



Circuit Diagram

Input 1 – Port 0.0

Input 2 – Port 0.1

Enable 1 – Directly giving 5v

Working Algorithm

Forward

EN Pin High (En1 = 1 or En2 = 1)

Input 1 or Input 3 Pin High (In1 = 1 or In3=1)

Input 2 or Input 4 Pin Low (In2 = 0 or In4 = 0)

Reverse

EN Pin High (En1 = 1 or En2 = 1)

Input 1 or Input 3 Pin Low (In1 = 0 or In3=0)

Input 2 or Input 4 Pin Low (In2 = 1 or In4 = 1)

```

#include<lpc214x.h>

#define bit(x) (1<<x)

#define delay for(i=0;i<=60000;i++)

unsigned int i;

int main()
{
    IO0DIR=0xf;          //Declaring as a output

    IO0PIN=0;            //Clear all IO Pins in P0

    VPBDIV=0x01;         //PCLK = 60MHz

    while(1) {
        /*Forward*/
        IO0SET=bit(0);    //IN1 = 1
        IO0CLR=bit(1);    //IN2 = 0

        delay;delay;

        /*Off*/
        IO0CLR=bit(0) | bit(1); //IN1 = IN2 = 0

        delay;delay;

        /*Reverse*/
        IO0SET=bit(1);    //IN2 = 1
        IO0CLR=bit(0);    //IN0 = 0

        delay;delay;

        /*Off*/
        IO0CLR=bit(0) | bit(1); //IN1 = IN2 = 0

        delay;delay;
    }
}

```

Output