Doncy 1 Check if they updated the firmware Marco Accame will provide assistance (in vacation Mon-Tue) 2) Codote Firmware - a github, corn/robotology/RA/issues/240: How to update your robot to use 1.8.0 guide to migrate to latest ilub release (applies to CAN and CTH robots) (2.1) On server computer: pull repositories [1- your /master and compile 12- icub-main /master On icub-head/pclo4: pull garp, icub-main, icub-firmware shaped, -build, robots-configuration 2-compile youp 3-compile Part Firmurae shared: cd build-peloy 5- Install robot-configuration files + instructions at ... dogy/robot conf 6- Firmware update of ETH/CAN boards & instructions icub firmware build/ Firmwardpolator, readme, guick fxt Firmware update uses Firmware updater (From icub-main master) Power on motors tirmware Updater GUI Find firmware update ini (should be installed with robots-configuration) Select ETH agrice. Click discover to find available boards Select an EUS board Can view (on side) board properties (running/idle etc).
Click DI to select all boards of the same type click Force ETH maintenance? Select all boards in maintenance, ich himwore build click Upload application -> load the ems. hex file (in rotal configuration?)
Select board a check in Board Properties panel if correct Firmware version e. Scover Select all bounds of type \$1 click force ETH application (send them in application state = re-start application equivalent of power off. power on motors) Done Quit. 4 approbation terface 3 Use Firmware Updater For debugging a board which is not regarding with a. Search board. See if it finds it

b. Ding board -> if it replies -> is yarprobotinterface enashed?

(not found) does not reply -> is a cable loose? not well connected? Click restant board (in magic state W/ more buttons). Firmward polater check conside & debug into an silence time, timeout, etc. - admin ob (Note: robot config does not install firm an expedite in (check amake life)