

66) at $t_1 = 4s$
 $t_2 = 10s$
 $\Delta t = 10 - 4 = 6s$
 $\Rightarrow 6s = \frac{3}{4}t \Rightarrow t = 8s$
 $T = \frac{2\pi r}{v}$

$\Rightarrow r = \frac{vT}{2\pi} = \frac{0.8}{2\pi} = 0.127m$

a) $\Rightarrow x = 5 + 3.14 \cdot 0.127 = 1.9m$

b) $8m$

$8.82, 0.1m$

20) $v_{og} = v_{ow} + v_{wg}$

a) $14\hat{i} + (-9)\hat{j} = 5\hat{i}$

$v_{og} + (-9)\hat{j} = 5\hat{i}$

$\Rightarrow v = 5km/h$

b) $|v_{og}| + x$

c) $\vec{v}_{og} = \vec{v}_{ow} + \vec{v}_{wg}$

e) $(-6\hat{i} - 4\hat{j}) = -11\hat{i}$

the main guide

15 $v_{og} = 11km/h$

76) $v_{pg} = \frac{g \cdot 0.8}{2} = 450km/h$

$v_{pw} = 500 \sin 20^\circ + \cos 20^\circ \cdot 200$
 $\hat{h} = 121$

$v_{pg} = v_{pw} + v_{wg}$

$\Rightarrow v = -171km/h$

$\Rightarrow v = \sqrt{171^2 + 20^2} = 172.10km/h$

a) $\cos \theta = \frac{-171}{-172}$

$\theta = \cos^{-1} \frac{-171}{-172} = 6.6^\circ$