Do Gyoon Lee

Machine Learning Engineer, Computer Vision Expert 108-1804, 140, Geumho-ro, Seongdong-gu, Seoul, Korea / (+82) 1048996866

Email: dogyoonlee@gmail.com / Website: https://dogyoonlee.github.io / Github: https://github.com/dogyoonlee

RESEARCH INTERESTS

Computer Vision & Graphics

Neural Rendering, 3D from Images, 3D Reconstruction Generative Model, Image & Video Enhancement

Machine Learning & Deep Learning

Data Augmentation & Regularization Self-supervised Learning, Unsupervised Learning

EDUCATION

Yonsei University | College of Engineering

Ph.D Candidate in Electrical Electronics Engineering

Advisor: Prof. Sangyoun Lee

Yonsei University | College of Engineering

BE in Electrical Electronics Engineering

Seoul, Korea

Mar.2012-Feb.2019 (Including Military Service: May. 2014 – Feb. 2016)

Seoul, Korea

Mar. 2019 - Aug. 2024

Sep. 2024 – Present

WORK EXPERIENCE

Samsung Research

Staff Engineer

Yonsei University Mar. 2019 – Aug. 2024

Image and Video Pattern Recognition Lab Graduate Student Research Assistance

PUBLICATIONS

2024

ProDepth: Boosting Self-Supervised Multi-Frame Monocular Depth with Probabilistic Fusion

Sungmin Woo*, Wonjoon Lee*, WooJin Kim, **Dogyoon Lee**, Sangyoun Lee European Conference on Computer Vision (ECCV), 2024

Dual Prototype Attention for Unsupervised Video Object Segmentation

Suhwan Cho, Minhyeok Lee, Seunghoon Lee, **Dogyoon Lee**, Sangyoun Lee *IEEE/CVF Computer Vision and Pattern Recognition* (CVPR), 2024

Guided Slot Attention for Unsupervised Video Object Segmentation

Minhyeok Lee, Suhwan Cho, **Dogyoon Lee**, Chaewon Park, Jungho Lee, Sangyoun Lee *IEEE/CVF Computer Vision and Pattern Recognition (CVPR)*, 2024

2023

DP-NeRF: Deblurred Neural Radiance Field with Physical Scene Priors

Dogyoon Lee, Minhyeok Lee, Chajin Shin, Sangyoun Lee

IEEE/CVF Computer Vision and Pattern Recognition (CVPR), 2023

Hierarchically Decomposed Graph Convolutional Networks for Skeleton-Based Action Recognition

Jungho Lee, Minhyeok Lee, Dogyoon Lee, Sangyoun Lee

IEEE/CVF International Conference on Computer Vision (ICCV), 2023

TSANet: Temporal and Scale Alignment for Unsupervised Video Object Segmentation

Seunghoon Lee, Suhwan Cho, Dogyoon Lee, Minhyeok Lee, Sangyoun Lee

IEEE International Conference on Image Processing (ICIP), 2023

Multidimensional Feature Representation for Point Cloud Analysis

Sungmin Woo, Dogyoon Lee, Sangwon Hwang, Sangyoun Lee

Pattern Recognition, 2023

2022

Expanded Adaptive Scaling Normalization for End-to-End Image Compression

Chajin Shin, Hyeongmin Lee, Hanbin Son, Sangjin Lee, Dogyoon Lee, Sangyoun Lee

European Conference on Computer Vision (ECCV), 2022

Robust Lane Detection via Expanded Self attention

Minhyeok Lee, Junhyeop Lee, Dogyoon Lee, Woojin Kim, Sangwon Hwang, Sangyoun Lee

IEEE/CVF Winter Conference on Applications of Computer Vision (WACV), 2022

2021

Regularization Strategy for Point Cloud via Rigidly Mixed Sample

Dogyoon Lee, Jacha Lee, Junhyeop Lee, Hyeongmin Lee, Minhyeok Lee, Sungmin Woo, Sangyoun Lee *IEEE/CVF Computer Vision and Pattern Recognition (CVPR)*, 2021

3D Mesh Transformation Preprocessing System in the Real Space for Augmented Reality Services

Young-Suk Yoon, Sangwon Hwang, **Dogyoon Lee**, Sangyoun Lee, Jae-Won Suh, Sung-Uk Jung *ICT Express*, 2021

2020

False Positive Removal For 3D Vehicle Detection with Penetrated Point Classifier

Sungmin Woo, Sangwon Hwang, Woojin Kim, Junhyeop Lee, Dogyoon Lee, Sangyoun Lee *IEEE International Conference on Image Processing (ICIP)*, 2020

PENDING

Synchronizing Vision and Language: Bidirectional Token-Masking AutoEncoder for Referring Image Segmentation

Minhyeok Lee, **Dogyoon Lee**, Jungho Lee, Suhwan Cho, Heeseung Choi, Ig-jae Kim, Sangyoun Lee *Arxiv Preprint*, *Under Review 2024*

SMURF: Continuous Dynamics for Motion-Deblurring Radiance Fields

Jungho Lee, **Dogyoon Lee**, Minhyeok Lee, Donghyeong Kim, Sangyoun Lee *Arxiv Preprint*, *Under Review 2024*

CRiM-GS: Continuous Rigid Motion-Aware Gaussian Splatting from Motion Blur Images

Jungho Lee, Donghyeong Kim, **Dogyoon Lee**, Suhwan Cho, Sangyoun Lee

Under Review 2024

Sparse-DeRF: Deblurred Neural Radiance Fields from Sparse View

Dogyoon Lee, Donghyeong Kim, Jungho Lee, Minhyeok Lee, Seunghoon Lee, Sangyoun Lee

Under Review, 2024

PROJECT EXPERIENCE

Robust Large-Scale 3D Scene Reconstruction based on Neural Rendering with Noisy Data	May.2024-Present
Yonsei University National Research Foundation of Korea (NRF)	Korea
Project Manager / Researcher	

Real-Time Novel View Synthesis for Dynamic Scene from Sparse View via Active Learning Yonsei University | Electronics and Telecommunications Research Institute (ETRI) Korea Project Manager / Researcher

Auto Labeling Unlabeled Real Point Cloud Data via Semi-supervised Point Cloud Classification	Apr.2021-Apr.2022
Yonsei University Hyundai Motors	Korea
Project Manager / Researcher	

3D Recognition System for Autonomous Driving with Single- and Sparse Multi-LiDAR	Mar.2020-Dec.2021
Yonsei University Mando Halla Company	Korea

Project Manager / Researcher

Surface Reconstruction of Actual 3D Space from RGB Images for Augmented Reality Yonsei University | Electronics and Telecommunications Research Institute (ETRI) Korea

Researcher

Natural Dense 3D Map Generation from Multi Sensors for Smart Vehicle System. July.2019-Dec.2021

Yonsei University | Institute of Information & Communications Technology Planning & Evaluation (IITP) Korea Research Assistant

PROFESSIONAL SERVICES

Journal / Conference Reviewer	
IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)	2022, 2023, 2024
IEEE/CVF International Conference on Computer Vision (ICCV)	2023
European Conference on Computer Vision (ECCV)	2022, 2024
AAAI conference on Artificial Intelligence (AAAI)	2025
IEEE/CVF Winter Conference on Applications of Computer Vision (WACV)	2023, 2024
IEEE Transactions on Circuits and Systems for Video Technology (TCSVT)	2023
International Conference on 3D Vision (3DV)	2022

PATENTS

Apparatus for Data Augmentation and Training Strategy on Point Cloud	Feb, 2024
10-2637318	Patent Registration Korea

Apparatus and Method for Depth Inpainting method on LiDAR Point Cloud
10-2433632.

Aug, 2022
Patent Registration, Korea

Apparatus and Method for Moving Object Detection using Background Modeling based on Inpainting Nov, 2021 10-2021-0165052 Patent Application, Korea

Apparatus and Method for Correcting Errors of Detected Objects based on Point Cloud.

Oct, 2021
Patent Registration, Korea

LANGUAGE

Korean(Native), English(Proficient)

SKILLS

Programming Language / Deep Learning Framework

Python, C, C++, MATLAB / PyTorch, TensorFlow, Jax