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Recurrent Neural Networks

Recurrent Layer

Many prediction problems require memorization capabilities along a particular dimension. Typical examples are time series prediction problems. A common method to address those are Recurrent Neural Networks (RNNs). To implement RNNs we can reuse most algorithms of our framework. The only necessary new components are new layers implementing the specific RNN cells.

1 Refactoring

Task:

Add additional accessors to all layers with trainable weights: Refactor layers Conv, FullyConnected and BatchNormalization to expose their weights with two methods set_weights and get_weights.

2 Activation functions

Two common activation functions which we didn't implement so far will come in handy: The hyperbolic tangent (Tangens Hyperbolicus) and the Sigmoid.

Task:

Implement two <u>classes</u> **TanH** and **Sigmoid** in files: "TanH.py" and "Sigmoid.py" in the folder "Layers".

- Implement the operations forward(input_tensor), backward(error_tensor) for the TanH and the Sigmoid activation function.
- Specifically store *activations* for the dynamic programming component, instead of the **input_tensor**. This is possible because the gradient involves only activations instead of the input (see slides).

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3 Elman Recurrent Neural Network (RNN)

The type of recursive neural networks known as Elman network consists of the simplest RNN cells. They can be modularly implemented as layers.

Task:

Implement a <u>class</u> **RNN** in the file: "RNN.py" in folder "Layers". This <u>class</u> has to provide all the <u>methods</u> required by a trainable layer for our framework.

- Write a <u>constructor</u>, receiving the <u>arguments</u> (input_size, hidden_size, output_size, bptt_length). Here input_size denotes the dimension of the *input vector* while hidden_size denotes the dimension of the *hidden state*. The bptt_length controls how many steps backwards are considered in the calculation of the gradient with respect to the weights. Initialize the hidden state with all zeros.
- Add a <u>method</u> toggle_memory() which switches a boolean member variable representing whether the RNN regards subsequent sequences as a belonging to the same long sequence. In the constructor, initialize this member with False.
- Implement a <u>method</u> **forward(input_tensor)** which returns the **input_tensor** for the next layer. Consider the *batch* dimension as the *time* dimension of a sequence over which the recurrence is performed. The first *hidden_state* for this iteration is all zero if the boolean member variable is False, otherwise restore the hidden state from the last iteration. You can choose to <u>compose</u> parts of the RNN from other *layers* you already implemented.
- Implement a <u>method</u> **backward(error_tensor)** which updates the parameters and returns the **error_tensor** for the next layer. Truncate the calculation of gradients with respect to the weights after the *steps* specified by **bptt_length**. Remember that **optimizers** are decoupled from our *layers*.
- Implement the accessor <u>methods</u> **get_gradient_weights()**, **get_weights()** and **set_weights(weights)**. Here the **weights** are not uniquely defined. Return all weights involved in calculating the *hidden_state*.
- To be able to reuse all regularizers, add the <u>methods</u> to add an optimizer as **set_optimizer(optimizer)** and to calculate the loss caused by *regularization* as **calculate_regularization_loss()** as introduced in the regularization exercise. Finally add the <u>method</u> initialize(weights_initializer, bias_initializer) to use our *intializers*.



4 Long Short-Term Memory (LSTM)

Elman networks severely suffer from the vanishing gradient problem. A common method to remedy this is to use more complicated RNN cells. The classical example is the LSTM cell.

Task:

Implement a <u>class</u> **LSTM** in the file: "LSTM.py" in folder "Layers". This <u>class</u> has to provide all the <u>methods</u> required by a trainable layer for our framework.

- Write a <u>constructor</u>, receiving the <u>arguments</u> (input_size, hidden_size, output_size, bptt_length). Here input_size denotes the dimension of the *input vector* while hidden_size denotes the dimension of the *hidden state*. The bptt_length controls how many steps backwards are considered in the calculation of the gradient with respect to the weights. Initialize the hidden state with all zeros.
- Add a <u>method</u> **toggle_memory()** which switches a boolean member variable representing whether the RNN regards subsequent sequences as a belonging to the same long sequence. In the constructor, initialize this member with False. This is required to switch form BPTT to TBPTT.
- Implement a <u>method</u> **forward(input_tensor)** which returns the **input_tensor** for the next layer. Consider the *batch* dimension as the *time* dimension of a sequence over which the recurrence is performed. The first *hidden_state* for this iteration is all zero if the boolean member variable is False, otherwise restore the hidden state from the last iteration. You can choose to <u>compose</u> parts of the LSTM from other *layers* you already implemented.
- Implement a <u>method</u> **backward(error_tensor)** which updates the parameters and returns the **error_tensor** for the next layer. Truncate the calculation of gradients with respect to the weights after the *steps* specified by **bptt_length**. Remember that **optimizers** are decoupled from our *layers*.
- Implement the accessor <u>methods</u> **get_gradient_weights()**, **get_weights()** and **set_weights(weights)**. Return all weights involved in calculating the *hidden_state*.
- To be able to reuse all regularizers, add the <u>methods</u> to add an optimizer as **set_optimizer(optimizer)** and to calculate the loss caused by *regularization* as **calculate_regularization_loss()** as introduced in the regularization exercise. Finally add the <u>method</u> initialize(weights_initializer, bias_initializer) to use our *intializers*.

Deep Learning Exercises [DL E] Exercise 4 Recurrent Neural Networks L Mill N Ravikumar T Würfl K Breininger S Gündel M Hoffmann F Thamm F Denzinger December 17, 2018



5 Test, Debug and Finish

Now we implemented everything.

Task:

Debug your implementation until every test in the suite passes. You can run all tests by providing no commandline parameter.