

Q1.

Rewrite $f(t)$ as unit step function we have:

$$\begin{aligned} f(t) &= t[u(t) - u(t-1)] \\ \rightarrow F(s) &= \mathcal{L}\{f(t)\} = \frac{1}{s^2} + \left(\frac{1}{s^2} + \frac{1}{s}\right)e^{-s} \\ (\mathcal{L}\{tu(t-1)\}) &= \mathcal{L}\{(t-1+1)u(t-1)\} = \mathcal{L}\{(t+1)u(t)\}e^{-s} \end{aligned}$$

Q2.

Rewrite $f(t)$ as unit step function we have:

$$f(t) = (t-4)u(t) + (2t^2 - t - 4)u(t-3) - 2t^2u(t-5)$$

Q3.

$$\mathcal{L}^{-1}\left\{\frac{s+10}{(s^2+4)(s+2)}\right\} = \mathcal{L}^{-1}\left\{\frac{-s+3}{s^2+4} + \frac{1}{s+2}\right\} = -\cos 2t + \frac{3}{2}\sin 2t + e^{-2t}$$

Q4.

Given that:

$$y_{k+2} - 5y_{k+1} + 6y_k = 4^n (*), \quad y_0 = 0, \quad y_1 = 1$$

Let $Y(z) = \mathcal{Z}\{y_k\}$, it holds that:

$$\begin{aligned} \mathcal{Z}\{y_{k+1}\} &= zY(z) - zy_0 = zY(z) \\ \mathcal{Z}\{y_{k+2}\} &= z^2Y(z) - z^2y_0 - zy_1 = z^2Y(z) - z \end{aligned}$$

Taking \mathcal{Z} -transform both side of (*), we obtain:

$$\begin{aligned} [z^2Y(z) - z] - 5[zY(z)] + 6[Y(z)] &= \frac{z}{z-4} \\ \Leftrightarrow Y(z)(z^2 - 5z + 6) &= \frac{z}{z-4} + z \\ \rightarrow \frac{Y(z)}{z} &= \frac{1}{(z-4)(z^2 - 5z + 6)} + \frac{1}{z^2 - 5z + 6} \\ \Leftrightarrow \frac{Y(z)}{z} &= \frac{1}{2}\left(\frac{1}{z-4} - \frac{1}{z-2}\right) \\ \rightarrow Y(z) &= \frac{1}{2}\frac{1}{z-4} - \frac{1}{2}\frac{1}{z-2} \end{aligned}$$

a)

$$Y(z) = \frac{1}{2}\frac{1}{z-4} - \frac{1}{2}\frac{1}{z-2}$$

b)

$$\rightarrow y_k = \mathcal{Z}^{-1}\{Y(z)\} = \frac{1}{2} \cdot 4^k - \frac{1}{2} \cdot 2^k$$

Thus, the solution of the given system difference equations is:

$$y_k = \frac{1}{2} \cdot 4^k - \frac{1}{2} \cdot 2^k$$

Q5.

$$\begin{aligned} F(\omega) &= \mathcal{F}\{f(t)\} = \int_{-\infty}^{+\infty} f(t)e^{-j\omega t} dt = \int_{-1}^1 (1-|t|)e^{-j\omega t} dt \\ &= \int_0^1 (1-t)e^{-j\omega t} dt + \int_{-1}^0 (1+|t|)e^{-j\omega t} dt = \left[\frac{t-1}{j\omega} e^{-j\omega t} + \frac{1}{(j\omega)^2} e^{-j\omega t} \right]_0^1 \\ &= \frac{1}{(j\omega)^2} e^{-j\omega} - \frac{1}{(j\omega)^2} + \frac{1}{j\omega} = \frac{1}{\omega^2} (-\cos \omega + 1 + j(\sin \omega - \omega)) \end{aligned}$$

Q6.

We have:

$$\begin{aligned} f(t) &= \mathcal{F}^{-1}\{F(\omega)\} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \frac{2 \sin \omega}{\omega} e^{-j\omega t} dt \\ &= \frac{1}{\pi} \int_{-\infty}^{+\infty} \frac{\sin \omega}{\omega} (\cos \omega t + j \sin \omega t) dt \\ &= \frac{1}{\pi} \left[\int_{-\infty}^{+\infty} \frac{\sin \omega \cos \omega t}{\omega} dt + j \int_{-\infty}^{+\infty} \frac{\sin \omega \sin \omega t}{\omega} dt \right] \end{aligned}$$

Since we have: $\frac{\sin \omega \sin \omega t}{\omega}$ is an odd function with respect to ω , which leads to:

$$\int_{-\infty}^{+\infty} \frac{\sin \omega \sin \omega t}{\omega} dt = 0$$

Therefore,

$$f(t) = \frac{1}{\pi} \int_{-\infty}^{+\infty} \frac{\sin \omega \cos \omega t}{\omega} dt$$

Since $f(t) = 0$ for $t > 1$

Thus,

$$\int_{-\infty}^{+\infty} \frac{\sin \omega \cos \omega t}{\omega} dt = 0, \quad \forall t > 1$$

Q7.

Given that: $f(t) = 1 - |t|$, $-1 \leq t \leq 1$, $T = 2 \rightarrow \omega = \frac{2\pi}{T} = \pi$

a)

Since, $f(t)$ is an even function, so:

$$a_0 = \frac{4}{T} \int_0^{T/2} f(t) dt = \frac{4}{2} \int_0^1 (1 - t) dt = 1$$

b)

$$\begin{aligned} a_n &= \frac{4}{T} \int_0^{T/2} f(t) \cos(n\omega t) dt = \frac{4}{2} \int_0^1 (1 - t) \cos(n\pi t) dt \\ &= 2 \left[\frac{1-t}{n\pi} \sin(n\pi t) - \frac{1}{(n\pi)^2} \cos(n\pi t) \right] \Big|_0^1 \\ &= \frac{2}{n^2 \pi^2} (1 - (-1)^n) \end{aligned}$$

For any even integer n : $a_n = 0$

c)

For any odd integer $n = 2k - 1, k \geq 1$: $a_n = 4/n^2 \pi^2$

d)

Due to the given function is even, therefore, $b_n = 0$

e)

By Parseval's identity we obtain:

$$\begin{aligned} \frac{1}{2} \int_{-1}^1 (1 - |t|)^2 dt &= \frac{1}{4} 1^2 + \frac{1}{2} \sum_{n=1}^{+\infty} \left[\frac{2}{n^2 \pi^2} (1 - (-1)^n) \right]^2 \\ \Leftrightarrow \frac{1}{3} &= \frac{1}{4} + \frac{1}{2} \sum_{k=1}^{+\infty} \left[\frac{4}{(2k-1)^2 \pi^2} \right]^2 \Leftrightarrow \sum_{k=1}^{+\infty} \frac{1}{(2k-1)^4} = \frac{\pi^4}{96} \end{aligned}$$