# FINAL EXAMINATION

### DIGITAL SIGNAL PROCESSING

Dated: June 24th 2020 - Class IU-2017

Timed allowed: 120 minutes

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#### **INSTRUCTION:**

- 1. One A4 page of notes is allowed in the exam
- 2. Answer all questions

### Question 1: (20 Marks)

A linear time-invariant (LTI) system is characterized by the system function

$$H(z) = \frac{3 - 4z^{-1}}{1 - 3.5z^{-1} + 1.5z^{-2}}$$

Sketch the Pole/Zero Pattern then specify the ROC of H(z) and determine the inverse Z-tranform of H(Z) for the following conditions:

- a. The system is stable
- b. The system is causal
- c. The system is anticausal.

### Question 2: (20 Marks)

The input  $x(n) = 2^n[u(n)-3u(n-1)]$  to an LTI system produces the output  $y(n)=(3^n-2^n)u(n)$ .

- a. Find the Z-transforms of the x(n) and y(n)?
- b. What are the ROCs of X(z) and Y(z)?
- c. Determine the transfer function of H(z) of the system and its ROC? Then specify the possible impulse response h(n) of the system.
- d. What the h(n) if the system is unstable?
- e. What the h(n) if the system is causal?

## Question 3: (20 Marks)

A causal discrete time sequence h(n) are:

$$h(n)=-2\delta(n)+3\delta(n-1)+2\delta(n-2)+h(n-1)+h(n-2)+h(n-3).$$

- a. Write the first ten number of the sequence, h(n) for n=0, 1, ...,9?
- b. Calculate the modulo-4 wrapped signal of the sequence in (a).
- c. Calculate the 4-DFT of the wrapped signal in (b)
- d. Calculate the 4-FFT of the sequence in (b)
- e. Finally, compute the 4-point IDFT of the result and verify that you recover the mod-4 wrapped version of h(n) in question (b).

## Question 4: (20 Marks)

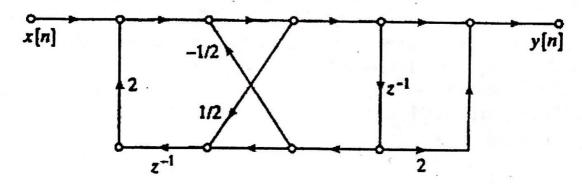
The 2-sided z-transform of transfer function x(n) of a system is given by

$$X(z) = \frac{z^{-1}}{\left(1 - 3z^{-1}\right)\left(1 - 5z^{-1}\right)}$$

- a. Determine all possible ROCs for X(z)
- b. For each ROC in (a), find x(n)
- c. Discuss the stability and causality of each case.
- d. Sketch the pole and zero pattern then draft the frequency response of the system.
- e. Realize the canonical form of the system.

### Question 5: (20 Marks)

The flow graph shown in the figure is an implementation of a causal, LTI system



- a. Draw the transpose of the signal flow graph
- b. Determine the difference equation relating to the input signal x(n) to the y(n)
- c. Find and sketch the pole/zero pattern of the system. Is the system stable?
- d. Realize the system in the direct and canonical form.
- e. Determine y(2) if x(n)=(1/2)n u(n).

#### Good lucks!