SLR in the Matrix Form

If you are not familiar with matrix algebra, please read KNNL Sections 5.1-5.7.

Matrix form

- Matrices and vectors will be written in **bold face** type.
- Subscripts will indicate the dimension of the matrix. For example,

$$A_{3X2} = \begin{bmatrix} 1 & 0.2 \\ 1 & 3.4 \\ 1 & 2.1 \end{bmatrix}$$

is a 3-row by 2-column matrix.

Dimension subscripts will only be used when needed for clarity.

Warm up exercise

$$\mathbf{A}_{2\times 2} = \begin{bmatrix} 2 & 5 \\ 4 & 1 \end{bmatrix} \qquad \mathbf{B}_{2\times 2} = \begin{bmatrix} 4 & 6 \\ 5 & 8 \end{bmatrix}$$

A)
$$AB = \begin{bmatrix} 8 & 30 \\ 2 & 28 \end{bmatrix}$$
 B) $AB = \begin{bmatrix} 38 \\ 28 \end{bmatrix}$

C)
$$AB = \begin{bmatrix} 38 \\ 28 \end{bmatrix}$$
 D) $AB = \begin{bmatrix} 33 & 52 \\ 21 & 32 \end{bmatrix}$

Warm up exercise

$$Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ \vdots \\ y_i \end{bmatrix}$$

$$Y'Y = \sum y_i^2$$

$$Y'\begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{bmatrix} Y = (\Sigma y_i)^2$$

SST =
$$\Sigma y_i^2 - (\Sigma y_i)^2 = Y'Y - Y' \begin{bmatrix} 1...1 \\ 1...1 \end{bmatrix} Y$$

The SLR Model in Scalar Form

$$Y_i = \beta_0 + \beta_1 X_i + \varepsilon_i$$
 where $\varepsilon_i \stackrel{\text{iid}}{\sim} N(0, \sigma^2)$

Consider now writing an equation for each observation:

$$Y_{1} = \beta_{0} + \beta_{1}X_{1} + \varepsilon_{1}$$

$$Y_{2} = \beta_{0} + \beta_{1}X_{2} + \varepsilon_{2}$$

$$\vdots \quad \vdots$$

$$Y_{n} = \beta_{0} + \beta_{1}X_{n} + \varepsilon_{n}$$

The SLR Model in Matrix Form

$$\begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} \beta_0 + \beta_1 X_1 \\ \beta_0 + \beta_1 X_2 \\ \vdots \\ \beta_0 + \beta_1 X_n \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

$$\begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} 1 & X_1 \\ 1 & X_2 \\ \vdots & \vdots \\ 1 & X_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

In matrix notation, the simple linear regression model is written as,

$$Y_{n\times 1} = X_{n\times 2}\beta_{2\times 1} + \varepsilon_{n\times 1}$$

Or more simply as,

- *Y* is the *response vector*
- ullet X is called the *design matrix*
- β is the parameter vector
- ε is the *error vector*

Example (Flavor deterioration). The results shown below were obtain in a small-scale experiment to study the relation between F of storage temperature (X) and number of weeks before flavor deterioration of a food product begins occur (Y).

Observation	1	2	3	4	5
Temp (X)	8	4	0	-4	-8
Week (Y)	7.8	9	10.2	11	11.7

Write the matrix notation for X and Y.

$$Y = X \beta + \varepsilon$$

```
week<-c(7.8,9,10.2,11,11.7)
week
```

```
y<-as.matrix(week)
colnames(y)<-c("week")
y</pre>
```

```
temp<-c(8,4,0,-4,-8)
Intercept<-rep(1,5)
x<-cbind(Intercept,temp)
x</pre>
```

```
[1] 7.8 9.0 10.2 11.0 11.7
```

	week
[1,]	7.8
[2,]	9.0
[3,]	10.2
[4,]	11.0
[5,]	11.7

	Intercept	temp
[1,]	1	8
[2,]	1	4
[3,]	1	0
[4,]	1	-4
[5,]	1	-8

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Observation	1	2	3	4	5
Temp (X)	8	4	0	-4	-8
Week (Y)	7.8	9	10.2	11	11.7

Use the matrix notation to compute SST.

$$J \leftarrow matrix(1,nrow=5,ncol=5)$$

 $SST \leftarrow t(y)\%\%y - (1/5)\%t(y)\%\%J\%\%y$

Introducing the Variance-Covariance Matrix for a random multivariable, U

•
$$U = \begin{bmatrix} U_1 \\ U_2 \\ U_3 \\ \dots \\ U_n \end{bmatrix}$$
 is a multivariate. The mean, $\mathbf{E}\{U\} = \begin{bmatrix} E(U_1) \\ E(U_2) \\ E(U_3) \\ \dots \\ E(U_n) \end{bmatrix}$

• The variance,

$$Var(U_i) = \sigma^2(U_i) = E\left[\left(U_i - E(U_i)\right)\left(U_i - E(U_i)\right)'\right] = E\left(U_i^2\right) - [E(U_i)]^2$$

• The covariance of two random multivariate, U and V, describes the linear relationship between U and V

$$Cov(U_i, U_j) = \sigma(U_i, U_j) = E[(U_i - E(U_i))(U_j - E(U_j))] = E(U_i U_j) - E(U_i)E(U_j)$$

• The variance-Covariance Matrix is a n-by-n matrix consisting both variance and covariance in the multivariate.

$$\Sigma\{\boldsymbol{U}\}_{nXn} = \begin{bmatrix} Var(U_i), Cov(U_i, U_j) \\ Cov(U_j, U_i), Var(U_j) \end{bmatrix}$$

Features on Normal Variable

- Usually, independent variables are always uncorrelated, but uncorrelated variables are not necessarily independent. That is, correlation only measures dependence in the linear dimension.
- Except when the variables follow Normal distribution, in which case correlation and dependence are the same.
- If variables are (completely) uncorrelated, their covariance is 0.
- The variance-covariance matrix of uncorrelated variables will therefore be a diagonal matrix, since all the covariances are 0.

$$\Sigma\{\boldsymbol{U}\}_{nXn} = \begin{bmatrix} Var(U_i), 0\\ 0, Var(U_j) \end{bmatrix}$$

More General Notations

Let $U \sim N$ (E(U), $\Sigma(U)$) be a multivariate normal vector, and let V = c + D U be a linear transformation of U where c is a vector of constants and D is a matrix of constants.

Then $V \sim N(c + D \mu, D \Sigma D^t)$.

The Variance-Covariance Matrix for the Random Error, $\Sigma\{\varepsilon\}$

$$\begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \dots \\ \epsilon_n \end{bmatrix} \sim \text{Normal} \begin{bmatrix} 0 \\ 0 \\ 0 \\ \dots \\ 0 \end{bmatrix}, \begin{bmatrix} \sigma^2 \ 0 \ 0 \ \dots 0 \\ 0 \ \sigma^2 \ 0 \ \dots 0 \\ 0 \ 0 \ \sigma^2 \ \dots 0 \\ \dots \\ 0 \ 0 \ 0 \ \dots \sigma^2 \end{bmatrix} \qquad \qquad \\ \Sigma \{\epsilon\}_{nXn} = \begin{bmatrix} \sigma^2 \ 0 \ 0 \ \dots 0 \\ 0 \ \sigma^2 \ 0 \ \dots 0 \\ 0 \ 0 \ \sigma^2 \ \dots 0 \\ \dots \\ 0 \ 0 \ 0 \ \dots \sigma^2 \end{bmatrix} = \quad \\ \sigma^2 I_{nXn} \qquad \qquad \\ \bullet \text{ have a mean of 0, and} \\ \bullet \text{ a constant variance}$$

$$\Sigma\{\epsilon\}_{nXn} = \begin{bmatrix} \sigma^2 & 0 & 0 & \dots & 0 \\ 0 & \sigma^2 & 0 & \dots & 0 \\ 0 & 0 & \sigma^2 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & \sigma^2 \end{bmatrix} = \sigma^2 I_{nXn}$$

This is true when the random errors are

$$\begin{bmatrix} Y_1 \\ Y_2 \\ Y_3 \\ \dots \\ Y_n \end{bmatrix} \sim \text{Normal} \begin{bmatrix} X_1 \beta \\ X_2 \beta \\ X_3 \beta \\ \dots \\ X_n \beta \end{bmatrix}, \begin{bmatrix} \sigma^2 \ 0 \ 0 \ \dots 0 \\ 0 \ \sigma^2 \ 0 \dots 0 \\ 0 \ 0 \ \sigma^2 \dots 0 \\ \dots \\ 0 \ 0 \ 0 \dots \sigma^2 \end{bmatrix}$$

$$\Sigma \{Y\}_{nXn} = \Sigma \{\epsilon\}_{nXn}$$

$$\Sigma\{Y\}_{nXn} = \Sigma\{\epsilon\}_{nXn}$$

- $Y = X\beta + \varepsilon = X\beta + I\varepsilon$, and
- No assumption violation

Least Squares Parameter Estimation

We want to minimize the sum of residuals.

To find the solution, set the derivative with respect to the vector β equal to a zero vector and

solve:

$$\frac{d}{d\beta} (\varepsilon^t \varepsilon) = \frac{d}{d\beta} ((Y - X \beta)^t (Y - X \beta))$$
$$= -2X^t (Y - X \beta)$$

(Partially) Solving for $m{\beta}$ yields the so-called *Normal Equations* :

$$-2X^{t}(Y - X\beta) = \mathbf{0}$$
$$X^{t}Y = X^{t}X\beta$$

$$\widehat{\boldsymbol{\beta}} = (\boldsymbol{X}^{t}\boldsymbol{X})^{-1}(\boldsymbol{X}^{t}\boldsymbol{Y}) = \begin{bmatrix} b_{0} \\ b_{1} \end{bmatrix} = \begin{bmatrix} (\overline{\boldsymbol{Y}}) - \frac{(\overline{\boldsymbol{X}})SS_{XY}}{SS_{X}} \\ \frac{SS_{XY}}{SS_{X}} \end{bmatrix}$$

The details
$$\beta = (X^t X)^{-1} (X^t Y) = \begin{bmatrix} D_0 \\ D_1 \end{bmatrix}$$

$$X^{t}X = \begin{bmatrix} 1 & 1 & \dots & 1 \\ X_1 & X_2 & \dots & X_n \end{bmatrix} \begin{bmatrix} 1 & X_1 \\ 1 & X_2 \\ \vdots & \vdots \\ 1 & X_n \end{bmatrix} = \begin{bmatrix} n & \Sigma X_i \\ \Sigma X_i & \Sigma X_i^2 \end{bmatrix}$$

$$(X^{t}X)^{-1} = \frac{1}{n\Sigma X_{i}^{2} - (\Sigma X_{i})^{2}} \begin{bmatrix} \Sigma X_{i}^{2} & -\Sigma X_{i} \\ -\Sigma X_{i} & n \end{bmatrix} = \frac{1}{nSS_{X}} \begin{bmatrix} \Sigma X_{i}^{2} & -\Sigma X_{i} \\ -\Sigma X_{i} & n \end{bmatrix}$$

$$X^{t}Y = \begin{bmatrix} 1 & 1 & \dots & 1 \\ X_1 & X_2 & \dots & X_n \end{bmatrix} \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} \Sigma Y_i \\ \Sigma X_i Y_i \end{bmatrix}$$

Plug these into the equation for b:

$$\mathbf{b} = (X^{t}X)^{-1}(X^{t}Y)$$

$$= \frac{1}{nSS_{X}} \begin{bmatrix} \Sigma X_{i}^{2} & -\Sigma X_{i} \\ -\Sigma X_{i} & n \end{bmatrix} \begin{bmatrix} \Sigma Y_{i} \\ \Sigma X_{i}Y_{i} \end{bmatrix}$$

$$= \frac{1}{nSS_{X}} \begin{bmatrix} (\Sigma X_{i}^{2})(\Sigma Y_{i}) - (\Sigma X_{i})(\Sigma X_{i}Y_{i}) \\ -(\Sigma X_{i})(\Sigma Y_{i}) + n(\Sigma X_{i}Y_{i}) \end{bmatrix}$$

$$= \frac{1}{SS_X} \begin{bmatrix} (\Sigma X_i^2)(\overline{Y}) - (\overline{X})(\Sigma X_i Y_i) \\ -n(\overline{X})(\overline{Y}) + (\Sigma X_i Y_i) \end{bmatrix}$$

$$= \frac{1}{SS_X} \left[\frac{(\Sigma X_i^2)(\overline{Y}) - \overline{Y}(n\overline{X}^2) + \overline{X}(n\overline{X}\overline{Y}) - (\overline{X})(\Sigma X_i Y_i)}{SS_{XY}} \right]$$

$$= \frac{1}{SS_X} \begin{bmatrix} SS_X(\overline{Y}) - (\overline{X})SP_{XY} \\ SS_{XY} \end{bmatrix} = \begin{bmatrix} (\overline{Y}) - \frac{(\overline{X})SS_{XY}}{SS_X} \\ \frac{SS_{XY}}{SS_X} \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \end{bmatrix}$$
 Finally!

temp

Example (Flavor deterioration). The results shown below were obtain in a small-scale experiment to study the relation between F of storage temperature (X) and number of weeks before flavor deterioration of a food product begins occur (Y).

i	1	2	3	4	5
Xi	8	4	0	-4	-8
Yi	7.8	9	10.2	11	11.7

Compute estimators in matrix form

Intercept

$$\widehat{\boldsymbol{\beta}} = (\mathbf{X}'\mathbf{X})^{-1}(\mathbf{X}'\mathbf{Y}) = \begin{bmatrix} 9.94 \\ -0.245 \end{bmatrix}$$

The Hat Matrix

$$\hat{Y} = X b$$

$$= X (X ^t X)^{-1} X ^t Y$$

$$= H Y$$

where $H = X (X^t X)^{-1} X^t$ is called the *hat matrix* because it turns Y's into \hat{Y} 's.

The hat matrix will give us many useful diagnostic tools in MLR.

In the flavor example

$$H = \begin{bmatrix} 0.6 & 0.4 & 0.2 & 0.0 & -0.2 \\ 0.4 & 0.3 & 0.2 & 0.1 & 0.0 \\ 0.2 & 0.2 & 0.2 & 0.2 & 0.2 \\ 0.0 & 0.1 & 0.2 & 0.3 & 0.4 \\ -0.2 & 0.0 & 0.2 & 0.4 & 0.6 \end{bmatrix}$$

The matrix H is symmetric and has the special property called **idempotent**:

$$HH = H$$

Predicted value, residual, SSE, and MSE

$$\hat{\boldsymbol{Y}} = \begin{bmatrix} \hat{Y}_1 \\ \hat{Y}_2 \\ \vdots \\ \hat{Y}_n \end{bmatrix} = \begin{bmatrix} b_0 + b_1 X_1 \\ b_0 + b_1 X_2 \\ \vdots \\ b_0 + b_1 X_n \end{bmatrix} = \begin{bmatrix} 1 & X_1 \\ 1 & X_2 \\ \vdots & \vdots \\ 1 & X_n \end{bmatrix} \begin{bmatrix} b_0 \\ b_1 \end{bmatrix} = \boldsymbol{X} \boldsymbol{b}$$

$$e = Y - \widehat{Y} = (I - H)Y$$

$$SSE = e'e = \begin{bmatrix} -0.18 & 0.04 & 0.26 & 0.08 & -0.2 \end{bmatrix}$$

$$= \begin{bmatrix} -0.18 & 0.04 & 0.26 & 0.08 & -0.2 \end{bmatrix}$$

$$= \begin{bmatrix} -0.18 & 0.04 & 0.26 & 0.08 & -0.2 \end{bmatrix}$$

$$= 0.148$$

$$= 0.148$$

$$MSE = SSE/(n - p) = 0.0493$$

The Matrix Form of the coefficients

$$b = (X {}^t X)^{-1} X {}^t Y$$

And

$$Y \sim N(X \beta, \sigma^2 I)$$

Since b is a linear combination of Y, b follows Normal distribution.

$$E(b) = (X {}^{t}X)^{-1}X {}^{t}E(Y)$$

= $(X {}^{t}X)^{-1}X {}^{t}X \beta = \beta$

Therefore, \boldsymbol{b} is an unbiased estimator of $\boldsymbol{\beta}$.

The variance-covariance matrix for the coefficient

$$\Sigma_{\{b\}} = \left[(X'X)^{-1}X' \right] \sigma^2 I \left[(X'X)^{-1}X' \right]'$$

$$= \sigma^2 \left[(X'X)^{-1}X' \right] I \left[(X'X)^{-1}X' \right]'$$

$$= \sigma^2 (X'X)^{-1}(X'X) \left[(X'X)^{-1} \right]'$$

$$= \sigma^2 (X'X)^{-1}$$

- In the last step, $X \, ^t \! X$ and its inverse are both symmetric, therefore $(X \, ^t \! X)^{-1} = (X \, ^t \! X)^{-1}$
- $\sigma^2(X \ ^t X)^{-1}$ generally is **NOT** a diagonal matrix, because the estimates b_0 and b_1 are generally **not** independent of each other.
- $\Sigma\{b\}$ has a dimension of p by p, where p is the number of parameters.

Example (Flavor deterioration).

Compute the covariance matrix for \boldsymbol{b}

$$\Sigma\{b\} = \sigma^2 \quad (X^t X)^{-1} = MSE(X^t X)^{-1}$$

$$= 0.0493 \begin{pmatrix} 0.2 & 0.00000 \\ 0.0 & 0.00625 \end{pmatrix} = \begin{pmatrix} 0.009866667 \\ 0.0000000000 \\ 0.0003083333 \end{pmatrix}$$

Intercept temp

1 8

X = 1 4

1 -4

1 -8

- The diagonal elements in $\Sigma\{b\}$ are $s^2\{b_0\}$ and $s^2\{b_1\}$
- The non-diagonal elements are generally not 0 due to dependency.

week

The Matrix Form of the Mean Response at One X

To estimate the mean response at X_h , define a matrix form

$$\mathbf{X}_h = \begin{bmatrix} 1 \\ X_h \end{bmatrix}$$

$$\hat{Y}_h = \mathbf{X}_h' \mathbf{b} = \begin{bmatrix} 1 & X_h \end{bmatrix} \begin{bmatrix} b_0 \\ b_1 \end{bmatrix} = [b_0 + b_1 X_h]$$

$$\Sigma\{\widehat{Y}_h\} = X_h'\Sigma\{b\}X_h$$

Example (Flavor deterioration): find the point estimator and standard error of \hat{Y}_h when $X_h = -6$

$$\hat{Y}_h = \mathbf{X}'_h \mathbf{b} = [1, -6] \begin{bmatrix} 9.94 \\ -0.245 \end{bmatrix} = 11.41$$

$$\Sigma\{\widehat{Y}_h\} = X_h'\Sigma\{\mathbf{b}\}X_h = \begin{bmatrix} 1 & -6 \end{bmatrix} \begin{bmatrix} 0.00986 & 0 \\ 0 & 0.00031 \end{bmatrix} \begin{bmatrix} 1 \\ -6 \end{bmatrix}$$
$$= 0.021$$
$$= s^2 \{\widehat{Y}_h\}$$

- The variance covariance matrix of the mean response has a dimension of 1 by 1, and reduces to $s^2\{\widehat{Y}_h\}$
- Note that the X_h matrix differs from the design matrix!

The Matrix Form of the Mean Response at Multiple Xs

To estimate the mean response at m multiple points, define a 2 by m matrix form for X_h

Example (Flavor deterioration): find the point estimator and standard error of \widehat{Y}_h when X = -6 and -5

$$X_h = \begin{bmatrix} 1 & 1 \\ -6 & -5 \end{bmatrix} \qquad \hat{Y}_h = \mathbf{X}_h' \mathbf{b} = \begin{bmatrix} 1 & -6 \\ 1 & -5 \end{bmatrix} \begin{bmatrix} 9.94 \\ -0.245 \end{bmatrix} = \begin{bmatrix} 11.41 \\ 11.17 \end{bmatrix}$$

$$\Sigma\{\widehat{Y}_h\} = X_h'\Sigma\{\mathbf{b}\}X_h = \begin{bmatrix} 1 & -6 \\ 1 & -5 \end{bmatrix} \begin{bmatrix} 0.00986 & 0 \\ 0 & 0.00031 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -6 & -5 \end{bmatrix} = \begin{bmatrix} 0.021 & * \\ * & 0.018 \end{bmatrix}$$

- The diagonal values, $s^2\{\hat{Y}_h\}$ = 0.021 and 0.018 for the X=-6 and -5, respectively.
 - Use the $s^2\{\widehat{Y}_h\}$ to compute the confidence interval for the mean response: $\widehat{Y}_h \pm ts\{\widehat{Y}_h\}$
 - Use the $s^2\{\widehat{Y}_h\}$ to compute the variance (and the CI) for the single response: $s^2\{pred\} = s^2 + s^2\{\widehat{Y}_h\}$
- The off-diagonal values, or the "*" part is not applicable under the assumption of independence.
- $\Sigma\{\hat{Y}_h\}$ has a dimension of m by m, where m is the number of X levels to predict.