Q1.

a)

Since, we have: $f(t) = tu(t) \rightarrow F(s) = \mathcal{L}\{f(t)\} = 1/s^2$

Let: g(t) = (f * f)(t), it leads to:

$$G(s) = \mathcal{L}{g(t)} = \mathcal{L}{(f * f)(t)} = F(s).F(s)$$
$$\to G(s) = \frac{1}{s^4} \to g(t) = \mathcal{L}^{-1}\left{\frac{1}{s^4}\right} = \frac{t^3}{6}$$

Thus,

$$(f*f)(t) = \frac{t^3}{6}$$

b)

Given that:

$$\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + 2y = \delta(t - \pi) \ (*), \quad y(0) = 1, \quad y'(0) = 0$$

Let $Y(s) = \mathcal{L}\{y(t)\}$, it holds that:

$$\mathcal{L}{y'(t)} = sY(s) - y(0) = sY(s) - 1$$

$$\mathcal{L}{y''(t)} = s^2Y(s) - sy(0) - y'(0) = s^2Y(s) - s$$

Taking Laplace transform both sides of (*), we obtain:

$$[s^{2}Y(s) - s] + 2[sY(s) - 1] + 2Y(s) = e^{-\pi s}$$

$$\leftrightarrow Y(s)(s^{2} + 2s + 2) = s + 2 + e^{-\pi s}$$

$$\leftrightarrow Y(s) = \frac{s + 2 + e^{-\pi s}}{s^{2} + 2s + 2}$$

$$\leftrightarrow Y(s) = \frac{s + 1 + 1}{(s + 1)^{2} + 1^{2}} + \frac{1}{(s + 1)^{2} + 1^{2}}e^{-\pi s}$$

$$\to y(t) = \mathcal{L}^{-1}\{Y(s)\} = (e^{-t}\cos t + e^{-t}\sin t)u(t) + e^{-(t-\pi)}\sin(t-\pi)u(t-\pi)$$

Thus, the solution of the given differential equation is:

$$y(t) = (e^{-t}\cos t + e^{-t}\sin t)u(t) + e^{-(t-\pi)}\sin(t-\pi)u(t-\pi)$$

Q2.

Given that:

$$L\frac{di}{dt} + Ri = E[u(t) - u(t - a)] \ (*), \qquad i(0) = 0$$

Let $I(s) = \mathcal{L}\{i(t)\} \rightarrow \mathcal{L}\{i'(t)\} = sI(s) - i(0) = sI(s)$

Taking Laplace transform both sides of (*), we obtain:

$$LsI(s) + RI(s) = E \frac{1}{s} (1 - e^{-as})$$

$$\leftrightarrow I(s)(Ls + R) = \frac{E}{s} (1 - e^{-as})$$

$$\leftrightarrow I(s) = \frac{E}{s(Ls + R)} (1 - e^{-as})$$

$$\leftrightarrow I(s) = \frac{E}{r} \left(\frac{1}{s} - \frac{1}{s + R/L}\right) (1 - e^{-as})$$

$$\to I(s) = \frac{E}{r} \left(\frac{1}{s} - \frac{1}{s + R/L}\right) (1 - e^{-as})$$

$$\to I(t) = \mathcal{L}^{-1} \{I(s)\} = \frac{E}{r} \left(1 - e^{-\frac{R}{L}t}\right) u(t) - \frac{E}{r} \left(1 - e^{-\frac{R}{L}(t - a)}\right) u(t - a)$$

Thus, the current with time *t* is:

$$i(t) = \frac{E}{R} \left(1 - e^{-\frac{R}{L}t} \right) u(t) - \frac{E}{R} \left(1 - e^{-\frac{R}{L}(t-a)} \right) u(t-a)$$

Cal 3 2019/06

Q3.

Given that:
$$f(t) = 5 \sin \frac{t}{2}, \quad 0 \le t \le 2\pi, \qquad T = 2\pi \to \omega = \frac{2\pi}{T} = 1$$
a)
$$\bullet a_0 = \frac{2}{T} \int_{t_0}^{t_0 + T} f(t) dt = \frac{2}{2\pi} \int_0^{2\pi} 5 \sin \frac{t}{2} dt = \frac{20}{\pi}$$

$$\bullet a_n = \frac{2}{T} \int_{t_0}^{t_0 + T} f(t) \cos(n\omega t) dt = \frac{2}{2\pi} \int_0^{2\pi} 5 \sin \frac{t}{2} \cos(nt) dt$$

$$= \frac{5}{2\pi} \left[\frac{\cos[t(\frac{1}{2} - n)]}{\frac{1}{2} - n} + \frac{\cos[t(\frac{1}{2} + n)]}{\frac{1}{2} + n} \right]_0^{2\pi}$$

$$= \frac{20}{\pi (1 - 4n^2)}$$

$$\bullet b_n = \frac{2}{T} \int_{t_0}^{t_0 + T} f(t) \sin(n\omega t) dt = \frac{2}{2\pi} \int_0^{2\pi} 5 \sin \frac{t}{2} \sin(nt) dt$$

$$= \frac{5}{2\pi} \left[\frac{\sin[t(\frac{1}{2} - n)]}{\frac{1}{2} - n} + \frac{\sin[t(\frac{1}{2} + n)]}{\frac{1}{2} + n} \right]_0^{2\pi}$$

$$= 0$$

The Fourier series is given by:

$$f(t) = \frac{1}{2}a_0 + \sum_{n=1}^{+\infty} a_n \cos(n\omega t) + \sum_{n=1}^{+\infty} b_n \sin(n\omega t)$$
$$= \frac{10}{\pi} + \sum_{n=1}^{+\infty} \frac{20}{\pi (1 - 4n^2)} \cos(nt)$$

b)

Since we have: $f(t) = 5 \sin(\frac{t}{2}) \rightarrow f(0) = 0$

Therefore,

$$f(0) = \frac{10}{\pi} + \sum_{n=1}^{+\infty} \frac{20}{\pi (1 - 4n^2)} = 0$$

$$\rightarrow \sum_{n=1}^{+\infty} \frac{20}{\pi (4n^2 - 1)} = \frac{10}{\pi}$$

$$\leftrightarrow \sum_{n=1}^{+\infty} \frac{1}{4n^2 - 1} = \frac{1}{2}$$

$$\rightarrow \frac{1}{1.3} + \frac{1}{3.5} + \frac{1}{5.7} + \dots = \frac{1}{2}$$

Q4.

a)

Let:

$$Y(z) = \frac{z^2 + z}{(z - 2)^2}$$

$$\to \frac{Y(z)}{z} = \frac{z + 1}{(z - 2)^2} = \frac{3}{(z - 2)^2} + \frac{1}{z - 2}$$

Cal 3 2019/06

$$\rightarrow Y(z) = \frac{3z}{(z-2)^2} + \frac{z}{z-2}$$

Thus,

$$Z^{-1}\left\{\frac{z^2+z}{(z-2)^2}\right\} = Z^{-1}\left\{\frac{3z}{(z-2)^2} + \frac{z}{z-2}\right\} = 3n2^{n-1} + 2^n$$

b)

Given that:

$$\begin{cases} x_{n+1} = x_n - 2y_n (1) \\ y_{n+1} = -6y_n (2) \end{cases} \quad x_0 = -1, y_0 = 3$$

Let: $X(z) = Z\{x_n\}, Y(z) = Z\{y_n\}$

$$\to \begin{cases} \mathcal{Z}\{x_{n+1}\} = zX(z) - zx_0 = zX(z) + z \\ \mathcal{Z}\{y_{n+1}\} = zY(z) - zy_0 = zY(z) - 3z \end{cases}$$

Taking Z-transform both side of (2), we obtain:

$$(2) \to zY(z) - 3z = -6Y(z)$$

$$\to Y(z) = \frac{3z}{z+6} \to y_n = Z^{-1}\{Y(z)\} = 3(-6)^n$$

Taking Z-transform both side of (1), we obtain:

$$(1) \to zX(z) + z = X(z) - 2Y(z)$$

$$\to X(z)(z-1) = -\frac{6z}{z+6} - z$$

$$\to \frac{X(z)}{z} = -\frac{6}{(z+6)(z-1)} - \frac{1}{z-1} = \frac{6/7}{z+6} - \frac{13/7}{z-1}$$

$$\to X(z) = \frac{6}{7} \frac{z}{z+6} - \frac{13}{7} \frac{z}{z-1} \to x_n = Z^{-1} \{X(z)\} = \frac{6}{7} (-6)^n - \frac{13}{7}$$

Thus, the solution of the given system difference equations is:

$$\begin{cases} x_n = \frac{6}{7}(-6)^n - \frac{13}{7} \\ y_n = 3(-6)^n \end{cases}$$