Approximation

Marcin Kuta

Approximation

Basis functions: $\{\phi_0(t), \ldots, \phi_n(t)\}$

$$p(x) = \sum_{j=0}^{n} c_j \phi_j(x)$$
 (1)

 $x = [x_0, \dots, x_m]$ m > n (often $m \gg n$)

$$p(x_j) \approx f(x_j) \tag{2}$$

Approximation error E:

	Discrete	Continuous	
max	$\min_{p \in \mathbb{P}_n} \max_{\substack{0 \le j \le m \\ m}} f(x_j) - p(x_j) $	$\min_{p \in \mathbb{P}_n} \max_{x \in [a,b]} f(x) - p(x) $	
L_2^2	$\min_{p\in\mathbb{P}_n}\sum_{j=0}^{\infty} f(x_j)-p(x_j) ^2$	$\min_{p\in\mathbb{P}_n}\int_a^b f(x)-p(x) ^2$	

Discrete least squares approximation

$$p(x) = \sum_{i=0}^{n} c_i x^i \tag{3}$$

$$S_k = \sum_{i=0}^n x_i^k, \ k = 0, 1, \dots, 2m$$
 (4)

$$T_k = \sum_{i=0}^n x_i^k y_i, \ k = 0, 1, \dots m$$
 (5)

$$c_{0} \cdot S_{0} + c_{1} \cdot S_{1} + \cdots + c_{m} \cdot S_{m} = T_{0}$$

$$c_{0} \cdot S_{1} + c_{1} \cdot S_{2} + \cdots + c_{m} \cdot S_{m+1} = T_{1}$$

$$c_{0} \cdot S_{2} + c_{1} \cdot S_{3} + \cdots + c_{m} \cdot S_{m+2} = T_{2}$$

$$\cdots$$

$$c_{0} \cdot S_{k} + c_{1} \cdot S_{k+1} + \cdots + c_{m} \cdot S_{m+k} = T_{k}$$
(6)

 $c_0 \cdot S_m + c_1 \cdot S_{m+1} + \cdots + c_m \cdot S_{2m} = T_m$

Discrete least squares approximation

$$A = \begin{bmatrix} 1 & x_0 & x_0^2 & \dots & x_0^n \\ 1 & x_1 & x_1^2 & \dots & x_1^n \\ \dots & \dots & \dots & \dots & \dots \\ 1 & x_m & x_m^2 & \dots & x_m^n \end{bmatrix}, c = \begin{bmatrix} c_0 \\ c_1 \\ \dots \\ c_n \end{bmatrix}, y = \begin{bmatrix} f(x_0) \\ f(x_1) \\ \dots \\ f(x_m) \end{bmatrix}$$
(7)

Normal equation:

$$A^T A c = A^T y \tag{8}$$

$$c = (A^T A)^{-1} A^T y = A^+ y (9)$$

Continuous least squares approximation

 $p_{\star}(t)$ to be optimal requires approximation error $E = E(c_0, \dots, c_n)$ to satisfy

$$\frac{\partial E}{\partial c_0} = \dots \frac{\partial E}{\partial c_n} = 0 \tag{10}$$

Continuous least squares approximation

$$\langle f, g \rangle = \int_{-1}^{1} w(x) f(x) g(x) dx,$$
 (11)

$$\begin{bmatrix}
\langle \phi_0, \phi_0 \rangle & \dots & \langle \phi_0, \phi_n \rangle \\
\langle \phi_1, \phi_0 \rangle & \dots & \langle \phi_1, \phi_n \rangle \\
\dots & \dots & \dots \\
\langle \phi_n, \phi_0 \rangle & \dots & \langle \phi_n, \phi_n \rangle
\end{bmatrix}
\begin{bmatrix}
c_0 \\
c_1 \\
\dots \\
c_n
\end{bmatrix} =
\begin{bmatrix}
\langle f, \phi_0 \rangle \\
\langle f, \phi_1 \rangle \\
\dots \\
\langle f, \phi_n \rangle
\end{bmatrix}$$
(12)

Continuous least squares approximation

$$\begin{bmatrix} \langle \phi_0, \phi_0 \rangle & 0 & \dots & 0 \\ 0 & \langle \phi_1, \phi_1 \rangle & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & \langle \phi_n, \phi_n \rangle \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ \dots \\ c_n \end{bmatrix} = \begin{bmatrix} \langle f, \phi_0 \rangle \\ \langle f, \phi_1 \rangle \\ \dots \\ \langle f, \phi_n \rangle \end{bmatrix}$$
(13)

$$c_k = \frac{\langle f, \phi_k \rangle}{\langle \phi_k, \phi_k \rangle} \tag{14}$$

$$p_{\star} = \sum_{k=0}^{n} c_{k} \phi_{k} = \sum_{k=0}^{n} \frac{\langle f, \phi_{k} \rangle}{\langle \phi_{k}, \phi_{k} \rangle} \phi_{k}$$
 (15)

Orthogonal polynomials

Name	Symbol	Interval	Weight function
Legendre	P_n	[-1, 1]	1
Chebyshev, 1st kind	T_n	[-1,1]	$(1-t^2)^{-1/2}$
Chebyshev, 2st kind	U_n	[-1,1]	$(1-t^2)^{1/2}$
Jacobi	J_n	[-1,1]	$(1-t)^{lpha}(1-t)^{eta}$
Lagurerre	L _n	$[0,\infty)$	e^{-t}
Hermite	H_n	$(-\infty,\infty)$	e^{-t^2}

Orthogonal trigonometric functions

Functions	Interval	Weight
$\frac{1}{\sqrt{2\pi}}, \frac{1}{\sqrt{\pi}}\sin(nx), \frac{1}{\sqrt{\pi}}\cos(nx), n = 1, 2\dots$	$[-\pi,\pi]$	1
$\frac{2}{\sqrt{\pi}}\sin(nx), n=1,2$	$[0,\pi]$	1
$\frac{1}{\sqrt{\pi}}, \frac{2}{\sqrt{\pi}}\cos(nx), n = 1, 2$	$[0,\pi]$	1

References

- [1] Włodzimierz Funika,
 Aproksymacja,
 http://home.agh.edu.pl/~funika/mownit/lab3/
 aproksymacja.pdf
- [2] Michael T. Heath, Scientific Computing. An Introductory Survey, 2nd Edition, Chapter 7: Interpolation 2002