Weak forms and finite element method in 1d Problems & solutions

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1 Weak forms in 1d

Problem 1. Consider the following Dirichlet boundary value problem:

$$\left\{ \begin{array}{rcl} -\left(\left(2+\sin x\right)\cdot u'\left(x\right)\right)'+3\cdot u'\left(x\right) & = & x^{2} & \quad \text{in } \Omega=\left(K,L\right) \\ u\left(K\right) & = & 4 & \\ u\left(L\right) & = & 5 \end{array} \right. ,$$

where $K \in \mathbb{R}$, $L \in \mathbb{R}$, K < L. Derive the weak form.

Solution 1. Consider the space $U = H^1(\Omega)$.

For all test functions $v \in V = \{w \in U : w(K) = w(L) = 0\}$:

$$\underbrace{\int_{K}^{L} -\left(\left(2+\sin x\right) \cdot u'\left(x\right)\right)' \cdot v\left(x\right) dx}_{\downarrow \text{ per partes } \uparrow} + \underbrace{\int_{K}^{L} 3 \cdot u'\left(x\right) \cdot v\left(x\right) dx}_{L} = \underbrace{\int_{K}^{L} x^{2} \cdot v\left(x\right) dx}_{L}$$

$$\int_{K}^{L} (2 + \sin x) \cdot u'(x) \cdot v'(x) dx - [(2 + \sin x) \cdot u'(x) \cdot v(x)]_{K}^{L} + \int_{K}^{L} 3 \cdot u'(x) \cdot v(x) dx = \int_{K}^{L} x^{2} \cdot v(x) dx$$

Since
$$v \in V$$
, $v(K) = v(L) = 0$ holds.

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$$\underbrace{\int_{K}^{L} (2 + \sin x) \cdot u'(x) \cdot v'(x) \, dx + \int_{K}^{L} 3 \cdot u'(x) \cdot v(x) \, dx}_{a(u,v)} = \underbrace{\int_{K}^{L} x^{2} \cdot v(x) \, dx}_{b(v)}$$

The weak solution of the boundary value problem is a function u that fulfills:

$$\begin{cases} u \in U_D = \{w \in U : w(K) = 4 \land w(L) = 5\} \\ a(u, v) = b(v) \quad \forall v \in V \end{cases}$$

Problem 2. Consider the following Neumann boundary value problem:

$$\begin{cases}
-u''(x) + u(x) &= 0 & \text{in } \Omega = (3,8) \\
-u'(3) &= 5 & \\
u(8) &= 0
\end{cases}.$$

Derive the weak form.

Solution 2. Consider the space $U = H^1(\Omega)$.

For all test functions $v \in V = \{w \in U : w(8) = 0\}$:

$$\int_{3}^{8} -u''(x) \cdot v(x) \, dx + \int_{3}^{8} u(x) \cdot v(x) \, dx = \int_{3}^{8} 0 \cdot v(x) \, dx$$

$$\int_{3}^{8} u'(x) \cdot v'(x) \, dx - \left[u'(x) \cdot v(x)\right]_{3}^{8} + \int_{3}^{8} u(x) \cdot v(x) \, dx = 0$$

$$\int_{3}^{8} u'(x) \cdot v'(x) \, dx - \left(u'(8) \cdot \underbrace{v(8) - u'(3)}_{=0} \cdot v(3)\right) + \int_{3}^{8} u(x) \cdot v(x) \, dx = 0$$

$$\int_{3}^{8} u'(x) \cdot v'(x) \, dx + \int_{3}^{8} u(x) \cdot v(x) \, dx = 0$$

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The weak solution of the boundary value problem is a function u that fulfills:

$$\begin{cases} u \in U_D = V \\ a(u, v) = b(v) \ \forall v \in V \end{cases}.$$

Problem 3. Consider the following Newton boundary value problem:

$$\left\{ \begin{array}{rcl} -3 \cdot u^{\prime \prime} \left(x \right) & = & f \left(x \right) & \quad \text{v } \Omega = \left(0, L \right) \\ u \left(0 \right) & = & 1 & \quad \\ -3 \cdot u^{\prime} \left(L \right) & = & \alpha \left(u \left(L \right) - 7 \right) \end{array} \right. ,$$

where $L \in \mathbb{R}^+$ a $f \in L_2(\Omega)$. Derive the weak form.

Solution 3. Consider the space $U = H^1(\Omega)$.

For all test functions $v \in V = \{w \in U : w(0) = 0\}$:

$$\int_{0}^{L} -3 \cdot u''(x) \cdot v(x) dx = \int_{0}^{L} f(x) \cdot v(x) dx$$

$$\int_{0}^{L} 3 \cdot u'(x) \cdot v'(x) dx - [3u'(x) \cdot v(x)]_{0}^{L} = \int_{0}^{L} f(x) \cdot v(x) dx$$

$$\int_{0}^{L} 3 \cdot u'(x) \cdot v'(x) dx - \left(\underbrace{\underbrace{3 \cdot u'(L)}_{=-\alpha(u(L)-7)} \cdot v(L) - u'(0) \cdot \underbrace{v(0)}_{=0}\right)}_{=0} = \int_{0}^{L} f(x) \cdot v(x) dx$$

$$\int_{0}^{L} 3 \cdot u'(x) \cdot v'(x) dx + (\alpha(u(L)-7) \cdot v(L)) = \int_{0}^{L} f(x) \cdot v(x) dx$$

$$\int_{0}^{L} 3 \cdot u'(x) \cdot v'(x) dx + \alpha \cdot u(L) \cdot v(L) = \int_{0}^{L} f(x) \cdot v(x) dx + 7\alpha \cdot v(L)$$

$$\int_{0}^{L} 3 \cdot u'(x) \cdot v'(x) dx + \alpha \cdot u(L) \cdot v(L) = \int_{0}^{L} f(x) \cdot v(x) dx + 7\alpha \cdot v(L)$$

The weak solution of the boundary value problem is a function u that fulfills:

$$\begin{cases} u \in U_D = \{w \in U : w(0) = 1\} \\ a(u, v) = b(v) \quad \forall v \in V \end{cases}$$

2 Finite element method in 1d

Problem 4 (Continuation of problem 1). Consider the space $U = H^1(\Omega)$, where $\Omega = (K, L)$, test space $V = \{w \in U : w(K) = w(L) = 0\}$ and the following weak form:

$$\begin{cases} u \in U_D = \{w \in U : w(K) = 4 \land w(L) = 5\} \\ \int\limits_{K}^{L} (2 + \sin x) \cdot u'(x) \cdot v'(x) \, \mathrm{d}x + \int\limits_{K}^{L} 3 \cdot u'(x) \cdot v(x) \, \mathrm{d}x = \int\limits_{K}^{L} x^2 \cdot v(x) \, \mathrm{d}x \quad \forall v \in V \\ \int\limits_{a(u,v)}^{L} (2 + \sin x) \cdot u'(x) \cdot v'(x) \, \mathrm{d}x + \int\limits_{K}^{L} 3 \cdot u'(x) \cdot v(x) \, \mathrm{d}x = \int\limits_{K}^{L} x^2 \cdot v(x) \, \mathrm{d}x \quad \forall v \in V \end{cases}$$

Calculate the local FEM matrix A_E and the local right-hand-side vector \mathbf{b}_E for the segment $E = \langle \pi, 2\pi \rangle$. Use linear finite elements. Assume $K < \pi$ and $L > 2\pi$.

Solution 4. We can simply derive that linear finite elements have the following forms and derivatives at the segment E (i.e. we consider restriction to E):

$$\phi_{1}(x) = \frac{x - 2\pi}{-\pi}, \ \phi'_{1}(x) = -\frac{1}{\pi}$$

$$\phi_{2}(x) = \frac{x - \pi}{\pi}, \ \phi'_{2}(x) = \frac{1}{\pi}$$

The local matrix has the form:

$$A_E = \begin{bmatrix} a_E \left(\phi_1, \phi_1\right) & a_E \left(\phi_2, \phi_1\right) \\ a_E \left(\phi_1, \phi_2\right) & a_E \left(\phi_2, \phi_2\right) \end{bmatrix},$$

where

$$a_{E}(\phi_{1},\phi_{1}) = \int_{\pi}^{2\pi} (2+\sin x) \cdot (\phi'_{1}(x))^{2} dx + \int_{\pi}^{2\pi} 3 \cdot \phi'_{1}(x) \cdot \phi_{1}(x) dx =$$

$$= \frac{1}{\pi^{2}} \int_{\pi}^{2\pi} (2+\sin x) dx - \frac{3}{\pi} \int_{\pi}^{2\pi} \phi_{1}(x) dx = \frac{1}{\pi^{2}} [2x - \cos x]_{\pi}^{2\pi} - \frac{3}{2} =$$

$$= \frac{1}{\pi^{2}} \underbrace{(4\pi - \cos(2\pi) - 2\pi + \cos(\pi))}_{=2\pi - 2} - \frac{3}{2}$$

$$a_{E}(\phi_{1},\phi_{2}) = \int_{\pi}^{2\pi} (2+\sin x) \cdot \phi'_{1}(x) \cdot \phi'_{2}(x) dx + \int_{\pi}^{2\pi} 3 \cdot \phi'_{1}(x) \cdot \phi_{2}(x) dx =$$

$$= -\frac{1}{\pi^{2}} (2\pi - 2) - \frac{3}{2}$$

$$a_{E}(\phi_{2},\phi_{1}) = \int_{\pi}^{2\pi} (2+\sin x) \cdot \phi'_{2}(x) \cdot \phi'_{1}(x) dx + \int_{\pi}^{2\pi} 3 \cdot \phi'_{2}(x) \cdot \phi_{1}(x) dx =$$

$$= -\frac{1}{\pi^{2}} (2\pi - 2) + \frac{3}{2}$$

$$a_{E}(\phi_{2},\phi_{2}) = \int_{\pi}^{2\pi} (2+\sin x) \cdot (\phi'_{2}(x))^{2} dx + \int_{\pi}^{2\pi} 3 \cdot \phi'_{2}(x) \cdot \phi_{2}(x) dx =$$

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$$a_{E}(\phi_{2},\phi_{2}) = \int_{\pi}^{2\pi} (2+\sin x) \cdot (\phi'_{2}(x))^{2} dx + \int_{\pi}^{2\pi} 3 \cdot \phi'_{2}(x) \cdot \phi_{2}(x) dx =$$

$$= \frac{1}{\pi^{2}} (2\pi - 2) + \frac{3}{2}$$

The local right-hand-side vector has the form

$$\mathbf{b}_{E} = \left[\begin{array}{c} b_{E}\left(\phi_{1}\right) \\ b_{E}\left(\phi_{2}\right) \end{array} \right],$$

where

$$b_{E}(\phi_{1}) = \int_{\pi}^{2\pi} x^{2} \cdot \phi_{1}(x) dx = \int_{\pi}^{2\pi} x^{2} \cdot \left(\frac{x - 2\pi}{-\pi}\right) dx = \int_{\pi}^{2\pi} -\frac{x^{3}}{\pi} + 2x^{2} dx =$$

$$= \left[-\frac{x^{4}}{4\pi} + 2\frac{x^{3}}{3}\right]_{\pi}^{2\pi} = -\frac{16\pi^{4}}{4\pi} + \frac{16\pi^{3}}{3} + \frac{\pi^{4}}{4\pi} - \frac{2\pi^{3}}{3} = \frac{11}{12}\pi^{3}$$

$$b_{E}(\phi_{2}) = \int_{\pi}^{2\pi} x^{2} \cdot \phi_{2}(x) dx = \int_{\pi}^{2\pi} x^{2} \cdot \left(\frac{x - \pi}{\pi}\right) dx = \int_{\pi}^{2\pi} \frac{x^{3}}{\pi} - x^{2} dx =$$

$$= \left[\frac{x^{4}}{4\pi} - \frac{x^{3}}{3}\right]_{\pi}^{2\pi} = \frac{16\pi^{4}}{4\pi} - \frac{8\pi^{3}}{3} - \frac{\pi^{4}}{4\pi} + \frac{\pi^{3}}{3} = \frac{17}{12}\pi^{3}$$

Problem 5 (Continuation of problem 2). Consider the space $U = H^1(\Omega)$, where $\Omega = (3,8)$, test space $V = \{w \in U : w(8) = 0\}$ and the following weak form:

$$\begin{cases}
 u \in V \\
 \int_{8}^{8} u'(x) \cdot v'(x) dx + \int_{3}^{8} u(x) \cdot v(x) dx = \underbrace{5 \cdot v(3)}_{b(v)} \quad \forall v \in V \\
 \underbrace{3}_{a(u,v)}
\end{cases}$$

Calculate the extended FEM matrix A and the extended right-hand-side vector \mathbf{b} corresponding to the discretization $\mathcal{T} = \{\langle 3, 5 \rangle, \langle 5, 6 \rangle, \langle 6, 8 \rangle\}$. (Extended = contains also rows/columns corresponding to nodes with Dirichlet b. c.) Use linear finite elements.

Solution 5. First, we can find $a_E(\phi_i, \phi_j)$ for a general segment E. Note that in the case of this bilinear form, we can use substitution to the segment $E = \langle 0, h \rangle$ (see the geometric interpretation of the integration). At this segment, linear finite elements have the following forms and derivatives:

$$\phi_{1}(x) = 1 - \frac{x}{h}, \ \phi'_{1}(x) = -\frac{1}{h}$$

$$\phi_{2}(x) = \frac{x}{h}, \ \phi'_{2}(x) = \frac{1}{h}$$

The calculations can be further simplified by noting that $a_E(\phi_1, \phi_1) = a_E(\phi_2, \phi_2)$ (again use the geometric interpretation of the integration).

$$a_{E}(\phi_{1},\phi_{1}) = a_{E}(\phi_{2},\phi_{2}) = \int_{0}^{h} (\phi'_{2}(x))^{2} dx + \int_{0}^{h} (\phi_{2}(x))^{2} dx =$$

$$= \int_{0}^{h} \frac{1}{h^{2}} dx + \int_{0}^{h} \frac{x^{2}}{h^{2}} dx = \frac{1}{h} + \left[\frac{x^{3}}{3h^{2}}\right]_{0}^{h} = \frac{1}{h} + \frac{h}{3}$$

$$a_{E}(\phi_{1},\phi_{2}) = a_{E}(\phi_{2},\phi_{1}) = \int_{0}^{h} \phi'_{1}(x) \cdot \phi'_{2}(x) dx + \int_{0}^{h} \phi_{1}(x) \cdot \phi_{2}(x) dx =$$

$$= \int_{0}^{h} -\frac{1}{h^{2}} dx + \int_{0}^{h} \frac{x}{h} - \frac{x^{2}}{h^{2}} dx = -\frac{1}{h} + \left[\frac{x^{2}}{2h} - \frac{x^{3}}{3h^{2}}\right]_{0}^{h} = -\frac{1}{h} + \frac{h}{6}$$

The local matrices are obtained by substituting the lengths of the corresponding segments:

The global FEM matrix is constructed using these local matrices:

$$A = \frac{1}{6} \begin{bmatrix} 7 & -1 & 0 & 0 \\ -1 & 7+8 & -5 & 0 \\ 0 & -5 & 8+7 & -1 \\ 0 & 0 & -1 & 7 \end{bmatrix}$$

The construction of local right-hand-side vectors is simple in this case (the only non-zero contribution is given by the value of the Neumann b. c.):

$$\mathbf{b}_{\langle 3,5\rangle} = \left[\begin{array}{c} 5 \\ 0 \end{array} \right], \, \mathbf{b}_{\langle 5,6\rangle} = \left[\begin{array}{c} 0 \\ 0 \end{array} \right], \, \mathbf{b}_{\langle 6,8\rangle} = \left[\begin{array}{c} 0 \\ 0 \end{array} \right].$$

Therefore, the global extended right-hand-side vector \mathbf{b} is

$$\mathbf{b} = \begin{bmatrix} 5 \\ 0 \\ 0 \\ 0 \end{bmatrix}.$$

Problem 6 (Continuation of problem 3). Consider the bilinear form

$$a(u,v) = \int_{0}^{L} 3 \cdot u'(x) \cdot v'(x) dx + \alpha \cdot u(L) \cdot v(L),$$

where $u, v \in H^1((0, L))$. Calculate the local FEM matrix A_E for the segment $E = \langle K, L \rangle$, 0 < K < L. Use linear finite elements.

Solution 6. We can simply derive that linear finite elements have the following forms and derivatives at the segment E (i.e. we consider restriction to E):

$$\phi_1(x) = \frac{x - L}{K - L}, \ \phi'_1(x) = \frac{1}{K - L}$$

 $\phi_2(x) = \frac{x - K}{L - K}, \ \phi'_2(x) = \frac{1}{L - K}$

The local matrix has the form:

$$A_{E} = \left[\begin{array}{cc} a_{E}\left(\phi_{1},\phi_{1}\right) & a_{E}\left(\phi_{2},\phi_{1}\right) \\ a_{E}\left(\phi_{1},\phi_{2}\right) & a_{E}\left(\phi_{2},\phi_{2}\right) \end{array} \right],$$

where

$$a_{E}(\phi_{1}, \phi_{1}) = \int_{K}^{L} 3 \cdot (\phi'_{1}(x))^{2} dx + \alpha \cdot \underbrace{(\phi_{1}(L))^{2}}_{=0} = 3 \left(\frac{1}{K - L}\right)^{2} (L - K) = \frac{3}{L - K}$$

$$a_{E}(\phi_{1}, \phi_{2}) = a_{E}(\phi_{2}, \phi_{1}) = \int_{K}^{L} 3 \cdot \phi'_{1}(x) \cdot \phi'_{2}(x) dx + \alpha \cdot \underbrace{\phi_{1}(L)}_{=0} \cdot \underbrace{\phi_{2}(L)}_{=1} = \frac{3}{K - L}$$

$$a_{E}(\phi_{2}, \phi_{2}) = \int_{K}^{L} 3 \cdot (\phi'_{2}(x))^{2} dx + \alpha \cdot (\phi_{2}(L))^{2} = \frac{3}{L - K} + \alpha$$

Problem 7 (Continuation of problem 3). Consider the linear functional

$$b(v) = \int_{0}^{L} f(x) \cdot v(x) dx + 7\alpha \cdot v(L),$$

where $v \in H^1((0,L))$ a $f(x) = \cos(x)$. Calculate the local right-hand-side vector \mathbf{b}_E for the segment $E = \langle 0, K \rangle$, 0 < K < L. Use linear finite elements.

Solution 7. We can simply derive that linear finite elements have the following forms and derivatives at the segment E (i.e. we consider restriction to E):

$$\phi_{1}(x) = -\frac{x}{K} + 1, \ \phi'_{1}(x) = -\frac{1}{K}$$

$$\phi_{2}(x) = \frac{x}{K}, \ \phi'_{2}(x) = \frac{1}{K}$$

The local right-hand-side vector has the form:

$$\mathbf{b}_{E}=\left[egin{array}{c} b_{E}\left(\phi_{1}
ight) \ b_{E}\left(\phi_{2}
ight) \end{array}
ight],$$

where

$$b_{E}(\phi_{1}) = \int_{0}^{K} \cos(x) \cdot \phi_{1}(x) \, dx + 7\alpha \cdot \underbrace{\phi_{1}(L)}_{=0} = -\frac{1}{K} \underbrace{\int_{0}^{K} x \cdot \cos(x) \, dx}_{K} + \int_{0}^{K} \cos(x) \, dx =$$

$$= -\frac{1}{K} [x \cdot \sin(x)]_{0}^{K} + \frac{1}{K} [-\cos(x)]_{0}^{K} + [\sin(x)]_{0}^{K} = -\frac{\cos(K)}{K} + \frac{1}{K}$$

$$b_{E}(\phi_{2}) = \int_{0}^{K} \cos(x) \cdot \phi_{2}(x) \, dx + 7\alpha \cdot \underbrace{\phi_{2}(L)}_{=0} = \frac{1}{K} \int_{0}^{K} x \cdot \cos(x) \, dx =$$

$$= \frac{1}{K} [x \cdot \sin(x)]_{0}^{K} - \frac{1}{K} [-\cos(x)]_{0}^{K} = \sin(K) + \frac{\cos(K)}{K} - \frac{1}{K}$$

References

[1] Blaheta, R. Matematické modelování a metoda konečných prvků. 2012. URL: http://mi21.vsb.cz/modul/matematicke-modelovani-metoda-konecnych-prvku-numericke-metody-2