

**University of Science and Technology of Hanoi
Information and Communication Technology Department**

**IMAGE DEBLURRING USING GAN
AND AUTOENCODER**

Group 22

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1. INTRODUCTION

Context and Motivation:

- Image deblurring is essential in computer vision.
- Crucial for fields: photography, surveillance, autonomous driving, medical imaging.
- Blurry images degrade performance in vision-based applications.
- Common causes: camera shake, defocus, fast-moving objects.



- (a) camera shake
- (b) defocus scene
- (c) moving objects.

1. INTRODUCTION

Objectives:

- Investigate GAN and Autoencoder for single-image motion deblurring.
- Train models on the GoPro dataset.
- Evaluate models with PSNR and SSIM.
- Compare performance with baseline models.

Expected outcomes:

- Develop GAN and Autoencoder-based deblurring systems.
- Evaluate image restoration performance.
- Identify strengths and limitations of each model.
- Demonstrate practical potential for real-world applications.

2.DATASET

- **GoPro Dataset:** High-quality dataset for motion deblurring.
- Captured using GoPro Hero4 Black camera at 240 fps.
- 3,214 image pairs: blurry and sharp ground truth.
- Resolution: 1280×720 pixels.
- Used for training and benchmarking deblurring models.

3. DATA PREPROCESSING

GAN Models:

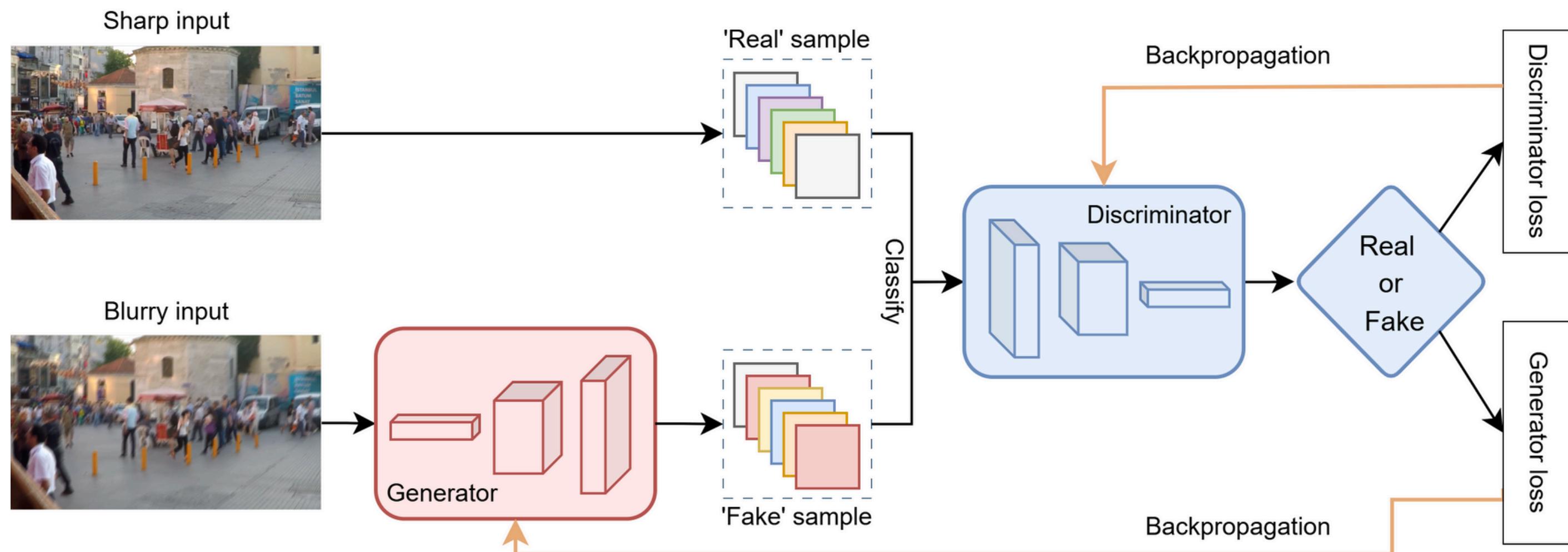
- Resize images to 448×448 pixels.
- Convert to tensor format for PyTorch.

Autoencoder Model:

- Resize images to 224×224 pixels.
- Normalize pixel values to range $[0, 1]$.

4. GAN ARCHITECTURE

Generator Architecture:



4. GAN ARCHITECTURE

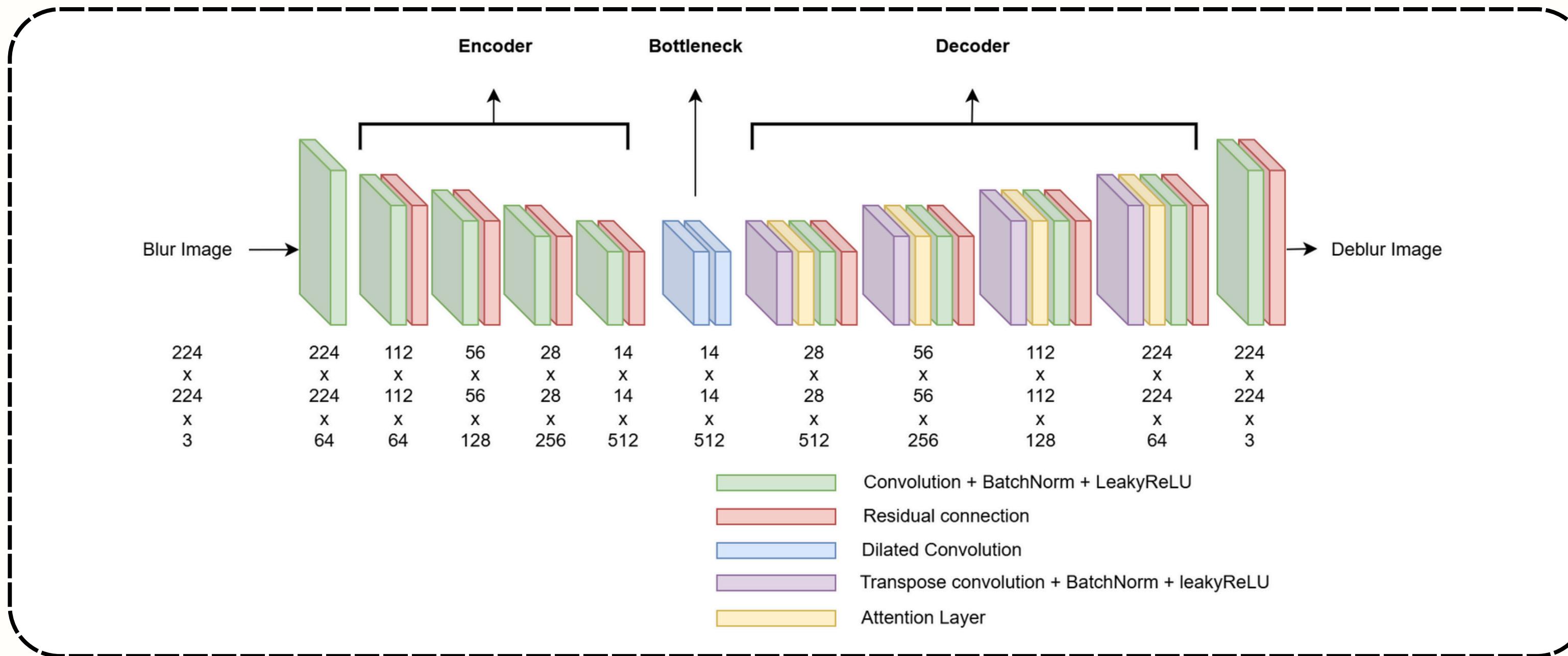
Generator:

- Encoder-decoder architecture.
- Extracts features from blurred images and reconstructs sharp images.
- Uses residual blocks for better feature propagation.

Discriminator:

- Classifies images as "real" (sharp) or "fake" (generated).
- Uses convolutional layers with batch normalization and LeakyReLU activation.
- Final layer: Sigmoid activation for real/fake probability.

5. AUTOENCODER ARCHITECTURE



5. AUTOENCODER ARCHITECTURE

Encoder:

- Progressive downsampling with increasing feature depth.
- Captures blur patterns at various resolutions.

Bottleneck:

- Dilated convolutions for a larger receptive field.
- Captures wide contextual information for accurate blur estimation.

Decoder:

- Upsamples to reconstruct sharp images.
- Uses residual connections and attention mechanisms to focus on important regions.

6. EVALUATION METRICS

PSNR (Peak Signal-to-Noise Ratio):

$$\text{MSE} = \frac{1}{M \cdot N} \sum_{i=0}^{M-1} \sum_{j=0}^{N-1} [I(i, j) - K(i, j)]^2$$

$$\text{PSNR} = 10 \cdot \log_{10} \left(\frac{\text{MAX}_I^2}{\text{MSE}} \right)$$

- Higher PSNR indicates better image quality.

SSIM (Structural Similarity Index Measure):

$$\text{SSIM}(x, y) = \frac{(2\mu_x\mu_y + C_1)(2\sigma_{xy} + C_2)}{(\mu_x^2 + \mu_y^2 + C_1)(\sigma_x^2 + \sigma_y^2 + C_2)}$$

- Closer to 1 means higher perceptual quality.

7. EXPERIMENTAL RESULTS

MODEL	Parameters	PSNR	SSIM
Kupyn et al	-	28.7	0.958
Nah et al	-	28.93	0.91
Ji et al	-	31.15	0.96
Li et al	11.4M	29.3	0.72
GAN (ours)	8.1M	27.24	0.8568
Autoencoder (ours)	10.3M	26.95	0.839

7. EXPERIMENTAL RESULTS

Autoencoder:

- From left to right: Input blur image, Ground truth sharp image, autoencoder output.



7. EXPERIMENTAL RESULTS

GAN architecture:

- From left to right: Input blur image, GAN output, Ground truth sharp image.



8. CHALLENGES AND LIMITATIONS

Challenges:

- Difficulty in restoring fine details in images.
- GAN architecture lacked advanced techniques like attention mechanisms and Wasserstein loss.
- Performance gap due to simplicity of models.

Limitations:

- Low PSNR and SSIM scores indicate challenges in fine detail restoration.
- Simple architectures in GAN and Autoencoder hinder performance on complex blur patterns.
- Lack of advanced regularization techniques.

9. CONCLUSION AND FUTURE WORK

Conclusions:

- Developed GAN and Autoencoder models for image deblurring.
- GAN performed slightly better, but both models showed potential.
- Integrated techniques like residual connections and attention for improved performance.

Future work:

- Improve sharpness and finer details for better deblurring.
- Capture more nuanced textures and structures in the blur.
- Expand the models' capabilities to handle diverse blur scenarios.
- Develop an application to demonstrate real-world model performance.

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**THANK YOU
FOR YOUR ATTENTION!**