VIETNAM NATIONAL UNIVERSITY-HCMC INTERNATIONAL UNIVERSITY

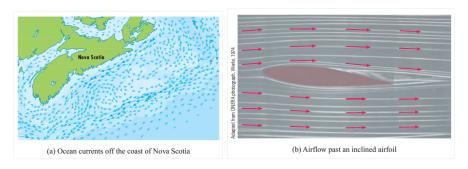


Chapter 5. Vector Calculus

CONTENTS

Introduction

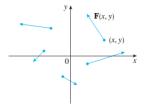
Reference: Chapter 16, textbook by Stewart.



Integrals of vector fields are used in the study of phenomena such as electromagnetism, fluid dynamics, wind speed, and heat transfer.

Definition

Let D be a set in \mathbb{R}^2 (a plane region). A vector field on \mathbb{R}^2 is a function F that assigns to each point (x, y) in D a two-dimensional vector F(x, y).

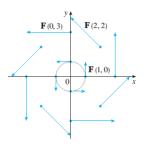


Since F(x, y) is a two-dimensional vector, we can write it in terms of its component functions P and Q as follows:

$$F(x,y) = P(x,y)\mathbf{i} + Q(x,y)\mathbf{j} = \langle P(x,y), Q(x,y) \rangle$$

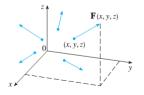
Example

A vector field on \mathbb{R}^2 is defined by $F(x,y) = -y\mathbf{i} + x\mathbf{j}$. Describe by sketching some of the vectors F(x,y).



Definition

Let E be a subset of \mathbb{R}^3 . A vector field on \mathbb{R}^3 is a function F that assigns to each point (x, y, z) in E a three-dimensional vector F(x, y, z).

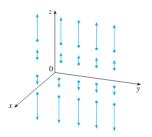


F(x, y, z) can be written as follows:

$$F(x, y, z) = P(x, y, z)\mathbf{i} + Q(x, y, z)\mathbf{j} + R(x, y, z)\mathbf{k}$$
$$F(x, y, z) = \langle P(x, y, z), Q(x, y, z), R(x, y, z)\rangle$$

Example

Sketch the vector field on \mathbb{R}^3 given by $F(x, y, z) = z\mathbf{k}$.

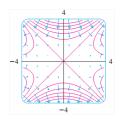


Gradient fields

Gradient fields

If is a scalar function of two variables then the gradient $\nabla f(x,y) = \langle f_x(x,y), f_y(x,y) \rangle$ is really a vector field on \mathbb{R}^2 and is called a gradient vector field.

The figures below shows the gradient vector field of $f(x, y) = x^2y - y^3$.



Likewise, if f is a scalar function of three variables, its gradient is a vector field on \mathbb{R}^3 given by $\nabla f(x, y, z) = \langle f_x(x, y, z), f_y(x, y, z), f_z(x, y, z) \rangle$.

Conservative vector field

Conservative vector field

A vector field F is called a conservative vector field if it is the gradient of some scalar function, that is, if there exists a function V such that $F = \nabla V$. In this situation V is called a potential function for F.

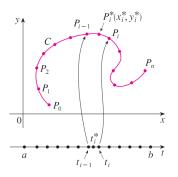
Example

 $V(x, y, z) = xy + yz^2$ is a potential function for the vector field $F = \langle y, x + z^2, 2yz \rangle$ since $F = \nabla V$.

Line integrals

We start with a plane curve given by the parametric equations:

$$x = x(t), y = y(t), a \le x \le b.$$



Riemann sum: $\sum_{i=1}^{n} f(x_i^*, y_i^*) \Delta s_i$ We take the limit of Riemann sum and make the definition by analogy with a single integral.

Line integrals

Definition

If f is defined on a smooth curve C given by x = x(t), y = y(t), $a \le x \le b$, then the line integral of f along C is

$$\int_{C} f(x,y) dS = \lim_{n \to \infty} \sum_{i=1}^{n} f(x_{i}^{*}, y_{i}^{*}) \Delta s_{i}$$

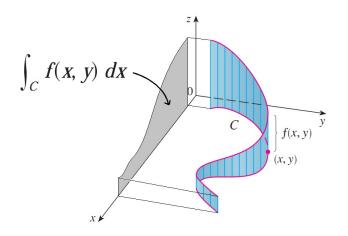
if this limit exists.

Theorem

If f is defined on a smooth curve C given by x = x(t) and y = y(t), then the line integral of f along C is:

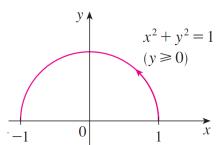
$$\int_{C} f(x,y) ds = \int_{a}^{b} f(x(t),y(t)) \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$

Line integrals: Geometric meaning



 $\int_C f(x,y) ds$ is the area of the blue fence (the blue strip) and $\int_C f(x,y) ds$ is the area of its shadow (projection) on Oxy-plane.

12/1



Example: Evaluate $\int_C (2 + x^2 y) ds$, where C is the upper half of the unit circle $x^2 + y^2 = 1$.

Solution

The the upper half of the unit circle can be parametrized by $x = \cos t$, $y = \sin t$, $0 \le t \le \pi$.

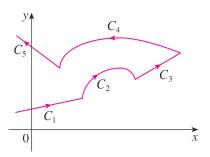
$$\int_{C} (2+x^{2}y) dS = \int_{0}^{\pi} (2+\cos^{2}t\sin t) \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$

$$= \int_{0}^{\pi} \left(2 + \cos^{2}t \sin t\right) \sqrt{\sin^{2}t + \cos^{2}t} dt = 2t - \frac{\cos^{3}t}{3} \Big|_{0}^{\pi} = 2\pi + \frac{2}{3}.$$

Remark on piecewise-smooth curves

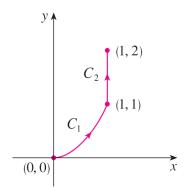
If C is a piecewise-smooth curve, that is, C is a union of a finite number of smooth curves $C_1, C_2, ..., C_n$: $C = C_1 \cup \cdots \cup C_n$ then

$$f(x,y)ds = \int_{C_1} f(x,y)ds + \cdots + \int_{C_n} f(x,y)ds$$



Example

Evaluate $\int_C 2x ds$, where C consists of the arc C_1 of the parabola $y = x^2$ from (0,0) to (1,1) followed by the vertical line segment C_2 from (1,1) to (1,2)



Solution

The parametric equations for C_1 :

$$x = t, y = t^2, 0 \leqslant t \leqslant 1$$

Therefore

$$\int_{C_1} 2x ds = \int_{0}^{1} 2t \sqrt{1 + 4t^2} dt = \frac{5\sqrt{5} - 1}{6}$$

The parametric equations of C_2 are $x = 1, y = t, 1 \le t \le 2$

$$\int_{C_2} 2xds = \int_{1}^{2} 2\sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt = \int_{1}^{2} 2dt = 2$$

$$\int_{C} 2xds = \int_{C_1} 2xds + \int_{C_2} 2xds = \frac{5\sqrt{5} - 1}{6} + 2$$

Solution 2

Remark:

We can also use x or y as an parameter as follows.

The parametric equations for C_1 :

$$x = x, y = x^2, 0 \leqslant x \leqslant 1$$

Therefore

$$\int_{C_1} 2x ds = \int_{0}^{1} 2x \sqrt{1 + 4x^2} dx = \frac{5\sqrt{5} - 1}{6}$$

The parametric equations of C_2 are $x = 1, y = y, 1 \leq y \leq 2$

$$\int_{C_2} 2xds = \int_{1}^{2} 2\sqrt{\left(\frac{dx}{dy}\right)^2 + \left(\frac{dy}{dy}\right)^2} dy = \int_{1}^{2} 2dy = 2$$

$$\int_{C} 2xds = \int_{C_1} 2xds + \int_{C_2} 2xds = \frac{5\sqrt{5} - 1}{6} + 2$$

Line integral with respect to arc length

In the Definition of line integral, two other line integrals are obtained by replacing Δs_i by either Δx_i or Δy_i . They are called the line integrals of f along with respect to x and y.

If C is a smooth curve given by x = x(t), y = y(t), $t \in [a, b]$ and f(x, y) is continuous, then:

$$\int_C f(x,y) \mathrm{d}x = \int_a^b f\big(x(t),y(t)\big) x'(t) \mathrm{d}t$$

$$\int_{C} f(x,y) dy = \int_{a}^{b} f(x(t),y(t))y'(t) dt$$

Line integral with respect to arc length

It frequently happens that line integrals with respect to x and y occur together. When this happens, it's customary to abbreviate by writing:

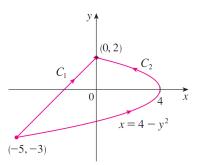
$$\int_C P(x,y) \mathrm{d}x + \int_C Q(x,y) \mathrm{d}y = \int_C P(x,y) \mathrm{d}x + Q(x,y) \mathrm{d}y$$

Example

Evaluate $\int_C y^2 dx + x dy$, where:

- a. $C = C_1$, is the line segment from (-5, -3) to (0, 2)
- b. $C = C_2$, is the arc of the parabola $x = 4 y^2$ from (-5, -3) to (0, 2)
- 3. $C = -C_1$ is the line segment from (0,2) to (-5,-3)

Line integral with respect to arc length

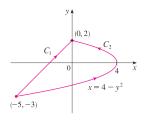


Solution

(a) A parametric representation for the line segment is x=5t-5, y=5t-3, $0\leqslant t\leqslant 1$. Thus,

$$\int_{C_1} y^2 dx + x dy = \int_{0}^{1} (5t - 3)^2 (5dt) + (5t - 5) (5dt) = -\frac{5}{6}$$

Solution (Cont.)



(b) Let's take y as the parameter and write C_2 as

$$x = 4 - y^2, y = y, -3 \le y \le 2$$

Therefore,

$$\int_{C_2} y^2 dx + x dy = \int_{-3}^{2} y^2 (-2y dy) + (4 - y^2) dy = 40 \frac{5}{6}$$

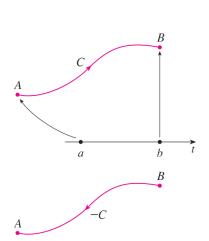
(c) Parametrization: $x=-5t, y=2-5t, 0\leqslant t\leqslant 1$. Therefore, $\int\limits_{-C_1}y^2dx+xdy=\frac{5}{6}$.

Remark 1

From Chapter 2 (slide #47), vector representation of the line segment that starts at r_0 and ends at r_1 is given by

$$r(t) = (1-t)r_0 + tr_1, 0 \leqslant t \leqslant 1$$

Remark 2



If -C denotes the curve consisting of the same points as C but with the *opposite orientation*. Then:

$$\int_{-C} f(x, y) dx = -\int_{C} f(x, y) dx$$
$$\int_{-C} f(x, y) dy = -\int_{C} f(x, y) dy$$

But if we integrate with respect to arc length, the value of the line integral does not change:

$$\int_{-C} f(x,y) ds = \int_{C} f(x,y) ds$$

Line Integrals in Space

Suppose that C is a smooth space curve given by the parametric equations

$$x = x(t)$$
, $y = y(t)$, $z = z(t)$, $a \le t \le b$

or by a vector equation $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$. If f is a function of

three variables that is continuous on some region containing C, then we define the line integral of along C:

$$\int_{C} f(x, y, z) ds = \int_{a}^{b} f(x(t), y(t), z(t))$$

$$\sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2} + \left(\frac{dz}{dt}\right)^{2}} dt$$

Line Integrals in Space

Line integrals along C with respect to x, y, and z can also be defined:

$$\int_{C} f(x, y, z) dx = \int_{a}^{b} f(x(t), y(t), z(t)) x'(t) dt$$

$$\int_{C} f(x, y, z) dy = \int_{a}^{b} f(x(t), y(t), z(t)) y'(t) dt$$

$$\int_{C} f(x, y, z) dz = \int_{a}^{b} f(x(t), y(t), z(t)) z'(t) dt$$

Line integrals in the plane:

$$\int_{C} P(x, y, z) dx + \int_{C} Q(x, y, z) dy + \int_{C} R(x, y, z) dz$$

$$= \int_{C} P(x, y, z) dx + Q(x, y, z) dy + R(x, y, z) dz$$

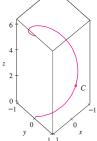
Example

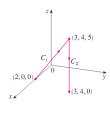
• Evaluate $\int_C y \sin z ds$, where C is the circular helix given by the equations $x = \cos t$, $y = \sin t$, z = t, $0 \le t \le 2\pi$

Evaluate $\int_C y dx + z dy + x dz$, where C consists of the line segments (2,0,0), (3,4,5), (3,4,0)

Answers

- $\sqrt{2}\pi$
- $\frac{49}{2} 15 = \frac{19}{2}$





Line Integrals of Vector Fields

How to compute the work done by a force field along a curve?

Definition

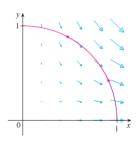
Let F be a continuous vector field defined on a smooth curve C given by a vector function r(t), $a \le t \le b$. Then the line integral of F along C is

$$\int_{C} F \cdot dr = \int_{a}^{b} F(r(t)) \cdot r'(t) dt = \int_{C} F \cdot Tds$$

Example

Find the work done by the force field $F(x, y) = x^2 \mathbf{i} - xy \mathbf{j}$ in moving a particle along the quarter-circle $r(t) = \cos t \mathbf{i} + \sin t \mathbf{j}$, $0 \le t \le \pi/2$.

Solution



Since $x = \cos t$ and $y = \sin t$, we have

$$F(r(t)) = \cos^2 t \mathbf{i} - \cos t \sin t \mathbf{j}$$
$$r'(t) = -\sin t \mathbf{i} + \cos t \mathbf{j}$$

$$\int_{C} F \cdot dr = \int_{0}^{\pi/2} F(r(t)) \cdot r'(t) dt = \int_{0}^{\pi/2} -2\cos^{2}t \sin t dt = -\frac{2}{3}$$

Line Integrals of Vector Fields

Remarks: If $F = \langle P, Q, R \rangle$ then

$$\int_{C} F \cdot dr = \int_{a}^{b} F(r(t)) \cdot r'(t) dt = \int_{C} Pdx + Qdy + Rdz$$

Exercise

Evaluate $\int_C F \cdot dr$, where F(x, y, z) = xyi + yzj + zxk and C is the twisted cubic given by $x = t, y = t^2, z = t^3, 0 \le t \le 1$.

Solution:

$$r(t) = \langle t, t^{2}, t^{3} \rangle$$

$$\int_{C} F \cdot dr = \int_{0}^{1} F(r(t)) \cdot r'(t) dt = \int_{0}^{1} (t^{3} + 5t^{6}) dt = \frac{27}{28}$$

The Fundamental Theorem for Line Integrals

Recall that Part 2 of the Fundamental Theorem of Calculus can be written as

$$\int_{a}^{b} f'(x) dx = f(b) - f(a)$$

If we think of the gradient vector ∇f of a function of two or three variables as a sort of derivative of f, then the following theorem can be regarded as a version of the Fundamental Theorem for line integrals.

Theorem

Let C be a smooth curve given by the vector function r(t), $a \le t \le b$. Let f be a differentiable function of two or three variables whose gradient vector ∇f is continuous on C. Then

$$\int_{C} \nabla f \cdot dr = f(r(b)) - f(r(a))$$

The Fundamental Theorem for Line Integrals

Example

Find the work done by the vector field

$$F = \left\langle y, x + z^2, 2yz \right\rangle$$

in moving a particle with mass from the point (0,4,3) to the point (2,2,0) along a piecewise-smooth curve C.

Solution

We have $F = \nabla f$, where $f = xy + yz^2$ (see slide # ??). That is, F is a conservative vector field.

Therefore, the work done is

$$W = \int_{C} F \cdot dr = \int_{C} \nabla f \cdot dr = f(2,2,0) - f(0,4,3) = 4 - 36 = -32.$$

Independence of Path

Definition

If F is a continuous vector field with domain D, we say that the line integral $\int\limits_C F\cdot dr$ is independent of path if $\int\limits_{C_1} F\cdot dr=\int\limits_{C_2} F\cdot dr$ for any two paths C_1 and C_2 in that have the same initial and terminal points.

For example, line integrals of conservative vector fields are independent of path.

Independence of Path

Definition

A curve is called closed if its terminal point coincides with its initial point, that is, r(b) = r(a).



Theorem

 $\int\limits_C F\cdot dr$ is independent of path in D if and only if $\int\limits_C F\cdot dr=0$ for every closed path C in D.

Conservative vector field

Theorem

Suppose F is a vector field that is continuous on an open connected region D. If $\int_C F \cdot dr$ is independent of path in D, then F is a conservative vector field on D; that is, there exists a function f such that $\nabla f = F$.

The question remains: How is it possible to determine whether or not a vector field is conservative?

Theorem

If F is a conservative vector field, where P and Q have continuous first-order partial derivatives on a domain D, then throughout D we have

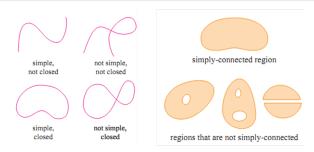
$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$$

Q: Is the converse is true?

Simply-connected region

Definition

- 1. A simple curve is a curve that doesn't intersect itself any-where between its endpoints.
- 2. A simply-connected region in the plane is a connected region D such that every simple closed curve in D encloses only points that are in D.



Intuitively speaking, a simply-connected region contains no hole and can't consist of two separate pieces

Conservative vector fields

Theorem

Let $F = P\mathbf{i} + Q\mathbf{j}$ be a vector field on an open simply-connected region D. Suppose that P and Q have continuous first-order derivatives and

$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x} \quad \text{throughout } D$$

Then F is conservative.

Example

Determine whether or not the vector field $F(x, y) = (x - y)\mathbf{i} + (x - 2)\mathbf{j}$ is conservative.

Let
$$P = x - y$$
, $Q = x - 2$. Since $\frac{\partial P}{\partial y} = -1 \neq \frac{\partial Q}{\partial x} = 1$, F is not conservative.

Conservative vector fields

Example

Determine whether or not the vector field

$$F(x, y) = (3 + 2xy)\mathbf{i} + (x^2 - 3y^2)\mathbf{j}$$
 is conservative.

Solution

Let
$$P = 3 + 2xy$$
, $Q = x^2 - 3y^2$. Since $\frac{\partial P}{\partial y} = 2x = \frac{\partial Q}{\partial x}$.

Also, the domain of F is the entire plane $(D = \mathbb{R}^2)$, which is open and simply-connected.

Thus, F is conservative.

Conservative vector fields

Exercise

- (a) If $F(x, y) = (3 + 2xy)\mathbf{i} + (x^2 3y^2)\mathbf{j}$, find a function f such that $F = \nabla f$.
- (b) Evaluate the line integral $\int_C F \cdot dr$, where C is the curve given by $r(t) = e^t \sin t \mathbf{i} + e^t \cos t \mathbf{j}$, where $0 \le t \le \pi$.

Hint

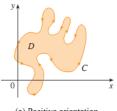
(a)
$$f(x,y) = 3x + x^2y - y^3 + C$$

$$\int_{C} F \cdot dr = \int_{C} \nabla f \cdot dr = f(0, -e^{\pi}) - f(0, 1) = e^{3\pi} + 1$$

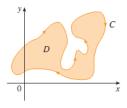
Green Theorem

Definition: Positive Orientation

The positive orientation of a simple closed curve C refers to a single counterclockwise traversal of C. That is, if C is given by the vector function r(t), $a \le t \le b$, then the region D is always on the left as the point traverses C.

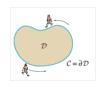






(b) Negative orientation

Green Theorem



Green Theorem

Let C be a positively oriented, piecewise-smooth, simple closed curve in the plane and let D be the region bounded by C. If P and Q have continuous partial derivatives on an open region that contains D, then:

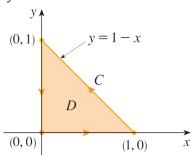
$$\oint_C P dx + Q dy = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

The equation in Green's Theorem can be written as

$$\oint_{\partial D} P dx + Q dy = \iint_{D} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

Example

- Evaluate $I_1 = \oint_C x^4 dx + xy dy$, where C is the triangular curve consisting of the line segments from (0,0) to (1,0), from (1,0) to (0,1), and from (0,1) to (0,0).
- $\textbf{ Evaluate } I_2 = \oint_C \left(3y e^{\sin x}\right) \mathrm{d}x + \left(7x + \sqrt{y^4 + 1}\right) \mathrm{d}y \text{, where } C \text{ is the circle } x^2 + y^2 = 9$

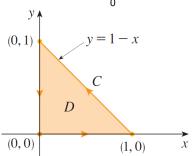


Solutions

1. Using Green's Theorem

$$I_1 = \oint_C x^4 dx + xy dy = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \int_0^1 \int_0^{1-x} (y - 0) \, dy dx$$

Therefore, $I_1 = \frac{1}{2} \int_{0}^{1} (1-x)^2 = \frac{1}{6}$.



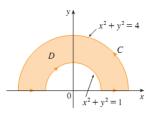
2. Hint:
$$I_2 = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = 4 \int_0^{2\pi} d\theta \int_0^3 r dr = 36\pi.$$

Example

3. Evaluate

$$I_3 = \oint_C y^2 dx + 3xy dy$$

where C is the boundary of the semiannular region D in the upper half-plane between the circles $x^2 + y^2 = 1$ and $x^2 + y^2 = 4$.



Hint:
$$D = \{(r, \theta) : 1 \le r \le 2, 0 \le \theta \le \pi\}$$

$$I_{3} = \iint_{D} \left(\frac{\partial (3xy)}{\partial x} - \frac{\partial (y^{2})}{\partial y} \right) dA = \int_{0}^{\pi} \int_{0}^{2} (r \sin \theta) r dr d\theta = \frac{14}{3}$$

Remarks

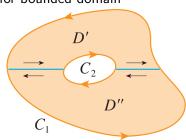
• The Green's Theorem gives the following formulas for the area of *D*:

$$A = \oint_C x dy = -\oint_C y dx = \frac{1}{2} \left[\oint_C x dy - y dx \right]$$

Extended Versions of Green's Theorem for bounded domain

$$\iint_{D} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy =$$

$$\oint_{C_{1}} P dx + Q dy + \oint_{C_{2}} P dx + Q dy$$



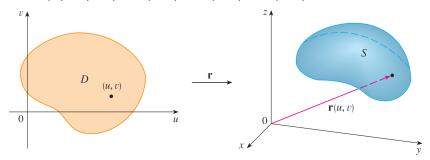
Parametric Surfaces

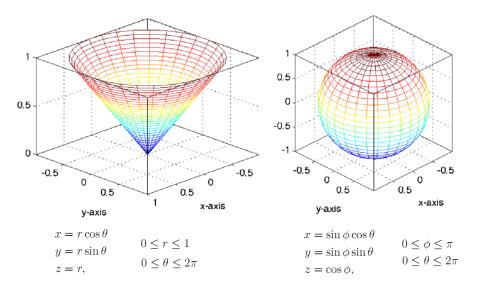
The set of all points $(x, y, z) \in \mathbb{R}^3$ such that:

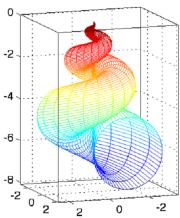
$$x = x(u, v), \quad y = y(u, v), \quad z = z(u, v)$$

where $(u, v) \in D$ is called a *parametric surface* S and the equations above are called *parametric equations* of S.

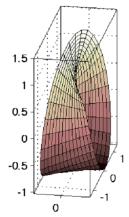
We write (S): $\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$







$$\begin{split} x &= 2\left[1 - e^{u/(6\pi)}\right]\cos u \cos^2\left(\frac{v}{2}\right) \\ y &= 2\left[-1 + e^{u/(6\pi)}\right]\sin u \cos^2\left(\frac{v}{2}\right) \\ z &= 1 - e^{u/(3\pi)} - \sin v + e^{u/(6\pi)}\sin v, \end{split}$$



$$x = \frac{v}{2} \sin \frac{u}{2} \qquad \left(\text{Mobius Strip} \right)$$
$$y = \left(1 + \frac{v}{2} \cos \frac{u}{2} \right) \sin u$$
$$z = \left(1 + \frac{v}{2} \cos \frac{u}{2} \right) \cos u,$$
$$0 \le u \le 2\pi \qquad -1 < v < 1$$

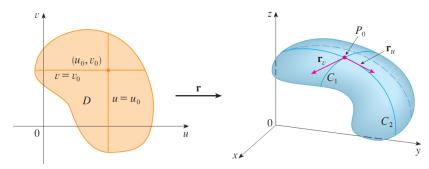
 $0 \le u \le 6\pi$ $0 \le v \le 2\pi$

Normal vector to the tangent plane

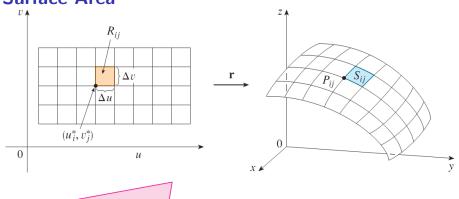
$$\mathbf{r}(u,v) = x(u,v)\mathbf{i} + y(u,v)\mathbf{j} + z(u,v)\mathbf{k}, \quad (u,v) \in D$$

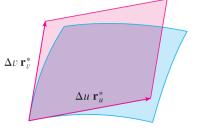
$$\mathbf{r}_{u}(x_{0},y_{0}) = \frac{\partial x}{\partial u}(x_{0},y_{0})\mathbf{i} + \frac{\partial y}{\partial u}(x_{0},y_{0})\mathbf{j} + \frac{\partial z}{\partial u}(x_{0},y_{0})\mathbf{k}$$

$$\mathbf{r}_{v}(x_{0},y_{0}) = \frac{\partial x}{\partial v}(x_{0},y_{0})\mathbf{i} + \frac{\partial y}{\partial v}(x_{0},y_{0})\mathbf{j} + \frac{\partial z}{\partial v}(x_{0},y_{0})\mathbf{k}$$



The vector $\mathbf{n} = \mathbf{r}_u \times \mathbf{r}_v$ is the normal vector to the tangent plane.





$$\Delta S_{ij} \approx |(\Delta u \mathbf{r}_u^*) \times (\Delta v \mathbf{r}_v^*)|$$
$$= |\mathbf{r}_u^* \times \mathbf{r}_v^*| \Delta u \Delta v$$

$$S \approx \sum_{i=1}^{m} \sum_{j=1}^{n} |\mathbf{r}_{u}^{*} \times \mathbf{r}_{v}^{*}| \Delta u \Delta v$$

Surface Area

If a smooth parametric surface S is given by the equation $\mathbf{r}(u,v) = x(u,v)\mathbf{i} + y(u,v)\mathbf{j} + z(u,v)\mathbf{k}$ and is covered just once as (u,v) ranges throughout the parameter domain D, then the surface area of S is

$$A(S) = \iint_D |\mathbf{r}_u \times \mathbf{r}_v| \mathrm{d}u \mathrm{d}v$$

where

$$r_{u} = \frac{\partial x}{\partial u}i + \frac{\partial y}{\partial u}j + \frac{\partial z}{\partial u}k, r_{v} = \frac{\partial x}{\partial v}i + \frac{\partial y}{\partial v}j + \frac{\partial z}{\partial v}k$$

Example

- 1. Find the surface area of a sphere of radius a
- 2. Surface Area of the Graph of a Function: Show that the surface area of S: z = f(x, y), where $(x, y) \in D$ is

$$A(S) = \iint_{D} \sqrt{1 + \left(\frac{\partial z}{\partial x}\right)^{2} + \left(\frac{\partial z}{\partial y}\right)^{2}} dxdy$$

Solution

1. We have

$$x = a\cos\theta\sin\phi, y = a\sin\theta\sin\phi, z = a\cos\phi$$

where

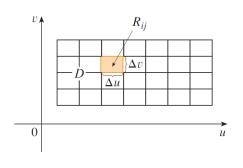
$$0 \le \theta \le 2\pi, 0 \le \phi \le \pi.$$

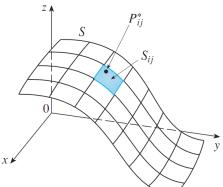
$$|r_{\phi} \times r_{\theta}| = \begin{vmatrix} i & j & k \\ \frac{\partial x}{\partial \phi} & \frac{\partial y}{\partial \phi} & \frac{\partial z}{\partial \phi} \\ \frac{\partial x}{\partial \theta} & \frac{\partial y}{\partial \theta} & \frac{\partial x}{\partial \theta} \end{vmatrix}| = a^{2} \sin \phi$$

Therefore, the surface area of a sphere of radius a is

$$A = \iint\limits_{D} |r_{\phi} \times r_{\theta}| dA = \int\limits_{0}^{2\pi} \int\limits_{0}^{\pi} a^{2} \sin \phi d\phi d\theta = 4\pi a^{2}$$

Surface Integral





Riemann sum:

$$\sum_{i=1}^{m} \sum_{j=1}^{n} f(P_{ij}^{*}) \Delta S_{ij} \approx \sum_{i=1}^{m} \sum_{j=1}^{n} f(P_{ij}^{*}) |\mathbf{r}_{u} \times \mathbf{r}_{v}| \Delta u \Delta v$$

Surface Integral

Surface integral of *f* over the surface *S*:

$$\iint_{S} f(x,y,z) d\sigma = \iint_{D} f(\mathbf{r}(u,v)) |\mathbf{r}_{u} \times \mathbf{r}_{v}| du dv$$

Example:

- 1. Evaluate $\iint_S x^2 d\sigma$ where *S* is the unit sphere.
- 2. Let S: z = g(x, y), where $(x, y) \in D$. Show that:

$$\iint_{S} f(x, y, z) d\sigma = \iint_{D} f(x, y, g(x, y)) \sqrt{1 + \left(\frac{\partial z}{\partial x}\right)^{2} + \left(\frac{\partial z}{\partial y}\right)^{2}} dx dy$$

Solution

1. We have

$$x = \cos \theta \sin \phi, y = \sin \theta \sin \phi, z = \cos \phi$$

where $0 \le \theta \le 2\pi, 0 \le \phi \le \pi$.

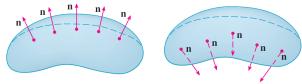
$$|r_{\phi} \times r_{\theta}| = |\begin{vmatrix} i & j & k \\ \frac{\partial x}{\partial \phi} & \frac{\partial y}{\partial \phi} & \frac{\partial z}{\partial \phi} \\ \frac{\partial x}{\partial \theta} & \frac{\partial y}{\partial \theta} & \frac{\partial x}{\partial \theta} \end{vmatrix}| = \sin \phi$$

Therefore,

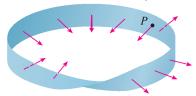
$$\iint\limits_{S} x^2 dS = \iint\limits_{D} (\sin\phi\cos\theta)^2 |r_{\phi} \times r_{\theta}| dA = \int\limits_{0}^{2\pi} \int\limits_{0}^{\pi} \cos^2\theta\sin^3\phi d\phi d\theta = \frac{4\pi}{3}$$

Oriented Surfaces

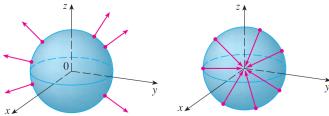
If it is possible to choose a *unit normal vector* \mathbf{n} at every such point (x, y, z) so that $\mathbf{n}(x, y, z)$ varies continuously over S, then S is called an *oriented surface* and the given choice of \mathbf{n} provides with an orientation.



Not all surfaces can be oriented. For example, Möbius surface.



For a closed surface, the convention is that the *positive orientation* is the one for which the normal vectors point outward from, and inward-pointing normals give the negative orientation.



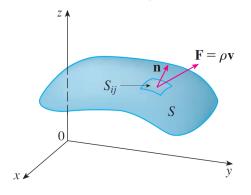
If S is oriented and defined by $\mathbf{r}(u, v)$ then the unit normal vector is

$$\mathbf{n} = \pm \frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|}$$

The unit normal vector of z = g(x, y):

$$\mathbf{n} = \frac{-g_x \mathbf{i} - g_y \mathbf{j} + \mathbf{k}}{\sqrt{1 + (g_x)^2 + (g_y)^2}}$$

Consider a fluid with density $\rho(x,y,z)$ flowing S with velocity field $\mathbf{v}(x,y,z) = (v_1(x,y,z),v_2(x,y,z),v_3(x,y,z))$ Then the rate of flow (mass per unit time) per unit area is: $\mathbf{F} = \rho \mathbf{v}$



We can approximate the mass of fluid per unit time crossing S_{ij} in the direction of the normal \mathbf{n} :

$$(\rho \mathbf{v} \cdot \mathbf{n}) A(S_{ii})$$

The total mass of fluid per unit time crossing S (per unit time)

$$\iint_{\mathcal{S}} \rho(x, y, z) \mathbf{v}(x, y, z) \cdot \mathbf{n}(x, y, z) d\sigma = \iint_{\mathcal{S}} \mathbf{F} \cdot \mathbf{n} d\sigma$$

Definition

If \mathbf{F} is a continuous vector field defined on an oriented surface S with unit normal vector \mathbf{n} , then the surface integral of over S is

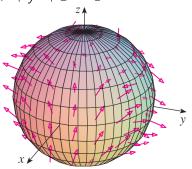
$$\iint_{\mathcal{S}} \mathbf{F} \cdot d\mathbf{S} = \iint_{\mathcal{S}} \mathbf{F} \cdot \mathbf{n} d\sigma$$

This integral is also called the flux \mathbf{F} of across S.

If S is defined by $\mathbf{r}(u, v)$ $((u, v) \in D)$, then:

$$\iint_{\mathcal{S}} \mathbf{F} \cdot d\mathbf{S} = \iint_{D} \mathbf{F} \cdot (\mathbf{r}_{u} \times \mathbf{r}_{v}) du dv$$

Example: Find the flux of the vector field $\mathbf{F}(x, y, z) = z\mathbf{i} + y\mathbf{j} + x\mathbf{k}$ across the unit sphere $S: x^2 + y^2 + z^2 = 1$



Answer: $\frac{4\pi}{3}$

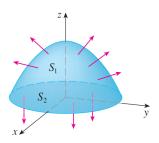
If S is defined by the surface z = g(x, y) and $F = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$, then:

$$\iint_{S} \mathbf{F} \cdot d\mathbf{S} = \iint_{D} (-P \frac{\partial g}{\partial x} - Q \frac{\partial g}{\partial y} + R) dA$$

Example: Evaluate

$$\iint_{S} \mathbf{F} \cdot d\mathbf{S}$$

where $\mathbf{F}(x,y,z) = y\mathbf{i} + x\mathbf{j} + z\mathbf{k}$ and S is the boundary of the solid region enclosed by the paraboloid $z = 1 - x^2 - y^2$ and the plane z = 0.



Solution:

Note that P(x, y, z) = y, Q(x, y, z) = x, $R(x, y, z) = z = 1 - x^2 - y^2$.

$$\iint_{S_1} \mathbf{F} \cdot \mathrm{d}\mathbf{S} = \iint_D (-P \frac{\partial g}{\partial x} - Q \frac{\partial g}{\partial y} + R) \mathrm{d}A$$

$$= \iint_D (1+4xy-x^2-y^2) dA = \int_0^{2\pi} \int_0^1 (1+4r^2\cos\theta\sin\theta-r^2)r dr d\theta = \frac{\pi}{2}$$

The disk S_2 is oriented downward, so its unit normal vector $\mathbf{n} = -\mathbf{k}$. Thus,

$$\iint_{S_2} \mathbf{F} \cdot d\mathbf{S} = \iint_{S_2} \mathbf{F} \cdot \mathbf{n} d\sigma = \iint_D -z dA = 0$$

since z = 0 on S_2 . Therefore,

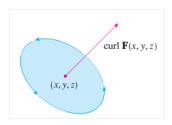
$$\iint_{\mathcal{S}} \mathbf{F} \cdot \mathrm{d}\mathbf{S} = \iint_{\mathcal{S}_1} \mathbf{F} \cdot \mathrm{d}\mathbf{S} + \iint_{\mathcal{S}_2} \mathbf{F} \cdot \mathrm{d}\mathbf{S} = \frac{\pi}{2}.$$

Curl

Definition

If $F = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$ is a vector field on \mathbb{R}^3 and the partial derivatives of P, Q, and R all exist, then the curl of F is the vector field on \mathbb{R}^3 defined by

curl
$$F = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}\right)\mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x}\right)\mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right)\mathbf{k}$$



Curl

Recall:

$$\nabla = \mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y} + \mathbf{k} \frac{\partial}{\partial z} = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle$$

We can consider the formal cross product of ∇ with the vector field F as follows:

$$\nabla \times F = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k}$$

So the easiest way to remember Definition is by means of the symbolic expression:

curl
$$F = \nabla \times F$$

Example

If
$$F(x, y, z) = xzi + xyzj - y^2k$$
, find curl F .

Solution

$$\operatorname{curl} F = \nabla \times F = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xz & xyz & -y^2 \end{vmatrix} = \begin{bmatrix} \frac{\partial}{\partial y} \left(-y^2 \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(-y^2 \right) - \frac{\partial}{\partial z} \left(xz \right) \right] j + \begin{bmatrix} \frac{\partial}{\partial x} \left(xyz \right) - \frac{\partial}{\partial y} \left(xz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial x} \left(-y^2 \right) - \frac{\partial}{\partial z} \left(xz \right) \right] j + \begin{bmatrix} \frac{\partial}{\partial x} \left(xyz \right) - \frac{\partial}{\partial y} \left(xz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial y} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right) \right] i - \begin{bmatrix} \frac{\partial}{\partial z} \left(xyz \right) - \frac{\partial}{\partial z} \left(xyz \right)$$

Curl

Theorem

If f is a function of three variables that has continuous second-order partial derivatives, then

curl
$$(\nabla f) = 0$$

Remark: Since a conservative vector field is one for which $F = \nabla f$, thus if F is conservative, then curl (F) = 0.

This gives us a way of verifying that a vector field is not conservative.

Example

Show that the vector field $F = xz\mathbf{i} + xyz\mathbf{j} - y^2\mathbf{k}$ is not conservative.

Solution We have

$$\operatorname{curl} F = (-2y - xy) i + xj + yzk$$

Therefore, curl $F \neq 0$, so F is not conservative.

Curl

The converse of previous Theorem is not true in general, but the following theorem says the converse is true if F is defined everywhere.

Theorem

If F is a vector field defined on all of \mathbb{R}^3 whose component functions have continuous partial derivatives and curl F=0, then F is a conservative vector field.

Example

- (a) Show that $F(x, y, z) = y^2 z^3 i + 2xyz^3 j + 3xy^2 z^2 k$ is a conservative vector field.
- (b) Find a function such that $F = \nabla f$.

Hint: (a) Show that curl F = 0, then F is thus a conservative vector field.

(b) $f(x, y, z) = xy^2z^3 + C$.

Divergence

If $F = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$ is a vector field on \mathbb{R}^3 and the partial derivatives of P, Q, and R all exist, then the divergence of F is the function

$$\operatorname{div} F = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = \nabla \cdot F$$

Example

If $F(x, y, z) = xzi + xyzj - y^2k$, find div F.

$$\operatorname{div} F = \nabla \cdot F = z + xz$$

Theorem

If $F = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$ is a vector field on \mathbb{R}^3 and P, Q, and R have continuous second-order partial derivatives, then

div curl
$$F = 0$$

Divergence Theorem

Theorem

Let E be a simple solid region and let S be the boundary surface of E, given with positive (outward) orientation. Let $\mathbf{F}(x,y,z) = P(x,y,z)\mathbf{i} + Q(x,y,z)\mathbf{j} + R(x,y,z)\mathbf{k} \text{ be a vector field whose component functions have continuous partial derivatives on an open region}$

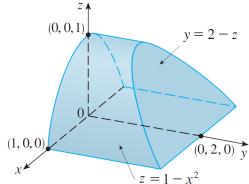
$$\iint_{S} \mathbf{F} \cdot d\mathbf{S} = \iiint_{E} \operatorname{div} \mathbf{F} \, dV$$

The Divergence Theorem is sometimes called Gauss's Theorem.

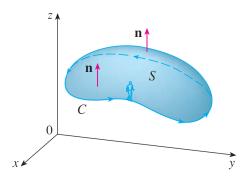
that contains E. Then

Example

Evaluate $\iint_{S} \mathbf{F} \cdot d\mathbf{S}$ where $\mathbf{F}(x,y,z) = xy\mathbf{i} + \left(y^2 + e^{xz^2}\right)\mathbf{j} + \sin(xy)\mathbf{k}$ and S be the boundary surface of E bounded by $z = 1 - x^2$ and the planes $z = 0, \ y = 0, \ y + z = 2$



Stokes Theorem



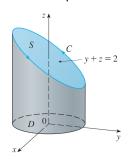
Theorem

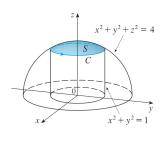
Let S be an oriented piecewise-smooth surface that is bounded by a simple, closed, piecewise-smooth boundary curve C with positive orientation. Let F be a vector field whose components have continuous partial derivatives on an open region in that contains S. Then

$$\iint_{S} \operatorname{curl} F \cdot d\mathbf{S} = \oint_{C} P dx + Q dy + R dz$$

Example

- 1. Evaluate $\int_C -y^2 dx + x dy + z^2 dz$, where C is the curve of intersection of the plane y + z = 2 and the cylinder $x^2 + y^2 = 1$.
- 2. Use Stokes' Theorem to compute the integral $\int_S \operatorname{curl} \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F}(x,y,z) = (xz,yz,xy)$ and S is the part of the sphere $x^2 + y^2 + z^2 = 4$ that lies inside the cylinder $x^2 + y^2 = 1$ and above the xt-plane.





-THE END-