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Appendix C

Notation

In this section we discuss the conventions, abbreviations, mathematical symbols, and symbols used in the book.

C.1 Conventions

The following conventions have been used:

- 1. Boldface roman denotes a vector or matrix.
- 2. The symbol | · | means the magnitude of the scalar contained within.
- 3. The symbol $\|\cdot\|$ denotes the Euclidean norm of the vector or matrix contained within.
- 4. Multiple integrals are frequently written as,

$$\int d au f(au) \int dt g(t, au) riangleq \int f(au) \left\{ \int dt g(t, au)
ight\} d au,$$

that is, an integral is inside all integrals to its left unless a multiplication is specifically indicated by parentheses.

- 5. $E[\cdot]$ denotes the statistical expectation of the quantity in the bracket.
- 6. The probability density of x is denoted by $p_x(\cdot)$ and the probability distribution by $P_x(\cdot)$. The probability of an event, A, is denoted by Pr[A]. The probability density of x, given that the random variable a has a value A, is denoted by $p_{x|a}(X|A)$.

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7. A vertical line in an expression means "such that" or "given that"; that is, $Pr[A|x \leq X]$ is the probability that event A occurs given that the random variable x is less than or equal to the value of X.

We list acronyms used in the text.

C.2 Acronyms

AAR adaptive angular response ACCR asymptotic conditional CRB AIC Akaike Information Criterion AMalternating maximization AMF adaptive matched filter AML asymptotic ML estimator APalternating projection AR. auto-regressive (model)

ARMA auto-regressive moving average (model)

ASNR array signal-to-noise ratio

 BW_{NN} null-null bandwidth

BS beamspace

CCRB conditional CRB

CFAR constant false alarm rate

CM constant modulus

CML conditional ML estimator CMT covariance matrix taper CRB Cramér-Rao bound

DEMT Detection, Estimation, and Modulation Theory

DFT discrete Fourier transform

DISPARE distributed signal parameter estimator

DL diagonal loading

DMI direct matrix inversion

DMR dominant-mode rejection (beamformer)

DOA direction of arrival DOF degrees of freedom

DPSS discrete prolate spheroidal sequence
DSPE distributed signal parameter estimation

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EV eigenvalue

EM expectation maximization

ES eigenspace

ESPRIT estimation of signal parameter

via rotational invariance technique

FB forward-backward (averaging)

FBSS forward-backward spatial smoothing

FCA filled circular array

FIM Fisher information matrix FIR finite impulse response FO forward-only (averaging)

GL grating lobe GLRT generalized LRT

GSC generalized sidelobe canceller

HPBW half-power bandwidth

HCRB hybrid CRB

HSST Householder subspace transformation

ICASSP International Conference on Acoustic,

Speech, and Signal Processing

IDFT inverse discrete Fourier transform

IMODE iterative MODE

INR interference-to-noise ratio

IQML iterative quadratic maximum likelihood

IQML-QC IQML with quadratic constraint

IR invisible region

JASA Journal Acoustic Society of America

LCMP linear constrained minimum

power (beamformer)

LCMV linear constrained minimum

variance (beamformer)

LEO low-earth orbit
LMS least mean square
LNR loading-to-noise ratio

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LP linear prediction LRT likelihood ratio test

LS least squares

LS-ESPRIT least squares ESPRIT

ML maximum likelihood MA moving average (model)

MAP maximum a posteriori probability

MBA multiple beam antenna
MDL minimum description length
MMSE minimum mean-square error
MODE method of direction estimation

MPDR minimum power distortionless response MPQR minimum power quiescent response

MRA (i) minimum redundancy array (ii) maximum response axis

MRLA minimum redundancy linear array MUSIC multiple signal characterization

MVDR minimum variance distortionless response MVQR minimum variance quiescent response

PM Parks-McClellan

QC quadratic constraint
QP quiescent pattern
QRD QR decomposition

RMSE root mean-square error RLS recursive least square

SALP subaperture linear prediction SCMV soft constraint minimum variance

SH sequential hypothesis
SHA standard hexagonal array

SINR signal-to-interference and noise ratio SLA standard linear array $(d = \lambda/2)$

SLL sidelobe level

SMI sample matrix inversion SNR signal-to-noise ratio

SRA standard rectangular array $(d_x = d_y = \lambda/2)$

STAP space-time adaptive processing

SS (i) spatial smoothing (ii) steady state

SVD singular value decomposition

TAM Toeplitz approximation method

TDL tapped delay line

TDRSS Tracking and Data Relay Satellite System

TLS total least squares

TLS-ESPRIT total least squares ESPRIT TNA thermal noise algorithm

UCA uniform circular array
UHA uniform hexagonal array
ULA uniform linear array

UML unconditional ML estimator URA uniform rectangular array

VR visible region

WES weighted eigenspace WSF weighted subspace fitting

C.3 Mathematical Symbols

 $\mathbf{a}^H,\,\mathbf{A}^H$ conjugate transpose (A.6)

 \mathbf{a}^T , \mathbf{A}^T transpose (A.4) \mathbf{A}^{-1} inverse (A.40)

 $\|\mathbf{a}\|$ Euclidean norm of \mathbf{a} (A.36)

 \mathbf{A}^* conjugate of \mathbf{A} [\mathbf{A}]_{ij} ij element of \mathbf{A} (A.1)

 $[\mathbf{A}]_k^{(r)}$ kth row of \mathbf{A} $[\mathbf{A}]_k^{(c)}$ kth column of \mathbf{A}

□ Khatri-Rao product (A.96)

 $\|\mathbf{A}\|_F$ Frobenius (Euclidean) norm of \mathbf{A} (A.39) $CN[\mathbf{m}, \mathbf{\Lambda}]$ probability density of complex Gaussian

(normal) vector

 \otimes Kronecker product (A.80)

 \triangle defined as

 $\det \mathbf{A}, |\mathbf{A}|$ determinant of \mathbf{A} (A.20)

```
\dim[\mathbf{A}]
                              number of free parameters in A
÷
                              equal to first order
                              Hadamard product (A.71)
\odot
                              logarithm: base 10
log
                              logarithm: base e
ln
(n)!
                              n factorial
\nabla_{\boldsymbol{\theta}}
                              partial derivative matrix operator
\propto
                              proportional to
o(N)
                              negligible as N \to \infty
O(N)
                              proportional to N as N \to \infty
                              columns of A are orthonormalized
orth[\mathbf{A}]
                              real part
Re\{\cdot\}
Im\{\cdot\}
                              imaginary part
rank(A)
                              rank of \mathbf{A} (A.34)
\operatorname{tr}\left(\mathbf{A}\right)
                              trace of \mathbf{A} (A.26)
vec(\mathbf{A})
                              stacked vector (A.112)
Ŷ
                              estimate of \mathbf{x}
t \to T^-
                              t approaches T from below
A + B \triangle A \cup B
                              A 	ext{ or } B 	ext{ or both}
l.i.m.
                              limit in the mean
\int_{-\infty}^{\infty} d\mathbf{x}
                              an integral over the same dimension as
                              the vector
\operatorname{diag}[a_1,a_2,\cdots,a_N]
                              diagonal matrix with elements a_1, a_2, \dots, a_N
\int_{\Omega} d\mathbf{x}
                              integral over the set \Omega
                              matrix with all zero elements
                              unity vector: [1 \ 1 \ \cdots \ 1]^T
1
\begin{pmatrix} N \\ k \end{pmatrix}
                              binomial coefficient \left(=\frac{N!}{k!(N-k)!}\right)
```

C.4 Symbols

We list symbols that are used in the text. The equation number indicates where the symbol was defined. If the symbol was defined in the text, a nearby equation number is listed. Symbols that are obvious modifications of other symbols are not included.

a signal direction vector (2.15)

$$\mathbf{A}(K)$$
 data matrix ($\mathbf{A}(K) = \sqrt{K}\tilde{\mathbf{X}}^T$) (7.271)

A_c	conventional array gain (6.32)
A_{iso}	array gain: isotropic noise (2.144)
A_{mpdr}	array gain: MPDR beamformer (6.73)
A_{mvdr}	array gain: MVDR beamformer (6.28)
$\mathbf{A}_{\mu}(K)$	exponentially weighted data matrix (7.269)
\mathbf{A}_L	left circulant matrix (A.150)
A_{lcmp}	array gain: LCMP beamformer (6.390)
A_{lcmv}	array gain: LCMV beamformer (6.389)
A_o	optimum array gain (6.28)
\mathbf{A}_R	right circulant matrix (A.148)
A_w	array gain for spatially white
	noise input (2.185)
$AF_{\mathbf{k}}(\mathbf{k})$	array factor in \mathbf{k} -space (2.234)
$AF_{m{\psi}}(\psi)$	array factor in ψ -space (2.234)
$AF_u(u)$	array factor in u -space (2.234)
AR(p)	autoregressive process of order p (5.311)
ARMA(p,q)	autoregressive moving average process of
	order (p,q) (5.303)
α	step size in LMS algorithm (7.405)
$\alpha(K)$	step size in LMS algorithm (7.405)
В	(i) blocking matrix (6.361)
D	(ii) matrix in polynomial parameterization (8.490)
	(iii) beam pattern matrix (2.82)
	(iv) output of DFT (3.96)
$B_a(\psi)$	asymmetric beam pattern (3.285)
\mathbf{B}_{bs}	beamspace matrix (3.327)
	beamspace blocking matrix (6.530)
$\mathbf{b}_{h_0 m}^{H}$	weight vector for m th beamspace beam (6.499)
$egin{aligned} \mathbf{B}_{bsbl} \ \mathbf{b}_{bs,m}^{H} \ \mathbf{B}_{bsx}^{II} \ \mathbf{B}_{bsy}^{H} \end{aligned}$	x-component of beamspace matrix, planar array (9.372)
\mathbf{B}_{heu}^{H}	y-component of beamspace matrix, planar array (9.374)
$B_{du}^{osg}(u)$	desired beam pattern in <i>u</i> -space
B_f	ratio of signal bandwidth to center frequency (5.288)
$\mathbf{B}_{no}^{'}$	non-orthogonal beamspace matrix (3.329)
$B_{mvdr}(\psi)$	beam pattern of MVDR beamformer (6.93)
$B_R(\psi)$	beam pattern using rectangular window (3.213)
$B_{ue}(u)$	element beam pattern (2.232)
$B(u_x, u_y)$	beam pattern in u_x , u_y -space (4.11)
$B(heta,\phi)$	beam pattern in (θ, ϕ) -space (2.38)
	· · · · · · · · · · · · · · · · · · ·

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B(\omega:\theta,\phi)
                   beam pattern in (\theta, \phi)-space (2.38)
B_{v}(v)
                   beam pattern in v-space (3.170)
B(\psi_x,\psi_y)
                   2-D beam pattern in \psi_x, \psi_y space (4.11)
                   beam pattern polynomial in z-plane (3.42)
B_z(z)
B_{\mathbf{z}}(z_1,z_2)
                   2-D z-transform (4.93)
B_c(\mathbf{k}:\mathbf{k}_T)
                   conventional beam pattern in k-space (2.124)
B_d(\psi)
                   desired beam pattern (3.82)
                   ith eigenbeam (7.126)
B_{eig,i}
B^{(n)}(\mathbf{k})
                   nominal beam pattern (2.196)
\mathbf{B}_{PM}
                   phase mode excitation beamformer
B_{\psi}(\psi)
                   beam pattern in \psi-space (2.71)
B_{s}
                   bandwidth of signal (Hz) (2.40)
                   beam pattern using Taylor weighting (3.173)
B_T(u)
                   Taylor beam pattern: circular aperture (4.220)
B_{TAY}(u)
B_{\theta}(\theta)
                   beam pattern in \theta-space (2.69)
B_{\boldsymbol{u}}(u)
                   beam pattern in u-space (2.70)
B_{\psi c}(\psi:\psi_T)
                   conventional beam pattern in \psi-space (2.125)
B_{\theta c}(\theta:\theta_T)
                   conventional beam pattern in \theta-space (2.131)
B_{uc}(u:u_T)
                   conventional beam pattern in u-space (2.126)
BW_{NN}
                   bandwidth: null-to-null (2.105)
                   velocity of propagation (2.14)
c
\mathbf{C}
                   constraint matrix N \times M_c (3.256)
\mathbf{C}_{A\!C\!R}(oldsymbol{\psi})
                   approximate Cramér-Rao bound on \psi (8.110)
                   Bayesian Cramér-Rao bound (= \mathbf{J}_B^{-1}) (8.53)
\mathbf{C}_{BCR}(\boldsymbol{\theta})
                   constraint matrices using derivatives (3.251),(3.253),(3.255)
\mathbf{C}_0, \mathbf{C}_1, \mathbf{C}_2
\mathbf{C}_{CR}(oldsymbol{\psi})
                   Cramér-Rao bound on \psi (8.94)
\mathbf{C}_{HCR}(oldsymbol{\phi},oldsymbol{
ho})
                   hybrid Cramér-Rao bound (8.676)
\mathbf{C}_{C\!C\!R}(oldsymbol{\psi})
                   conditional Cramér-Rao bound on \psi (8.235)
\mathbf{C}_{A\!C\!C\!R}(oldsymbol{\psi})
                   asymptotic conditional Cramér-Rao bound on \psi (8.236)
CRB_{bs}(\boldsymbol{\psi})
                   beamspace Cramér-Rao bound on \psi (8.273)
C_{CR,bs}(oldsymbol{\psi})
                   beamspace Cramér-Rao bound on \psi (8.616)
\mathbf{C}_{CR}(\boldsymbol{\theta})
                   Cramér-Rao bound matrix (8.25)
\mathbf{C}_K
                   scaled spectral matrix (7.3)
\mathbf{C}_{\mathbf{x}}
                   sample spectral matrix (7.10)
\mathbf{C}_{\mathbf{x},fb}
                   forward-backward averaged sample spectral matrix (7.40)
\mathbf{C}_{\mathbf{x},Re}
                   real sample spectral matrix (9.56)
\mathbf{C}_{MU}
                   error covariance matrix using
                   MUSIC algorithm (9.246)
\mathbf{C}_{WES}
                   error covariance matrix, weighted eigenspace (9.263)
```

\mathbf{C}_{BMU}	error covariance matrix, beamspace MUSIC (9.300)
\mathbf{C}_0	constraint matrix, zero-order nulls (3.251)
χ^2	complex chi-squared random variable (7.16)
λ	
d	distance between sensors, uniformly spaced array (2.3)
D	(i) directivity of an array or aperture (2.144),
	(ii) number of source signals (also d) (6.143)
D	(i) diagonal matrix of $e^{j\psi_m}$ terms (6.616)
	(ii) matrix of derivative vectors (8.97)
$\mathbf{d}_n(u)$	nth derivative of $\mathbf{v}(u)$ with respect to u (3.260)
$D(heta,\phi)$	difference beam pattern in (θ, ϕ) space (4.236)
d_{cir}	distance along circumference (4.157)
$D_{MU}(z)$	MUSIC polynomial
$D_{lpha}(heta,\phi)$	complementary difference beams (4.240)
$D_{eta}(heta,\phi)$	complementary difference beams (4.243)
$\mathrm{diag}[a_1,\cdots,a_N]$	$N N \times N$ diagonal matrix whose
	elements are a_1, \dots, a_N (A.119)
δ_p	filter's upper peak of ripple (3.222)
δ_s	filter's lower peak of ripple (3.222)
$rac{\Delta g_i}{\Delta k^2} \ rac{\Delta L^2}{\Delta l^2}$	amplitude perturbation (2.193)
$\frac{\Delta k^2}{m}$	normalized mean-square width of response (3.3)
	normalized mean-square width of weighting (3.3)
$\Delta \mathbf{p}_i$	perturbation of sensor position (2.195)
$\Delta p_{xi}, \Delta p_{yi},$	
Δp_{zi}	perturbation of sensor position $(x, y,$
	and z components) (2.195)
$\Delta\phi_i$	perturbation of sensor phase (2.194)
$\Delta\phi_n$	phase error, nth sensor (2.194)
$\Delta \psi_i$	error in ψ direction in estimate
	of ith root (9.199)
Δr_i	radial error in estimate of <i>i</i> th root (9.199)
ΔT	segment of observation interval (5.1)
ΔT_{ij}	travel time between i and j elements (2.43)
ΔT_{max}	maximum travel time across array (2.43)
Δu_1	HPBW (half-power beamwidth) (2.100)
Δu_2	BW_{NN} (null-null beamwidth) (2.105)
Δu_s	sampling interval in <i>u</i> -space (3.74)
Δz_i	error in estimate of <i>i</i> th root (9.199)
DI	directivity index (2.167)

 d_s displacement between subarrays in ESPRIT algorithm (9.101) vector with 1 in nth position \mathbf{e}_n and zero elsewhere (A.104) matrix with 1 in ij element and zero elsewhere (A.107) \mathbf{E}_{ij} $e_{pm}(\psi)$ error function in Parks-McClellan algorithm (3.222) EFF_{MU} efficiency of MUSIC algorithm (9.251) noise level across band (8.373) noise level at mw_0 (8.373) η_m F $N \times N$ matrix in discrete Fourier transform (3.97) $\mathbf{F}(\omega, \mathbf{p})$ Fourier transform of $\mathbf{f}(t, \mathbf{p})$ (2.12) $F(\boldsymbol{\psi})$ cost function in ψ -space (8.389) $\mathbf{F}(k)$ kth frequency-domain snapshot of complex source-signal vector (8.200) $F_{map}(\boldsymbol{\theta}, \boldsymbol{\rho})$ MAP cost function (8.690) $\mathbf{f}(t,\mathbf{p}_n)$ signal input to array at time t (2.6) $f_{c_n}(t)$ real part of f(t) $F_x(\tau:\mathbf{k})$ temporal correlation-spatial wavenumber spectrum (5.92) F_{aml} AML cost function (8.390) F_{cml} CML cost function (8.391) F_{WSF} WSF cost function (8.392) F_{MODE} MODE cost function (8.392) $\mathbf{F}(w, \mathbf{p})$ Fourier transform of signal at \mathbf{p} (2.12) f(t)complex envelope (5.71) value of constraints (6.279) $\mathbf{g}(K)$ gain vector (7.157)amplitude of complex weight w_i (2.190) $\Gamma_N(k)$ generalization of Gamma function (7.13) \mathbf{H} matrix in CRB, $\mathbf{D}^H \mathbf{P}_{\mathbf{V}}^{\perp} \mathbf{D}$ (8.101) H_0, H_1 hypotheses 0 and 1 (10.1) $\mathbf{h}(\tau)$ impulse response of vector filter (2.9) $\mathbf{H}(\mathbf{y})$ transformation in EM algorithms (8.454) $\mathbf{H}_o(w)$ MMSE weight vector (6.42) \mathbf{H}_{w} whitening matrix (6.517) \mathbf{H}_G Gaussian approximation to Hessian (8.426) \mathbf{H}_k Hessian matrix at kth iteration (8.401)

	$I_0(x)$	modified Bessel function of zero order (3.36)
	J	(i) exchange matrix (A.125)
		(ii) Fisher information matrix (8.26)
	\mathbf{J}_B	Bayesian version of Fisher information matrix (8.49)
	\mathbf{J}_D	data information matrix (8.50)
	\mathbf{J}_P^-	prior information matrix (8.51)
	${ m J}_{\psi\psi}$	sub-matrix of Fisher information matrix
	44	for ψ parameter (8.89)
	\mathbf{J}_s	selection matrix (9.103)
	$egin{aligned} \mathbf{J}_s \ \mathbf{ ilde{J}}_s \ \mathbf{ ilde{J}}_s^{(m_s)} \end{aligned}$	identity matrix component of J_s (9.103)
	$ ilde{f J}_s^{(m_s)}$	weighted diagonal matrix in ESPRIT
	O _S	selection matrix (9.132)
	$J(\mathbf{b})$	cost function for IQML (8.496) and MODE (8.532)
	0 (2)	(0.002)
	k	wavenumber (2.24)
	K	number of snapshots (5.1)
	\mathbf{k}_T	steering direction in k -space (2.119)
	k_0	magnitude of wavenumber (2.57)
	k_r	radial component of wavenumber (5.131)
	$K_x(t_1,t_2:\mathbf{p}_1,\mathbf{p}_2)$)space-time covariance function (5.85)
		space-time covariance function;
		wide-sense stationary process (5.86)
	$K_x(t_1,t_2:\mathbf{p}_{\Delta})$	space-time covariance function;
		homogeneous process (5.88)
	$K_x(au:\mathbf{p}_\Delta)$	space-time covariance function; homogeneous,
		wide-sense stationary process (5.90)
	$\mathbf{K}_{\mathbf{x}}(oldsymbol{ heta})$	covariance matrix of \mathbf{x} (as a function of $\boldsymbol{\theta}$) (8.8)
	k_z	z-component of wavenumber \mathbf{k} (2.56)
	L	(i) length of linear aperture (2.5)
		(ii) number of subarrays in linear
i		spatial smoothing (6.614)
	L	lower triangular matrix (A.151)
	$L(\boldsymbol{ heta})$	likelihood function (8.10)
	$L_d(d)$	likelihood function (as a function of d ,
	- ()	the number of signals) (7.502)
	$L(oldsymbol{\psi}, \mathbf{F})$	likelihood function (conditional model) (8.336)

$L(oldsymbol{\psi}, \mathbf{S_f})$	likelihood function (stochastic model) (8.277)
$L_{bs}(oldsymbol{\psi}, \mathbf{F})$	likelihood function in beamspace
,	(conditional model) (8.627)
λ	(i) wavelength (2.24),
,	(ii) Lagrange multiplier (2.163)
λ	Lagrange multiplier vector (3.262)
$\lambda(\omega)$	Lagrange multiplier as a function of frequency
$\lambda_i \ \lambda_l$	ith eigenvalue of matrix (A.196), (5.208)
λ_u^l	wavelength of lowest frequency (3.335)
	wavelength of highest frequency (3.335)
λ_{max}	maximum eigenvalue (5.213)
λ_{min}	maximum eigenvalue (5.213)
$\hat{\lambda}_i \ \hat{\lambda}_{fb}$	estimate of ith eigenvalue (7.21)
\wedge_{fb}	estimated eigenvalue with FB averaged
$\hat{\lambda}_{Re}$	sample spectral matrix (9.60)
λ_{Re}	estimated eigenvalue with real sample
A	spectral matrix (9.63)
$oldsymbol{\Lambda}_S$	diagonal matrix of signal subspace eigenvalues (5.238)
$oldsymbol{\Lambda}_N \ \hat{oldsymbol{\Lambda}}_S$	diagonal matrix of noise eigenvalues (5.239)
\mathbf{A}_{S}	diagonal matrix of estimated signal
$\hat{\boldsymbol{\Lambda}}_{N}$	subspace eigenvalues (8.361)
	diagonal matrix of estimated noise eigenvalues (8.361)
$\hat{m{\Lambda}}_{S,Re}$	real estimated signal subspace eigenvalue matrix (9.64)
$\hat{m{\Lambda}}_{N,Re}$	real estimated noise subspace eigenvalue matrix (9.64)
M	matrix representing data (8.362)
M	(i) number of sensors in linear subarray
	(spatial smoothing) (6.614)
	(ii) number of sensors in y -direction:
	rectangular planar array (4.11)
	(iii) number of frequency bins (5.7)
\mathcal{M}	misadjustment in LMS beamformer (7.452)
m_s	parameter in weighted ESPRIT (9.132)
$\mathbf{m}_{\mathbf{x}}(oldsymbol{ heta})$	mean of \mathbf{x} (as a function of $\boldsymbol{\theta}$) (8.8)
μ	exponential weight (7.138)
$\mu(K)$	diagonal exponential weighting matrix (7.270)
N	number of elements in the array (2.5)
n	index of elements (2.3)

```
\tilde{n}
                 symmetric index (3.11)
N_H
                 (i) number of holes (3.299)
                 (ii) number of elements in standard hexagonal array (4.256)
N_R
                 number of redundancies (3.299)
                 frequency separation (5.6)
\omega_{\Delta}
                 radian frequency (2.10)
\omega
\omega_c
                 center frequency (rad/sec) (2.39)
\Omega_A
                 beam solid angle (4.31)
p(d)
                 penalty function (7.503)
                 position of elements on z-axis (2.3)
p_{z_n}
                 inverse of \Phi^{-1}(K) (7.154)
\mathbf{P}(K)
P(\omega, \theta, \phi)
                 beam power pattern in frequency-angle space (6.306)
P(\theta,\phi)
                 beam power pattern with \omega suppressed (6.306)
P_{xx}(z)
                 output spectrum in z-domain, ARMA models (5.302)
P_D
                 probability of detection (7.511)
                 position difference (2.192)
\mathbf{p}_{\Delta}
P_{do}
                 desired output power (6.593)
P_F
                 probability of false alarm (7.511)
P_{Io}
                 interference output power (6.597)
p_n
                 position of nth sensor (1-D) (2.53)
                 position of nth element (3-D) (2.6);
\mathbf{p}_n
                 in rectangular coordinates, \mathbf{p}_n = [p_{xn}, p_{yn}, p_{zn}]^T
P_{no}
                 noise output power (6.598)
P_{\mathbf{V}}
                 projection matrix with respect to V (A.177)
\mathbf{P}_{\mathbf{V}}^{\perp}
                 orthogonal projection matrix (A.178)
P_x(\omega:\mathbf{k})
                 frequency-wavenumber spectrum (5.93)
P_B(\psi)
                 beamscan spectrum (9.2)
\hat{P}_{BW}(\psi)
                 weighted beamscan spectrum (9.5)
\hat{P}_{B,fb}(\psi)
                 beamscan spectrum with FB averaging (9.9)
P_{mvdr}(\psi)
                 MVDR spectrum (9.13)
Pr(\epsilon)
                 probability of error
φ
                 angle measured counterclockwise from positive x-axis (2.17)
Φ
                 diagonal matrix of phase terms in ESPRIT (9.107)
\phi_i
                 phase of complex weight w_i (2.190)
                 ith eigenvector of matrix (A.192), (A.196), (5.205)
\phi_i
\Phi(K)
                 exponentially weighted sample spectral matrix (7.138)
\Phi_{\mathbf{z}}(K)
                 exponentially weighted sample spectral matrix in
```

	generalized sidelobe canceller (7.196)
$\hat{oldsymbol{\phi}}_i$	estimate of i th eigenvector (7.21)
$\hat{oldsymbol{\phi}}_i \ \hat{oldsymbol{\phi}}_{Re}$	estimate of real eigenvector (9.59)
$\hat{oldsymbol{\phi}}_{fb}$	estimate of real eigenvector using FB averaging (9.60)
$ ilde{oldsymbol{\Phi}}(K)$	exponentially weighted sample spectral matrix
	using FB averaging (7.246)
$\overline{oldsymbol{\Phi}}(K)$	real exponentially weighted sample spectral matrix (7.256)
Ψ_H	half-power point beamwidth (4.29)
$\hat{oldsymbol{\psi}}_{aml}$	asymptotic ML estimate of ψ (8.310), (8.315)
$\hat{oldsymbol{\psi}}_{cml}$	conditional ML estimate (8.346)
$\hat{m{\psi}}_{cml,bs}$	CML estimate in beamspace (8.630)
ψ_p	design parameter in Parks-McClellan algorithm (3.223)
ψ_s	design parameter in Parks-McClellan algorithm (3.223)
ψ_x	x-component of ψ (4.2)
$\psi_y \ \hat{\psi}_{MODE}$	y -component of ψ (4.3)
ψ_{MODE}	MODE estimate of ψ (8.367)–(8.370)
$\widehat{m{\Psi}}_{bs,ULS}$	matrix in beamspace unitary LS-ESPRIT (9.324)
$\widehat{m{\Psi}}_{bs,UTLS}$	matrix in beamspace unitary TLS-ESPRIT (9.325)
Ψ_{LS}	matrix in LS-ESPRIT (9.120)
$\widehat{m{\Psi}}_{TLS}$	matrix in TLS-ESPRIT (9.122)
$\widehat{m{\Psi}}_{ULS}$	matrix in unitary LS-ESPRIT (9.163)
$\widehat{m \Psi}_{UTLS}$	matrix in unitary TLS-ESPRIT (9.165)
Q	(i) specific unitary matrix (A.161), (A.162), (7.58), (7.59),
	(7.248), (7.249)
_	(ii) matrix in quadratic form (6.337)
$\widehat{Q}_{MU}(\psi)$	MUSIC null spectrum (9.43)
$\widehat{Q}_{mvdr}(\psi)$	MVDR null spectrum (9.14)
$\widehat{Q}_{mvdr,fb}$	MVDR null spectrum with FB averaging
$egin{array}{c} \mathbf{Q}_N \ \widetilde{\mathbf{Q}}_{\mathbf{x}} \end{array}$	unitary matrix with dimension $N \times N$ (9.137)
$\mathbf{Q}_{\mathbf{x}}$	matrix in IQML algorithm (8.508)
$egin{aligned} \widetilde{\mathbf{Q}}_D \ \widehat{\mathbf{Q}}_{oldsymbol{z}}(z) \end{aligned}$	matrix in IMODE algorithm (8.536)
	null polynomial (9.20)
$\widehat{\mathbf{Q}}_{MU,z}(z)$	root MUSIC polynomial (9.48)
$\widehat{\mathbf{Q}}_{MU,fb,z}(z)$	root MUSIC polynomial with FB averaging (9.52)
$\widehat{\mathbf{Q}}_{MU,U,z}(z)$	unitary root MUSIC polynomial (9.65)
$\mathbf{Q}_{MN}(\psi)$	Min-Norm null spectrum (9.95)
$\mathbf{\hat{Q}}_{WES}(\psi)$	weighted eigenspace null spectrum (9.258)

$\widehat{\mathbf{Q}}_{bs,MU}(\psi)$	beamspace MUSIC null spectra (9.295)
R	ratio of main-lobe height to sidelobe height (3.143)
R[m]	discrete rectangular window (3.210)
$\mathbf{R}_e(K)$	weight error correlation matrix (7.438)
$\mathbf{\tilde{R}}(K)$	upper triangular matrix in QRD (7.282)
$\mathrm{R}_{\boldsymbol{\epsilon}}$	correlation matrix of errors (8.52)
$\mathbf{R_f}$	source-signal correlation matrix (8.68)
R_x	input correlation matrix (8.68)
$\mathbf{R_n}$	noise correlation matrix (8.68)
$R_W(\omega: m)$	co-array of linear array (5.187)
$R_W(\omega:\mathbf{p})$	aperture autocorrelation function (5.184)
$\mathbf{r_y}$	correlation vector for AR process (5.318)
$\mathbf{R}_{\mathbf{y}}$	correlation matrix for AR process (5.316)
$egin{array}{l} ext{r}_{ ext{y}} \ ilde{ ext{R}}_{ ext{y}} \ ilde{ ext{R}}_{ ext{y}}^{A} \ ho$	augmented correlation matrix for AR process (5.320)
$\boldsymbol{\rho}$	perturbation vector (6.240)
$oldsymbol{ ho}(\omega)$	normalized spectral matrix (6.27)
$ ho_{s1}$	spatial correlation coefficient (6.80)
$S_o(w: heta,\phi) \ \mathbf{S}_{d\mathbf{x}}^H$	spectral density on sphere (5.127)
$\mathbf{S}_{d\mathbf{x}}^{H}$	cross-spectral matrix between D and X (6.41)
$\mathbf{S_f}$	source-signal spectral matrix (5.67), (5.222)
$S_f(\omega)$	input signal frequency spectrum at each sensor (2.170)
$\mathbf{S}_{\mathbf{x},fb}$	forward–backward spatial spectral matrix (7.45)
$\mathbf{S_n}$	noise spectral matrix (6.37)
$S_n(\omega)$	input noise frequency spectrum at each sensor (2.170)
$\mathbf{S}_{\mathbf{x}}(\omega)$	spectral matrix of vector process (5.174)
$\mathbf{S}_{y_s}(\omega)$	array output signal spectrum (2.180)
$S_x(\omega:\mathbf{p}_\Delta)$	temporal frequency-spatial correlation function (5.91)
$egin{aligned} \mathbf{S}_{\mathbf{x}}(\omega_m) \ \mathbf{ ilde{S}}_{x,L} \end{aligned}$	spatial spectral matrix at frequency ω_m (5.175)
$\hat{f g}_{x,L}$	spectral matrix augmented with diagonal loading (7.115)
$\hat{\mathbf{S}}_{\mathbf{x},fb}$	estimated spatial spectral matrix using
â	forward–backward averaging (7.45)
$\hat{\mathbf{S}}_{\mathbf{x}}$	estimated spatial spectral matrix(7.9)
$\mathbf{S}_{\mathbf{x},bs}$	beamspace spatial spectral matrix(6.509)
$egin{array}{c} \mathbf{S}_{M}^{(i)} \ \mathbf{S}_{MB}^{(i)} \end{array}$	forward spatial spectral matrix of i th subarray (6.617)
	backward spatial spectral matrix of i th subarray (6.618)
\mathbf{S}_{SSFB}	forward-backward spatially smoothed
	spectral matrix (6.622)

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\mathbf{S}_{SS}
                   spatially smoothed spectral matrix (6.628)
\hat{\mathbf{S}}_{\mathbf{x},ml}
                   AML estimate of \mathbf{x} (8.299)
\hat{\mathbf{S}}_{\mathbf{f},ml}
                   AML estimate of \mathbf{f} (8.296)
\hat{\mathbf{S}}_{SS}
                   sample spectral matrix using spatial smoothing (9.288)
\hat{\mathbf{S}}_{FBSS}
                   sample spectral matrix using forward-backward
                   spatial smoothing (9.289)
{f \Sigma}
                   normalized signal spectral matrix (8.103)
\sigma_w^2
                   spectral height; white noise (5.191)
\mathbf{T}
                   transformation matrix (5.232)
                   test statistic: adaptive matched filter (10.21)
t_{AMF}
t_e
                   test statistic (10.5)
T_o
                   quadratic constraint (2.211)
                   delay at nth sensor relative to a sensor at the origin (2.14)
\tau_n
                   angle measured from positive z-axis (2.2)
\bar{\theta}
                   complement of \theta, \bar{\theta} = \frac{\pi}{2} - \theta (2.2)
\theta_H
                   half-power beamwidth in \theta-space, 1-D (2.136)
\Theta_H
                   half-power point beamwidth, 2-D (4.27)
\theta_{man}
                   MAP estimate of \theta (8.22)
\theta_{ml}
                   ML estimate of \theta (8.15)
                   wanted parameter (8.39)
\boldsymbol{\theta}_w
                   unwanted parameter (8.39)
\boldsymbol{\theta}_u
\boldsymbol{\theta}_1
                   nonrandom parameter (8.58)
\theta_2
                   random parameter (8.58)
\theta_R, \theta_L
                   right and left half-power point in \theta-space (2.134) (2.135)
T_n(x)
                   nth degree Chebychev polynomial (3.133)
T_{se}
                   sensitivity function (2.206)
                   direction cosine vector, \mathbf{u} = [u_x, u_y, u_z]^T (2.20)
u
\mathbf{U}
                   (i) upper triangular matrix (A.153);
                   (ii) left singular vector (A.261);
                   (iii) N \times N matrix of eigenvectors (6.439)
\mathbf{U}_N
                   matrix of noise subspace eigenvectors (5.234)
\widehat{\mathbf{U}}_N
                   estimate of \mathbf{U}_N (8.361)
u_R, u_L
                   right and left half-power points in u-space (2.132) (2.133)
\mathbf{U}_{RS}
                   real signal subspace matrix (9.158)
\mathbf{U}_S, \mathbf{U}_s
                   matrix of signal subspace eigenvectors (5.231)
\hat{\mathbf{U}}_{S}
                   estimate of U_S (8.361)
u_x, u_y, u_z
                   direction cosines with respect to x, y,
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	and z axes $(2.17)(2.18)(2.19)$
\mathbf{U}_Q	$N \times N$ matrix of eigenvectors (6.339)
$\mathbf{U}(oldsymbol{ heta}, \hat{oldsymbol{ heta}}^{(n)})$	function in EM algorithm (8.456)
\mathbf{u}_r	radial directional cosine (4.6)
\mathbf{U}_{dm}	dominant mode subspace (6.487)
$\hat{\mathbf{U}}_{bs,S}$	estimated beamspace signal subspace (9.295)
$\hat{\mathbf{U}}_{bs,N}$	estimated beamspace noise subspace (9.295)
$\hat{ ext{U}}_{FBSS,S}$	estimated signal subspace using FB
	spatial smoothing (9.291)
$\hat{\mathbf{U}}_{FBSS,N}$	estimated noise subspace using FB
	spatial smoothing (9.291)
\mathbf{U}_P	weight matrix in MUSIC analysis (9.216)
$\hat{ extbf{U}}_{S,Re} \ \hat{ extbf{U}}_{S,Re}$	real estimated signal subspace (9.64)
$\mathbf{U}_{S,Re}$	real estimated noise subspace (9.64)
$egin{array}{c} \mathbf{U}_{s1} \ \hat{\mathbf{U}}_{s1} \end{array}$	first subarray signal subspace (9.109)
	estimated first subarray signal subspace (9.117)
$egin{array}{c} \mathbf{U}_{s2} \ \hat{\mathbf{U}}_{s2} \end{array}$	second subarray signal subspace (9.110)
	estimated second subarray signal subspace (9.118)
$\Upsilon(\omega, \mathbf{k}) \ \Upsilon_z(z)$	frequency-wavenumber response function (2.37) frequency-wavenumber response function
1z(z)	in z -plane (2.63)
$\Upsilon_{\psi}(\psi)$	frequency-wavenumber response function
- ψ(τ)	in ψ -space (2.61)
$\Upsilon_e(\omega,{f k})$	frequency-wavenumber response function
	of sensor element (2.234)
$\Upsilon_u(u)$	frequency-wavenumber response function in u -space (3.72)
V	right singular vector (A.261)
$\mathbf{v}_{bs}(\psi)$	array manifold vector in beamspace (6.502)
$vec_H(u_x, u_y)$	array manifold vector for standard
${f v_k}({f k})$	hexagonal array (4.257) array manifold vector: k -space (2.28)
$\mathbf{v}_{\mathbf{k}}^{(\mathbf{k})}(\psi)$	kth derivative of array manifold vector (7.514)
$\mathbf{V}(oldsymbol{ heta},oldsymbol{ ho})$	perturbed array manifold vector (8.73)
\mathbf{V}^{\dagger}	Moore-Penrose pseudo-inverse of V
	(A.185)–(A.187), (8.326)
$\mathbf{v}_{\psi}(\psi)$	array manifold vector: ψ -space (1-D) (2.72)
$\mathbf{V}_{oldsymbol{\psi}}(oldsymbol{\psi})$	array manifold matrix (planar array) (4.52)
$\mathbf{V}_R^{m{ au}}(m{\psi})$	real array manifold matrix (9.152), (9.340)

$\mathbf{v}_R(\psi)$	real array manifold vector (9.140)
$\mathbf{v}_u(u)$	array manifold vector: u-space (1-D) (2.68)
$\mathbf{v}_{ heta}(heta)$	array manifold vector: θ -space (1-D) (2.67)
$\mathbf{v}_S(\psi)$	array manifold vector for reference subarray (9.290)
\mathbf{V}_{M}	array manifold matrix; M-element subarray
$\mathbf{V}_{oldsymbol{\psi}}^{oldsymbol{m}}(oldsymbol{\psi})$	array manifold matrix, linear array (8.67)
$\mathbf{v}^{\psi \cdot r}$	array manifold matrix, linear array
•	$(\psi \text{ suppressed}) (5.221)$
\mathbf{V}_{bs}	beamspace array manifold matrix,
• 08	linear array (ψ suppressed) (6.515)
\mathbf{V}_I	beamspace array manifold matrix of interference,
▼ <i>I</i>	linear array (ψ suppressed) (6.104)
	inteal array (ψ suppressed) (0.104)
W	weight matrix, planar array (4.56)
w	complex weight vector (2.49)
${\mathcal W}_N(K,{f S_x})$	complex Wishart density (7.11)
$\mathbf{W}(\omega)$	(i) weight vector in frequency domain (6.6)
(2)	(ii) $D \times N$ matrix processor (6.144)
$\mathbf{W}_o(\omega)$	optimum vector in frequency domain (6.12)
$w_a^*(z)$	aperture weighting function (2.214)
\mathbf{w}_a	adaptive weight vector in sidelobe canceller (6.373)
\mathbf{W}_{ao}	asymptotically optimal weighting (8.368)
\mathbf{w}_d	desired weight vector (3.262)
$\mathbf{w}_{dq}^{^{a}}$	desired quiescent weight vector (6.409)
w_i^{n}	nominal weight (2.190)
$egin{array}{c} w_i^n \ w_n^* \ \mathbf{w}^n \end{array}$	complex weighting of sensor output (2.49)
\mathbf{w}^n	nominal weight vector (2.190)
$\mathbf{W}^n(\omega)$.	nominal matrix filter
\mathbf{w}_o	optimum weight vector (3.264)
\mathbf{w}_e	error weight vector (3.271)
\mathbf{w}_{bs}	weight vector in beamspace (3.334)
$ar{\mathbf{w}}_{dq}$	normalized desired quiescent weight vector (6.409)
\mathbf{w}_{lcmv}^{H}	LCMV weight vector (6.357)
\mathbf{w}_{lcmn}^{H}	LCMP weight vector (6.358)
\mathbf{w}_{dm}^{H}	weight vector, dominant-mode beamformer (7.522)
$egin{array}{l} \mathbf{w}_{lcmv}^{dq} \\ \mathbf{w}_{lcmv}^{H} \\ \mathbf{w}_{lcmp}^{H} \\ \mathbf{w}_{dm}^{H} \\ \mathbf{W}_{mvdr}^{H} \end{array}$	minimum variance distortionless
	response weight vector (6.23)
\mathbf{w}_{mvdr}^{H}	minimum variance distortionless
	response weight vector (6.74)
	= · · · /

\mathbf{w}_{mpdr}^{H}	minimum power distortionless
	response weight vector (6.71)
$\mathbf{w}_{mpdr,dl}^{II}$	minimum power distortionless response weight vector
	with diagonal loading (6.270)
$\mathbf{w}_{mpdr.es}^{H}$	MPDR weight vector in eigenspace (6.449)
$\mathbf{w}_{mpdr,es}^{H}$ $\mathbf{w}_{lcmp,es}^{H}$	LCMP weight vector in eigenspace (6.464)
$W_{pm}(\psi)$	weighting function in Parks-McClellan-Rabiner
	algorithm (3.224)
\mathbf{w}_q	quiescent weight vector (6.360)
$w_R(r)$	radial weighting function: circular aperture (4.192)
\mathbf{w}_{bs}	beamspace weight vector
$\hat{\mathbf{w}}_{mvdr,smi}^{H}$	weight vector for SMI implementation of
,	MVDR beamformer (7.83)
$\hat{\mathbf{w}}_{mpdr,smi}^{H}$	weight vector for SMI implementation of
,	MPDR beamformer (7.85)
$\hat{\mathbf{w}}_{lse}(K)$	least squares error weight vector (7.149)
$\hat{\mathbf{w}}_{rls}(K)$	weight vector in RLS algorithm (7.431)
$\hat{\mathbf{w}}_{lms}(K)$	weight vector in LMS algorithm (7.432)
$\mathbf{V}(h)(alab \mathbf{V})$	fraguency demain anarchet wester (7.9)
$\tilde{\mathbf{X}}(\kappa)$ (also \mathbf{A}_{k})	frequency-domain snapshot vector (7.2)
$ ilde{ ilde{\mathbf{X}}}_{fb}$	$N \times K$ data matrix (7.4)
	$N \times 2K$ forward-backward data matrix (7.48)
$\mathbf{X}_{\Delta T}(\omega_m)$	finite interval Fourier transform (5.4)
$\mathbf{X}(\omega_m, k)$	kth frequency-domain snapshot at frequency ω_m
$\xi_{lms}(K)$	mean-square error: LMS
¢ (K)	beamformer at Kth iteration (7.448)
$\xi_{\mu}(K) \ \xi_{ex}(\infty)$	weighted summation of squared errors (7.148) steady state excess mean-square error (LMS) (7.451)
$\xi_{ex}(\mathcal{K})$	excess mean-square error (LMS) (7.449)
Sex(11)	CACCOS IIICAII-SQUAIC CITOI (LIVIS) (1.443)
$\xi_N(K)$	weighted summation of squared errors (7.132)
$\xi_N(K)$ $\xi_Y(K)$	weighted summation of squared errors (7.132) weighted summation of squared outputs (7.133)
$\xi_N(K)$ $\xi_Y(K)$ ξ_o	weighted summation of squared errors (7.132) weighted summation of squared outputs (7.133) MMSE (7.324)
$\xi_N(K)$ $\xi_Y(K)$ ξ_o ξ	weighted summation of squared errors (7.132) weighted summation of squared outputs (7.133) MMSE (7.324) MSE (6.39)
$\xi_N(K)$ $\xi_Y(K)$ ξ_o	weighted summation of squared errors (7.132) weighted summation of squared outputs (7.133) MMSE (7.324)
$\xi_N(K)$ $\xi_Y(K)$ ξ_o ξ $\xi_o(\omega)$ $\xi_{sd}(K)$	weighted summation of squared errors (7.132) weighted summation of squared outputs (7.133) MMSE (7.324) MSE (6.39) MMSE as a function of ω (6.48) transient MSE using steepest descent (7.368)
$\xi_N(K)$ $\xi_Y(K)$ ξ_o ξ $\xi_o(\omega)$	weighted summation of squared errors (7.132) weighted summation of squared outputs (7.133) MMSE (7.324) MSE (6.39) MMSE as a function of ω (6.48)

z_k	kth zero (3.58), (3.59)
\mathbf{z}_n	coordinate of n th element on z -axis (2.4)
z_{λ}	normalized distance on z-axis: = z/λ (3.72)

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