

1 Basic Concepts about Clustering

Let d be a positive integer and \mathbb{R} the field of real numbers. For a set S of n points $\vec{p}_i \in \mathbb{R}^d$, we denote by $|S|$ the number of points of S . We consider the problem that we will call “ k -means globally optimum clustering”.

Definition 1. The “ k -means globally optimum clustering” is to split $S \subset \mathbb{R}^d$ of n points \vec{p}_i , $i = 1, \dots, n$ into k disjoint nonempty subsets S_1, \dots, S_k called clusters in such a way that the following expression is minimized:

$$f_{S_1, \dots, S_k}(S) = \sum_{j=1}^k \sum_{\vec{p} \in S_j} \|\vec{p} - \vec{q}_j\|^2, \quad \text{where } \vec{q}_j = \frac{\sum_{\vec{p} \in S_j} \vec{p}}{|S_j|}.$$

S_1, \dots, S_k is called an optimal partition of S .

It is well known that, given S , there always exists $\vec{q}_1, \dots, \vec{q}_k$ such that the partition defined as,

$$S_j = \bigcap_{l=1}^k \{\vec{p} \in S : \|\vec{p} - \vec{q}_j\|^2 \leq \|\vec{p} - \vec{q}_l\|^2\},$$

is an optimal partition.¹ Indeed, the common approach to attack this problem is to use *Lloyd’s heuristic* [2], which was first used in [3] and, under minor modifications, performs quite well in practice, see [1, 4].

References

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- [2] Stuart P. Lloyd. Least squares quantization in PCM. *IEEE Transactions on Information Theory*, 28(2):129–137, March 1982.
- [3] James B. MacQueen. Some methods for classification and analysis of multivariate observations. In *Proceedings of the 5th Berkeley Symposium on Mathematical Statistics and Probability*, volume 1, pages 281–297. University of California Press, 1967.
- [4] Chen Zhang and Shixiong Xia. K -means clustering algorithm with improved initial center. In *Knowledge Discovery and Data Mining, 2009. WKDD 2009. Second International Workshop on*, pages 790–792, jan. 2009.

¹Using this definition it could be that one point belong to more than one clusters. Fortunately, it is always possible to solve the ties in a reasonable manner