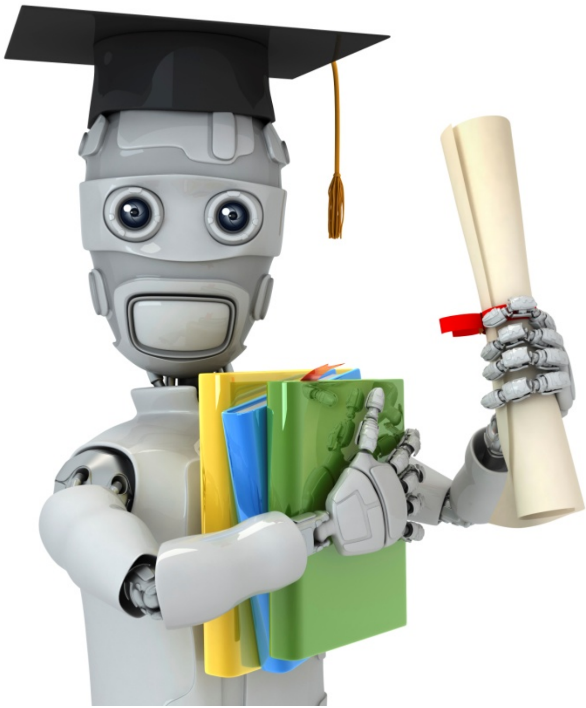


Machine Learning

Anomaly detection

Problem motivation

Anomaly detection example

Aircraft engine features:

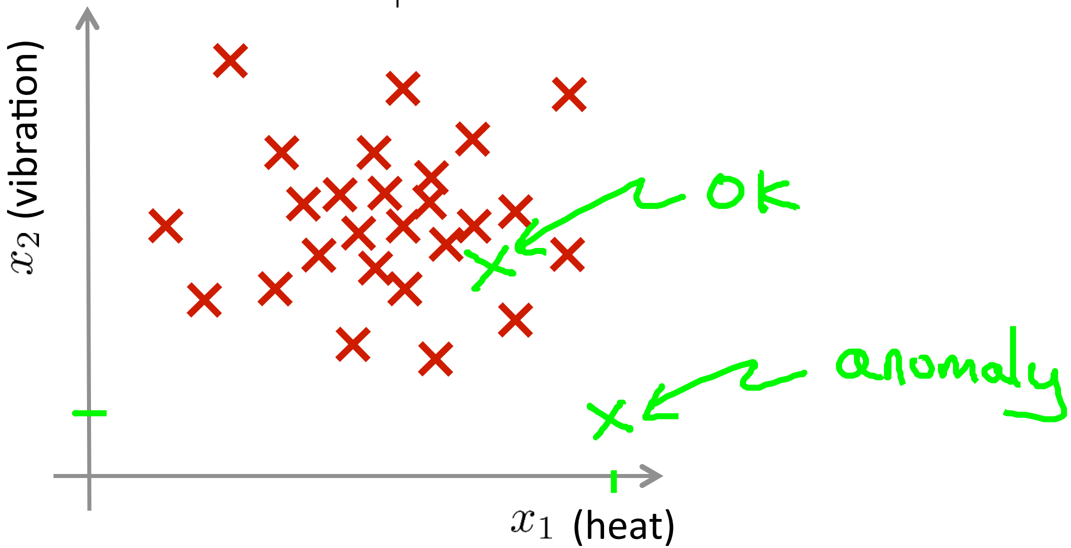
x_1 = heat generated

x_2 = vibration intensity

…

Dataset: $\{x^{(1)}, x^{(2)}, \ldots, x^{(m)}\}$

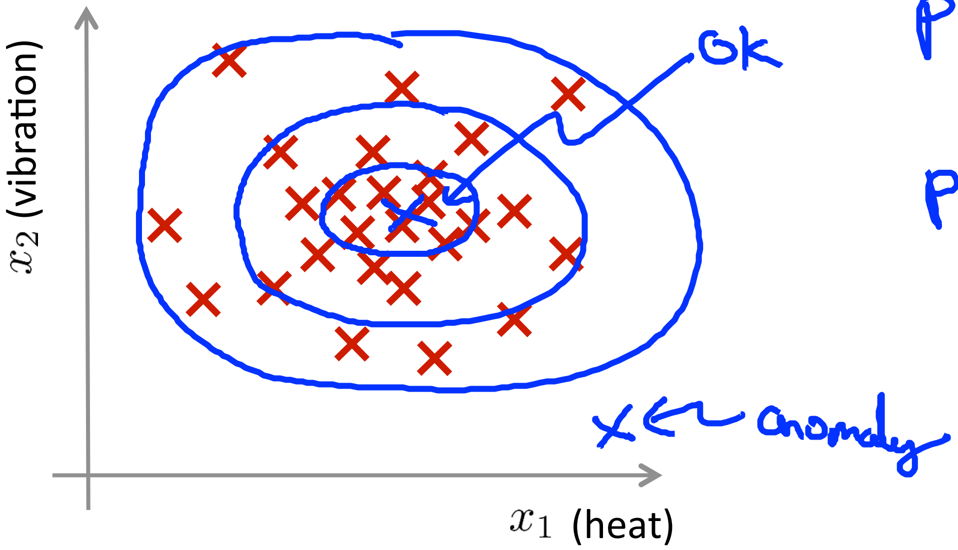
New engine: x_{test}



Density estimation

- Dataset: $\{x^{(1)}, x^{(2)}, \ldots, x^{(m)}\}$
- Is x_{test} anomalous?

Model $\underline{p(x)}$.



$p(x_{test}) < \varepsilon \rightarrow$ flag anomaly

$p(x_{test}) \geq \varepsilon \rightarrow$ OK

Anomaly detection example

x_1
x_2
x_3
x_4

$p(x)$

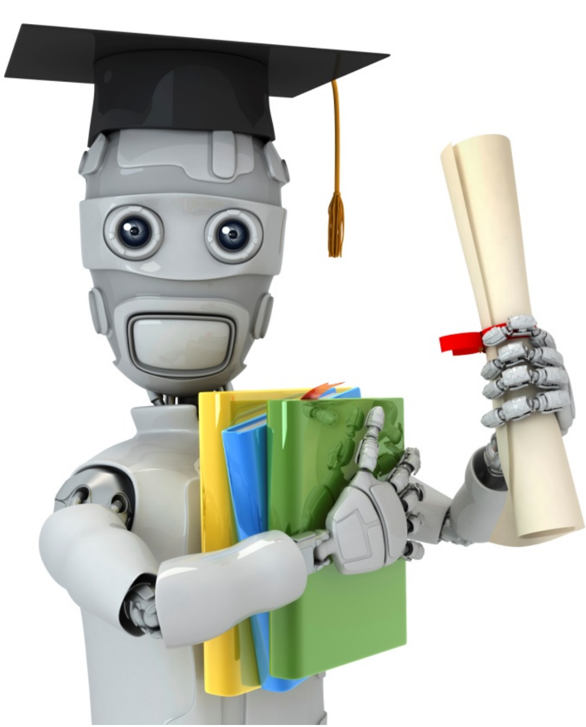
- Fraud detection:
  - $x^{(i)}$ = features of user i 's activities
  - Model $p(x)$ from data.
  - Identify unusual users by checking which have $p(x) < \varepsilon$
- Manufacturing
- Monitoring computers in a data center.
  - $x^{(i)}$ = features of machine i

    x_1 = memory use, x_2 = number of disk accesses/sec,

    x_3 = CPU load, x_4 = CPU load/network traffic.

    …

$p(x) < \varepsilon$



Machine Learning

Anomaly detection

Gaussian distribution

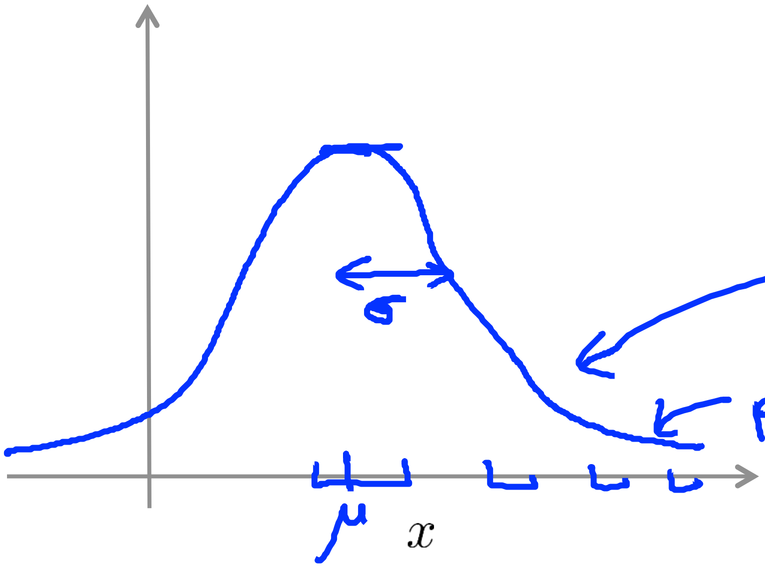
Gaussian (Normal) distribution

Say $x \in \mathbb{R}$. If x is a distributed Gaussian with mean μ, variance σ^2.

$x \sim \mathcal{N}(\mu, \sigma^2)$

"distributed as"

σ standard deviation

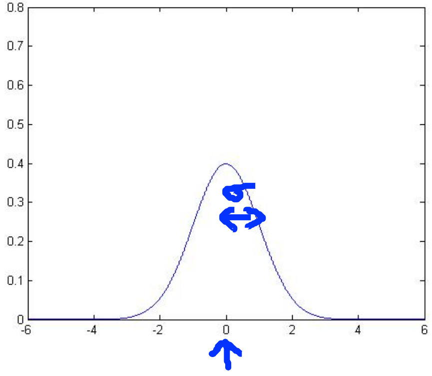


$$p(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\,\sigma} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$

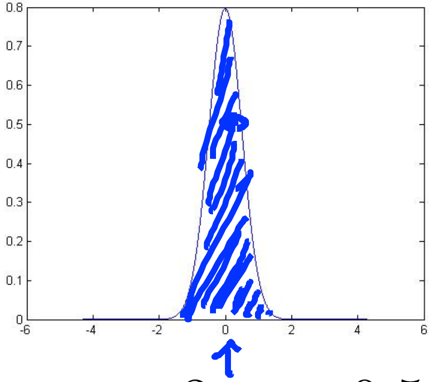
$p(x; \mu, \sigma^2)$

Gaussian distribution example

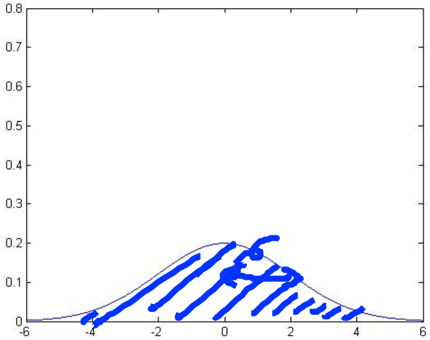
$\mu = 0, \sigma = 1$



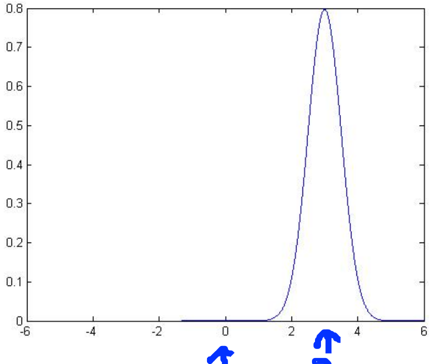
$\mu = 0, \sigma = \underline{0.5}$ $\quad \sigma^2 = 0.25$



$\mu = 0, \sigma = 2$



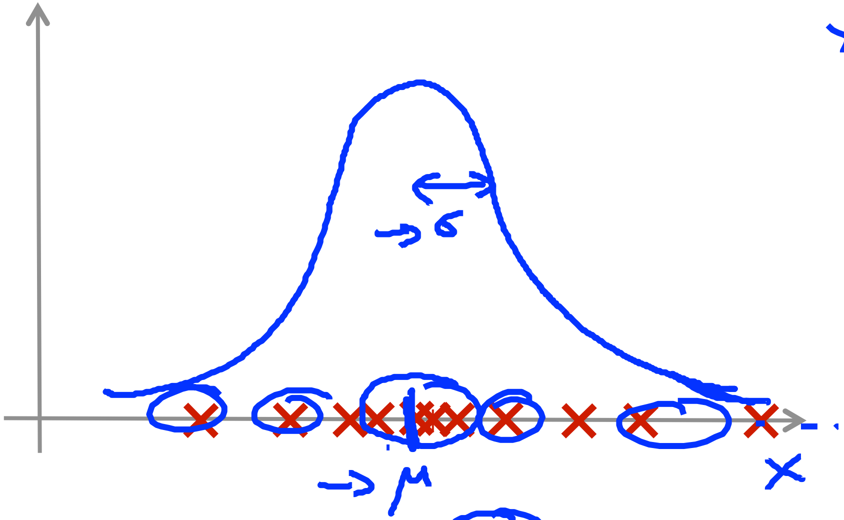
$\mu = 3, \sigma = 0.5$



Parameter estimation

→ Dataset: $\{x^{(1)}, x^{(2)}, \ldots, x^{(m)}\}$ $\quad \underline{x^{(i)} \in \mathbb{R}}$

$x^{(i)} \sim \mathcal{N}(\mu, \sigma^2)$



$$\rightarrow \mu = \frac{1}{m}\sum_{i=1}^{m} x^{(i)}$$

$$\rightarrow \sigma^2 = \frac{1}{m}\sum_{i=1}^{m} \underbrace{(x^{(i)} - \mu)^2}$$

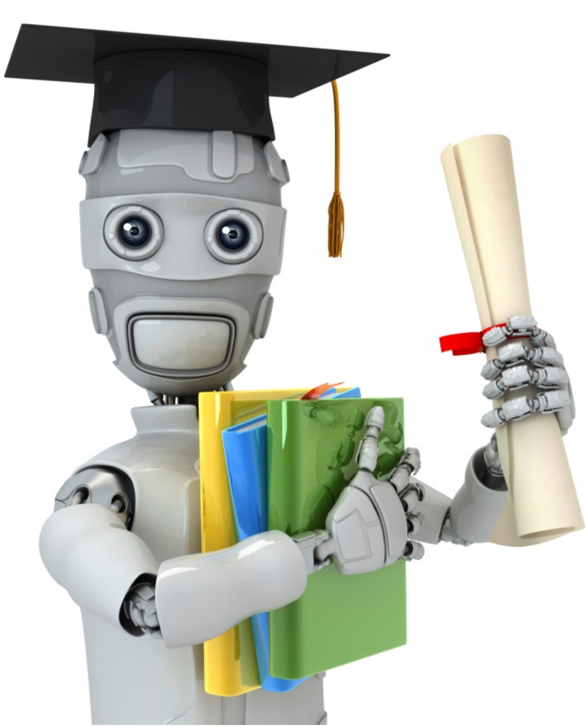
$m-1$

$\frac{1}{m-1}$

Andrew Ng

Anomaly detection

Algorithm



Machine Learning

Density estimation

Training set: $\{x^{(1)}, \ldots, x^{(m)}\}$

Each example is $x \in \mathbb{R}^n$

$x_1 \sim \mathcal{N}(\mu_1, \sigma_1^2)$

$x_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$

$x_3 \sim \mathcal{N}(\mu_3, \sigma_3^2)$

$p(x)$

$= \boxed{p(x_1; \mu_1, \sigma_1^2)\, p(x_2; \mu_2, \sigma_2^2)\, p(x_3; \mu_3, \sigma_3^2) \cdots p(x_n; \mu_n, \sigma_n^2)}$

$= \boxed{\prod_{j=1}^{n}} p(x_j; \mu_j, \sigma_j^2)$

$\sum_{i=1}^{n} i = 1 + 2 + 3 + \ldots + n$

$\prod_{i=1}^{n} i = 1 \times 2 \times 3 \times \ldots \times n$

Anomaly detection algorithm

1. Choose features x_i that you think might be indicative of anomalous examples.

   $\{x^{(1)}, \dots, x^{(m)}\}$

2. Fit parameters $\mu_1, \dots, \mu_n, \sigma_1^2, \dots, \sigma_n^2$

$$\boxed{\mu_j = \frac{1}{m}\sum_{i=1}^{m} x_j^{(i)}}$$

$$\sigma_j^2 = \frac{1}{m}\sum_{i=1}^{m} (x_j^{(i)} - \mu_j)^2$$

$p(x_j; \mu_j, \sigma_j^2)$

$\mu_1, \mu_2, \dots, \mu_n$

$$\mu = \begin{bmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_n \end{bmatrix} = \frac{1}{m}\sum_{i=1}^{m} x^{(i)}$$

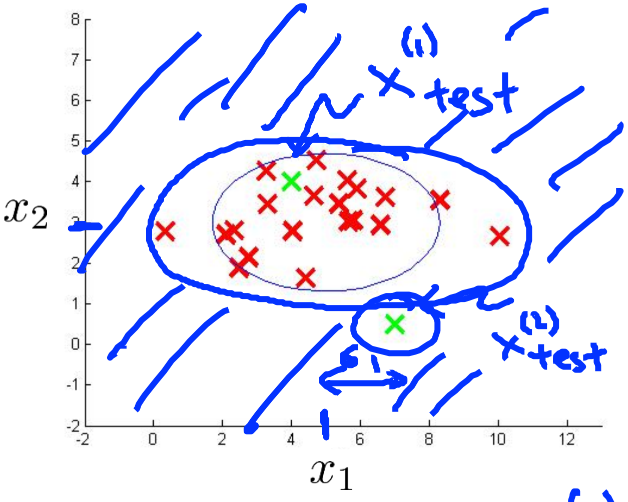
3. Given new example x, compute $p(x)$:

$$p(x) = \prod_{j=1}^{n} p(x_j; \mu_j, \sigma_j^2) = \prod_{j=1}^{n} \frac{1}{\sqrt{2\pi}\sigma_j} \exp\left(-\frac{(x_j - \mu_j)^2}{2\sigma_j^2}\right)$$

Anomaly if $p(x) < \varepsilon$

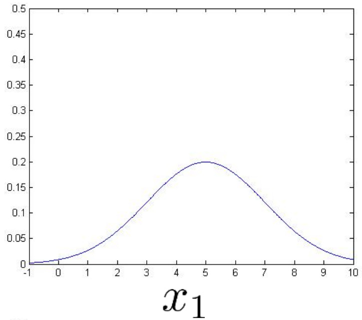
$\rightarrow p(x) = p(x_1; \mu_1, \sigma_1^2) \times p(x_2; \mu_2, \sigma_2^2)$

Anomaly detection example

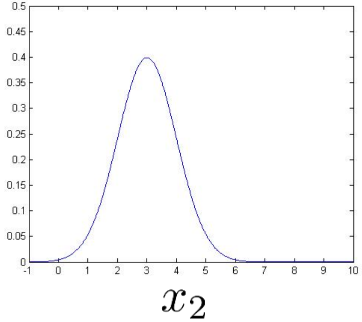


$\sigma_1^2, \sigma_2^2 = 4$

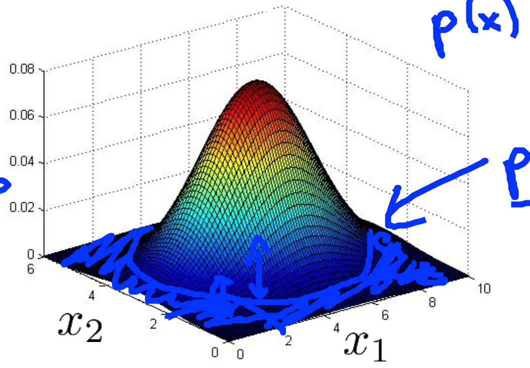
$$\boxed{\begin{aligned} \mu_1 &= 5, \sigma_1 = 2 \\ \mu_2 &= 3, \sigma_2 = 1 \end{aligned}}$$



$p(x_1; \mu_1, \sigma_1^2)$



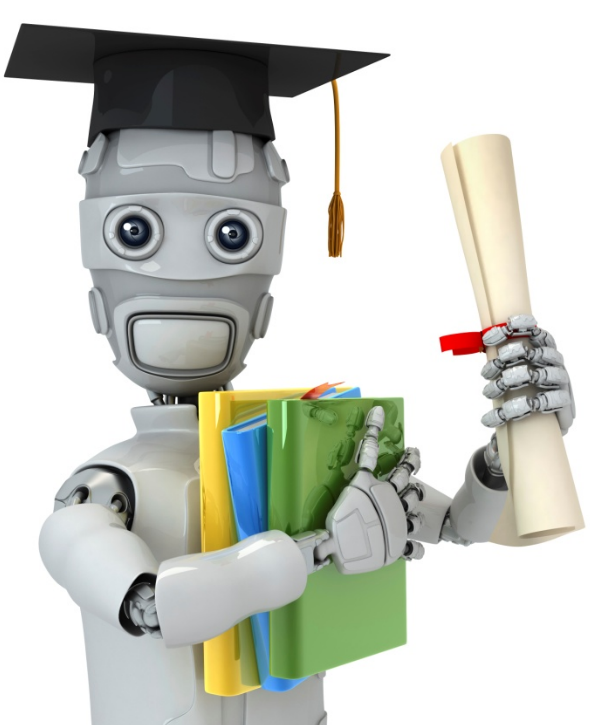
$p(x_2; \mu_2, \sigma_2^2)$



$\varepsilon = 0.02$

$p(x_{test}^{(1)}) = 0.0426 \quad > \varepsilon$

$p(x_{test}^{(2)}) = 0.0021 \quad < \varepsilon$



Machine Learning

Anomaly detection

Developing and evaluating an anomaly detection system

The importance of real-number evaluation

When developing a learning algorithm (choosing features, etc.), making decisions is much easier if we have a way of evaluating our learning algorithm.

→ Assume we have some labeled data, of anomalous and non-anomalous examples. ($y = 0$ if normal, $y = 1$ if anomalous).

→ Training set: $x^{(1)}, x^{(2)}, \ldots, x^{(m)}$ (assume normal examples/not anomalous)

→ Cross validation set: $(x_{cv}^{(1)}, y_{cv}^{(1)}), \ldots, (x_{cv}^{(m_{cv})}, y_{cv}^{(m_{cv})})$

→ Test set: $(x_{test}^{(1)}, y_{test}^{(1)}), \ldots, (x_{test}^{(m_{test})}, y_{test}^{(m_{test})})$

y=1

Aircraft engines motivating example

10000 good (normal) engines

20 flawed engines (anomalous) $\underline{2 - 50}$ $\underline{y=1}$

$\mu_1, \sigma_1^2, \ldots, \mu_n, \sigma_n^2$

Training set: 6000 good engines $(y=0)$ $p(x) = p(x_1; \mu_1, \sigma_1^2) \cdots p(x_n; \mu_n, \sigma_n^2)$

CV: 2000 good engines ($y = 0$), 10 anomalous ($y = 1$)

Test: 2000 good engines ($y = 0$), 10 anomalous ($y = 1$)

Alternative:

Training set: 6000 good engines

CV: 4000 good engines ($y = 0$), 10 anomalous ($y = 1$)

Test: 4000 good engines ($y = 0$), 10 anomalous ($y = 1$)

Algorithm evaluation

- Fit model $p(x)$ on training set $\{x^{(1)}, \ldots, x^{(m)}\}$ $(x_{test}^{(i)}, y_{test}^{(i)})$
- On a cross validation/test example x, predict

$$y = \begin{cases} 1 & \text{if } p(x) < \varepsilon \text{ (anomaly)} \\ 0 & \text{if } p(x) \geq \varepsilon \text{ (normal)} \end{cases}$$

$y = 0$

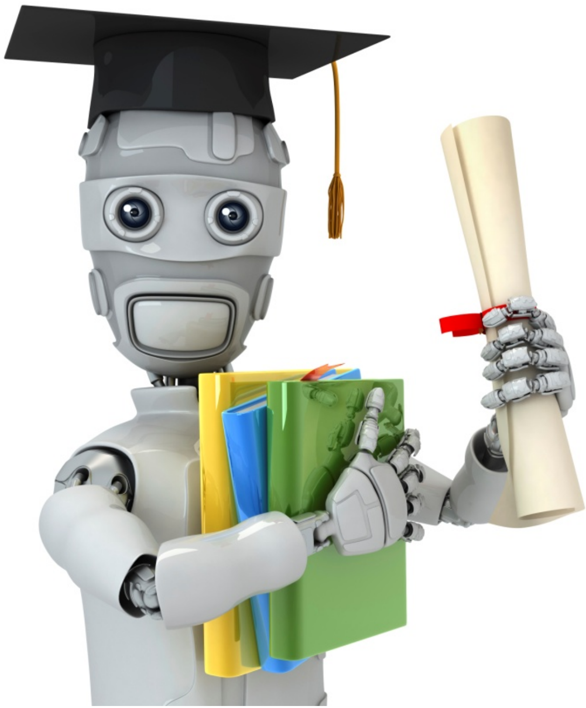
Possible evaluation metrics:

- True positive, false positive, false negative, true negative
- Precision/Recall
- F_1-score

CV

Test set

Can also use cross validation set to choose parameter ε



Machine Learning

Anomaly detection

Anomaly detection vs. supervised learning

Anomaly detection vs. Supervised learning

Anomaly detection

- Very small number of positive examples ($y = 1$). (0-20 is common).
- Large number of negative ($y = 0$) examples. $\boxed{p(x)}$
- Many different "types" of anomalies. Hard for any algorithm to learn from positive examples what the anomalies look like;
- future anomalies may look nothing like any of the anomalous examples we've seen so far.

Supervised learning

- Large number of positive and negative examples.
- Enough positive examples for algorithm to get a sense of what positive examples are like, future positive examples likely to be similar to ones in training set.

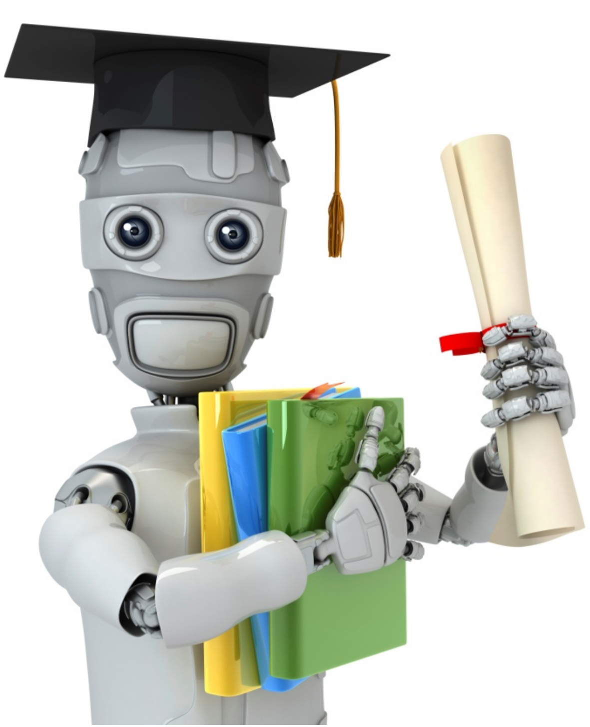
Spam

Anomaly detection vs. Supervised learning

Anomaly detection	Supervised learning
• Fraud detection $y=1$	• Email spam classification
• Manufacturing (e.g. aircraft engines)	• Weather prediction (sunny/rainy/etc).
• Monitoring machines in a data center	• Cancer classification
⋮	⋮

Anomaly detection

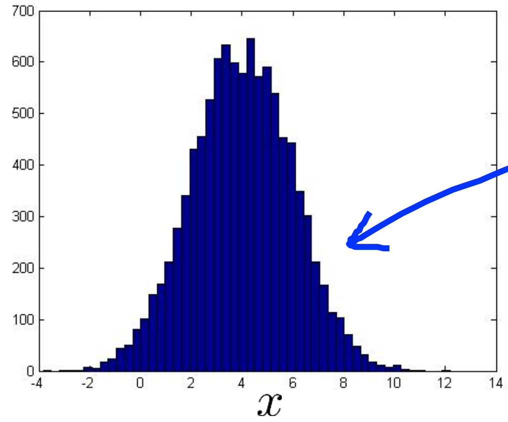
Choosing what features to use



Machine Learning

Non-gaussian features

$p(x_i; \mu_i, \sigma_i^2)$



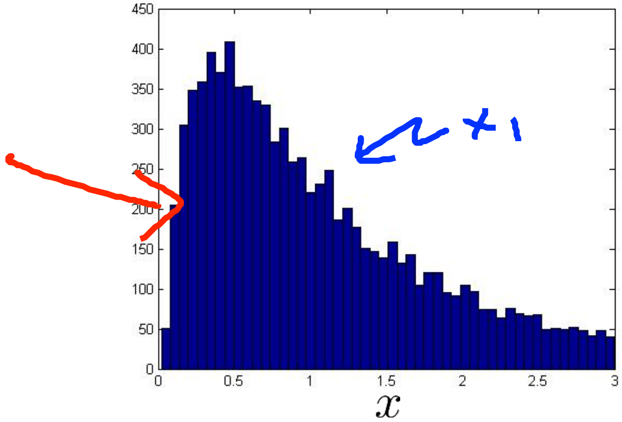
hist

$x_1 \leftarrow \log(x_1)$

$x_2 \leftarrow \log(x_2 + 1)$ $\qquad \log(x_2 + c)$

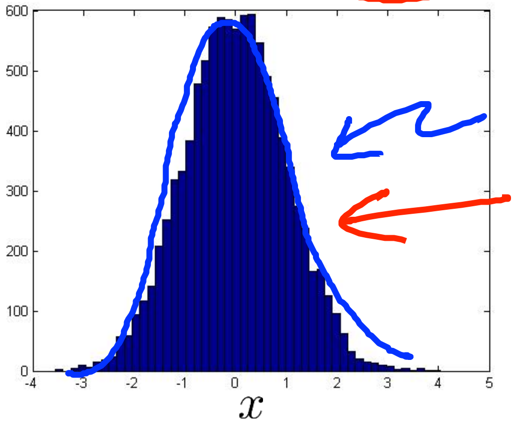
$x_3 \leftarrow \sqrt{x_3} = x_3^{\frac{1}{2}}$

$x_4 \leftarrow x_4^{\frac{1}{3}}$



x_1

$\xrightarrow{\log(x)}$



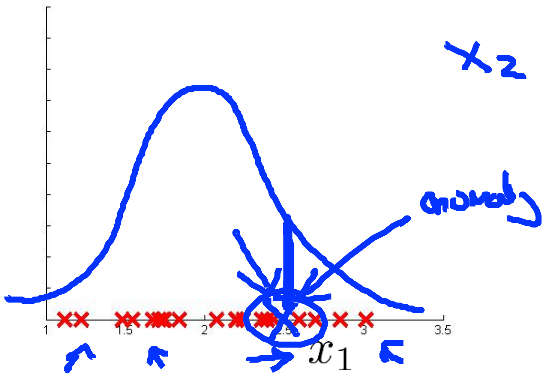
Error analysis for anomaly detection

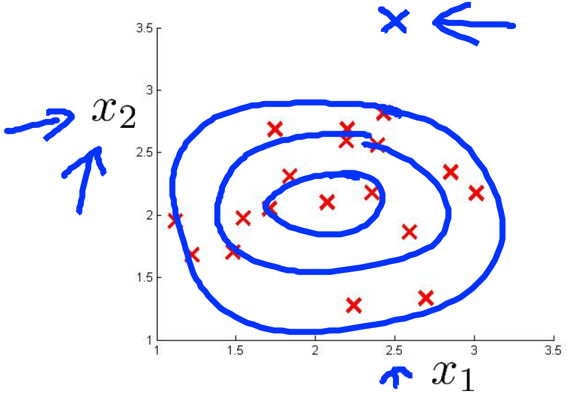
Want $p(x)$ large for normal examples x.

$p(x)$ small for anomalous examples x.

Most common problem:

$p(x)$ is comparable (say, both large) for normal and anomalous examples





Monitoring computers in a data center

Choose features that might take on unusually large or small values in the event of an anomaly.

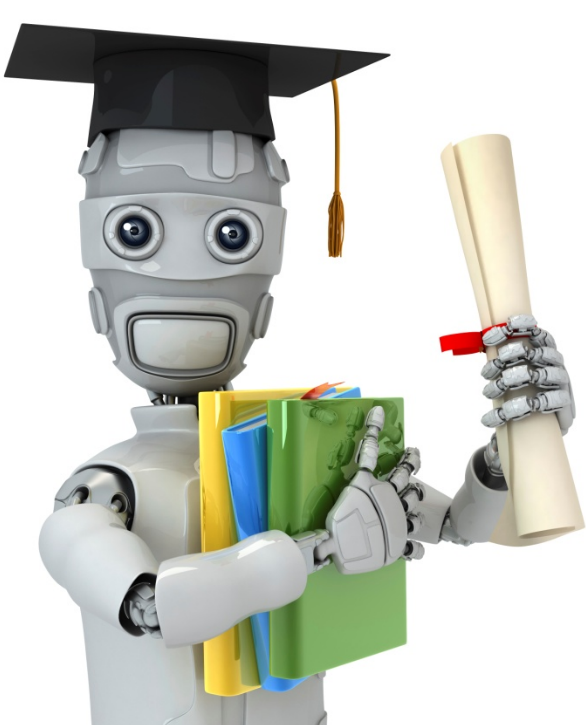
x_1 = memory use of computer

x_2 = number of disk accesses/sec

x_3 = CPU load

x_4 = network traffic

$$x_5 = \frac{\text{CPU load}}{\text{network traffic}} \qquad x_6 = \frac{(\text{CPU load})^2}{\text{network traffic}}$$

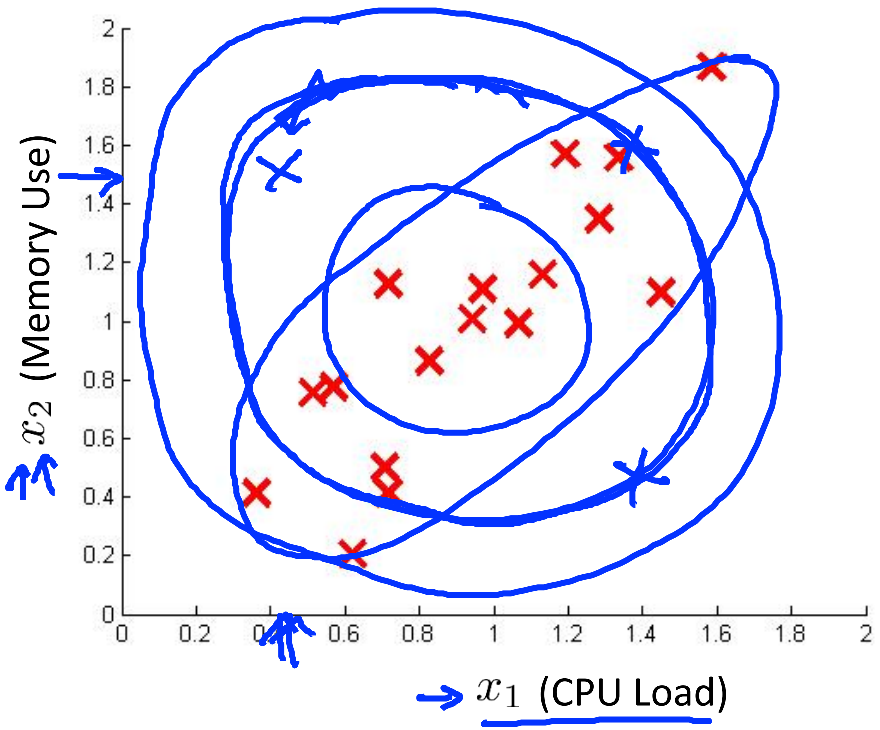


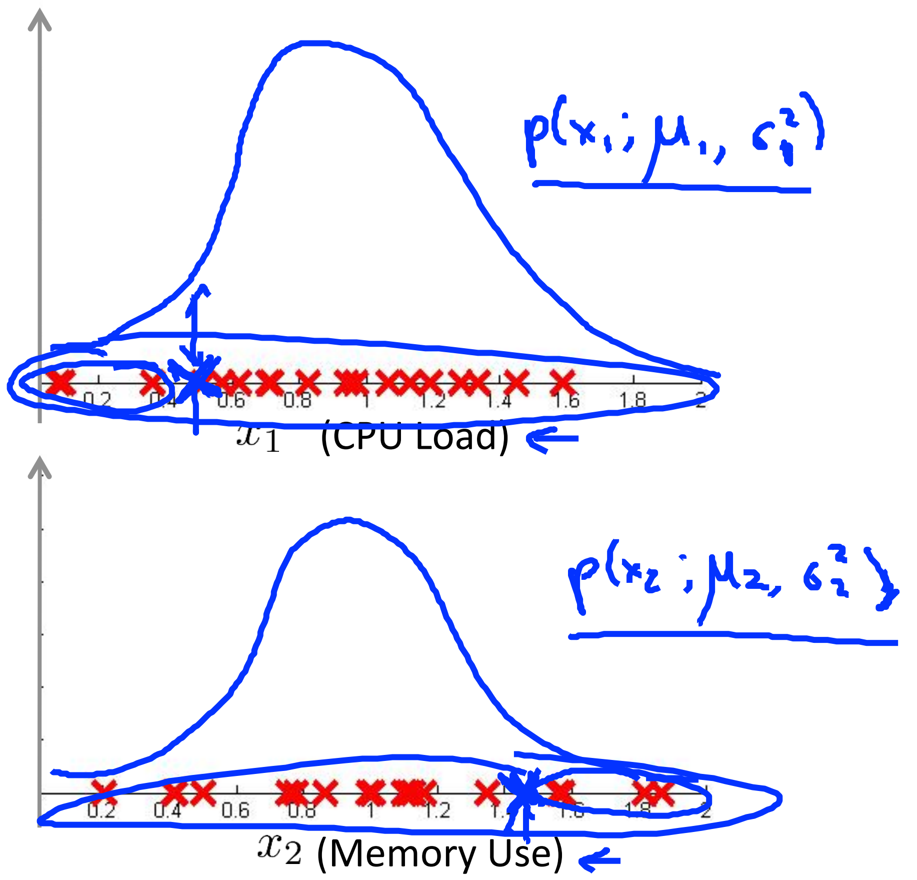
Machine Learning

Anomaly detection

Multivariate Gaussian distribution

Motivating example: Monitoring machines in a data center





Multivariate Gaussian (Normal) distribution

$x \in \mathbb{R}^n$. Don't model $p(x_1), p(x_2), \ldots,$ etc. separately.

Model $p(x)$ all in one go.

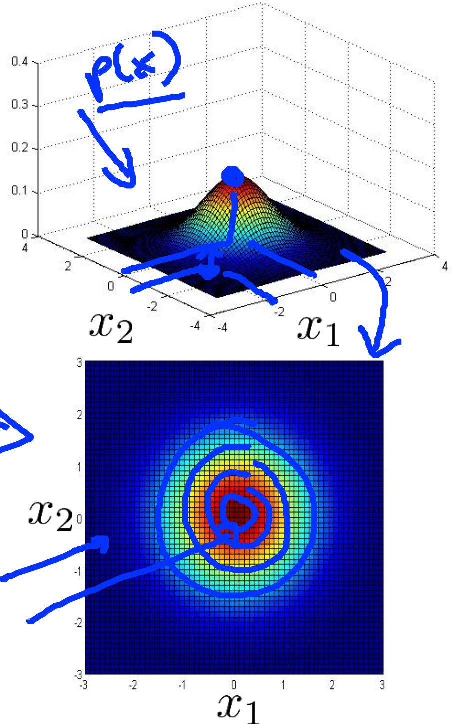
Parameters: $\mu \in \mathbb{R}^n$, $\boxed{\Sigma \in \mathbb{R}^{n \times n}}$ (covariance matrix)

$$p(x;\mu,\Sigma) = \frac{1}{(2\pi)^{n/2}|\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x-\mu)^T\Sigma^{-1}(x-\mu)\right)$$

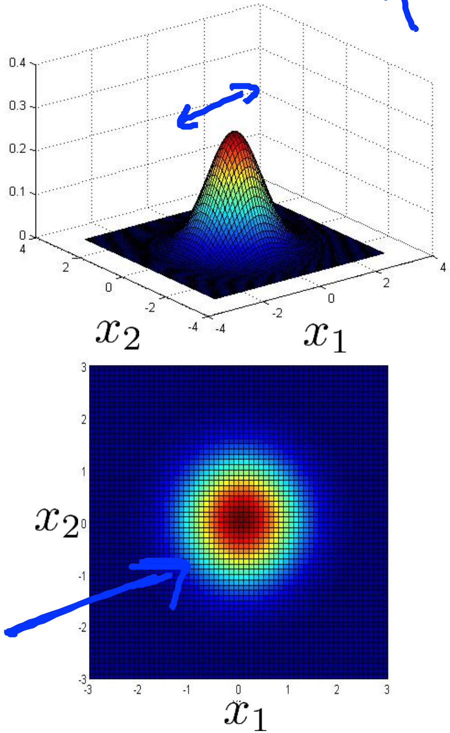
$|\Sigma|$ = determinant of Σ | det(Sigma)

Multivariate Gaussian (Normal) examples

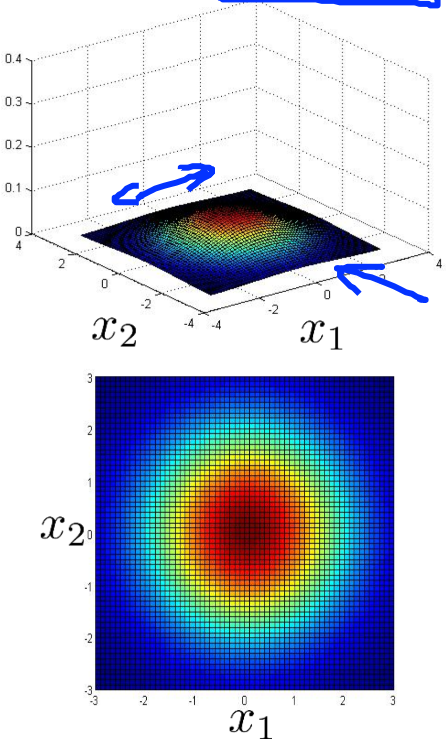
$$\boxed{\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}}$$



$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \boxed{\Sigma = \begin{bmatrix} 0.6 & 0 \\ 0 & 0.6 \end{bmatrix}}$$



$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \boxed{\Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}}$$



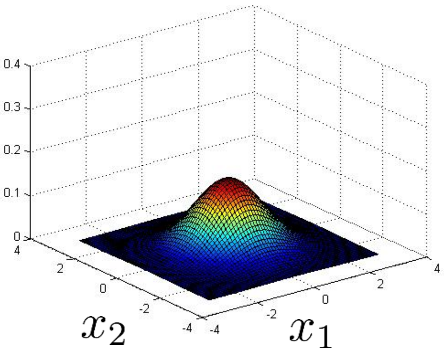
Andrew Ng

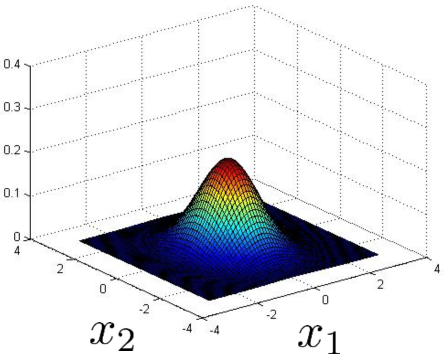
Multivariate Gaussian (Normal) examples

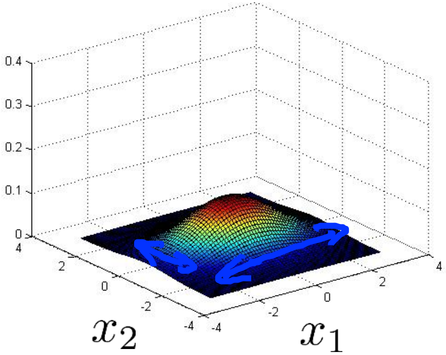
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

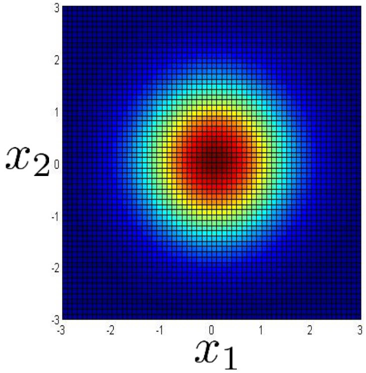
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 0.6 & 0 \\ 0 & 1 \end{bmatrix}$$

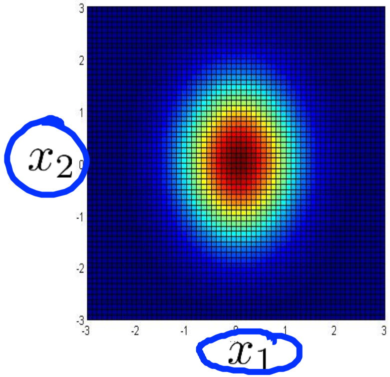
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

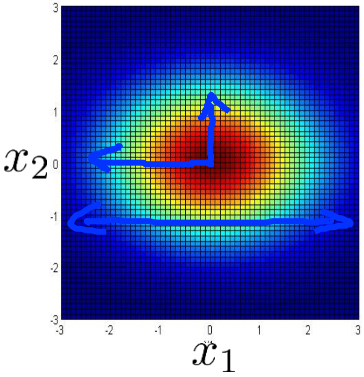












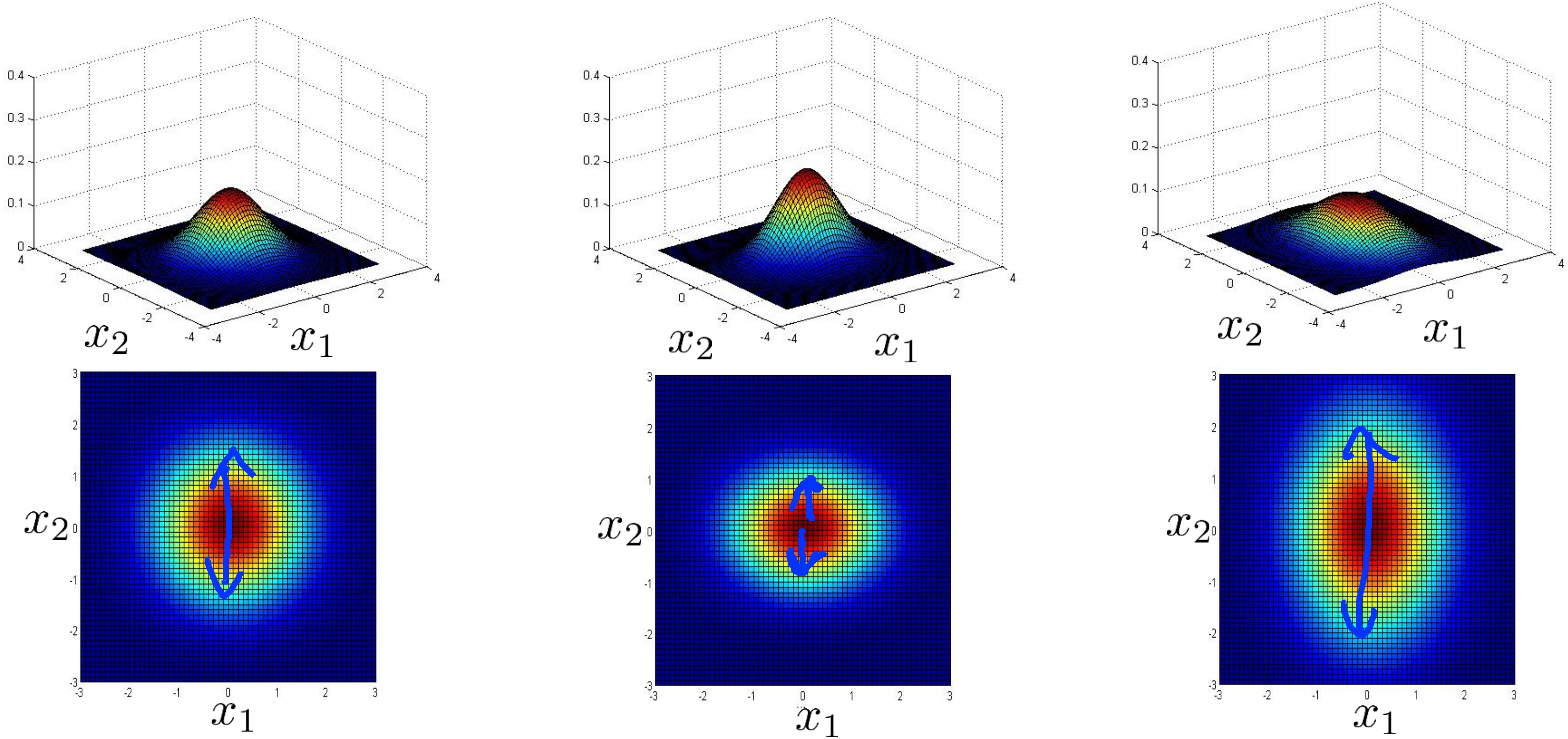
Andrew Ng

Multivariate Gaussian (Normal) examples

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 0.6 \end{bmatrix}$$

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

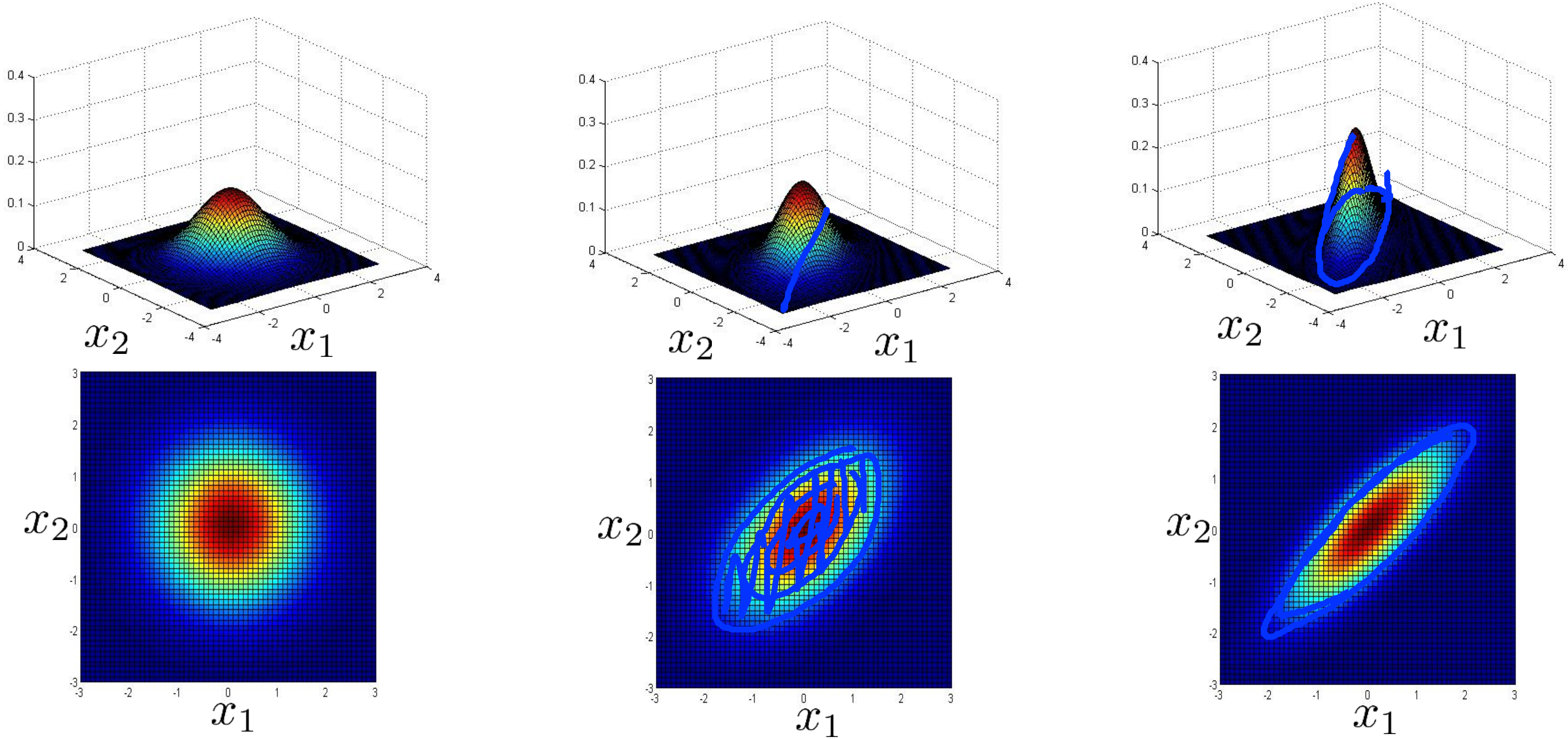


Multivariate Gaussian (Normal) examples

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

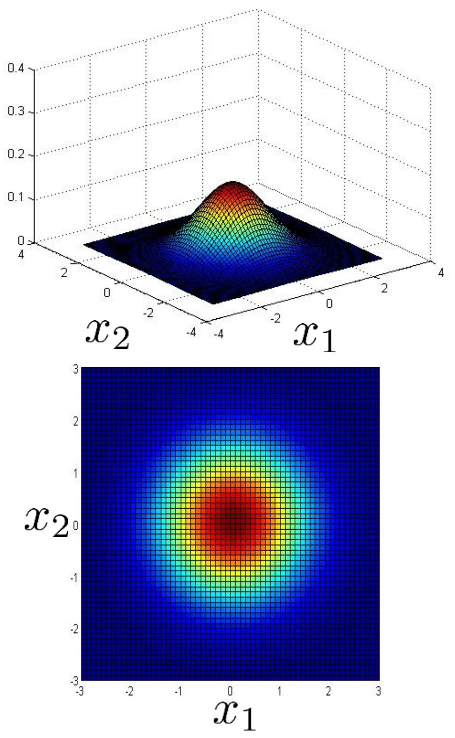
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$$

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0.8 \\ 0.8 & 1 \end{bmatrix}$$

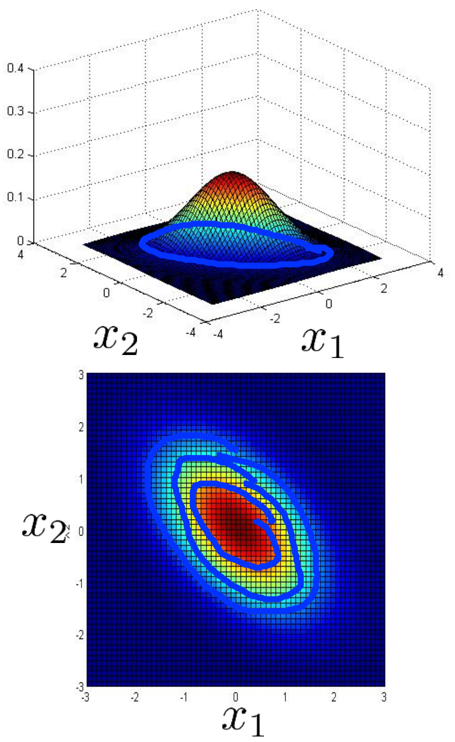


Multivariate Gaussian (Normal) examples

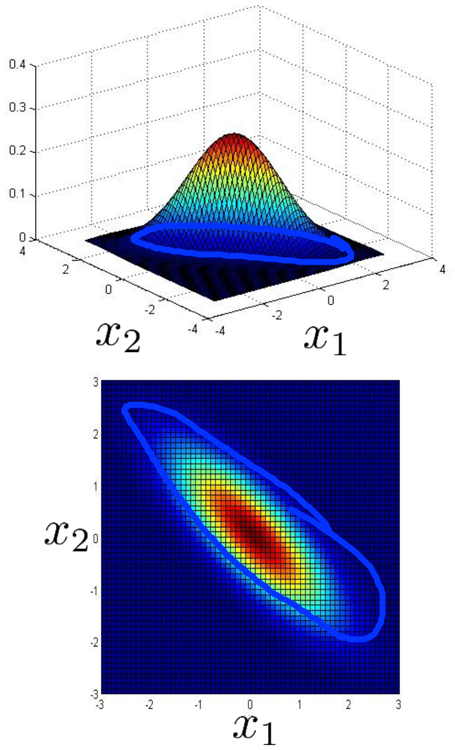
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & -0.5 \\ -0.5 & 1 \end{bmatrix}$$



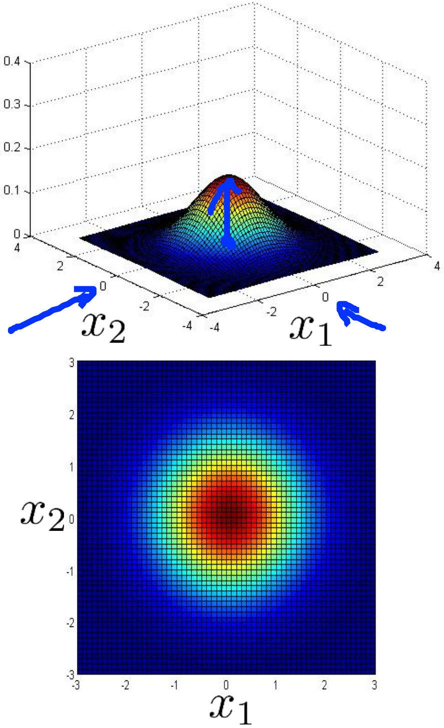
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & -0.8 \\ -0.8 & 1 \end{bmatrix}$$



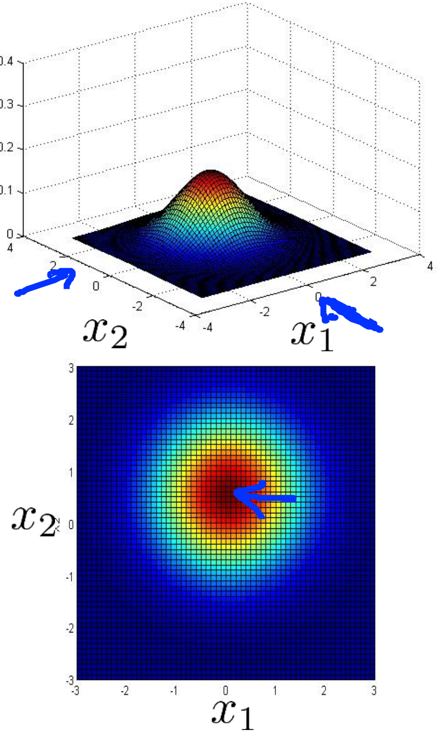
Andrew Ng

Multivariate Gaussian (Normal) examples

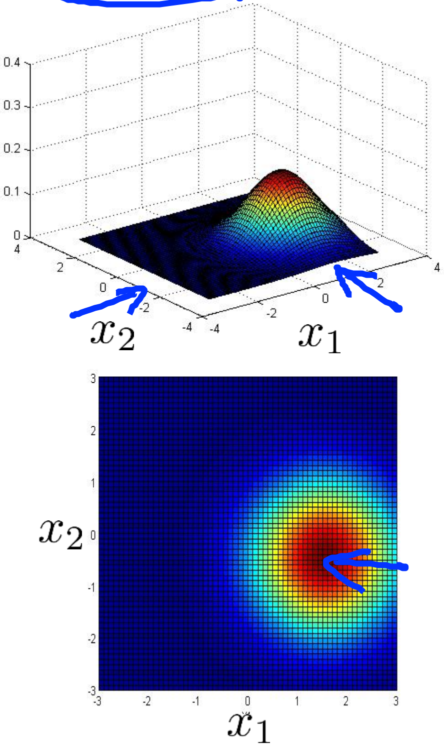
$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ $\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

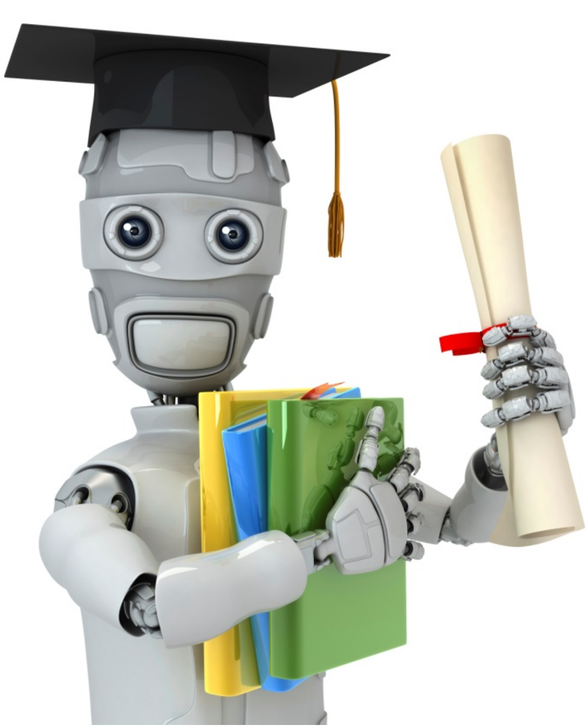


$\mu = \begin{bmatrix} 0 \\ 0.5 \end{bmatrix}$ $\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$



$\mu = \begin{bmatrix} 1.5 \\ -0.5 \end{bmatrix}$ $\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$





Machine Learning

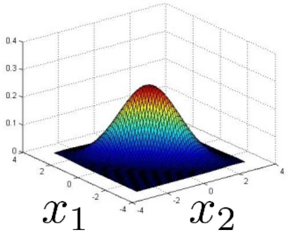
Anomaly detection

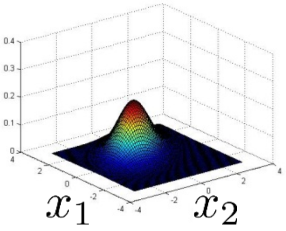
Anomaly detection using the multivariate Gaussian distribution

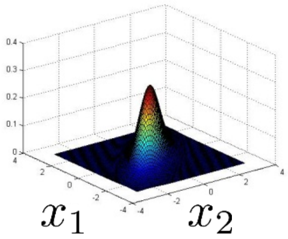
Multivariate Gaussian (Normal) distribution

Parameters μ, Σ $\qquad \mu \in \mathbb{R}^n \qquad \Sigma \in \mathbb{R}^{n \times n}$

$$p(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x-\mu)^T \Sigma^{-1} (x-\mu)\right)$$







Parameter fitting:

Given training set $\{x^{(1)}, x^{(2)}, \ldots, x^{(m)}\}$ $\qquad x \in \mathbb{R}^n$

$$\boxed{\mu} = \frac{1}{m}\sum_{i=1}^{m} x^{(i)} \qquad \boxed{\Sigma} = \frac{1}{m}\sum_{i=1}^{m}(x^{(i)}-\mu)(x^{(i)}-\mu)^T$$

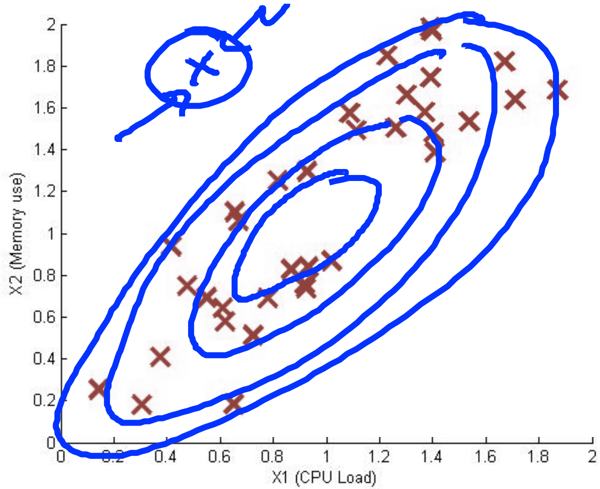
Andrew Ng

Anomaly detection with the multivariate Gaussian

1. Fit model $p(x)$ by setting

$$\mu = \frac{1}{m}\sum_{i=1}^{m} x^{(i)}$$

$$\Sigma = \frac{1}{m}\sum_{i=1}^{m}(x^{(i)} - \mu)(x^{(i)} - \mu)^T$$



2. Given a new example x, compute

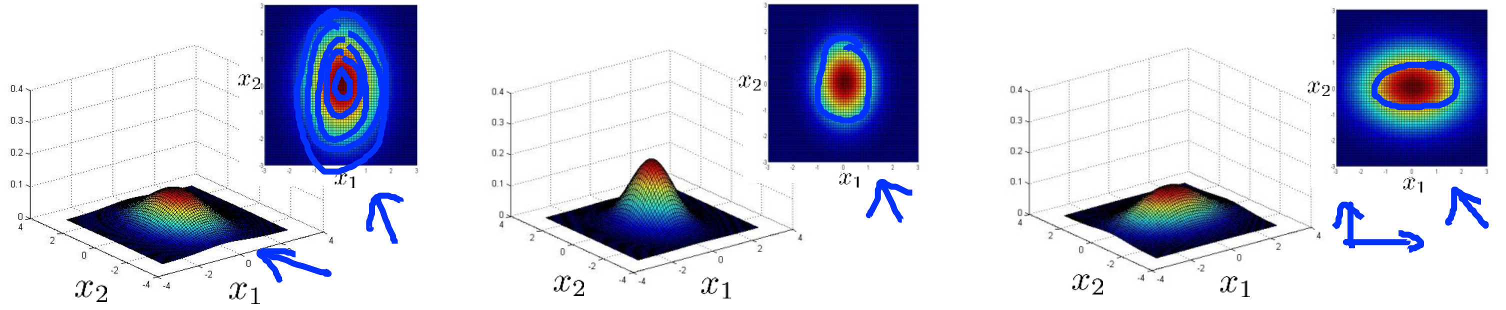
$$p(x) = \frac{1}{(2\pi)^{\frac{n}{2}}|\Sigma|^{\frac{1}{2}}}\exp\left(-\frac{1}{2}(x-\mu)^T\Sigma^{-1}(x-\mu)\right)$$

Flag an anomaly if $p(x) < \varepsilon$

Relationship to original model

Original model: $\boxed{p(x) = p(x_1;\mu_1,\sigma_1^2)\times p(x_2;\mu_2,\sigma_2^2)\times\cdots\times p(x_n;\mu_n,\sigma_n^2)}$

p(x)



$\Sigma = \begin{bmatrix} 1 & 0.8 \\ 0.8 & 1 \end{bmatrix}$

Corresponds to multivariate Gaussian

$$\boxed{p(x;\mu,\Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}}|\Sigma|^{\frac{1}{2}}}\exp\left(-\frac{1}{2}(x-\mu)^T\Sigma^{-1}(x-\mu)\right)}$$

where $\Sigma =$

Original model vs. Multivariate Gaussian

$$p(x_1;\mu_1,\sigma_1^2)\times\cdots\times p(x_n;\mu_n,\sigma_n^2)$$

Manually create features to capture anomalies where x_1, x_2 take unusual combinations of values.

$$\boxed{x_3 = \frac{x_1}{x_2} = \frac{\text{CPU load}}{\text{memory}}}$$

Computationally cheaper (alternatively, scales better to large n)

$n = 10{,}000$, $n = 100{,}000$

OK even if m (training set size) is small

$$p(x;\mu,\Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}}|\Sigma|^{\frac{1}{2}}}\exp\left(-\frac{1}{2}(x-\mu)^T\Sigma^{-1}(x-\mu)\right)$$

Automatically captures correlations between features

$\Sigma \in \mathbb{R}^{n\times n}$ Σ^{-1}

Computationally more expensive

Σ $\sim \frac{n^2}{2}$

$x_1 = \cancel{x_2}$

$\cancel{x_3} = x_4 + x_5$

Must have $\boxed{m > n}$ or else Σ is non-invertible.

$\boxed{m \geq 10n}$