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Mavic Mini Parameters .200 - .500

g_status_all_gyr_acc_need_calib_type	0	0	0	0	255	255	255	255	0	0	0	0
g_status_all_gyr_acc_msc_sampled_side	0	0	0	0	255	255	255	255	0	0	0	0
g_status_all_gyr_acc_msc_current_side	0	0	0	0	255	255	255	255	0	0	0	0
g_status_all_gyr_acc_calib_err	0	0	0	0	255	255	255	255	0	0	0	0
g_status_all_gyr_acc_calib_state	0	0	0	0	127	127	127	127	0	0	0	0
g_status_topodlogy_verify_user_interface imu_status	0	0	0	0	255	255	255	255	1	1	1	1
g_status_topodlogy_verify_user_interface mag_status	0	0	0	0	255	255	255	255	1	1	1	1
g_status_mag_adv_calib_status[0] process	0	0	0	0	100	100	100	100	0	0	0	0
g_status_mag_adv_calib_status[0] status	0	0	0	0	255	255	255	255	0	0	0	0
g_status_mag_adv_calib_status[0] item	0	0	0	0	255	255	255	255	0	0	0	0
g_status_mag_adv_calib_status[1] process	0	0	0	0	100	100	100	100	0	0	0	0
g_status_mag_adv_calib_status[1] status	0	0	0	0	255	255	255	255	0	0	0	0
g_status_mag_adv_calib_status[1] item	0	0	0	0	255	255	255	255	0	0	0	0
g_status_mag_adv_calib_status[2] process	0	0	0	0	100	100	100	100	0	0	0	0
g_status_mag_adv_calib_status[2] status	0	0	0	0	255	255	255	255	0	0	0	0
g_status_mag_adv_calib_status[2] item	0	0	0	0	255	255	255	255	0	0	0	0
g_status_have_mag_adv_param_flag	0	0	0	0	255	255	255	255	0	0	0	0
g_status_expg00_hw_type	0	0	0	0	255	255	255	255	0	0	0	0
g_status_expg01_hw_type	0	0	0	0	255	255	255	255	0	0	0	0
g_status_expg02_hw_type	0	0	0	0	255	255	255	255	0	0	0	0
g_config_fda_sensor[0]acc_bias	0	0	0	0	10000	10000	10000	10000	0	0	0	0
g_config_fda_sensor[0]gyr_bias	0	0	0	0	10000	10000	10000	10000	0	0	0	0
g_config_fda_sensor[0]mag_over	0	0	0	0	10000	10000	10000	10000	0	0	0	0
g_config_fda_sensor[0]acc_stat	0	0	0	0	255	255	255	255	0	0	0	0
g_config_fda_sensor[0]gyr_stat	0	0	0	0	255	255	255	255	0	0	0	0
g_config_fda_sensor[0]mag_stat	0	0	0	0	255	255	255	255	0	0	0	0
g_config_fda_sensor[1]acc_bias	0	0	0	0	10000	10000	10000	10000	0	0	0	0
g_config_fda_sensor[1]gyr_bias	0	0	0	0	10000	10000	10000	10000	0	0	0	0
g_config_fda_sensor[1]mag_over	0	0	0	0	10000	10000	10000	10000	0	0	0	0
g_config_fda_sensor[1]acc_stat	0	0	0	0	255	255	255	255	0	0	0	0
g_config_fda_sensor[1]gyr_stat	0	0	0	0	255	255	255	255	0	0	0	0
g_config_fda_sensor[1]mag_stat	0	0	0	0	255	255	255	255	0	0	0	0
g_config_fda_sensor[2]acc_bias	0	0	0	0	10000	10000	10000	10000	0	0	0	0
g_config_fda_sensor[2]gyr_bias	0	0	0	0	10000	10000	10000	10000	0	0	0	0
g_config_fda_sensor[2]mag_over	0	0	0	0	10000	10000	10000	10000	0	0	0	0
g_config_fda_sensor[2]acc_stat	0	0	0	0	255	255	255	255	0	0	0	0
g_config_fda_sensor[2]gyr_stat	0	0	0	0	255	255	255	255	0	0	0	0
g_config_fda_sensor[2]mag_stat	0	0	0	0	255	255	255	255	0	0	0	0
mag0_mod_sdvdr	0	0	0	0	10000	10000	10000	10000	0	0	0	0
mag1_mod_sdvdr	0	0	0	0	10000	10000	10000	10000	0	0	0	0
mag2_mod_sdvdr	0	0	0	0	10000	10000	10000	10000	0	0	0	0
mag0_mod	0	0	0	0	10000	10000	10000	10000	0	0	0	0
mag1_mod	0	0	0	0	10000	10000	10000	10000	0	0	0	0
mag2_mod	0	0	0	0	10000	10000	10000	10000	0	0	0	0
mag0_noise_large_flag	0	0	0	0	1	1	1	1	0	0	0	0
mag1_noise_large_flag	0	0	0	0	1	1	1	1	0	0	0	0
mag2_noise_large_flag	0	0	0	0	1	1	1	1	0	0	0	0
g_status_ns_busy_dev	0	0	0	0	65535	65535	65535	65535	0	0	0	0
g_status_user_info_statistical_info_total_distance	0	0	0	0	1000000000	1000000000	1000000000	1000000000	0	0	0	0
g_status_user_info_statistical_info_total_motor_start_time	0	0	0	0	1000000000	1000000000	1000000000	1000000000	0	0	0	0
g_status_user_info_statistical_info_last_total_distance	0	0	0	0	1000000000	1000000000	1000000000	1000000000	0	0	0	0
g_status_user_info_statistical_info_last_total_motor_start_time	0	0	0	0	1000000000	1000000000	1000000000	1000000000	0	0	0	0
g_status_battery_raw_info_capacity_percentage	0	0	0	0	255	255	255	255	0	0	0	0
motor_fail_for_mission_degrade_en	0	0	0	0	1	1	1	1	0	0	0	0
tempvar_switch_gearrig_config_gear_cfg_gear_func_en	0	0	0	0	1	1	1	1	0	0	0	0
limb_gearrig_config_gear_cfg_gear_control_enable	0	0	0	0	1	1	1	1	0	0	0	0
hale_gear_err_cfg_config_gear_cfg_hale_gear_en	0	0	0	0	1	1	1	1	0	0	0	0
near_ground_reminderig_config_gear_cfg_near_ground_reminder	0	0	0	0	1	1	1	1	0	0	0	0
fwitch_selectonig_config_control_mode[0]	0	0	0	0	14	14	14	14	12	12	12	12
fwitch_selecton_1ig_config_control_mode[1]	0	0	0	0	14	14	14	14	8	8	8	8
fwitch_selecton_2ig_config_control_mode[2]	0	0	0	0	14	14	14	14	7	7	7	7
mag0_att_rangep	10	10	10	10	60	60	60	60	15	15	15	15
wind_atm_intensityig_config_control_wind_atm_intensity	20	20	20	20	100	100	100	100	100	100	100	100
brake_sensitivity_fcig_config_control_brake_sensitivity_fc	0	0	0	0	2	2	2	2	0.800000011920929	0.800000011920929	0.800000011920929	0.800000011920929
brake_sensitivity_gaingig_config_control_brake_sensitivity	20	20	20	20	150	150	150	150	80	80	80	80
emergency_brake_sensitive	0	0	0	0	2	2	2	2	0.800000011920929	0.800000011920929	0.800000011920929	0.800000011920929
vert_vel_down_addingig_config_control_vert_vel_down_adding	0	0	0	0	5	5	5	5	0	0	0	0
vert_vel_down_adding_max	-10	0	0	0	-10	0	0	0	-3	-3	-3	-3
g_config_misic_cfg_gimbal_priority_en	0	0	0	0	1	1	1	1	0	0	0	0
ffg_speed_ctrl_percig_config_control_ffg_speed_ctrl_perc	0	0	0	0	100	100	100	100	5	4	4	4
sport_ffg_speed_ctrl_percig_config_control_sport_ffg_speed_ctrl_perc	0	0	0	0	100	100	100	100	5	4	4	4
trip_ffg_speed_ctrl_percig_config_control_trip_ffg_speed_ctrl_perc	0	0	0	0	100	100	100	100	5	4	4	4
g_config_misic_cfg_follow_gimbal_yaw_when_watchig_cfg_debug_follow_gimbal_yaw_when_watch	0	0	0	0	1	1	1	1	1	1	1	1
gimbal_gyro_follow_flight_sit	20	20	20	20	60	60	60	60	30	30	30	30
gimbal_tilt_max	-10	-10	-10	-10	45	45	45	45	-5	-5	-5	-5
quick_circle_tors_rate_limit	90	90	90	90	300	300	300	300	250	250	250	250
prop_cover_err_rc_scale	0.2000000002980232	0.2000000002980232	0.2000000002980232	0.2000000002980232	1	1	1	1	0.69999998879071	0.69999998879071	0.69999998879071	0.69999998879071
prop_cover_err_tilt_atti_range	5	5	5	5	5	5	5	5	20	20	20	20
prop_cover_err_tors_gyro_range	5	5	5	5	250	250	250	250	90	90	90	90
prop_cover_err_vel_vst_ap	1	1	1	1	10	10	10	10	1.5	1.5	1.5	1.5
prop_cover_err_vel_vst_down	-10	-10	-10	-10	-10	-10	-10	-10	-1.5	-1.5	-1.5	-1.5
prop_cover_err_tilt_exp_mid_point	0.1000000001490116	0.1000000001490116	0.1000000001490116	0.1000000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.2000000002980232	0.2000000002980232	0.2000000002980232	0.2000000002980232
prop_cover_err_tors_exp_mid_point	0.1000000001490116	0.1000000001490116	0.1000000001490116	0.1000000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.2000000002980232	0.2000000002980232	0.2000000002980232	0.2000000002980232
prop_cover_err_tilt_exp_mid_point	0.1000000001490116	0.1000000001490116	0.1000000001490116	0.1000000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.2000000002980232	0.2000000002980232	0.2000000002980232	0.2000000002980232
g_config_avoid_obstacle_limit_cfg_avoid_obstacle_enable	0	0	0	0	1	1	1	1	0	0	0	0
user_avoid_enableig_config_avoid_obstacle_limit_cfg_user_avoid_enable	0	0	0	0	1	1	1	1	0	0	0	0
avoid_dis	0	0	0	0	5	5	5	5	1	1	1	1
avoid_err_rc_scaleig_config_avoid_cfg_avoid_rc_scale	0.1000000001490116	0.1000000001490116	0.1000000001490116	0.1000000001490116	0.800000011920929	0.800000011920929	0.800000011920929	0.800000011920929	0.550000011920929	0.550000011920929	0.550000011920929	0.550000011920929
avoid_cfg_tors_rate_rangeig_config_avoid_cfg_avoid_tors_rate_range	30	30	30	30	90	90	90	90	70	70	70	70
notice_func_enableig_config_notice_cfg_notice_func_enabled	0	0	0	0	1	1	1	1	0	0	0	0
low_radius_limit_enable	0	0	0	0	1	1	1	1	0	0	0	0
g_config_flying_limit_max_radius	15	15	15	15	5000	5000	5000	5000	2000	2000	2000	2000
g_config_flying_limit_max_height	15	15	15	15	500	500	500	500	120	120	120	120
g_config_flying_limit_radius_limit_enableig_config_advanced_function_radius_limit_enabled	0	0	0	0	1	1	1	1	1	1	1	1
g_config_flying_limit_min_height	1	1	1	1	20	20	20	20	20	20	20	20
min_height_user	1	1	1	1	20	20	20	20	5	5	5	5
g_config_flying_limit_user_avoid_ground_enable	0	0	0	0	1	1	1	1	1	1	1	1
g_config_flying_limit_avoid_ground_and_smart_landing_enable	0	0	0	0	1	1	1	1	1	1	1	1
limit_height_red	0	0	0	0	30	30	30	30	5	5	5	5
g_config_flying_limit_roof_limit_enable	0	0	0	0	1	1	1	1	0	0	0	0
flying_limit_share_limit_enabled	0	0	0	0	1	1	1	1	0	0	0	0
flying_limit_water_low_limit_enable	0	0	0	0	1	1	1	1	0	0	0	0
prop_cover_limit_enable	0	0	0	0	1	1	1	1	0	0	0	0
prop_cover_limit_radius_max	5	5	5	5	300	300	300	300	100	100	100	100
prop_cover_limit_ah_max	5	5	5	5	300	300	300	300	120	120	120	120
gps_enableig_config_gps_cfg_gps_enable	0	0	0	0	1	1	1	1	1	1	1	1
forearm_led_ctrlig_config_misic_cfg_forearm_hump_ctrl	0	0	0	0	255	255	255	255	255	255	255	255
tilt_sensitive_gaingig_config_control_rc_tilt_sensitivity	0	20	20	20	100	100	100	100	100	100	100	100
yaw_sensitive_gain	20	20	20	20	100	100	100	100	100	100	100	100
rc_throttle_sensitivity	20	20	20	20	100	100	100	100	100	100	100	100
mounting_tpycig_config_topodlogy_verify_single_multi_controller	0	0	0	0	1	1	1	1	0	0	0	0
g_config_gyr_acc_cfg_msc_require_side	0	0	0	0	255	255	255	255	62	62	62	62
g_config_misic_cfg_follow_gimbal_yaw												

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level2_smart_battery_config.voltage2_level2_smart_battery_land	0	0	0	0	100	100	100	100	5	5	5	5
tracking_low_battery_act	0	0	0	0	1	1	1	1	0	0	0	0
pointing_low_battery_act	0	0	0	0	1	1	1	1	0	0	0	0
sop_type	0	0	0	0	755	755	755	755	3	3	3	3
over_temperature_protect_enable	0	0	0	0	1	1	1	1	1	1	1	1
emergency_capacity	0	0	0	0	100	100	100	100	0	0	0	0
emergency_voltage	2500	2500	2500	2500	4000	4000	4000	4000	3170	3170	3170	3170
lower_limit_power	0	0	0	0	5000	5000	5000	5000	30	30	30	30
enable_new_smart_battery	0	0	0	0	2	2	2	2	1	1	1	1
go_home_current	0	0	0	0	65535	65535	65535	65535	9000	9000	9000	9235
go_home_current_prop_cover	0	0	0	0	65535	65535	65535	65535	15000	15000	15000	15450
max_battery_power	0	0	0	0	65535	65535	65535	65535	100	100	100	100
lower_limit_temperature	-2000	-2000	-2000	-2000	2000	2000	2000	2000	-100	-100	-100	-100
batt_enable_cas2_protect	0	0	0	0	1	1	1	1	0	0	0	0
batt_enable_smart_batt_landing_protect	0	0	0	0	1	1	1	1	1	1	1	1
lowest_voltage	0	0	0	0	65535	65535	65535	65535	0	0	0	0
lowest_battery_power	0	0	0	0	65535	65535	65535	65535	90	90	90	90
sop_set_value_in_watt	0	0	0	0	4294967295	4294967295	4294967295	4294967295	0	0	0	0
sop_set_target_percentage	0	0	0	0	100	100	100	100	80	80	80	80
battery_type_name_detect	0	0	0	0	1	1	1	1	0	0	0	0
sop_limit_low_temp	-20	-20	-20	-20	50	50	50	50	-10	-10	-10	-10
sop_limit_low_temp_sop	10	10	10	10	250	250	250	250	30	30	30	30
sop_limit_high_temp	-20	-20	-20	-20	50	50	50	50	5	5	5	5
sop_limit_high_temp_sop	10	10	10	10	250	250	250	250	30	30	30	30
sop_min_takeoff_temp	-20	-20	-20	-20	50	50	50	50	-10	-10	-10	-10
rotate_theta	-180	-180	-180	-180	180	180	180	180	0	0	0	0
imu_0_pps_temp_cali_start_flag0_cfg.debug_imu_cali_state[0][1]	0	0	0	0	127	127	127	127	0	0	0	0
g_cfg.debug_imu_cali_state[1][1]	0	0	0	0	127	127	127	127	0	0	0	0
g_cfg.debug_imu_cali_state[2][1]	0	0	0	0	127	127	127	127	0	0	0	0
modify_type	0	0	0	0	43	43	43	43	0	0	0	0
map_0	0	0	0	0	255	255	255	255	0	0	0	0
map_1	0	0	0	0	255	255	255	255	0	0	0	0
map_2	0	0	0	0	255	255	255	255	0	0	0	0
map_3	0	0	0	0	255	255	255	255	0	0	0	0
map_4	0	0	0	0	255	255	255	255	0	0	0	0
map_5	0	0	0	0	255	255	255	255	0	0	0	0
map_6	0	0	0	0	255	255	255	255	0	0	0	0
map_7	0	0	0	0	255	255	255	255	0	0	0	0
map_8	0	0	0	0	255	255	255	255	0	0	0	0
map_9	0	0	0	0	255	255	255	255	0	0	0	0
map_10	0	0	0	0	255	255	255	255	0	0	0	0
map_11	0	0	0	0	255	255	255	255	0	0	0	0
map_12	0	0	0	0	255	255	255	255	0	0	0	0
map_13	0	0	0	0	255	255	255	255	0	0	0	0
map_14	0	0	0	0	255	255	255	255	0	0	0	0
map_15	0	0	0	0	255	255	255	255	0	0	0	0
map_16	0	0	0	0	255	255	255	255	0	0	0	0
map_17	0	0	0	0	255	255	255	255	0	0	0	0
map_18	0	0	0	0	255	255	255	255	0	0	0	0
map_19	0	0	0	0	255	255	255	255	0	0	0	0
map_20	0	0	0	0	255	255	255	255	0	0	0	0
map_21	0	0	0	0	255	255	255	255	0	0	0	0
map_22	0	0	0	0	255	255	255	255	0	0	0	0
map_23	0	0	0	0	255	255	255	255	0	0	0	0
map_24	0	0	0	0	255	255	255	255	0	0	0	0
map_25	0	0	0	0	255	255	255	255	0	0	0	0
map_26	0	0	0	0	255	255	255	255	0	0	0	0
map_27	0	0	0	0	255	255	255	255	0	0	0	0
map_28	0	0	0	0	255	255	255	255	0	0	0	0
map_29	0	0	0	0	255	255	255	255	0	0	0	0
R_RC_A	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_E	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_T	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_R	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_U	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_U_FAILSAFE	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_GEAR	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_GO_HOME_SQUARE	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_GO_HOME_SWITCH	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_EMERGENCY_MODE	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_EMERGENCY_STOP	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_PAUSE_STOP	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_IDC	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_K1	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_K2	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_K3	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_K4	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_K5	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_K6	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_D1	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_D2	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_D3	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_D4	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_D5	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_D6	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_D7	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_D8	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_FARM_LEFT	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_FARM_RIGHT	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_FARM_SET_A	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_FARM_SET_B	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_FARM_SET_AB	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_FARM_MANUAL_SPRAY	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_FARM_FLOW_SPEED	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_FARM_MODE	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_C1	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_START_STOP_MOTOR	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_FARM_FRONT	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_FARM_BACK	0	0	0	0	1	1	1	1	0	0	0	0
R_RC_CAMERA	0	0	0	0	1	1	1	1	0	0	0	0
rc_type	0	0	0	0	8	8	8	8	1	1	1	1
RC_ARM_STOP_ENABLE0_cfg.arm_action_enable	0	0	0	0	1	1	1	1	1	1	1	1
RC_EMERGENCY_STOP_ENABLE	0	0	0	0	1	1	1	1	0	0	0	0
RC_STOP_CHECK_ENABLE	0	0	0	0	1	1	1	1	1	1	1	1
knob_basic_roll	0	0	0	0	6	6	6	6	6	6	6	6
knob_basic_pitch	0	0	0	0	6	6	6	6	6	6	6	6
knob_basic_yaw	0	0	0	0	6	6	6	6	6	6	6	6
knob_basic_thrust	0	0	0	0	6	6	6	6	6	6	6	6
knob_control_channel_KNOB_ATTITUDE_GAIN	0	0	0	0	6	6	6	6	6	6	6	6
knob_control_channel_KNOB_CYRO_GAIN	0	0	0	0	6	6	6	6	6	6	6	6
knob_control_channel_KNOB_ATTITUDE_HORIZ_GAIN	0	0	0	0	6	6	6	6	6	6	6	6
knob_control_channel_KNOB_ATTITUDE_VERT_GAIN	0	0	0	0	6	6	6	6	6	6	6	6
knob_control_channel_KNOB_ATTITUDE_RANGE_GAIN	0	0	0	0	6	6	6	6	6	6	6	6
knob_control_channel_KNOB_ATTITUDE_VERT_UP_GAIN	0	0	0	0	6	6	6	6	6	6	6	6
knob_control_channel_KNOB_BRAKE_GAIN	0	0	0	0	6	6	6	6	6	6	6	6
knob_control_channel_KNOB_TILT_GAIN	0	0	0	0	6	6	6	6	6	6	6	6
knob_control_channel_KNOB_HORIZ_POS_GAIN	0	0	0	0	6	6	6	6	6	6	6	6
knob_control_channel_KNOB_HORIZ_VELOCITY_GAIN	0	0	0	0	6	6	6	6	6	6	6	6
dead_zone	0	0	0	0	10	10	10	10	3	3	3	3
RC_STOP_MOTOR_TYPE	0	0	0	0	255	255	255	255	6	6	6	6
rc_brake_pause_time_ms	0	0	0	0	4294967295	4294967295	4294967295	4294967295	2500	2500	2500	2500
hw_port	0	0	0	0	2	2	2	2	0	0	0	0
sd卡_baud	110	110	110	110	1000000	1000000	1000000	1000000	230400	230400	230400	230400
sd卡_enable	0	0	0	0	1	1	1	1	1	1	1	1
sd卡_enable_1860	0	0	0	0	1	1	1	1	1	1	1	1
enable_sd卡_lost_strategy	0	0	0	0	1	1	1	1	0	0	0	0
sd卡_lost_strategy	0	0	0	0	3	3	3	3	0	0	0	0
enable_prosh_mission_status0_cfg.api_entry_cfg.enable_prosh_mission_status	0	0	0	0	1	1	1	1	0	0	0	0
sd卡_data_type_acc	0	0	0	0	5	5	5	5	0	0	0	0
sd卡_data_type_gyro	0	0	0	0	5	5	5	5	0	0	0	0
sd卡_data_type_alti	0	0	0	0	5	5	5	5	0	0	0	0
sd卡_data_type_height	0	0	0	0	5	5	5	5	0	0	0	0
pos_data_type0_cfg.api_entry_cfg.pos_data_type	0	0	0	0	5	5	5	5	0	0	0	0
sd卡_timestamp	0	0	0	0	6	6	6	6	0	0	0	0
sd卡_qt	0	0	0	0	6	6	6	6	0			

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idk_ctrl_device	0	0	0	0	6	6	6	6	0	0	0	0
std_msg_freq_14	0	0	0	0	6	6	6	6	0	0	0	0
std_msg_freq_15	0	0	0	0	6	6	6	6	0	0	0	0
idle_leveling_config.engine.idle_level	1	1	1	1	30	30	30	30	10	10	10	10
idle_timing_config.engine.idle_time	1	1	1	1	5	5	5	5	1.10000002384186	1.10000002384186	1.10000002384186	1.10000002384186
prop_auto_preload_config.engine.prop.auto_preload	0	0	0	0	2	2	2	2	1	1	1	1
sequence_start_config.engine.sequence_start_en	0	0	0	0	1	1	1	1	0	0	0	0
g_config.takoff.auto.takoff_height	1.20000004768372	1.20000004768372	1.20000004768372	1.20000004768372	100	100	100	100	1.20000004768372	1.20000004768372	1.20000004768372	1.20000004768372
g_config.takoff.auto.takoff_vel	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	3	3	3	3	1	1	1	1
mode_manual_cfg.tilt_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.5	0.5	0.5	0.5
mode_manual_cfg.tors_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.5	0.5	0.5	0.5
mode_manual_cfg.roll_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.5	0.5	0.5	0.5
exit_landing_ground_not_smooth_enable_config.landing.exit_landing_ground_not_smooth_enable	0	0	0	0	1	1	1	1	1	1	1	1
adv_landing_enable_config.landing.adv_landing_enable	0	0	0	0	1	1	1	1	0	0	0	0
go_home.height_config.go_home.fixed.go_home.altitude	15	15	15	15	500	500	500	500	30	30	30	30
go_home.heading_config.go_home.go_home.heading_option	0	0	0	0	1	1	1	1	1	1	1	1
go_home.when_running_go_config.go_home.go_home.when_running_go	0	0	0	0	1	1	1	1	0	0	0	0
avoid_enable_config.go_home.avoid_enable	0	0	0	0	1	1	1	1	0	0	0	0
adv_gohome_enable_config.go_home.adv_gohome_enable	0	0	0	0	1	1	1	1	0	0	0	0
cur_height_gohome_enable_config.go_home.cur_height_gohome_enable	0	0	0	0	1	1	1	1	0	0	0	0
cur_height_gohome_disable_config.go_home.cur_height_gohome_disable	10	10	10	10	80	80	80	80	20	20	20	20
avoid_ascending_height_limit_disable_config.go_home.avoid_ascending_height_limit_disable	0	0	0	0	1	1	1	1	0	0	0	0
force_ascending_align_enable_config.go_home.force_ascending_align_enable	0	0	0	0	1	1	1	1	1	1	1	1
go_home.finish_radius	0.00999999776483	0.00999999776483	0.00999999776483	0.00999999776483	10	10	10	10	1	1	1	1
miss_rtk_use_rtk_data_config.miss_rtk_use_rtk_data	0	0	0	0	1	1	1	1	0	0	0	0
g_config.mode.tripod_cfg.rc_scale	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.600000023841858	0.600000023841858	0.600000023841858	0.600000023841858	0.379999995231628	0.379999995231628	0.379999995231628	0.379999995231628
mode_tripod_cfg.tilt_atti_range	10	10	10	10	10	60	60	60	20	20	20	20
g_config.mode.tripod_cfg.tors_gyro_range	1	1	1	1	5	300	300	300	30	30	30	30
g_config.mode.tripod_cfg.vert_vel_up	0.5	0.5	0.5	0.5	1	1	1	1	1.5	1.5	1.5	1.5
g_config.mode.tripod_cfg.vert_vel_down	-3	-3	-3	-3	-1	-0.5	-0.5	-0.5	-1	-1	-1	-1
tripod_fuse_enable_config.mode_tripod_en_cfg.tripod_fuse_enable	0	0	0	0	1	1	1	1	0	0	0	0
CM.tors_range	5	5	5	5	250	250	250	250	50	50	50	50
CM.brake_sensitive	10	10	10	10	150	150	150	150	10	10	10	10
mode_gentle_cfg.rc_scale	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	1	1	1	1	0.25	0.25	0.25	0.25
mode_gentle_cfg.tilt_atti_range	10	10	10	10	60	60	60	60	20	20	20	20
mode_gentle_cfg.tors_gyro_range	50	50	50	50	300	300	300	300	70	70	70	70
mode_gentle_cfg.vert_vel_down	1	1	1	1	10	10	10	10	1.5	1.5	1.5	1.5
mode_gentle_cfg.vert_vel_up	-10	-10	-10	-10	-10	-1	-1	-1	-1	-1	-1	-1
g_config.mode.gentle_cfg.tilt_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.40000005960465	0.40000005960465	0.40000005960465	0.40000005960465
g_config.mode.gentle_cfg.tors_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.40000005960465	0.40000005960465	0.40000005960465	0.40000005960465
g_config.mode.gentle_cfg.roll_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.40000005960465	0.40000005960465	0.40000005960465	0.40000005960465
g_config.mode.normal_cfg.rc_scale	0.20000002980232	0.20000002980232	0.20000002980232	0.20000002980232	1	1	1	1	0.70999996036314	0.70999996036314	0.70999996036314	0.70999996036314
g_config.mode.normal_cfg.tilt_atti_range	3	3	3	3	60	60	60	60	20	20	20	20
g_config.mode.normal_cfg.tors_gyro_range	5	5	5	5	130	130	130	130	130	130	130	130
g_config.mode.normal_cfg.vert_vel_up	1	1	1	1	10	10	10	10	2	2	2	2
g_config.mode.normal_cfg.vert_vel_down	-10	-10	-10	-10	-1	-1	-1	-1	-1	-1	-1	-1
g_config.mode.normal_cfg.tilt_exp_mid_point_config.control.tilt_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.40000005960465	0.40000005960465	0.40000005960465	0.40000005960465
g_config.mode.normal_cfg.tors_exp_mid_point_config.control.yaw_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.300000011920929	0.300000011920929	0.300000011920929	0.300000011920929
g_config.mode.normal_cfg.roll_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.40000005960465	0.40000005960465	0.40000005960465	0.40000005960465
g_config.mode.sport_cfg.rc_scale	0.20000002980232	0.20000002980232	0.20000002980232	0.20000002980232	1	1	1	1	0.925000011920929	0.925000011920929	0.925000011920929	0.925000011920929
mode_sport_cfg.tilt_atti_range_config.mode.sport_cfg.tilt_atti_range	10	10	10	10	10	60	60	60	30	30	30	30
g_config.mode.sport_cfg.tors_gyro_range	5	5	5	5	100	100	100	100	150	150	150	150
mode_sport_cfg.vert_vel_up_config.mode.sport_cfg.vert_vel_up	1	1	1	1	10	10	10	10	4	4	4	4
mode_sport_cfg.vert_vel_down_config.mode.sport_cfg.vert_vel_down	-10	-10	-10	-10	-1	-1	-1	-1	-3	-3	-3	-3
g_config.mode.sport_cfg.tilt_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.40000005960465	0.40000005960465	0.40000005960465	0.40000005960465
g_config.mode.sport_cfg.tors_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.300000011920929	0.300000011920929	0.300000011920929	0.300000011920929
g_config.mode.sport_cfg.roll_exp_mid_point	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.40000005960465	0.40000005960465	0.40000005960465	0.40000005960465
prop_cover_limit_fc_test	0.10000001490116	0.10000001490116	0.10000001490116	0.10000001490116	0.899999976158142	0.899999976158142	0.899999976158142	0.899999976158142	0.40000005960465	0.40000005960465	0.40000005960465	0.40000005960465
zenmuse_cfg.type_config.zenmuse_cfg.type	-1	-1	-1	-1	1	1	1	1	-1	-1	-1	-1
dynamic_brake_atti_enable	0	0	0	0	1	1	1	1	1	1	1	1
brake_scale_in_min_vel	1	1	1	1	100	100	100	100	80	80	80	80
brake_scale_in_max_vel	1	1	1	1	100	100	100	100	100	100	100	100
brake_atti_limit_min_vel	0	0	0	0	100	100	100	100	7	7	7	7
brake_atti_limit_max_vel	0	0	0	0	100	100	100	100	10	10	10	10
brake_scale_in_high_altitude	1	1	1	1	100	100	100	100	65	65	65	65
down_vel_scale_in_high_altitude	1	1	1	1	100	100	100	100	80	80	80	80
fc_dark_need_gyro	1	1	1	1	1	1	1	1	1	1	1	1
prop_abnormal_test	1	1	1	1	1	1	1	1	1	1	1	1
prop_abnormal_flag	1	1	1	1	1	1	1	1	1	1	1	1