

Midterm Examination – EE092IU

Date: Nov 5th, 2019

Duration: Unlimited

SUBJECT: DIGITAL SIGNAL PROCESSING-EE092IU

Instructions: Ten A4 pages of notes are allowed in the exam. Answer 5 of 6 given questions

Question 1:

By definition, the first and second of Fibonacci numbers are 0 and 1 (e.g. $x(0) = 0$ and $x(1) = 1$), and each subsequent number is the sum of the previous two.

- Write the first ten values of the Fibonacci sequence
- Express and sketch the sequence in (a) versus the Delta function (Impulse)
- Assumed the signal $x[n]$ in (a) is the input of a system with the impulse response $h[n] = \{-1, 2, 0, 1\}$. Using the convolution table to calculate the output signal $y[n] = x[n] * h[n]$
- Repeat the question (c) by using the 4-samples-block- Over Add Block algorithm?

Question 2:

A Causal discrete time LTI system is described by

$$y[n] - \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = x[n]$$

Where $x[n]$ and $y[n]$ are the input and output of the system, respectively

- Determine the frequency response $H(\omega)$ of the system.
- Find the impulse response $h[n]$ of the system
- Realize the block diagram of the system

Hint: Use the delay property of the Fourier Transform and $H(\omega) = Y(\omega)/X(\omega)$

Question 3:

Consider the following sound wave, where t is in milliseconds

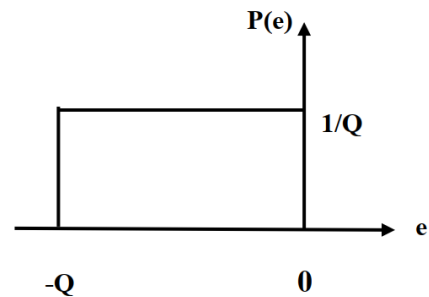
$$x(t) = \sin(10\pi t) + \sin(90\pi t) + 2 \sin(40\pi t) \cos(20\pi t)$$

This signal is prefiltered by an analog antialiasing prefilter $H(f)$ and then sampled at an audio rate of 40 kHz. The resulting samples are immediately reconstructed using an ideal reconstructor. Determine the output $y_a(t)$ of the reconstructor in the following cases and compare it with the audible part of $x(t)$:

- When there is no prefilter, that is, $H(f) = 1$.
- When $H(f)$ is an ideal prefilter with cut off of 20 kHz.
- When $H(f)$ is a practical prefilter that has a flat passband up to 20 kHz and attenuates at a rate of 48 dB/octave beyond 20 kHz (You may ignore the effects of the phase response of the filter.)

Question 4:

Find the mean and noise power of the quantization if the quantized value x_Q is obtained by truncation of x instead of rounding, show that the truncation error $e = x_Q - x$ will be in the interval $-Q < e \leq 0$. Assume a uniform probability density $p(e)$ over this interval, that is



$$p(e) = \begin{cases} \frac{1}{Q}, & -Q < e \leq 0 \\ 0, & \text{otherwise} \end{cases}$$

Question 5:

The Impulse response $h[n]$ of a filter is non-zero over the index range of n be $[3,6]$. The input signal $x[n]$ to this filter is non-zero over the index range of n be $[10,20]$.

Consider the direct and LTI forms of convolution

$$y[n] = \sum_m h[m]x[n-m] = \sum_m x[m]h[n-m]$$

- Determine the overall index range n for the output $y[n]$. For each n , determine the corresponding summation range over m , for both the direct and LTI forms.

- b) Assume $h[n] = 1$ and $x[n] = 1$ over their respective index ranges. Calculate and sketch the output $y[n]$ using the direct form of the Convolution. Identify (with an explanation) the input on/off transient and steady state parts of $y[n]$.

Question 6:

Determine whether the discrete time systems described by the following I/O equation are linear and/or time-invariant

- a) $y[n] = 3x[n] + 5$
- b) $y[n] = x^2[n - 1] + x[2n]$
- c) $y[n] = e^{x[n]}$

Good luck!