KCL at node - vi:

$$\frac{v - v_s}{R_1} + \frac{v_* - v_o}{R_2} = 0$$

$$\frac{-v_i - v_s}{R_n} + \frac{-v_i - v_o}{R_2} = 0$$
With  $\sqrt{N}$   $\sqrt{N}$ 

$$= \frac{v_i - v_s}{R_1} + \frac{v_i - Av_i}{R_2} = 0$$

$$\frac{v_s}{R_1} = \frac{v_i}{R_1} + \frac{v_i}{R_2} + \frac{Av_i}{R_2} = -v_i \left(\frac{1}{R_1} + \frac{1}{R_2} + \frac{A}{R_2}\right)$$

. Feedback network:

$$v_{g} = v_{s} - v_{i} = -v_{i} \left(1 + \frac{R_{1}}{R_{2}} + \frac{AR_{1}}{R_{2}}\right) - v_{i}$$

$$= -v_{i} \left(2 + \frac{R_{1}}{R_{2}} + \frac{AR_{1}}{R_{2}}\right)$$

$$= -\frac{v_{o}}{A} \left(2 + \frac{R_{1}}{R_{2}} + \frac{AR_{1}}{R_{2}}\right)$$

$$= \frac{1}{2 + \frac{R_{1}}{R_{2}} + \frac{R_{1}}{R_{2}}}$$

$$= \frac{1}{B}$$

$$\beta = -\frac{R_{1}}{R_{1}}, \text{ be cause } \frac{2 + \frac{R_{1}}{R_{2}}}{A} \Rightarrow 0$$

Scarnica with Can