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MIDTERM REVIEW

Chapter 4: Magnetism

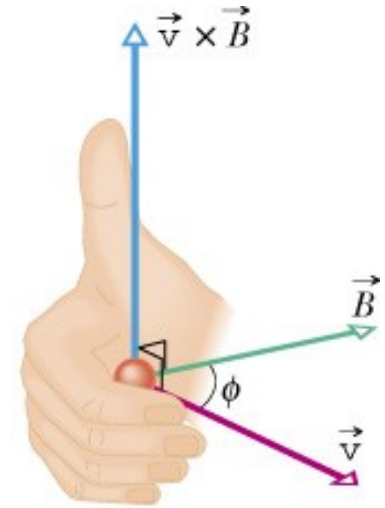
- Magnetic field: \vec{B} , unit: T - Tesla
- Magnetic force: $\vec{F}_B = q\vec{v} \times \vec{B}$

$$F_B = |q| v B \sin \phi$$

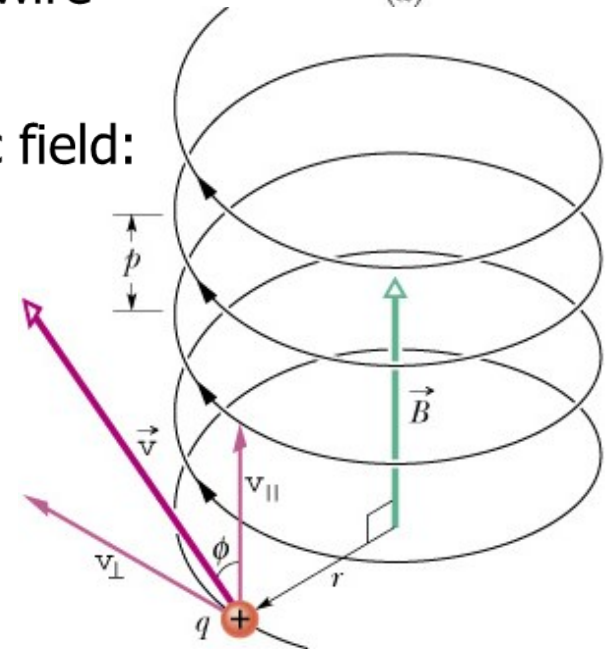
- The Hall effect: conduction electrons in a wire are deflected by a magnetic field.
- Motion of a charged particle in a magnetic field:

$$F_B = qvB = m \frac{v^2}{r}$$

$$T = \frac{2\pi r}{v} = \frac{2\pi m}{qB} \quad r = \frac{mv}{qB}$$



(a)



- Magnetic Force on a Current-Carrying Wire:

$$\vec{F}_B = i\vec{L} \times \vec{B}$$

$$F_B = iLB \sin \phi$$

$$d\vec{F}_B = id\vec{L} \times \vec{B}$$

- Magnetic Torque on a Current-Carrying Wire:

$$\tau = N\tau' = NiAB \sin \theta$$

- Magnetic dipole moment:

$$\mu = NiA$$

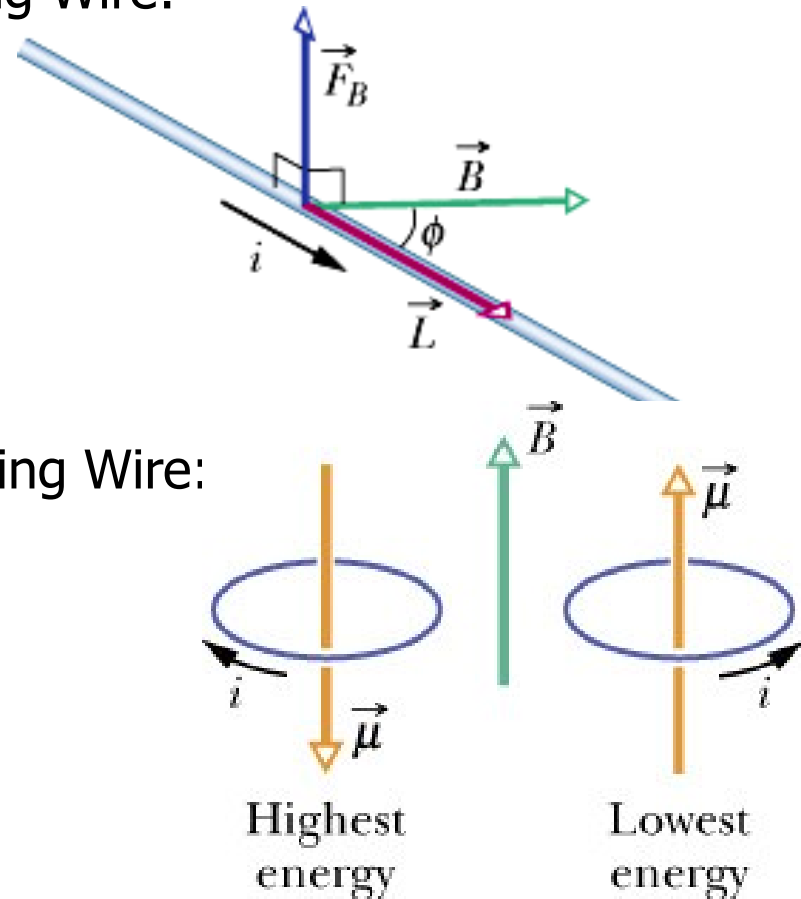
- Torque:

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

$$\tau = \mu B \sin(\vec{\mu}, \vec{B})$$

- Potential energy:

$$U(\theta) = -\vec{\mu} \cdot \vec{B} = -\mu B \cos \theta$$



- The Biot-Savart law:

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{id\vec{s} \times \vec{r}}{r^3}$$

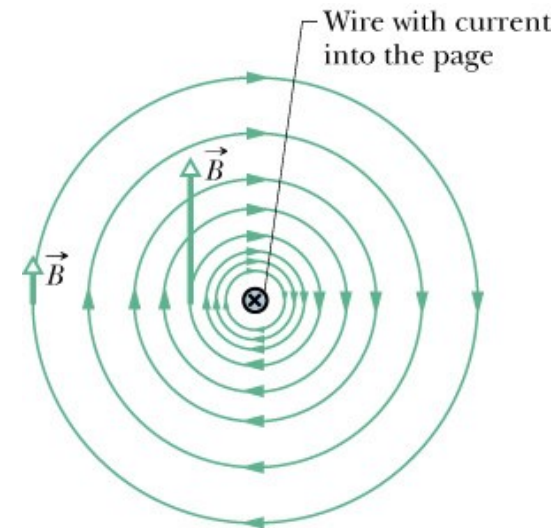
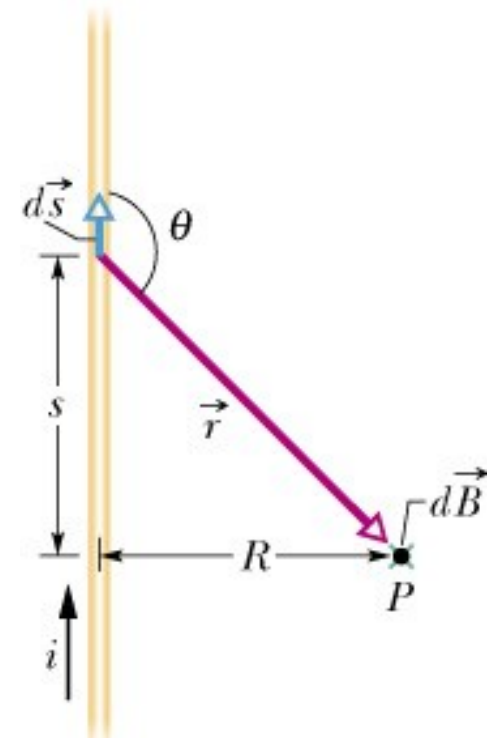
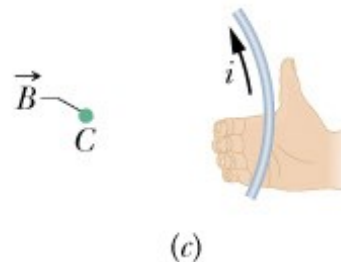
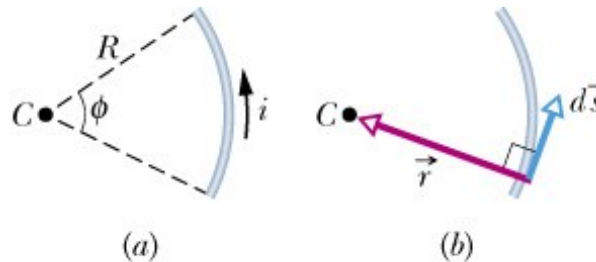
- Magnetic Field Due to a Current in a Long Straight Wire:

$$dB = \frac{\mu_0}{4\pi} \frac{id\vec{s} \sin \theta}{r^2}$$

$$B = \frac{\mu_0 i}{2\pi R}$$

- Magnetic Field Due to a Current in a Circular Arc of Wire

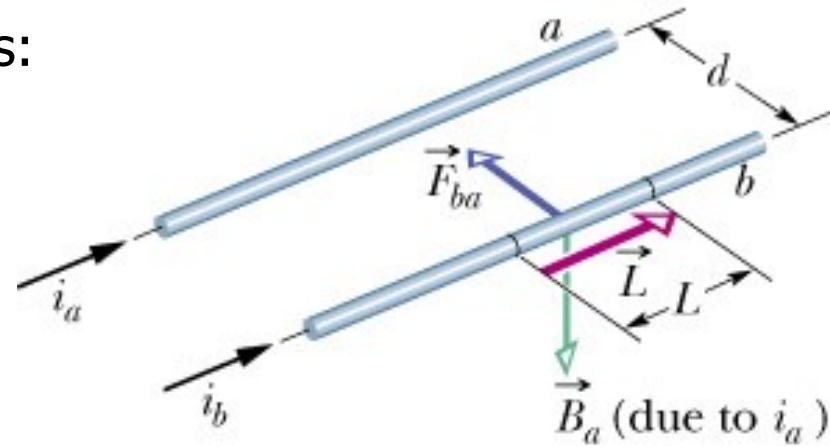
$$B = \frac{\mu_0 i \phi}{4\pi R}$$



- Force Between Two Parallel Currents:

$$\vec{F}_{ba} = i_b \vec{L} \times \vec{B}_a$$

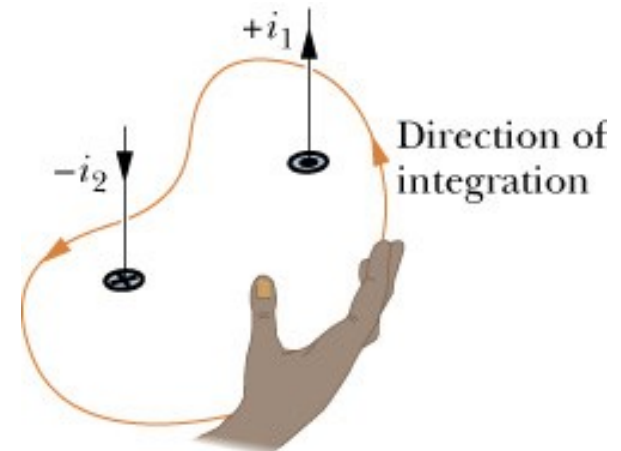
$$F_{ba} = \frac{\mu_0 L i_a i_b}{2\pi d}$$



- Ampere's Law

$$\oint \vec{B} d\vec{s} = \mu_0 i_{\text{enc}}$$

$$i_{\text{enc}} = i_1 - i_2$$



- The Magnetic Field Outside a Long Straight Wire with Current:

$$B = \frac{\mu_0 i}{2\pi r}$$

- The Magnetic Field Inside a Long Straight Wire with Current:

$$B = \left(\frac{\mu_0 i}{2\pi R^2} \right) r$$

- Magnetic Field of a Solenoid:

$$B = \mu_0 i n$$

$$n \leftarrow n = \frac{N}{L}$$

- Magnetic Field of a Toroid:

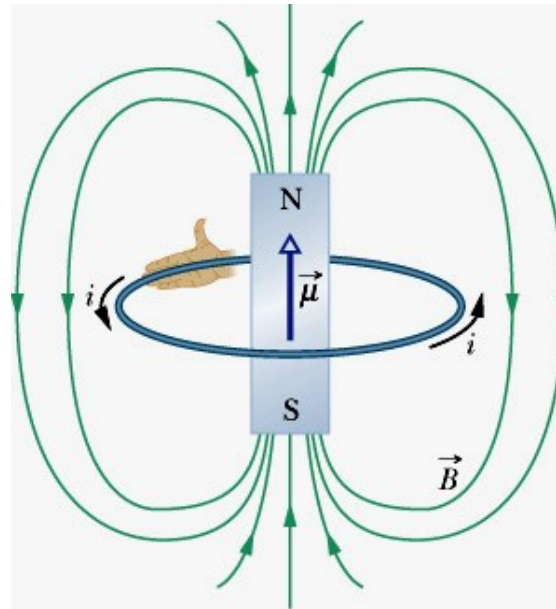
$$B = \frac{\mu_0 i N}{2\pi r}$$

- The Magnetic Field of a Current-Carrying Coil:

$$\vec{B}(z) = \frac{\mu_0}{2\pi} \frac{\vec{\mu}}{z^3}$$

$$B(z) = \frac{\mu_0 N i A}{2\pi z^3}$$

$z \sim$



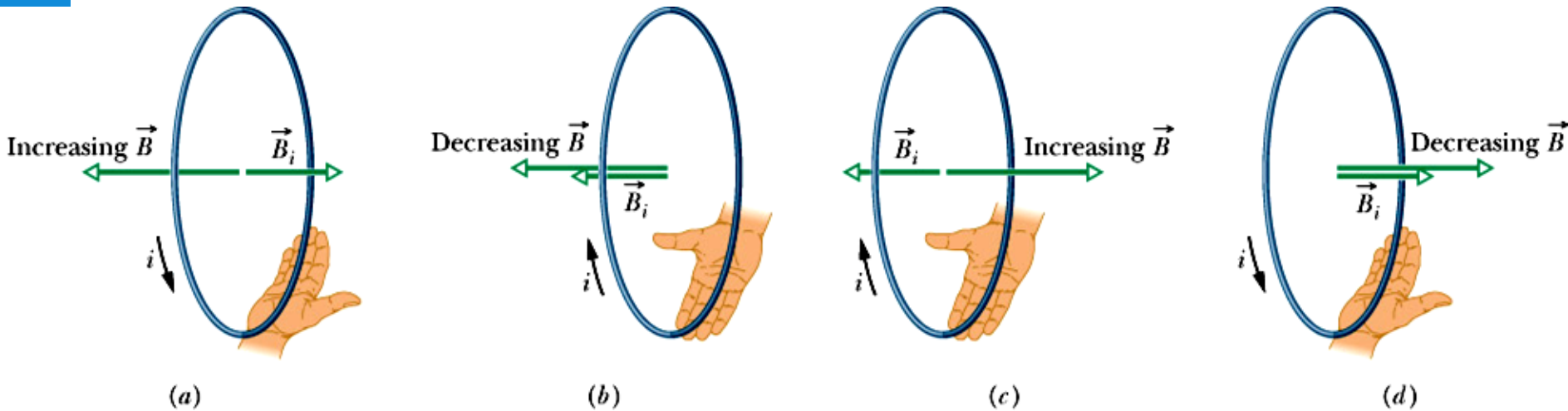
Chapter 5: Electromagnetic Induction

- Faraday's law: induced emf:

$$\mathcal{E} = -\frac{d\Phi_B}{dt}$$

$$\Phi_B = \int \vec{B} d\vec{A}$$

- Len's law:



- Induced electric field:

$$\oint \vec{E} d\vec{s} = -\frac{d\Phi_B}{dt}$$

- Inductance L (unit: Henry):

$$L = \frac{N\Phi_B}{i}$$

- Inductance of a solenoid:

$$\frac{L}{l} = \mu_0 n^2 A$$

- Self-Induced emf:

$$\mathcal{E}_L = -L \frac{di}{dt}$$

- RL Circuits

- Rise of current:

$$i = \frac{\mathcal{E}}{R} (1 - e^{-t/\tau_L})$$

- Decay of current:

$$i = \frac{\mathcal{E}}{R} e^{-t/\tau_L} = i_0 e^{-t/\tau_L}$$

- Magnetic potential energy:

$$U_B = \frac{1}{2} Li^2$$

Chapter 6: Alternating Current Circuits

- LC Oscillations: Conservation of energy

$$U_E = \frac{q^2}{2C} = \frac{Q^2}{2C} \cos^2(\omega t + \phi)$$

$$U_B = \frac{1}{2} L i^2 = \frac{1}{2} L \omega^2 Q^2 \sin^2(\omega t + \phi)$$

$$q = Q \cos(\omega t + \phi)$$

$$i = -I \sin(\omega t + \phi)$$

$$\omega = \frac{1}{\sqrt{LC}} \quad \omega = 2\pi f$$

- Alternating current: $\mathcal{E} = \mathcal{E}_m \sin \omega_d t$

$$i = I \sin(\omega_d t - \phi)$$

- Resistive load: $v_R = \mathcal{E}_m \sin \omega_d t = V_R \sin \omega_d t$

$$i_R = \frac{v_R}{R} = \frac{V_R}{R} \sin \omega_d t$$

- Capacitive load: $v_C = V_C \sin \omega_d t$

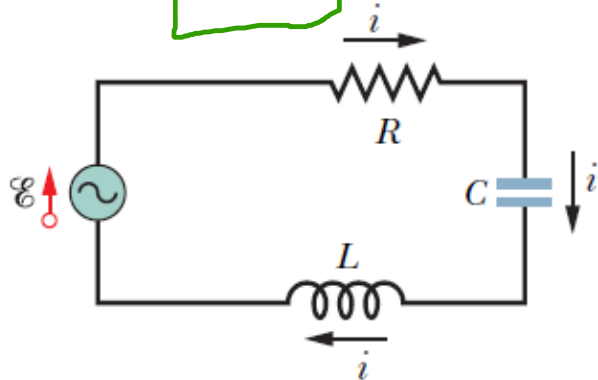
$$i_C = I_C \sin(\omega_d t + 90)$$

$$X_C = \frac{1}{\omega_d C}$$

- Inductive load: $v_L = V_L \sin \omega_d t$
 $i_L = I_L \sin(\omega_d t - 90)$

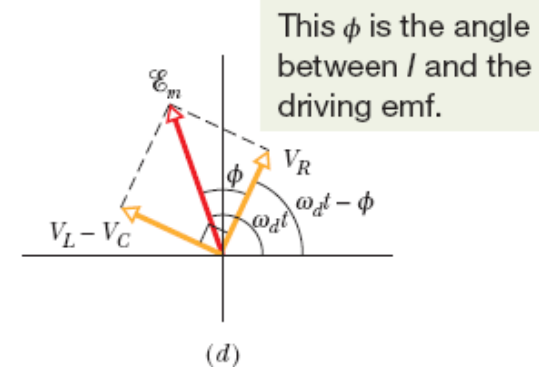
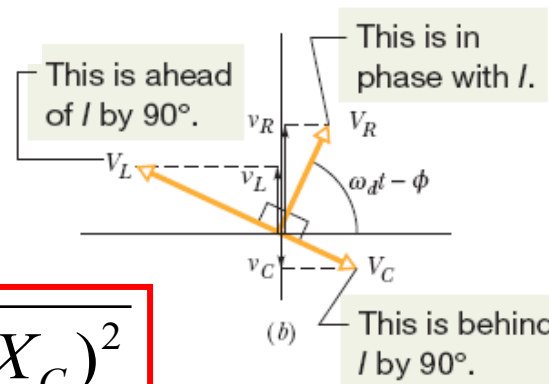
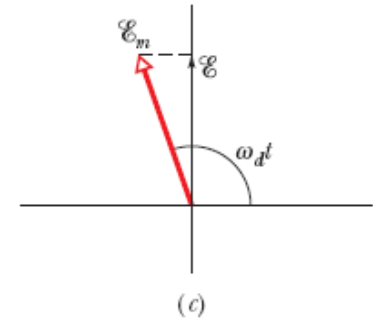
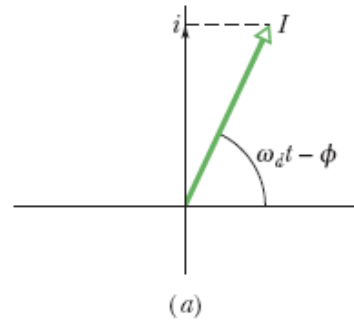
$$X_L = \omega_d L$$

- The Series RLC Circuit:



$$\varepsilon = \varepsilon_m \sin \omega_d t$$

$$i = I \sin(\omega_d t - \phi)$$



$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

$$I = \frac{\varepsilon_m}{\sqrt{R^2 + (\omega_d L - 1/\omega_d C)^2}}$$

$$\tan \phi = \frac{X_L - X_C}{R}$$

- Resonance:

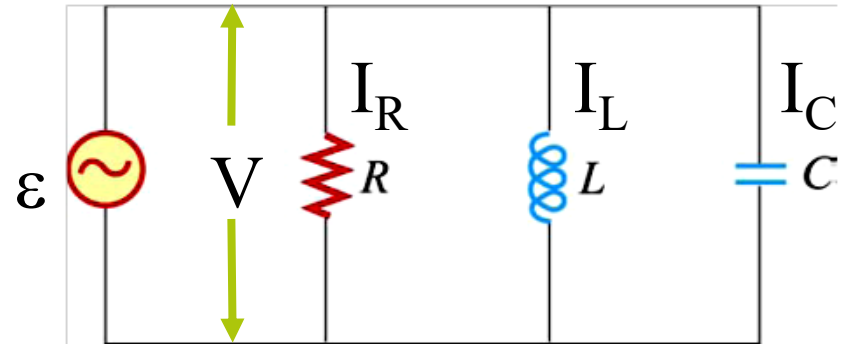
$$\omega_d = \omega = \frac{1}{\sqrt{LC}}$$

$$\omega = 2\pi f$$

- The Parallel RLC Circuit

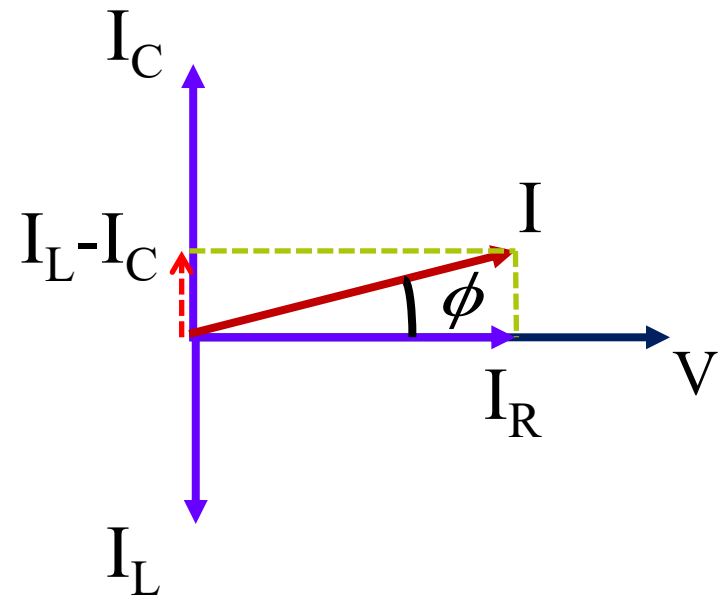
$$\varepsilon = \varepsilon_m \sin \omega_d t$$

$$i = I_m \sin(\omega_d t - \phi)$$



$$\frac{1}{Z} = \sqrt{\left(\frac{1}{R}\right)^2 + \left(\frac{1}{\omega_d L} - \omega_d C\right)^2}$$

$$\tan \phi = \frac{\frac{1}{\omega_d L} - \omega_d C}{\frac{1}{R}}$$



- Power in Alternating Current Circuits:

$$V_{rms} = \frac{V}{\sqrt{2}} \text{ and } \varepsilon_{rms} = \frac{\varepsilon_m}{\sqrt{2}}$$

$$I_{rms} = \frac{\varepsilon_{rms}}{Z} = \frac{\varepsilon_{rms}}{\sqrt{R^2 + (X_L - X_C)^2}}$$

$$I = \frac{V}{R}$$

$$P_{avg} = \varepsilon_{rms} I_{rms} \cos \phi \quad \cos \phi = \frac{VR}{\varepsilon_m} = \frac{IR}{IZ} = \frac{R}{Z}$$

- Transformer:

$$V_S = V_P \frac{N_S}{N_P}$$

$$I_S = I_P \frac{N_P}{N_S}$$

$$R_{eq} = \left(\frac{N_P}{N_S} \right)^2 R$$