

Date:
7/05/21

MID-I
C.S

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PART-A

- ① C
- ② ~~B~~. d.
- ③ b.
- ④ b.
- ⑤ a
- ⑥ c.
- ⑦ ~~a~~. c
- ⑧ a
- ⑨ a
- ⑩ d.

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PART-B

Open loop system.

→ The system whose control action is free from the O/P it is known as Open loop control system.

→ Non-feedback system.

→ Controller and controlled process.

closed loop system.

→ In closed loop the O/P depends on the control action of the system.

feedback system.

→ Amplifier, controller, controlled process, feedback.

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→ It is simple in construction.

→ Not - Reliable.

→ Accuracy depends on calibration.

→ More stable.

→ Optimization is Not Possible.

→ Fast response.

→ Open loop system is Non-linear.

→ Ex! Traffic lights, automatic washing machine.

→ It is complex in construction.

→ Reliable.

→ Accuracy is because of feedback.

→ less stable.

→ Optimization is possible.

→ Slow response.

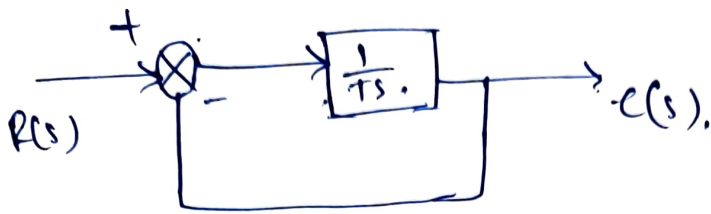
→ closed loop system is linear.

Ex! AC, temperature control system, Speed and pressure control system.

3) Time response of first order system for unit step input!

Consider closed loop with unity feedback.
1st order system.

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⇒ Eliminating -ve feedback.

$$\frac{C(s)}{R(s)} = \frac{1}{1+Ts}$$

$$C(s) = R(s) \frac{1}{1+Ts}$$

Let $R(s)$ be a unit step input.

$$\therefore R(s) = \frac{1}{s}$$

$$C(s) = 1/s \times \frac{1}{1+Ts}$$

$$= \frac{1/T}{s(s+1/T)}$$

By partial
fraction

$$C(s) = \frac{A}{s} + \frac{B}{s+1/T}$$

$$C(s) = \frac{1}{s} - \frac{1}{s+1/T}$$

Inverse Laplace on b.s.

$$C(t) = \mathcal{L}^{-1} \left(\frac{1}{s} - \frac{1}{s+1/T} \right)$$

$$C(t) = 1 - e^{-t/T}$$

$$A = C(s) \times s \Big|_{s=0} = \frac{1/T}{s(s+1/T)} \times s$$

$$\Big|_{s=0} = \frac{1/T}{s+1/T} \Big|_{s=0} = \frac{1/T}{1/T} = 1$$

$$B = C(s) \times \left(s + \frac{1}{T}\right) \Big|_{s=-1/T} = \frac{1/T}{s(s+1/T)} \times \left(s + \frac{1}{T}\right) \Big|_{s=-1/T}$$

$$\Big|_{s=-1/T} = \frac{1/T}{s} \Big|_{s=-1/T} = \frac{1/T}{-1/T} = -1$$

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for step response,
 $c(t) = A(1 - e^{-t/\tau})$

$$t = 0 \Rightarrow c(t) = 0.$$

$$t = \infty \Rightarrow c(t) = 1.$$

$$c(t) = \mathcal{L}^{-1}\{c(s)\} = \mathcal{L}^{-1}\left\{\frac{1}{s} - \frac{1}{s + 1/\tau}\right\}$$

$$= 1 - e^{-t/\tau} //$$

Response will be as follows:-

