Chapter 7 DISCRETE TIME SIGNALS AND SYSTEMS

TIME SHIFTING (TRANSLATION)

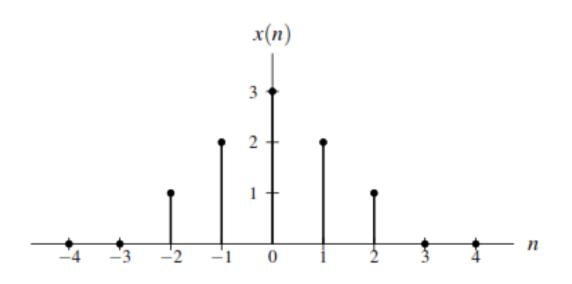
■ Time shifting (also called translation) maps the input sequence x to the output sequence y as given by

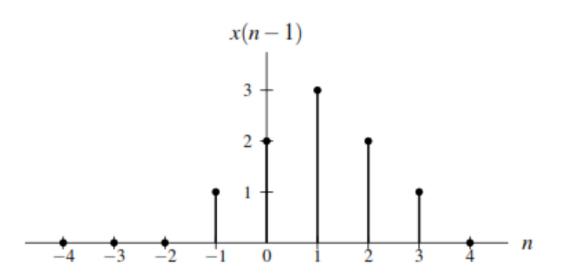
$$y(n) = x(n-b),$$

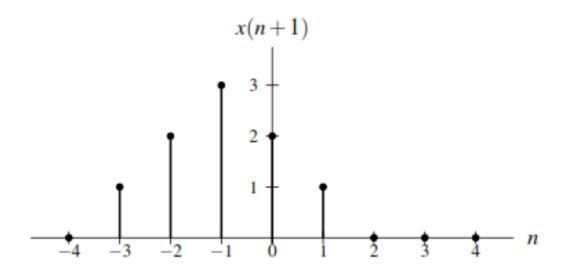
where b is an integer.

- Such a transformation shifts the sequence (to the left or right) along the time axis.
- If b > 0, y is shifted to the right by |b|, relative to x (i.e., delayed in time).
- If b < 0, y is shifted to the left by |b|, relative to x (i.e., advanced in time).

TIME SHIFTING (TRANSLATION)





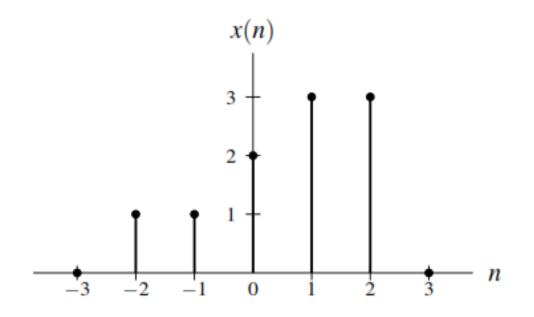


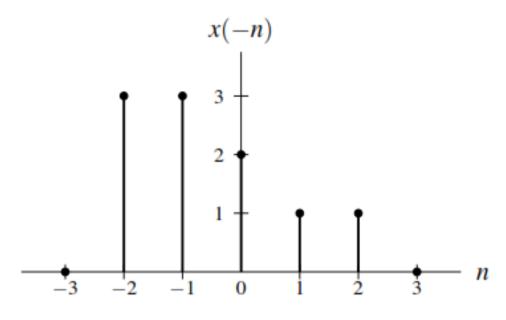
TIME REVERSAL (REFLECTION)

Time reversal (also known as reflection) maps the input sequence x to the output sequence y as given by

$$y(n) = x(-n)$$
.

• Geometrically, the output sequence y is a reflection of the input sequence x about the (vertical) line n = 0.





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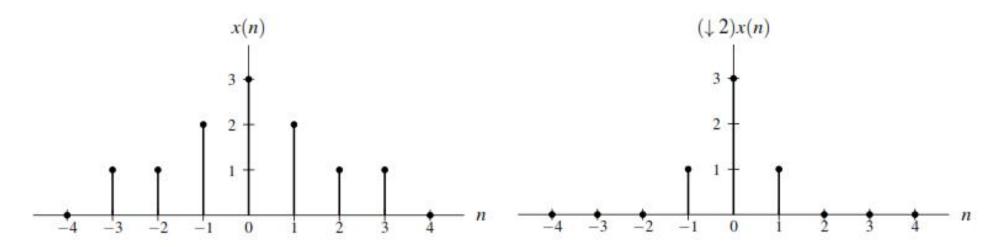
DOWNSAMPLING

Downsampling maps the input sequence x to the output sequence y as given by

$$y(n) = (\downarrow a)x(n) = x(an),$$

where a is a strictly positive integer.

The output sequence y is produced from the input sequence x by keeping only every ath sample of x.



The constant a is referred to as the **downsampling factor**.

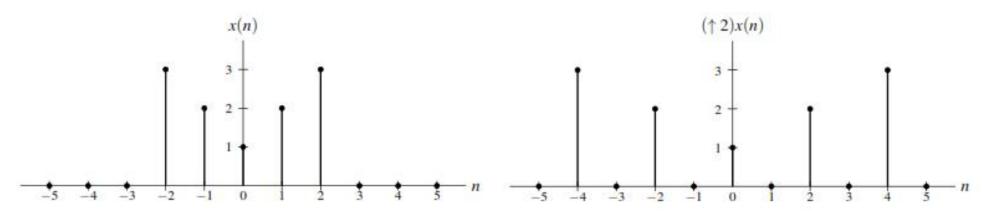
UPSAMPLING

Upsampling maps the input sequence x to the output sequence y as given by

$$y(n) = (\uparrow a)x(n) = \begin{cases} x(n/a) & n/a \text{ is an integer} \\ 0 & \text{otherwise,} \end{cases}$$

where *a* is a strictly positive integer.

The output sequence y is produced from the input sequence x by inserting a-1 zeros between all of the samples of x.



The constant a is referred to as the **upsampling factor**.

COMBINED INDEPENDENT-VARIABLE TRANSFORMATIONS

Consider a transformation that maps the input sequence x to the output sequence y as given by

$$y(n) = x(an - b),$$

where a and b are integers and $a \neq 0$.

- Such a transformation is a combination of time shifting, downsampling, and time reversal operations.
- Time reversal commutes with downsampling.
- Time shifting does not commute with time reversal or downsampling.
- The above transformation is equivalent to:
 - \blacksquare first, time shifting x by b;
 - 2 then, downsampling the result by |a| and, if a < 0, time reversing as well.
- If $\frac{b}{a}$ is an integer, the above transformation is also equivalent to:
 - If irst, downsampling x by |a| and, if a < 0, time reversing;
 - 2 then, time shifting the result by $\frac{b}{a}$.
- Note that the time shift is not by the same amount in both cases.

DECOMPOSITION OF A SEQUENCE INTO EVEN AND ODD PARTS

 \blacksquare Every sequence x has a *unique* representation of the form

$$x(n) = x_{e}(n) + x_{o}(n),$$

where the sequences x_e and x_o are even and odd, respectively.

In particular, the sequences x_e and x_o are given by

$$x_{e}(n) = \frac{1}{2} [x(n) + x(-n)]$$
 and $x_{o}(n) = \frac{1}{2} [x(n) - x(-n)]$.

- The sequences x_e and x_o are called the even part and odd part of x, respectively.
- For convenience, the even and odd parts of x are often denoted as $\text{Even}\{x\}$ and $\text{Odd}\{x\}$, respectively.

THEOREM

Let x be an arbitrary N-periodic sequence x. Then, the following assertions hold:

- 1. if x is even, then x(n) = x(N-n) for all $n \in \mathbb{Z}$;
- 2. if x is odd, then x(n) = -x(N-n) for all $n \in \mathbb{Z}$; and
- 3. if x is odd, then x(0) = 0 for both even and odd N, and $x(\frac{N}{2}) = 0$ for even N.

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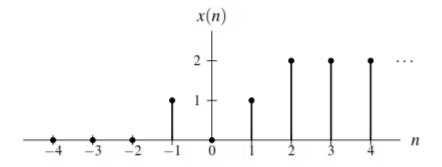
RIGHT SIDED SEQUENCES

A sequence x is said to be **right sided** if, for some (finite) integer constant n_0 , the following condition holds:

$$x(n) = 0$$
 for all $n < n_0$

(i.e., x is only potentially nonzero to the right of n_0).

An example of a right-sided sequence is shown below.



A sequence *x* is said to be causal if

$$x(n) = 0$$
 for all $n < 0$.

- A causal sequence is a special case of a right-sided sequence.
- A causal sequence is not to be confused with a causal system. In these two contexts, the word "causal" has very different meanings.

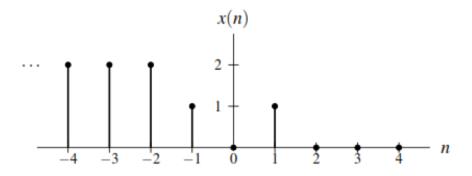
LEFT SIDED SEQUENCES

A sequence x is said to be **left sided** if, for some (finite) integer constant n_0 , the following condition holds:

$$x(n) = 0$$
 for all $n > n_0$

(i.e., x is *only potentially nonzero to the left of* n_0).

An example of a left-sided sequence is shown below.



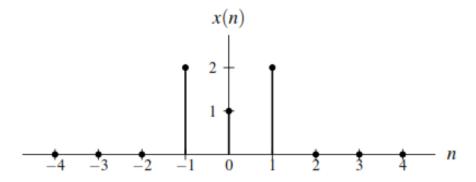
A sequence x is said to be anticausal if

$$x(n) = 0$$
 for all $n > 0$.

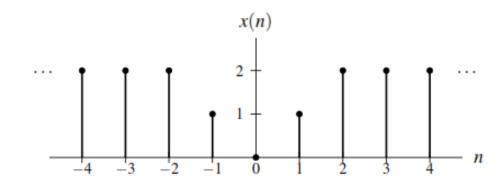
- An anticausal sequence is a special case of a left-sided sequence.
- An anticausal sequence is not to be confused with an anticausal system. In these two contexts, the word "anticausal" has very different meanings.

FINITE DURATION AND TWO SIDED SEQUENCES

- A sequence that is both left sided and right sided is said to be finite duration (or time limited).
- An example of a finite-duration sequence is shown below.



- A sequence that is neither left sided nor right sided is said to be two sided.
- An example of a two-sided sequence is shown below.



BOUNDED SEQUENCES

A sequence x is said to be bounded if there exists some (finite) positive real constant A such that

$$|x(n)| \le A$$
 for all n

(i.e., x(n) is *finite* for all n).

- Examples of bounded sequences include any constant sequence.
- Examples of unbounded sequences include any nonconstant polynomial sequence.

ENERGY OF A SEQUENCE

 \blacksquare The energy E contained in the sequence x is given by

$$E = \sum_{k=-\infty}^{\infty} |x(k)|^2.$$

A signal with finite energy is said to be an energy signal.

A sequence *x* has the following properties:

- x(n) = n + 2 for $-1 \le n \le 1$;
- $v_1(n) = x(n-1)$ is causal; and
- $v_2(n) = x(n+1)$ is even.

Find x(n) for all n.

Solution. Since $v_1(n) = x(n-1)$ is causal, we have

$$x(n-1) = 0 \text{ for } n < 0$$

 $\Rightarrow x([n+1]-1) = 0 \text{ for } (n+1) < 0$
 $\Rightarrow x(n) = 0 \text{ for } n < -1.$

From this and the fact that x(n) = n + 2 for $-1 \le n \le 1$, we have

$$x(n) = \begin{cases} n+2 & -1 \le n \le 1 \\ 0 & n \le -2. \end{cases}$$

So, we only need to determine x(n) for $n \ge 2$. Since $v_2(n) = x(n+1)$ is even, we have

$$v_2(n) = v_2(-n)$$

$$\Rightarrow x(n+1) = x(-n+1)$$

$$\Rightarrow x([n-1]+1) = x(-[n-1]+1)$$

$$\Rightarrow x(n) = x(-n+2)$$

$$\Rightarrow x(n) = x(2-n).$$

$$x(n) = x(2-n)$$

$$= \begin{cases} (2-n)+2 & -1 \le 2-n \le 1 \\ 0 & 2-n \le -2 \end{cases}$$

$$= \begin{cases} 4-n & -3 \le -n \le -1 \\ 0 & -n \le -4 \end{cases}$$

$$= \begin{cases} 4-n & 1 \le n \le 3 \\ 0 & n \ge 4. \end{cases}$$

$$= \begin{cases} 4-n & 1 \le n \le 3 \\ 0 & n \ge 4. \end{cases}$$

Therefore, we conclude

$$x(n) = \begin{cases} 0 & n \le -2\\ 2+n & n \in \{-1,0\}\\ 4-n & n \in \{1,2,3\}\\ 0 & n \ge 4. \end{cases}$$

PERIODICITY

The **least common multiple** (**LCM**) of two nonzero integers a and b, denoted lcm(a,b), is the smallest positive integer that is divisible by both a and b.

The quantity lcm(a,b) can be easily determined from a prime factorization of the integers a and b by taking the product of the highest power for each prime factor appearing in these factorizations.

The **greatest common divisor (GCD)** of two integers a and b, denoted gcd(a,b), is the largest positive integer that divides both a and b, where at least one of a and b is nonzero.

The quantity gcd(a,b) can be easily determined from a prime factorization of the integers a and b by taking the product of the lowest power for each prime factor appearing in these factorizations.

Find the LCM of each pair of integers given below.

- (a) 20 and 6;
- (b) 54 and 24;

Solution. (a) First, we write the prime factorizations of 20 and 6, which yields

$$20 = 2^2 \cdot 5^1$$
 and $6 = 2^1 \cdot 3^1$.

To obtain the LCM, we take the highest power of each prime factor in these two factorizations.

$$lcm(20,6) = 2^2 \cdot 3^1 \cdot 5^1$$
$$= 60.$$

(b) Using a similar process as above, we have

$$lcm(54,24) = lcm(2^{1} \cdot 3^{3}, 2^{3} \cdot 3^{1})$$
$$= 2^{3} \cdot 3^{3}$$
$$= 216.$$

Find the GCD of each pair of integers given below.

- (a) 20 and 6;
- (b) 54 and 24;

Solution. (a) First, we write the prime factorizations of 20 and 6, which yields

$$20 = 2^2 \cdot 5^1$$
 and $6 = 2^1 \cdot 3^1$.

To obtain the GCD, we take the lowest power of each prime factor in these two factorizations.

$$\gcd(20,6) = 2^1 \cdot 3^0 \cdot 5^0$$

= 2.

(b) Using a similar process as above, we have

$$\gcd(54, 24) = \gcd(2^{1} \cdot 3^{3}, 2^{3} \cdot 3^{1})$$
$$= 2^{1} \cdot 3^{1}$$
$$= 6.$$

SUM OF PERIODIC SEQUENCES

For any two periodic sequences x_1 and x_2 with periods N_1 and N_2 , respectively, the sequence $x = x_1 + x_2$ is periodic with period $N = \text{lcm}(N_1, N_2)$.

Proof. Since N is an integer multiple of both N_1 and N_2 , we can write $N = k_1N_1$ and $N = k_2N_2$ for some positive integers k_1 and k_2 . So, we can write

$$x(n+N) = x_1(n+N) + x_2(n+N)$$

$$= x_1(n+k_1N_1) + x_2(n+k_2N_2)$$

$$= x_1(n) + x_2(n)$$

$$= x(n).$$

Thus, x is periodic with period N.

Unlike in the case of the sum of periodic functions, the sum of periodic sequences is always periodic.

The sequences $x_1(n) = \cos\left(\frac{\pi}{6}n\right)$ and $x_2(n) = \sin\left(\frac{2\pi}{45}n\right)$ have fundamental periods $N_1 = 12$ and $N_2 = 45$, Find the fundamental period N of the sequence $y = x_1 + x_2$.

The sequences $x_1(n) = \cos\left(\frac{\pi}{6}n\right)$ and $x_2(n) = \sin\left(\frac{2\pi}{45}n\right)$ have fundamental periods $N_1 = 12$ and $N_2 = 45$, Find the fundamental period N of the sequence $y = x_1 + x_2$.

Solution. We have

$$N = lcm(N_1, N_2)$$

$$= lcm(12, 45)$$

$$= lcm(2^2 \cdot 3, 3^2 \cdot 5)$$

$$= 2^2 \cdot 3^2 \cdot 5$$

$$= 180.$$

Elementary Sequences

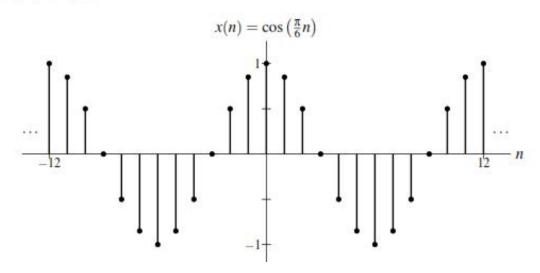
REAL SINUSOIDAL SEQUENCES

A real sinusoidal sequence is a sequence of the form

$$x(n) = A\cos(\Omega n + \theta),$$

where A, Ω , and θ are *real* constants.

- A real sinusoid is *periodic* if and only if $\frac{\Omega}{2\pi}$ is a *rational number*, in which case the fundamental period is the *smallest integer* of the form $\frac{2\pi k}{|\Omega|}$ where k is a (strictly) positive integer.
- For all integer k, $x_k(n) = A\cos([\Omega + 2\pi k]n + \theta)$ is the *same* sequence.
- An example of a periodic real sinusoid with fundamental period 12 is shown plotted below.



COMPLEX EXPONENTIAL SEQUENCES

A complex exponential sequence is a sequence of the form

$$x(n) = ca^n$$
,

where c and a are complex constants.

Such a sequence can also be equivalently expressed in the form

$$x(n) = ce^{bn},$$

where b is a *complex* constant chosen as $b = \ln a$. (This this form is more similar to that presented for CT complex exponentials).

- A complex exponential can exhibit one of a number of distinct modes of behavior, depending on the values of the parameters c and a.
- For example, as special cases, complex exponentials include real exponentials and complex sinusoids.

COMMPLEX SINUSOIDAL SEQUENCES

- A complex sinusoidal sequence is a special case of a complex exponential $x(n) = ca^n$, where c and a are complex and |a| = 1 (i.e., a is of the form $e^{j\Omega}$ where Ω is real).
- That is, a complex sinusoidal sequence is a sequence of the form

$$x(n) = ce^{j\Omega n},$$

where c is complex and Ω is real.

Using Euler's relation, we can rewrite x(n) as

$$x(n) = \underbrace{|c|\cos(\Omega n + \arg c)}_{\text{Re}\{x(n)\}} + j\underbrace{|c|\sin(\Omega n + \arg c)}_{\text{Im}\{x(n)\}}.$$

- Thus, $Re\{x\}$ and $Im\{x\}$ are real sinusoids.
- A complex sinusoid is periodic if and only if $\frac{\Omega}{2\pi}$ is a $rational\ number$, in which case the fundamental period is the $smallest\ integer$ of the form $\frac{2\pi k}{|\Omega|}$ where k is a (strictly) positive integer.

COMMPLEX SINUSOIDAL SEQUENCES

 $\Omega = \frac{2\pi\ell}{m}$ where ℓ and m are integers, x can be shown to have the fundamental period

$$N=\frac{m}{\gcd(\ell,m)}.$$

In the case that ℓ and m are coprime (i.e., have no common factors), $N = \frac{m}{\gcd(\ell,m)} = \frac{m}{1} = m$.

Determine if each sequence x given below is periodic, if it is, find its fundamental period.

- (a) $x(n) = e^{j42n}$; (b) $x(n) = e^{j(4\pi/11)n}$; and (c) $x(n) = e^{j(\pi/3)n}$.

Solution. (a) Since $\frac{2\pi}{42} = \frac{\pi}{21}$ is not rational, x is not periodic. (b) Since

$$(2\pi)/(\frac{4\pi}{11}) = (2\pi)(\frac{11}{4\pi}) = \frac{11}{2}$$

is rational, x is periodic. The fundamental period N is the smallest integer of the form $\frac{11}{2}k$, where k is a strictly positive integer. Thus, N = 11 (corresponding to k = 2). Alternatively, the fundamental period N of $x(n) = e^{j(2\pi[2/11])n}$ is given by

$$N = \frac{11}{\gcd(11,2)} = \frac{11}{\gcd(11^1,2^1)} = \frac{11}{1} = 11.$$

(c) Since

$$\left(2\pi\right)/\left(\frac{\pi}{3}\right) = \left(2\pi\right)\left(\frac{3}{\pi}\right) = \frac{6}{1}$$

is rational, x is periodic. The fundamental period N is the smallest integer of the form $\frac{6}{1}k$, where k is a strictly positive integer. Thus, N = 6 (corresponding to k = 1). Alternatively, the fundamental period N of $x(n) = e^{j(\pi/3)n} = e^{j(2\pi[1]/6)n}$ is given by

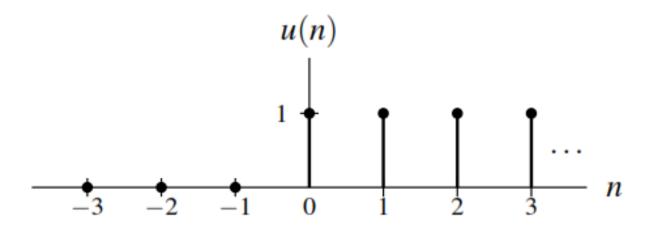
$$N = \frac{6}{\gcd(6,1)} = \frac{6}{\gcd(2^1 \cdot 3^1, 1)} = \frac{6}{1} = 6.$$

UNIT STEP SEQUENCE

■ The unit-step sequence, denoted u, is defined as

$$u(n) = \begin{cases} 1 & n \ge 0 \\ 0 & \text{otherwise.} \end{cases}$$

A plot of this sequence is shown below.



UNIT RECTANGULAR PULSES

A unit rectangular pulse is a sequence of the form

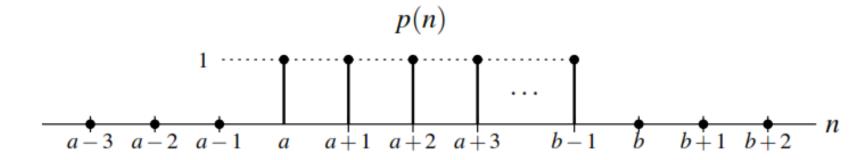
$$p(n) = \begin{cases} 1 & a \le n < b \\ 0 & \text{otherwise} \end{cases}$$

where a and b are integer constants satisfying a < b.

Such a sequence can be expressed in terms of the unit-step sequence as

$$p(n) = u(n-a) - u(n-b).$$

The graph of a unit rectangular pulse has the general form shown below.



UNIT IMPULSE SEQUENCE

■ The unit-impulse sequence (also known as the delta sequence), denoted δ , is defined as

$$\delta(n) = \begin{cases} 1 & n = 0 \\ 0 & \text{otherwise.} \end{cases}$$

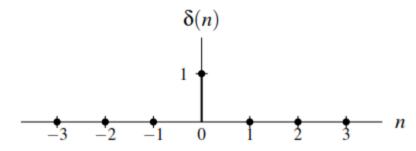
■ The first-order difference of u is δ . That is,

$$\delta(n) = u(n) - u(n-1).$$

■ The running sum of δ is u. That is,

$$u(n) = \sum_{k=-\infty}^{n} \delta(k).$$

 \blacksquare A plot of δ is shown below.



PROPERTIES OF THE UNIT IMPULSE SEQUENCES

For any sequence x and any integer constant n₀, the following identity holds:

$$x(n)\delta(n-n_0) = x(n_0)\delta(n-n_0)$$
. (Equivalence property).

For any sequence x and any integer constant n₀, the following identity holds:

$$\sum_{n=-\infty}^{\infty} x(n)\delta(n-n_0) = x(n_0).$$
 (Sifting property).

Trivially, the sequence δ is also even.

Evaluate the summation

$$\sum_{n=-\infty}^{\infty} \sin\left(\frac{\pi}{2}n\right) \delta(n-1).$$

Solution. Using the sifting property of the unit impulse sequence, we have

$$\sum_{n=-\infty}^{\infty} \sin\left(\frac{\pi}{2}n\right) \delta(n-1) = \sin\left(\frac{\pi}{2}n\right) \Big|_{n=1}$$

$$= \sin\left(\frac{\pi}{2}n\right)$$

$$= 1.$$

REPRESENTING RECTANGULAR PULSES

For integer constants a and b where a < b, consider a sequence x of the form</p>

$$x(n) = \begin{cases} 1 & a \le n < b \\ 0 & \text{otherwise} \end{cases}$$

(i.e., x is a *rectangular pulse* of height one that is nonzero from a to b-1 inclusive).

The sequence x can be equivalently written as

$$x(n) = u(n-a) - u(n-b)$$

(i.e., the difference of two time-shifted unit-step sequences).

- Unlike the original expression for x, this latter expression for x does not involve multiple cases.
- In effect, by using unit-step sequences, we have collapsed a formula involving multiple cases into a single expression.

Consider the piecewise-linear sequence x given by

$$x(n) = \begin{cases} n+7 & -6 \le n \le -4 \\ 4 & -3 \le n \le 2 \\ 6-n & 3 \le n \le 5 \\ 0 & \text{otherwise.} \end{cases}$$

Find a single expression for x(n) (involving unit-step sequences) that is valid for all n.

Solution.

$$v_1(n) = (n+7)[u(n+6) - u(n+3)].$$

$$v_2(n) = 4[u(n+3) - u(n-3)].$$

$$v_3(n) = (6-n)[u(n-3) - u(n-6)].$$

$$x(n) = v_1(n) + v_2(n) + v_3(n)$$

$$= (n+7)[u(n+6) - u(n+3)] + 4[u(n+3) - u(n-3)] + (6-n)[u(n-3) - u(n-6)]$$

$$= (n+7)u(n+6) - (n+7)u(n+3) + 4u(n+3) - 4u(n-3) + (6-n)u(n-3) - (6-n)u(n-6)$$

$$= (n+7)u(n+6) + (-n-3)u(n+3) + (2-n)u(n-3) + (n-6)u(n-6).$$

Discrete-Time (DT) Systems

PROPERTIES OF DT SYSTEM

- Memory
- Causality
- Invertibility
- BIBO Stability
- Time Invariance
- Linearity

Discrete-Time Linear Time-Invariant (LTI) Systems

Convolution

DT CONVOLUTION

The (DT) convolution of the sequences x and h, denoted x * h, is defined as the sequence

$$x * h(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k).$$

- The convolution x * h evaluated at the point n is simply a weighted sum of elements of x, where the weighting is given by h time reversed and shifted by n.
- Herein, the asterisk symbol (i.e., "*") will always be used to denote convolution, not multiplication.
- As we shall see, convolution is used extensively in the theory of (DT) systems.
- In particular, convolution has a special significance in the context of (DT) LTI systems.

DT CONVOLUTION

To compute the convolution

$$x * h(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k),$$

we proceed as follows:

- Plot x(k) and h(n-k) as a function of k.
- Initially, consider an arbitrarily large negative value for n. This will result in h(n-k) being shifted very far to the left on the time axis.
- Write the mathematical expression for x * h(n).
- Increase n gradually until the expression for x * h(n) changes form. Record the interval over which the expression for x * h(n) was valid.
- Repeat steps 3 and 4 until n is an arbitrarily large positive value. This corresponds to h(n-k) being shifted very far to the right on the time axis.
- The results for the various intervals can be combined in order to obtain an expression for x * h(n) for all n.

PROPERTIES OF DT CONVOLUTION

The convolution operation is commutative. That is, for any two sequences x and h,

$$x*h=h*x$$
.

The convolution operation is *associative*. That is, for any sequences x, h_1 , and h_2 ,

$$(x*h_1)*h_2 = x*(h_1*h_2).$$

The convolution operation is distributive with respect to addition. That is, for any sequences x, h1, and h2,

$$x*(h_1+h_2) = x*h_1+x*h_2.$$

REPRESENTATION OF SEQUENCES USING IMPULSES

For any sequence x,

$$x(n) = \sum_{k=-\infty}^{\infty} x(k)\delta(n-k) = x * \delta(n).$$

- Thus, any sequence x can be written in terms of an expression involving δ .
- Moreover, δ is the *convolutional identity*. That is, for any sequence x,

$$x * \delta = x$$
.

CIRCULAR CONVOLUTION

- The convolution of two periodic sequences is usually not well defined.
- This motivates an alternative notion of convolution for periodic sequences known as circular convolution.
- The circular convolution (also known as the DT periodic convolution) of the N-periodic sequences x and h, denoted $x \circledast h$, is defined as

$$x\circledast h(n)=\sum_{k=\langle N\rangle}x(k)h(n-k)=\sum_{k=0}^{N-1}x(k)h(\operatorname{mod}(n-k,N)),$$

where mod(a,b) is the remainder after division when a is divided by b.

The circular convolution and (linear) convolution of the N-periodic sequences x and h are related as follows:

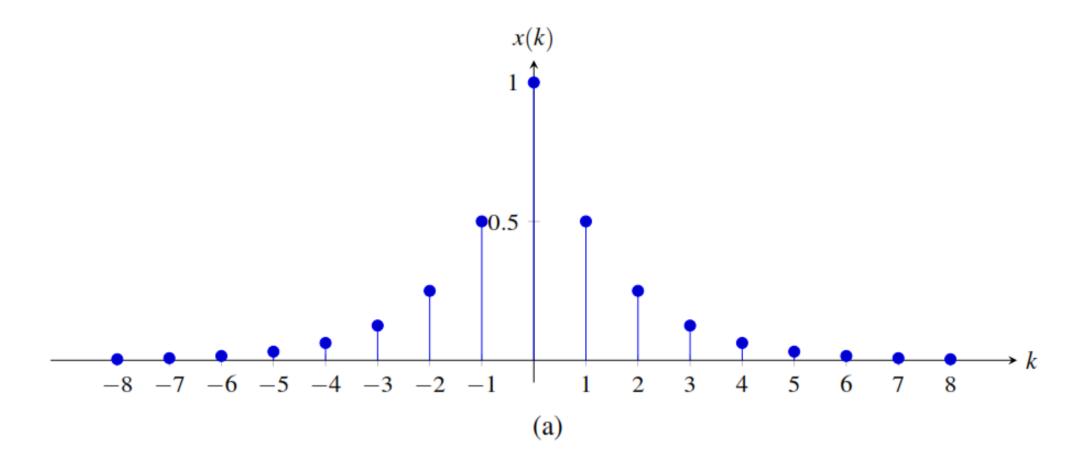
$$x \circledast h(n) = x_0 * h(n)$$
 where $x(n) = \sum_{k=-\infty}^{\infty} x_0(n-kN)$

(i.e., $x_0(n)$ equals x(n) over a single period of x and is zero elsewhere).

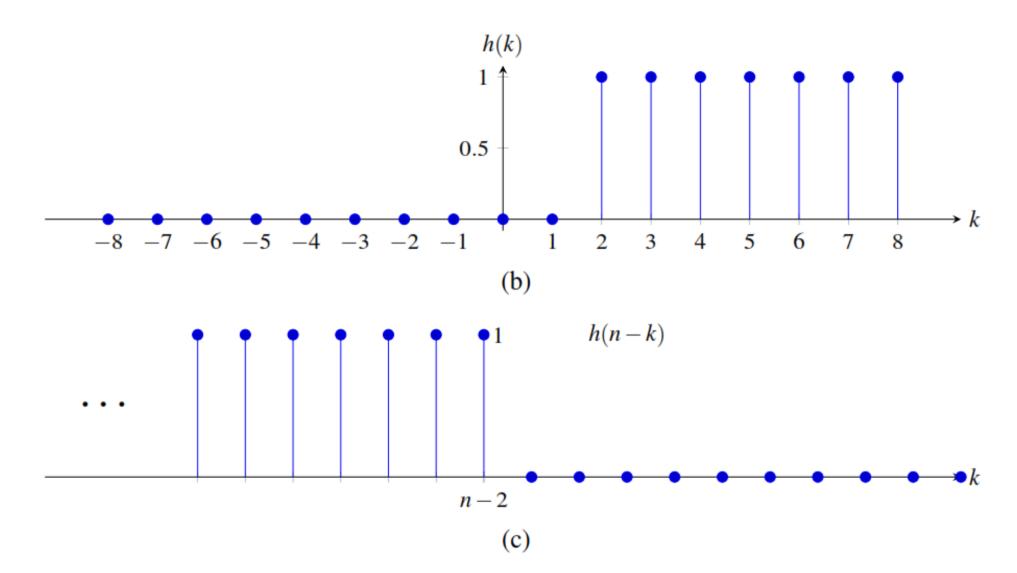
Compute x * h, where

$$x(n) = 2^{-|n|}$$
 and $h(n) = u(n-2)$.

Solution.



Solution.



Solution. From the definition of convolution, we have

$$x * h(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k)$$
$$= \sum_{k=-\infty}^{\infty} 2^{-|k|} u(n-k-2).$$

Since u(n-k-2) = 0 for k > n-2, we can write

$$x * h(n) = \sum_{k=-\infty}^{n-2} 2^{-|k|} = \begin{cases} \sum_{k=-\infty}^{n-2} 2^k & n-2 \le 0\\ \sum_{k=-\infty}^{0} 2^k + \sum_{k=1}^{n-2} 2^{-k} & n-2 > 0 \end{cases}$$
$$= \begin{cases} \sum_{k=-\infty}^{n-2} 2^k & n \le 2\\ \sum_{k=-\infty}^{0} 2^k + \sum_{k=1}^{n-2} 2^{-k} & n > 2. \end{cases}$$

$$\sum_{k=-\infty}^{n-2} 2^k = \sum_{k=2-n}^{\infty} \left(\frac{1}{2}\right)^k = \sum_{k=0}^{\infty} \left(\frac{1}{2}\right)^{k+2-n} = \sum_{k=0}^{\infty} \left(\frac{1}{2}\right)^{2-n} \left(\frac{1}{2}\right)^k$$

$$= \frac{\left(\frac{1}{2}\right)^{2-n}}{1 - \frac{1}{2}} = \left(\frac{1}{2}\right)^{2-n} \left(\frac{1}{2}\right)^{-1} = \left(\frac{1}{2}\right)^{1-n}$$

$$= 2^{n-1},$$

$$\sum_{k=-\infty}^{0} 2^k = \sum_{k=0}^{\infty} 2^{-k} = \sum_{k=0}^{\infty} \left(\frac{1}{2}\right)^k$$

$$= \frac{1}{1 - \frac{1}{2}} = \frac{1}{\frac{1}{2}} = (1)(2)$$

$$= 2, \quad \text{and}$$

$$\sum_{k=1}^{n-2} 2^{-k} = \sum_{k=0}^{n-3} 2^{-(k+1)} = \sum_{k=0}^{n-3} \left(\frac{1}{2}\right) \left(\frac{1}{2}\right)^k$$

$$= \left(\frac{1}{2}\right) \left(\frac{\left(\frac{1}{2}\right)^{n-2} - 1}{\frac{1}{2} - 1}\right) = \left(\frac{1}{2}\right) \left(\frac{\left(\frac{1}{2}\right)^{n-2} - 1}{-\frac{1}{2}}\right)$$

$$= 1 - \left(\frac{1}{2}\right)^{n-2}.$$

Substituting these simplified expressions into the earlier formula for x * h yields

$$x * h(n) = \begin{cases} 2^{n-1} & n \le 2\\ 3 - \left(\frac{1}{2}\right)^{n-2} & n > 2. \end{cases}$$

Convolution and LTI Systems

IMPULSE RESPONSE

- The response h of a system \mathcal{H} to the input δ is called the impulse response of the system (i.e., $h = \mathcal{H}\delta$).
- For any LTI system with input x, output y, and impulse response h, the following relationship holds:

$$y = x * h$$
.

- In other words, a LTI system simply computes a convolution.
- Furthermore, a LTI system is completely characterized by its impulse response.
- That is, if the impulse response of a LTI system is known, we can determine the response of the system to any input.

STEP RESPONSE

- The response s of a system \mathcal{H} to the input u is called the step response of the system (i.e., $s = \mathcal{H}u$).
- \blacksquare The impulse response h and step response s of a system are related as

$$h(n) = s(n) - s(n-1).$$

Therefore, the impulse response of a system can be determined from its step response by (first-order) differencing.

Properties of LTI Systems

MEMORY

■ A LTI system with impulse response *h* is memoryless if and only if

$$h(n) = 0$$
 for all $n \neq 0$.

That is, a LTI system is memoryless if and only if its impulse response h is of the form

$$h(n) = K\delta(n),$$

where *K* is a complex constant.

Consequently, every memoryless LTI system with input x and output y is characterized by an equation of the form

$$y = x * (K\delta) = Kx$$

(i.e., the system is an ideal amplifier).

For a LTI system, the memoryless constraint is extremely restrictive (as every memoryless LTI system is an ideal amplifier).

CAUSALITY

A LTI system with impulse response h is causal if and only if

$$h(n) = 0$$
 for all $n < 0$

(i.e., h is a causal sequence).

It is due to the above relationship that we call a sequence x, satisfying

$$x(n) = 0$$
 for all $n < 0$,

a causal sequence.

INVERTIBILITY

- The inverse of a LTI system, if such a system exists, is a LTI system.
- Let h and h_{inv} denote the impulse responses of a LTI system and its (LTI) inverse, respectively. Then,

$$h * h_{inv} = \delta$$
.

Consequently, a LTI system with impulse response h is invertible if and only if there exists a sequence h_{inv} such that

$$h * h_{inv} = \delta$$
.

Except in simple cases, the above condition is often quite difficult to test.

BIBO STABILITY

A LTI system with impulse response h is BIBO stable if and only if

$$\sum_{n=-\infty}^{\infty} |h(n)| < \infty$$

(i.e., h is absolutely summable).

EIGENSEQUENCES OF LTI SYSTEMS

- As it turns out, every complex exponential is an eigensequence of all LTI systems.
- For a LTI system \mathcal{H} with impulse response h,

$$\mathcal{H}\lbrace z^n\rbrace(n)=H(z)z^n,$$

where z is a complex constant and

$$H(z) = \sum_{n=-\infty}^{\infty} h(n)z^{-n}.$$

- That is, z^n is an eigensequence of a LTI system and H(z) is the corresponding eigenvalue.
- We refer to H as the system function (or transfer function) of the system \mathcal{H} .
- From above, we can see that the response of a LTI system to a complex exponential is the same complex exponential multiplied by the complex factor H(z).

REPRESENTATION OF SEQUENCES USING EIGENSEQUENCES

- \blacksquare Consider a LTI system with input x, output y, and system function H.
- Suppose that the input x can be expressed as the linear combination of complex exponentials

$$x(n) = \sum_{k} a_k z_k^n,$$

where the a_k and z_k are complex constants.

Using the fact that complex exponentials are eigenfunctions of LTI systems, we can conclude

$$y(n) = \sum_{k} a_k H(z_k) z_k^n.$$

- Thus, if an input to a LTI system can be expressed as a linear combination of complex exponentials, the output can also be expressed as linear combination of the same complex exponentials.
- The above formula can be used to determine the output of a LTI system from its input in a way that does not require convolution.

Discrete-Time Fourier Series (DTFS)

INTRODUCTION

- The Fourier series is a representation for periodic sequences.
- With a Fourier series, a sequence is represented as a linear combination of complex sinusoids.
- The use of complex sinusoids is desirable due to their numerous attractive properties.
- Perhaps, most importantly, complex sinusoids are eigensequences of (DT) LTI systems.

HARMONICALLY RELATED COMPLEX SINUSOIDS

- A set of periodic complex sinusoids is said to be harmonically related if there exists some constant $\frac{2\pi}{N}$ such that the fundamental frequency of each complex sinusoid is an integer multiple of $\frac{2\pi}{N}$.
- Consider the set of harmonically-related complex sinusoids given by

$$\phi_k(n) = e^{j(2\pi/N)kn}$$
 for all integer k .

■ In the above set $\{\phi_k\}$, only N elements are distinct, since

$$\phi_k = \phi_{k+N}$$
 for all integer k .

Since the fundamental frequency of each of the harmonically-related complex sinusoids is an integer multiple of $\frac{2\pi}{N}$, a linear combination of these complex sinusoids must be N-periodic.

DT FOURIER SERIES

 An N-periodic complex-valued sequence x can be represented as a linear combination of harmonically-related complex sinusoids as

$$x(n) = \sum_{k=\langle N \rangle} a_k e^{j(2\pi/N)kn},$$

where $\sum_{k=\langle N\rangle}$ denotes summation over any N consecutive integers (e.g., [0..N-1]). (The summation can be taken over any N consecutive integers, due to the N-periodic nature of x and $e^{j(2\pi/N)kn}$.)

- The above representation of x is known as the (DT) Fourier series and the a_k are called Fourier series coefficients.
- The above formula for x is often called the Fourier series synthesis equation.
- To denote that the sequence x has the Fourier series coefficient sequence a, we write

$$x(n) \stackrel{\text{\tiny DTFS}}{\longleftrightarrow} a_k$$
.

DT FOURIER SERIES

A periodic sequence x with fundamental period N has the Fourier series coefficient sequence a given by

$$a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x(n) e^{-j(2\pi/N)kn}.$$

(The summation can be taken over any N consecutive integers due to the N-periodic nature of x and $e^{-j(2\pi/N)kn}$.)

- The above equation for a_k is often referred to as the Fourier series analysis equation.
- Due to the N-periodic nature of x and $e^{-j(2\pi/N)kn}$, the sequence a is also N-periodic.

Properties of Fourier Series

PROPERTIES OF DT FOURIER SERIES

$$x(n) \stackrel{ exttt{DTFS}}{\longleftrightarrow} a_k \quad ext{ and } \quad y(n) \stackrel{ exttt{DTFS}}{\longleftrightarrow} b_k$$

Property	Time Domain	Fourier Domain
Linearity	$\alpha x(n) + \beta y(n)$	$\alpha a_k + \beta b_k$
Translation	$x(n-n_0)$	$e^{-jk(2\pi/N)n_0}a_k$
Modulation	$e^{j(2\pi/N)k_0n}x(n)$	a_{k-k_0}
Reflection	x(-n)	a_{-k}
Conjugation	$x^*(n)$	a_{-k}^*
Duality	a_n	$\frac{1}{N}x(-k)$
Periodic Convolution	$x \circledast y(n)$	Na_kb_k
Multiplication	x(n)y(n)	$a \circledast b_k$

Property	
Parseval's Relation	$\frac{1}{N}\sum_{n=\langle N\rangle} x(n) ^2 = \sum_{k=\langle N\rangle} a_k ^2$
Even Symmetry	x is even $\Leftrightarrow a$ is even
Odd Symmetry	x is odd $\Leftrightarrow a$ is odd
Real / Conjugate Symmetry	x is real $\Leftrightarrow a$ is conjugate symmetric

PARSEVAL'S RELATION

A sequence x and its Fourier series coefficient sequence a satisfy the following relationship:

$$\frac{1}{N} \sum_{n=\langle N \rangle} |x(n)|^2 = \sum_{k=\langle N \rangle} |a_k|^2.$$

- The above relationship is simply stating that the amount of energy in a single period of x and the amount of energy in a single period of a are equal up to a scale factor.
- In other words, the transformation between a sequence and its Fourier series coefficient sequence preserves energy (up to a scale factor).

TRIGONOMETRIC FORM OF A FOURIER SERIES

- Consider the N-periodic sequence x with Fourier series coefficient sequence a.
- If x is real, then its Fourier series can be rewritten in trigonometric form as shown below.
- The trigonometric form of a Fourier series has the appearance

$$x(n) = \begin{cases} \alpha_0 + \sum_{k=1}^{N/2-1} \left[\alpha_k \cos\left(\frac{2\pi kn}{N}\right) + \beta_k \sin\left(\frac{2\pi kn}{N}\right) \right] + \\ \alpha_{N/2} \cos(\pi n) & N \text{ even} \\ \alpha_0 + \sum_{k=1}^{(N-1)/2} \left[\alpha_k \cos\left(\frac{2\pi kn}{N}\right) + \beta_k \sin\left(\frac{2\pi kn}{N}\right) \right] & N \text{ odd,} \end{cases}$$

where $\alpha_0 = a_0$, $\alpha_{N/2} = a_{N/2}$, $\alpha_k = 2 \operatorname{Re} a_k$, and $\beta_k = -2 \operatorname{Im} a_k$.

Note that the above trigonometric form contains only real quantities.