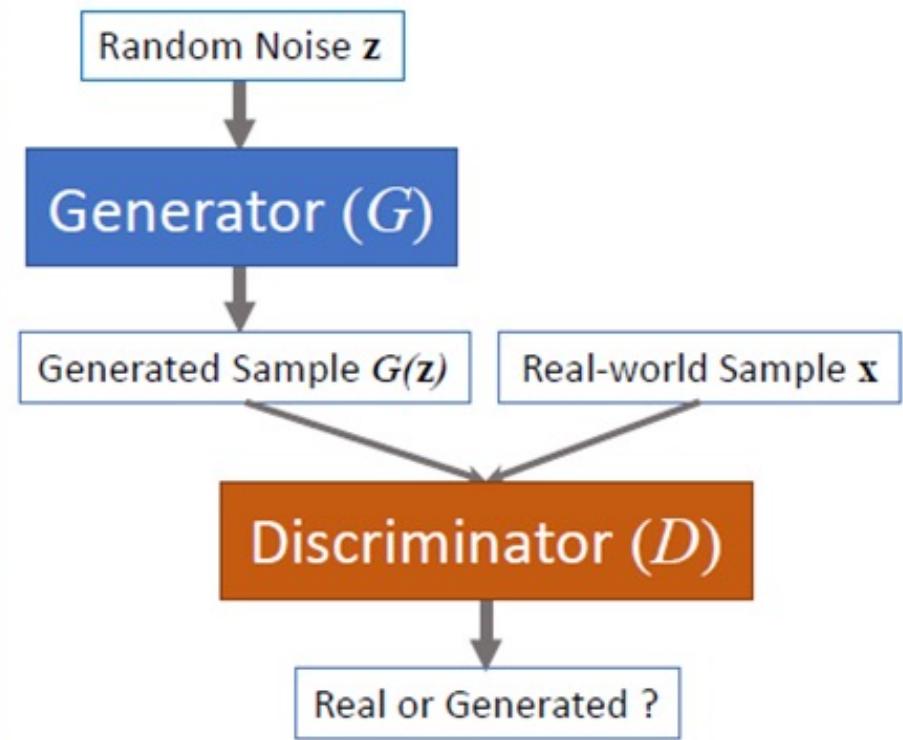
- Generative models
- Variational Autoencoder (VAE)
- Generative Adversarial Network (GAN)

Generative Adversarial Network (GAN)

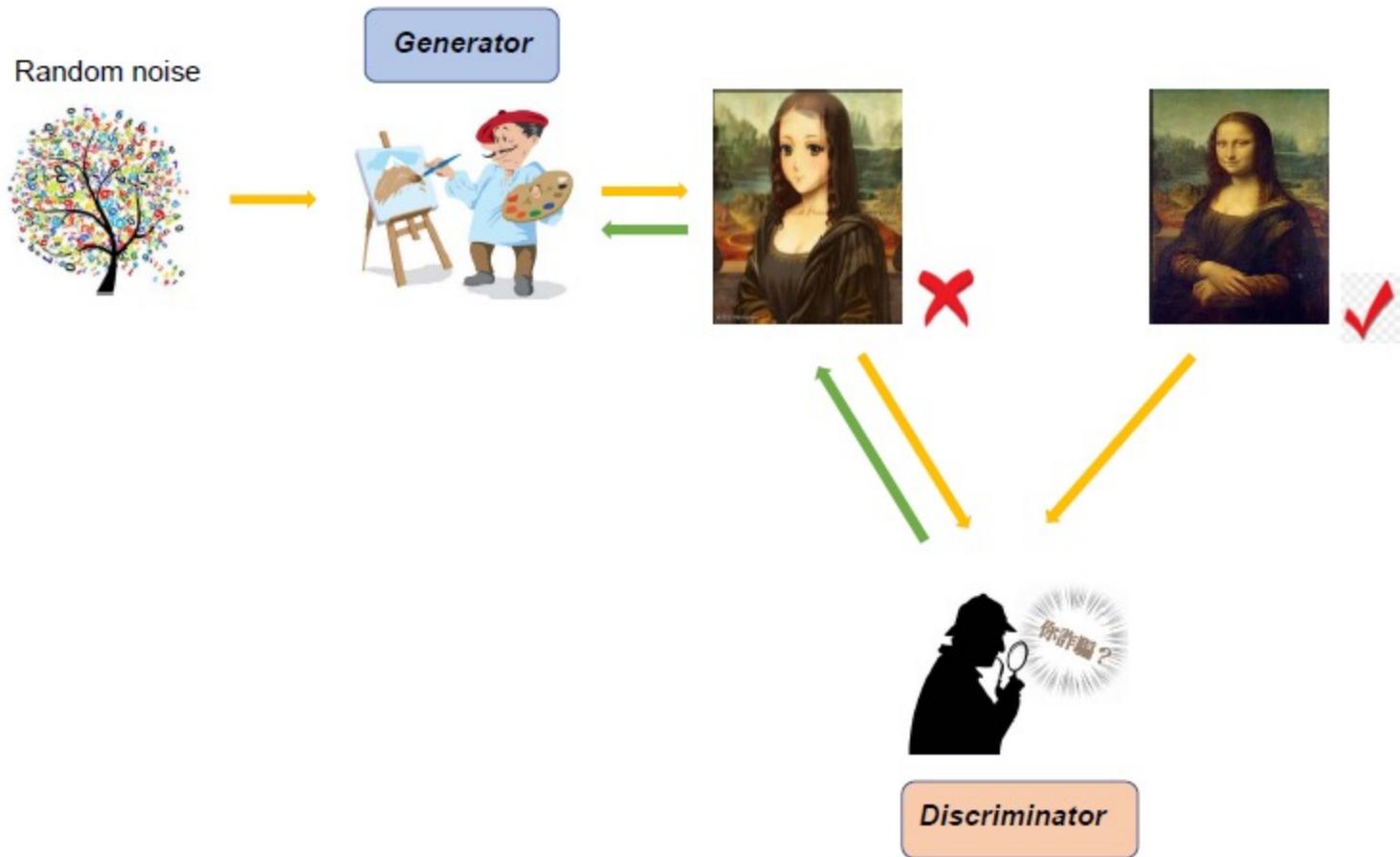
Traditional Generative Network



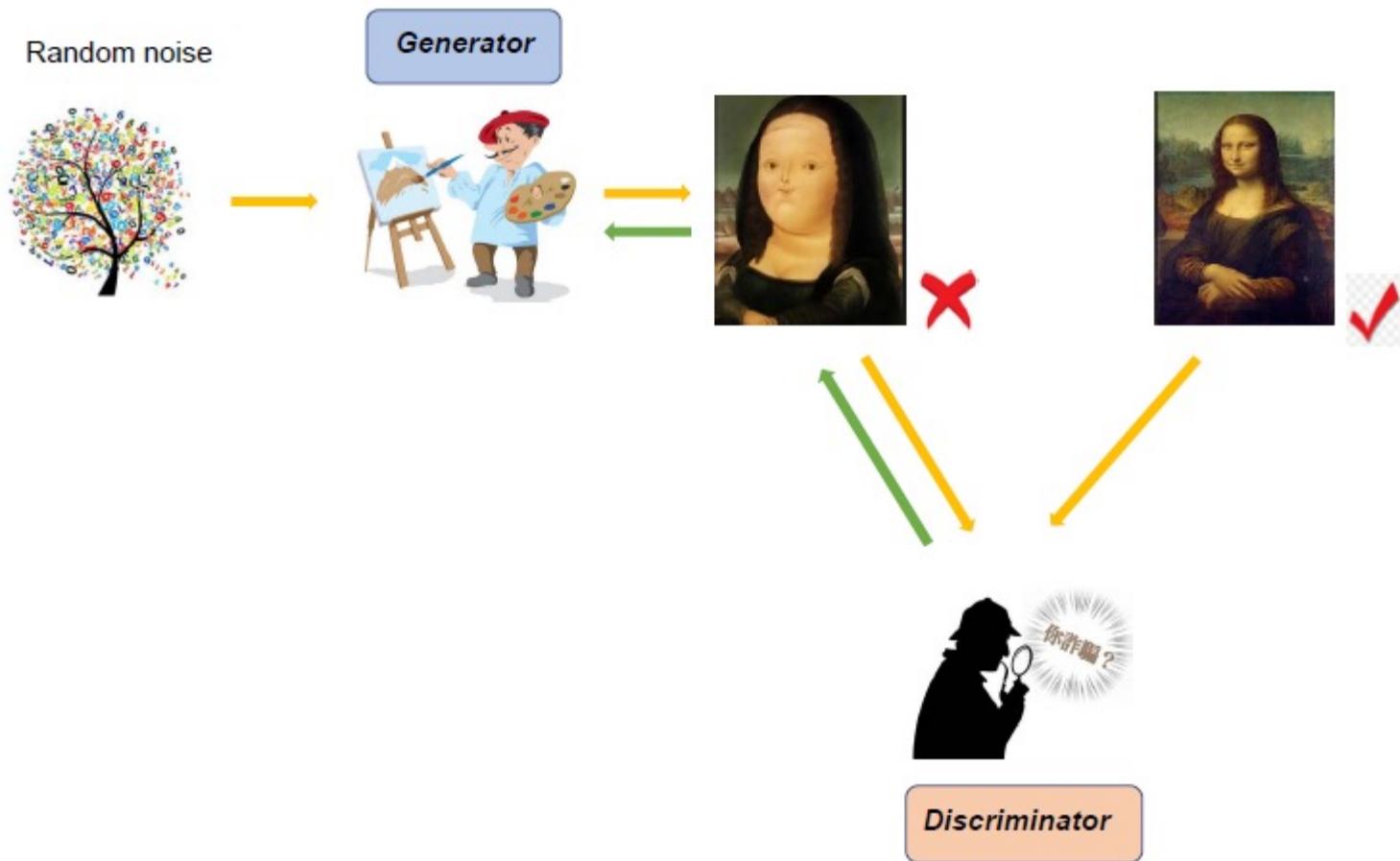
Generative Adversarial Network



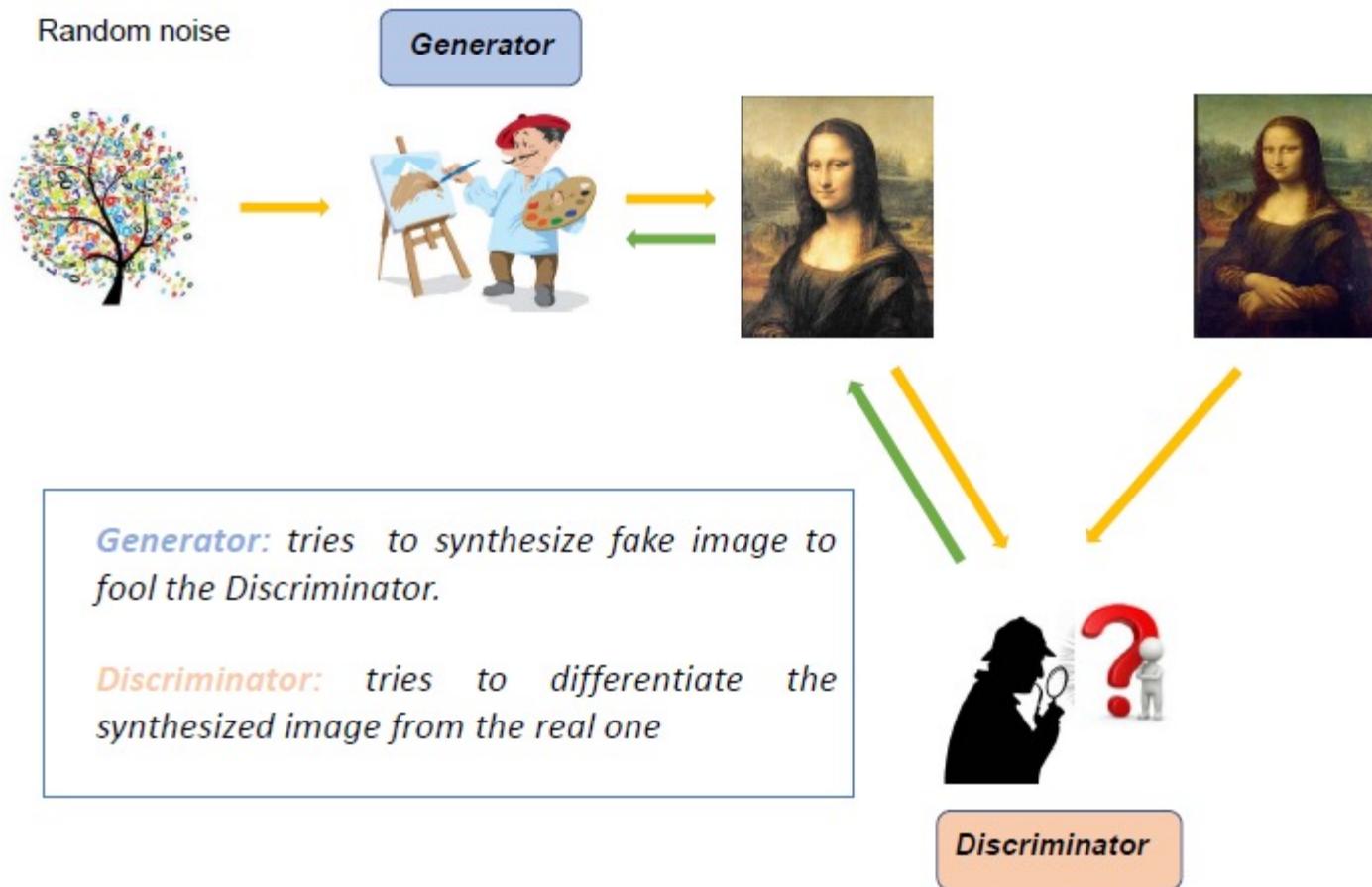
Generative Adversarial Network (GAN)



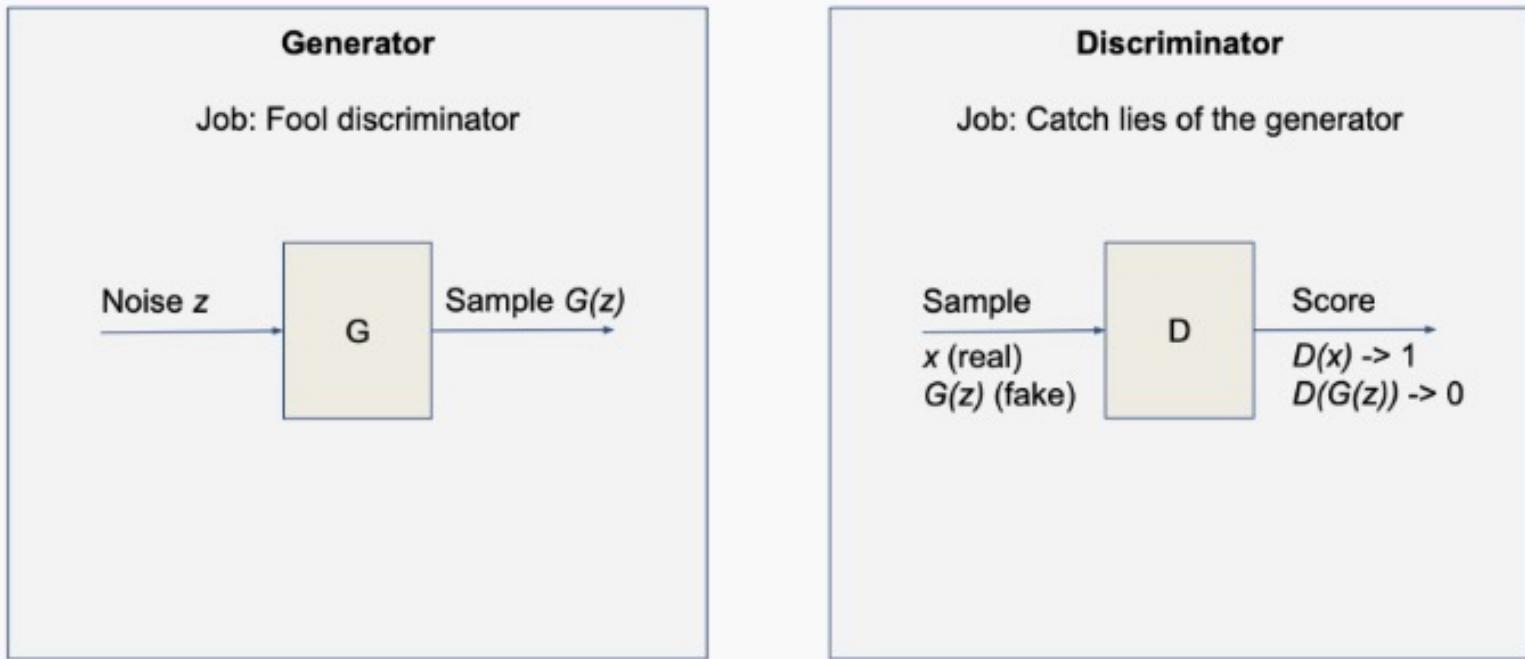
Generative Adversarial Network (GAN)



Generative Adversarial Network (GAN)



Generative Adversarial Network (GAN)



Generative Adversarial Network (GAN)

- The Discriminator is trying to maximize its reward $V(D, G)$
- The Generator is trying to minimize Discriminator's reward (or maximize its loss)

$$V(D, G) = \mathbb{E}_{x \sim p(x)} [\log D(x)] + \mathbb{E}_{z \sim q(z)} [\log(1 - D(G(z)))]$$

The overall objective of GAN is:

$$\min_G \max_D V(D, G) = \min_G \max_D \mathbb{E}_{x \sim p(x)} [\log D(x)] + \mathbb{E}_{z \sim q(z)} [\log(1 - D(G(z)))]$$

Generative Adversarial Network (GAN)

Conditional GAN:

GANs could be extended to conditional model if both the generator and the discriminator are conditioned on extra information \mathbf{y}

$$\min_G \max_D V(D, G) = \min_G \max_D \mathbb{E}_{x \sim p(x)} [\log D(x|\mathbf{y})] + \mathbb{E}_{z \sim q(z)} [\log(1 - D(G(z|\mathbf{y})))]$$

Generative Adversarial Network (GAN)

Pix2Pix GAN:

Translation between image pairs:

The input image x and the target image y has one-to-one correspondence

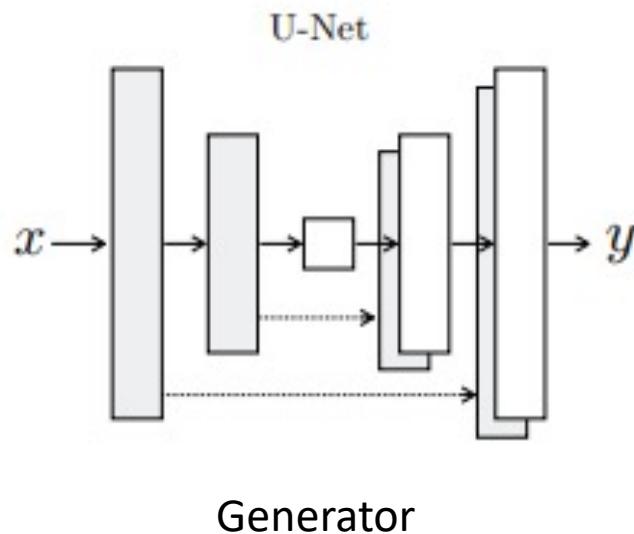


Generative Adversarial Network (GAN)

Generator loss:

$$\mathcal{L}_{cGAN}^G = \mathbb{E}_{\mathbf{x} \sim P_{data}(\mathbf{x})} [\log (1 - D(\mathbf{x}, G(\mathbf{x}))) + \lambda_{l1} \mathbb{E}_{\mathbf{x}, \mathbf{y} \sim P_{data}(\mathbf{x}, \mathbf{y})} [\|\mathbf{y} - G(\mathbf{x})\|_1]]$$

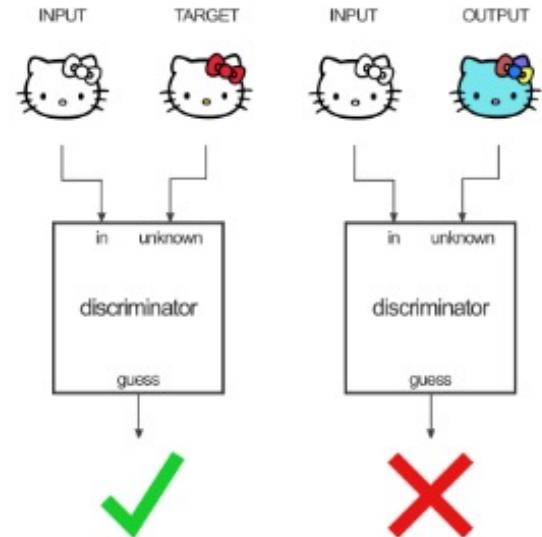
intensity loss



Generative Adversarial Network (GAN)

Discriminator loss:

$$\begin{aligned}\mathcal{L}_{cGAN}^D = & -\mathbb{E}_{\mathbf{x}, \mathbf{y} \sim P_{data}(\mathbf{x}, \mathbf{y})} [\log D(\mathbf{x}, \mathbf{y})] \\ & - \mathbb{E}_{\mathbf{x} \sim P_{data}(\mathbf{x})} [\log (1 - D(\mathbf{x}, G(\mathbf{x})))].\end{aligned}$$



Overall loss:

$$\mathcal{L}_{cGAN} = \mathcal{L}_{cGAN}^G + \mathcal{L}_{cGAN}^D$$

Generative Adversarial Network (GAN)

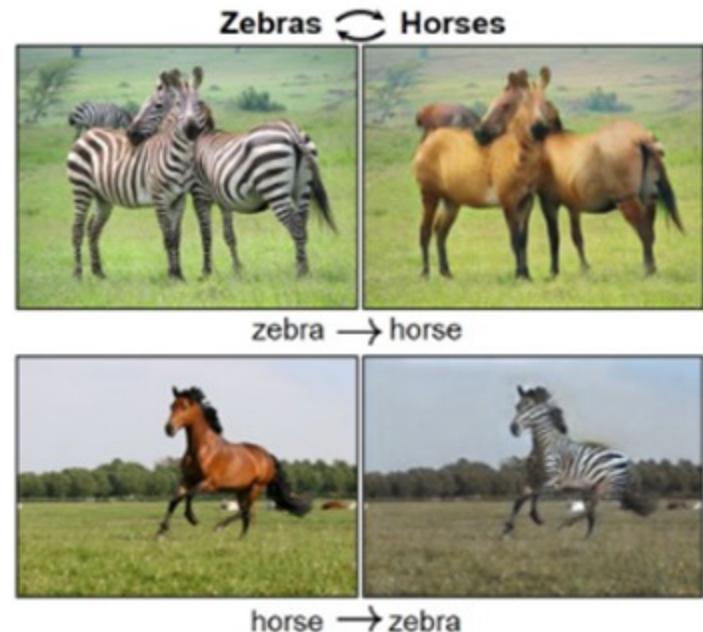
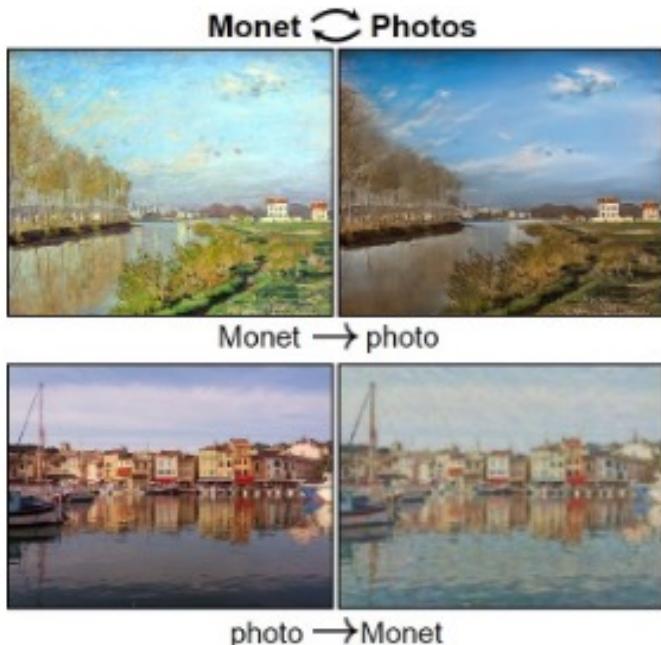


Generative Adversarial Network (GAN)

CycleGAN:

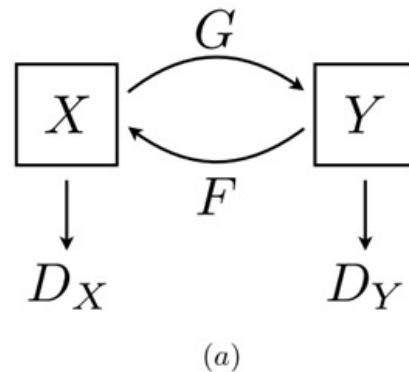
Translation between **unpaired** images:

The input image x and the target image y do **not** have correspondence

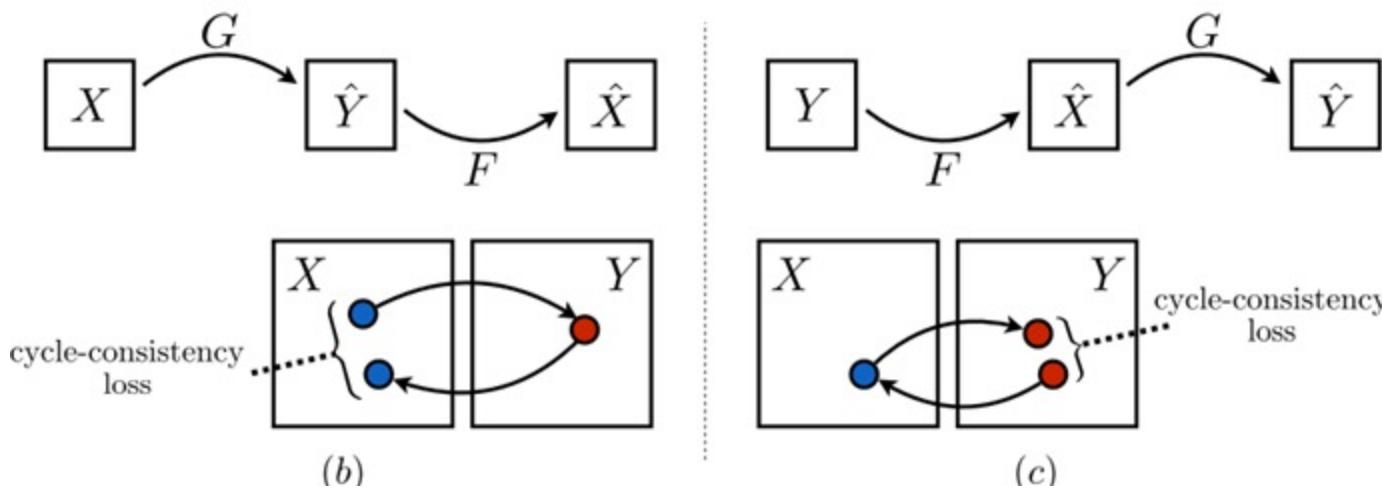


Generative Adversarial Network (GAN)

CycleGAN:



(a)



Jun-Yan Zhu*, Taesung Park*, Phillip Isola, Alexei A. Efros. Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks, ICCV2017

Generative Adversarial Network (GAN)

CycleGAN:

- Two generators,

G learns the mapping $X \rightarrow Y$

F learns the mapping $Y \rightarrow X$

- Two discriminators

D_X differentiates $\hat{x} = F(G(x))$ from x

D_Y differentiates $\hat{y} = G(F(y))$ from y

Generative Adversarial Network (GAN)

CycleGAN

Loss function:

$$\mathcal{L}(G, F, D_X, D_Y) = \mathcal{L}_{GAN}^{G, D_Y, X, Y} + \mathcal{L}_{GAN}^{G, D_X, Y, X} + \lambda \mathcal{L}_{cycle}^{G, F}$$

The diagram illustrates the components of the CycleGAN loss function. The total loss is the sum of three terms: two GAN losses (labeled "Common GAN loss") and one cycle consistency loss (labeled "Cycle consistency"). The cycle consistency term is highlighted with a red box.

Cycle consistency term:

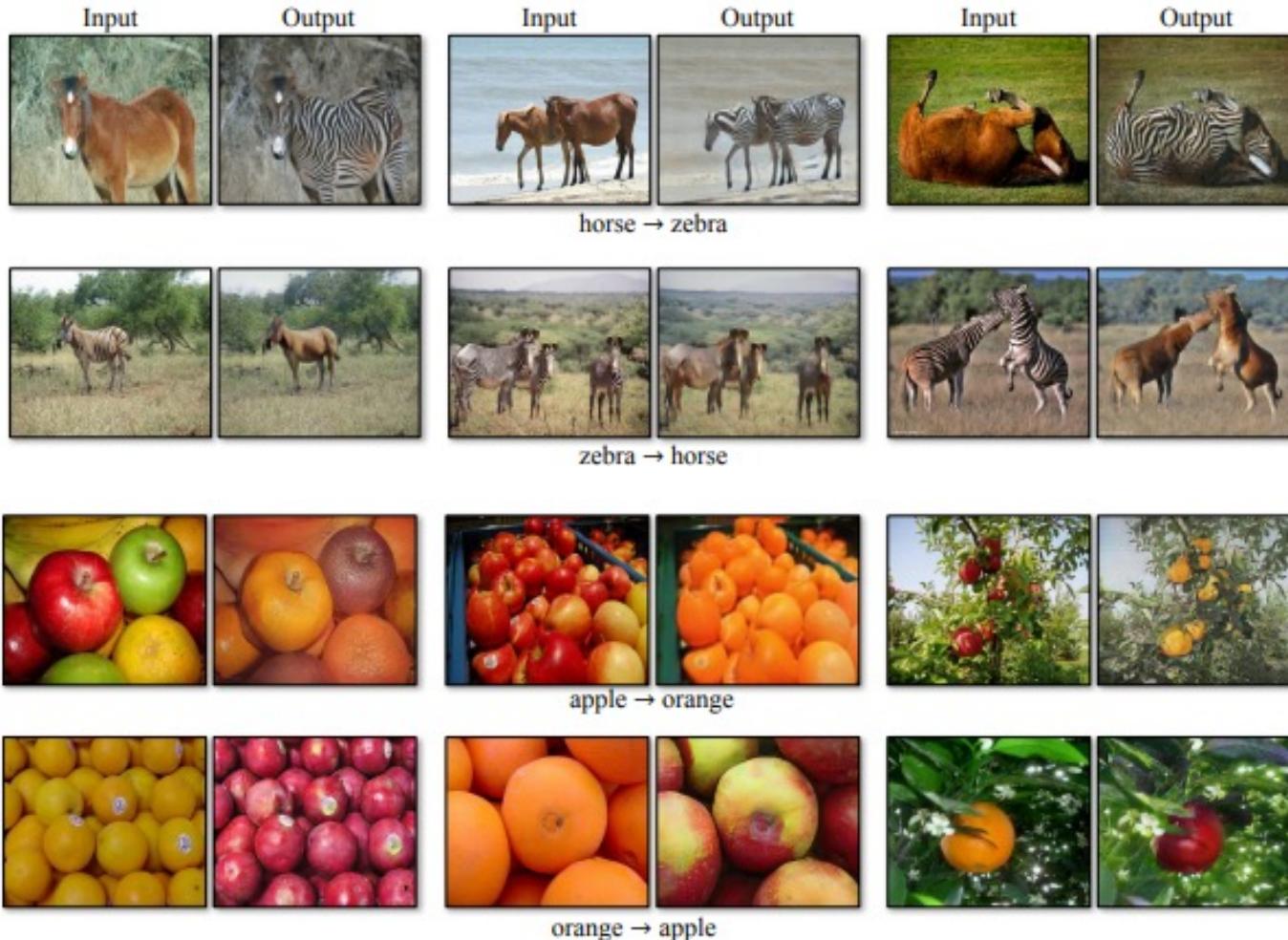
$$\mathcal{L}_{cycle}^{G, F} = \mathbb{E}_{\mathbf{x} \sim P_{data}(\mathbf{x})} [\|F(G(\mathbf{x})) - \mathbf{x}\|_1] + \mathbb{E}_{\mathbf{y} \sim P_{data}(\mathbf{y})} [\|G(F(\mathbf{y})) - \mathbf{y}\|_1]$$

Generative Adversarial Network (GAN)



Jun-Yan Zhu*, Taesung Park*, Phillip Isola, Alexei A. Efros. Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks, ICCV2017

Generative Adversarial Network (GAN)

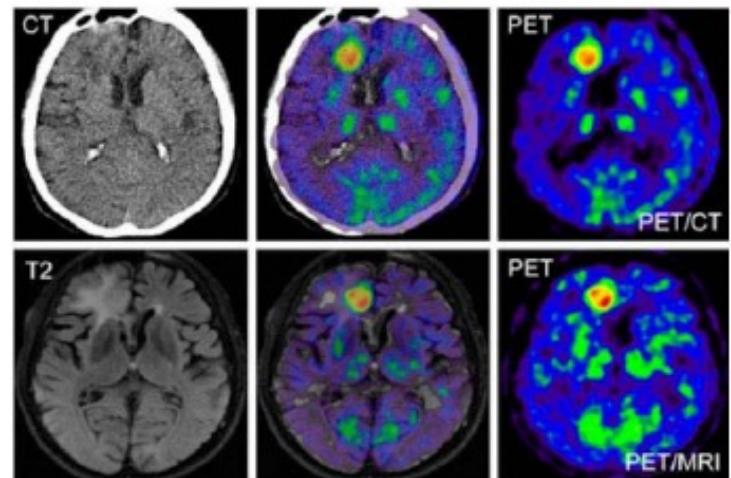


A Case Study

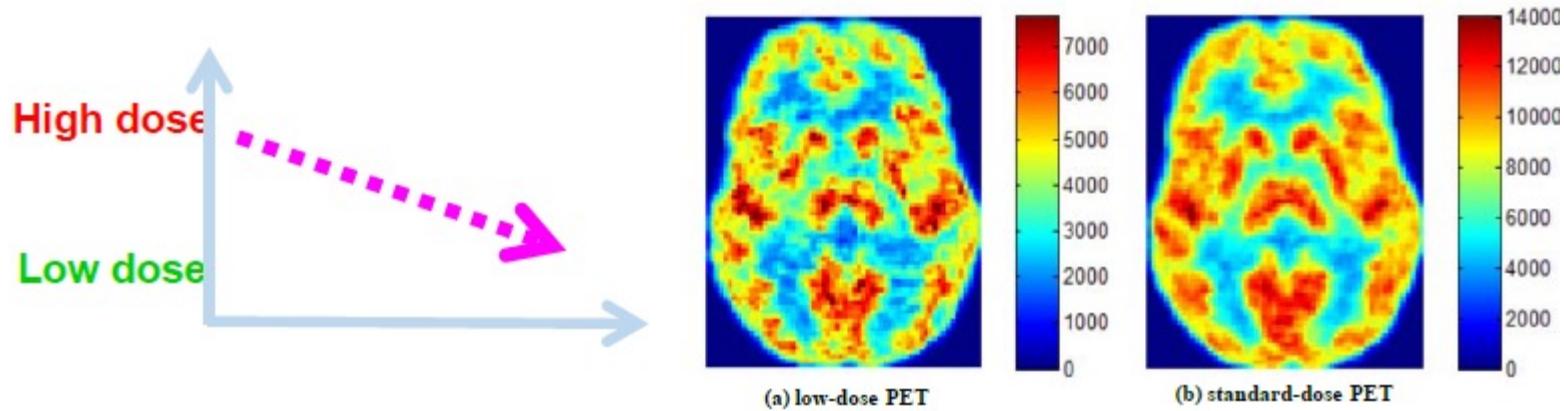
Y. Wang, B. Yu, L. Wang, C. Zu, D.S. Lalush, W. Lin, X. Wu, J. Zhou, D. Shen*, and L. Zhou*, "3D Conditional Generative Adversarial Networks for High-quality PET Image Estimation at Low Dose", Neuroimage, 2018

Estimating PET images from low dose

- Positron emission tomography (PET) can produce a 3D image of the functional processes in the body, i.e., using PET/CT.
→ Widely used in various clinical applications, such as cancer diagnosis.



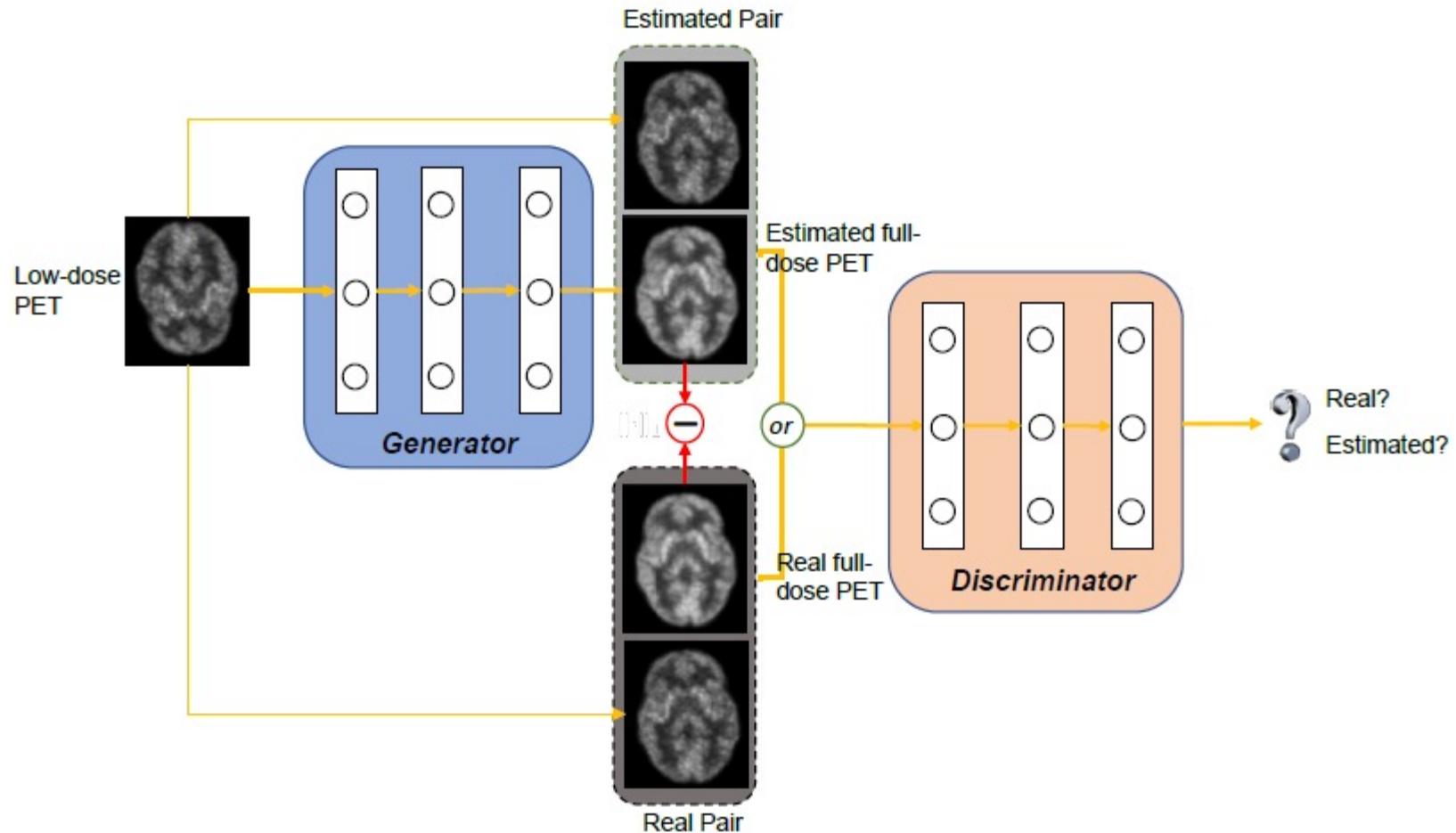
Estimating PET images from low dose



Comparison between low-dose (L-PET)
and full-dose PET (F-PET) images

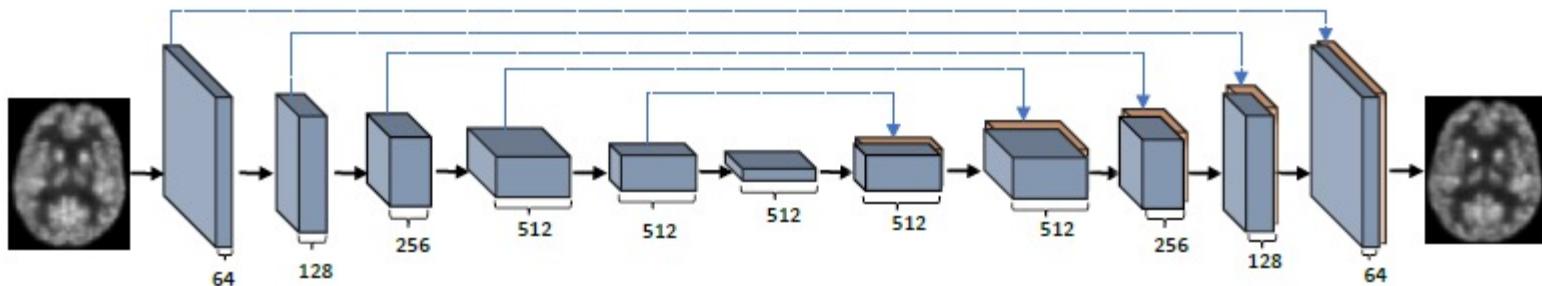
High quality PET image plays an essential role
in accurately diagnosing diseases/ disorders
and in assessing the response to therapy.

3D c-GAN based method

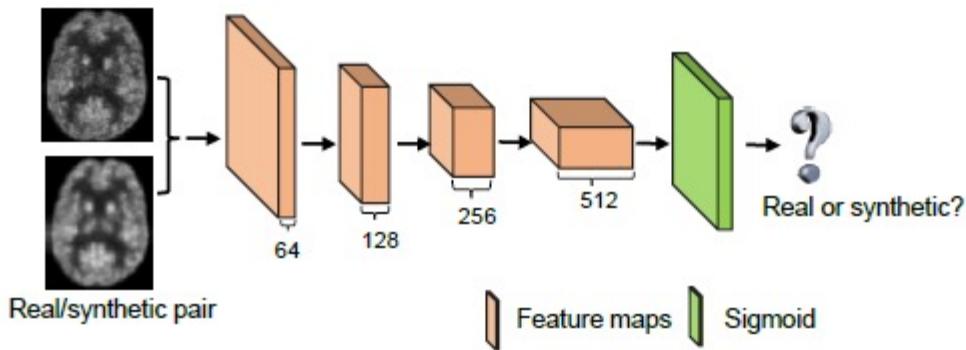


Estimating PET images from low dose

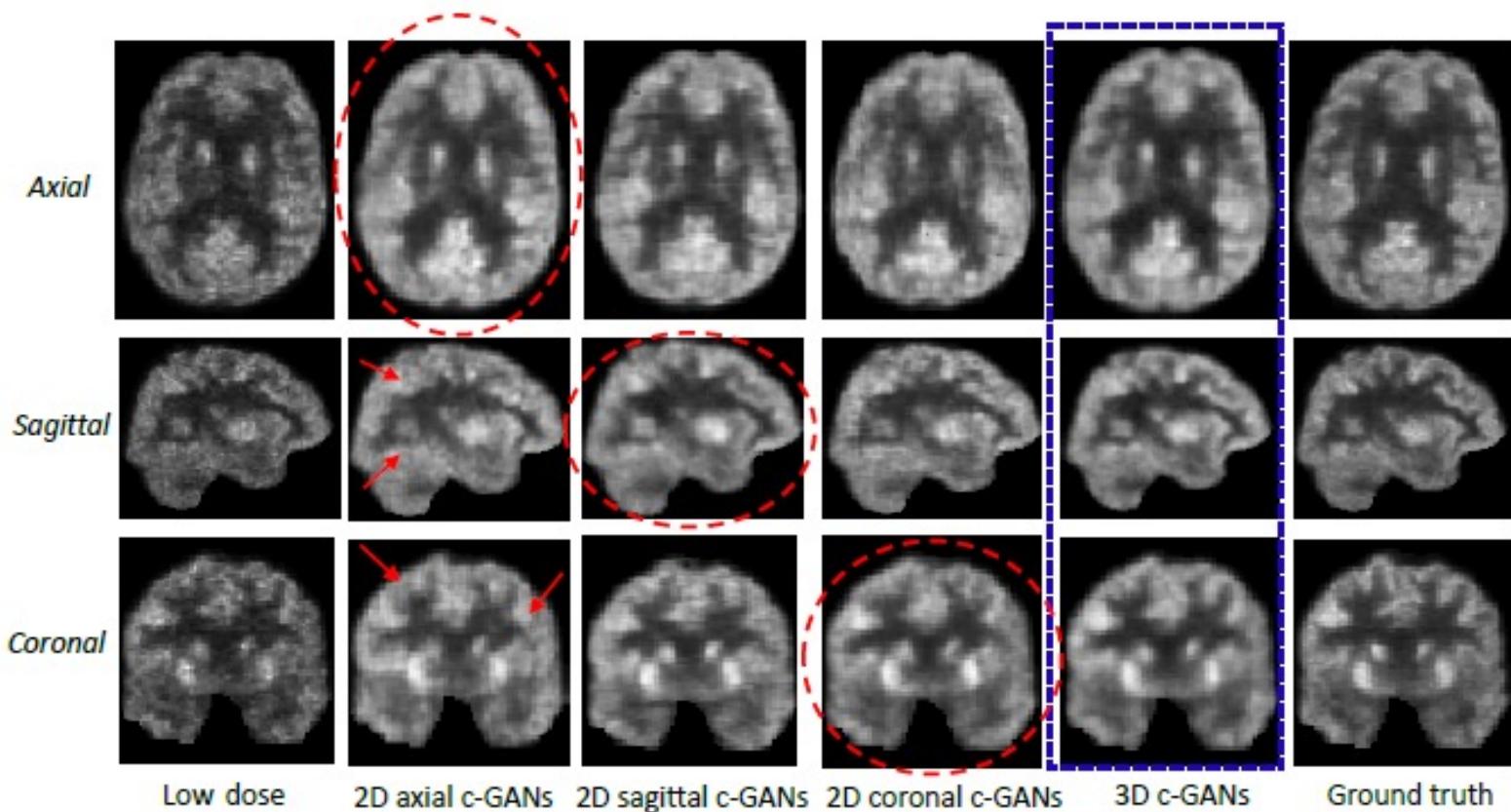
Generator:



Discriminator:



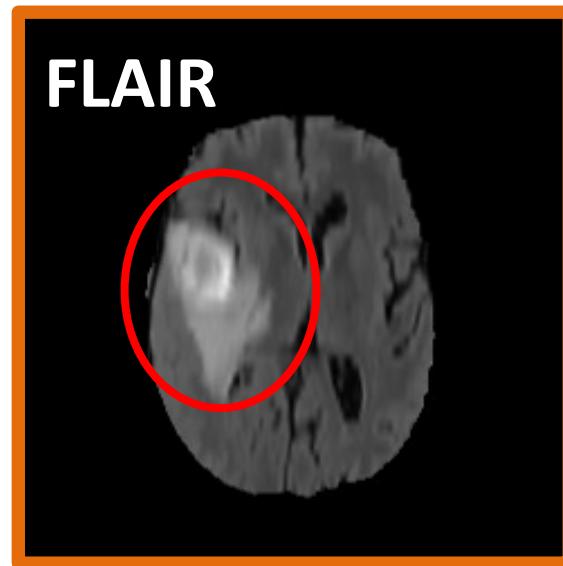
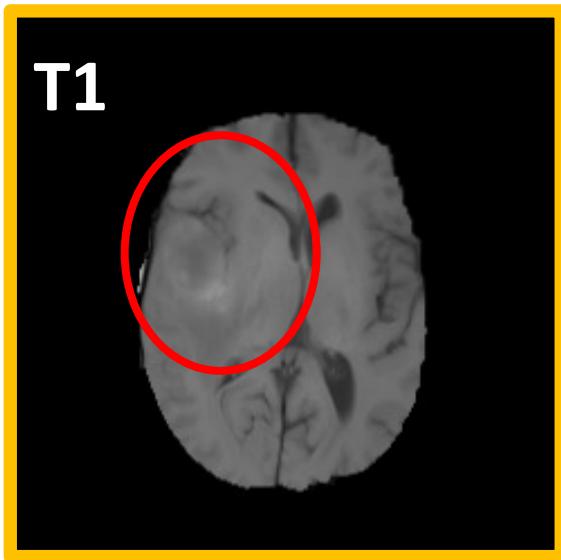
Estimating PET images from low dose



A Case Study II

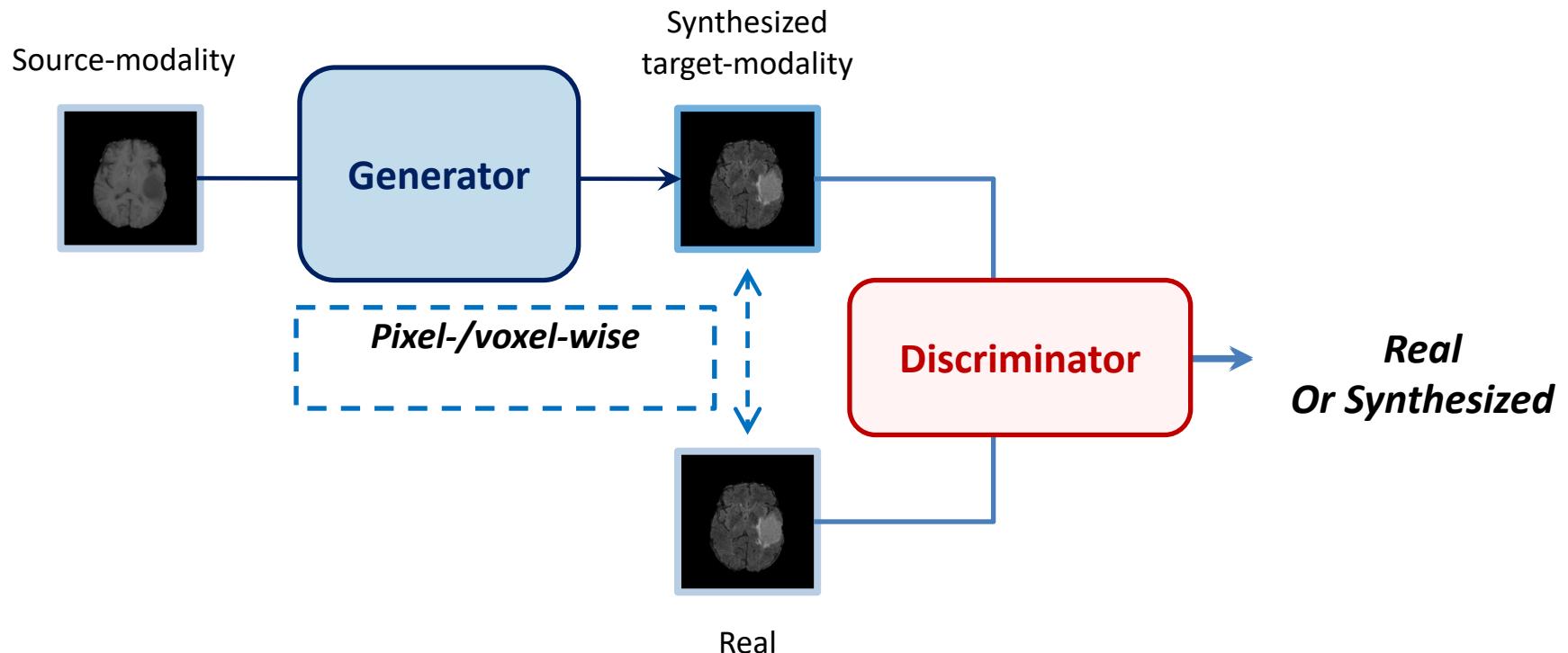
B. Yu, L. Zhou, L. Wang, Y. Shi, J. Fripp, and P. Bourgeat, “**Ea-GANs: Edge-aware Generative Adversarial Networks for Cross-modality MR Image Synthesis**”, IEEE Transactions on Medical Imaging (IEEE T-MI), 2019

Cross MR modality synthesis



Cross MR modality synthesis

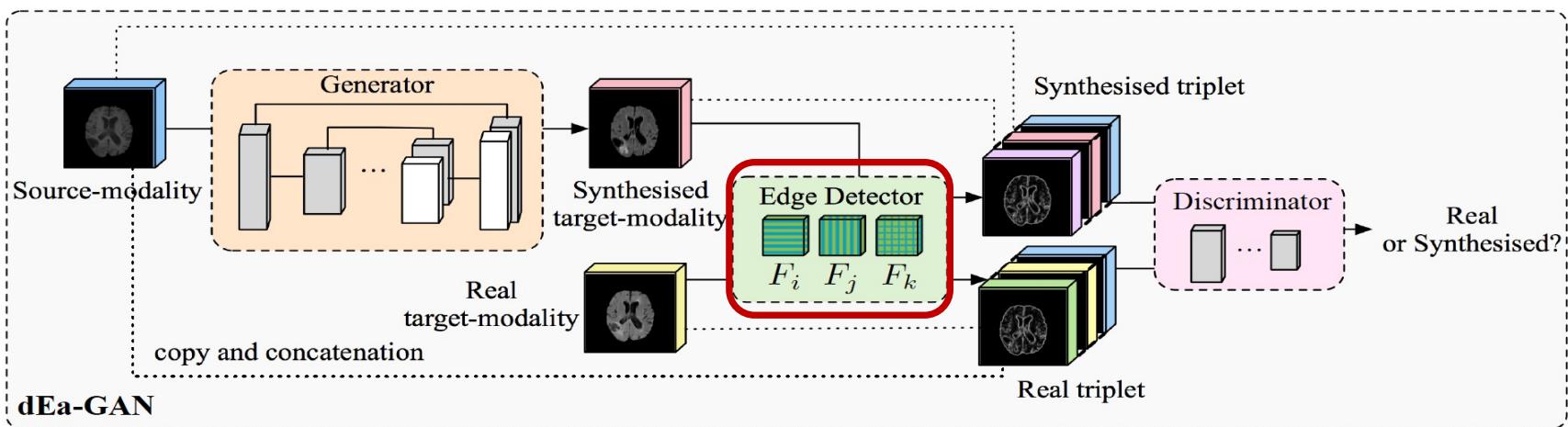
Existing Methods



Cross MR modality synthesis

- ***Discriminator-induced Ea-GAN (dEa-GAN)***

- incorporate edge information into training both the **generator** and the **discriminator**



Cross MR modality synthesis

