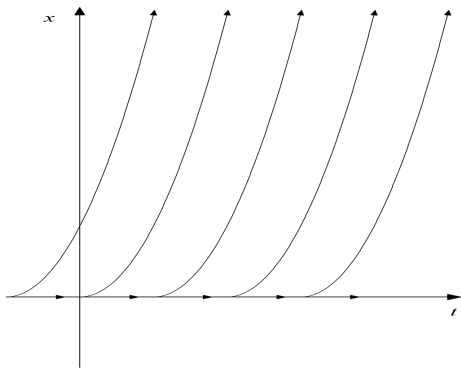


Ordinary differential equations

Marcin Kuta

Existence and Uniqueness

$$\frac{dx}{dt} = x^\beta, \quad 0 < \beta < 1, \quad x \geq 0$$



$$x(t) = (1 - \beta)^{\frac{1}{1-\beta}} (t - C)^{\frac{1}{1-\beta}} \quad (1)$$

$$x(t) \equiv 0 \quad (2)$$

Existence and Uniqueness

Function $f(t, y): \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$ is *Lipschitz continuous* if there is constant L such, that for any $t \in [a, b]$ and any $y, \hat{y} \in \Omega$

$$\|f(t, \hat{y}) - f(t, y)\| \leq L\|\hat{y} - y\|$$

If f is differentiable:

$$L = \max_{(t,y) \in D} \|J_f(t, y)\|$$

Stability of a problem

$$y' = f(y, t)$$

$$y(t_0) = y_0$$

$$\hat{y}(t_0) = \hat{y}_0$$

Solution to $y' = f(y, t)$ is *stable* if for every ε there exists δ such that if

$$\|\hat{y}(t_0) - y(t_0)\| < \delta$$

then

$$\|\hat{y}(t) - y(t)\| < \varepsilon \text{ for } t \geq t_0.$$

Stable solution to $y' = f(y, t)$ is *asymptotically stable* if

$$\|\hat{y}(t) - y(t)\| \rightarrow 0 \text{ for } t \rightarrow \infty.$$

Explicit Euler method

$$y_{k+1} = y_k + h_k f(t_k, y_k) \quad (3)$$

Stability:

$$|1 + h\lambda| < 1 \quad (4)$$

Implicit Euler method

$$y_{k+1} = y_k + h_k f(t_{k+1}, y_{k+1}) \quad (5)$$

Stability:

$$\left| \frac{1}{1 - h\lambda} \right| < 1 \quad (6)$$

Amplification factor

$$\varepsilon_{n+1} = Q(\lambda h)\varepsilon_n \quad (7)$$

| Method | Amplification factor |
|----------------|---|
| Explicit Euler | $1 + \lambda h$ |
| Implicit Euler | $\frac{1}{1 - \lambda h}$ |
| Trapezoidal | $\frac{1 + \frac{1}{2}\lambda h}{1 - \frac{1}{2}\lambda h}$ |
| Modified Euler | $1 + \lambda h + \frac{1}{2}(\lambda h)^2$ |
| RK4 | $1 + \lambda h + \frac{1}{2}(\lambda h)^2 + \frac{1}{6}(\lambda h)^3 + \frac{1}{24}(\lambda h)^4$ |

Local and global error

Local error

$$\ell_k = \frac{y_k - u_{k-1}(t_k)}{h_k} \quad (8)$$

Global error

$$e_k = y_k - y(t_k) \quad (9)$$

Local error

| Method | Local error |
|----------------|-------------|
| Explicit Euler | $O(h)$ |
| Implicit Euler | $O(h)$ |
| Trapezoidal | $O(h^2)$ |
| Modified Euler | $O(h^2)$ |
| RK4 | $O(h^4)$ |

Methods

| Fixed step | Adaptive step |
|----------------------------------|---|
| Euler method | Runge-Kutta 1(2), Adaptive Heun |
| Midpoint method | Runge-Kutta 2(3), Bogacki-Shampine |
| Runge-Kutta 4, 3/8 rule | Runge-Kutta 4(5), Dormand-Prince |
| Explicit Adams-Bashforth | Runge-Kutta 7(8), Dormand-Prince-Shampine |
| Implicit Adams-Bashforth-Moulton | |

- ① http://heath.cs.illinois.edu/scicomp/notes/cs450_chapt09.pdf