Graph theory algorithms

Bruce Merry

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Algorithm 1 Depth first search (recursive)

```
if not seen[x] then

seen[x] \leftarrow true

process(x)

for each neighbour y of x do

dfs(y)

end for

end if
```

${\bf Algorithm~2~Depth~first~search~(stack~based)}$

```
clear stack
push start
while stack not empty do

pop stack into cur

if not seen[cur] then

process(cur)

seen[cur] \leftarrow true

for each neighbour next of cur do

push next

end for
end if
end while
```

Algorithm 3 Unweighted shortest path (BFS)

```
clear queue
push start
for each node i do
  \operatorname{dist}[i] \leftarrow \infty
  parent[i] \leftarrow -1
end for
\operatorname{dist}[start] \leftarrow 0
while queue not empty do
  pop queue into cur
  for each neighbour next of cur do
     if dist[next] \neq \infty then
         \mathrm{dist}[next] \leftarrow \mathrm{dist}[cur] + 1
         parent[next] \leftarrow cur
         push next
     end if
  end for
end while
```

The path is found by starting at the end node, and following the parent links backwards.

Algorithm 4 Dijkstra's algorithm (shortest path)

```
clear priority queue
push start with priority 0
for each node i do
  \mathrm{dist}[i] \leftarrow \infty
  parent[i] \leftarrow -1
end for
\operatorname{dist}[start] \leftarrow 0
while priority queue not empty do
  pop priority queue into cur with priority prio
  if prio = dist[cur] then
     for each neighbour next of cur with length len do
        if prio + len < dist[next] then
           \text{dist}[next] \leftarrow prio + len
           parent[next] \leftarrow cur
          push next with priority \operatorname{dist}[next]
        end if
     end for
  end if
end while
```

Algorithm 5 Floyd's algorithm (all shortest paths)

```
for y=1 to N do

for x=1 to N do

if \max[x][y] \neq \infty then

for z=1 to N do

if \max[x][y] + \max[x][y] = \max[x][z] then

\max[x][x] = \max[x][y] + \max[x][y]

end if

end for

end for

end for

end for
```

The algorithm works in place, converting an adjacency matrix to a minimum distance matrix.