Introduction to Machine Learning (SS 2025) Programming Project

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I. INTRODUCTION

For this report the task consists of classifying images of sign language hand gestures. The dataset contains a total of 9680 instances of hands in a 128 x 128 pixel grayscale format. Hence, this is a multilabel classification task, where each image corresponds to a sign of the digits 0 to 9 and the letters a to z, totaling 36 classes.

The dataset is considerably imbalanced with the frequency for each sign ranging from 1.07% to 5.78%. 9 of the classes have frequencey of 5.78%, 6 classes have frequency of 2.89%, and the rest has 1.50% frequency.

II. IMPLEMENTATION / ML PROCESS

The methods chosen for this task are a convolutional neural network (CNN), as well as a multilabel support-vector-machine (SVM) classifier.

A. Data preprocessing

To prevent the model from ignoring minority classes, learning incorrect class distributions, or producing misleading metrics, the dataset was balanced by augmenting minority class samples. Augmentation techniques included horizontal mirroring and $\pm 90^{\circ}$ rotations, applied based on the required increase per class. This resulted in a balanced dataset of 18,056 instances, with class frequencies ranging from 2.48% to 3.10%. Additionally, all input images were scaled to [0,1] to improve numerical stability and prevent bias toward high-magnitude pixel values.

For the CNN, additional data was needed to exceed 87% accuracy. Therefore, a dynamic data loader was implemented, which expands the dataset by a specified factor using random augmentations: $\pm 15^{\circ}$ rotations, horizontal flips, and random scaling between 80% and 100%. A factor of 2 was used in this study, yielding 36,112 training instances while preserving class distribution.

For the SVM classifier, the high dimensionality of the image data made direct training infeasible. Therefore, PCA with 200 components was applied, retaining 90% of the explained variance.

B. Classifier architecture

A convolutional neural network (CNN) was chosen for this task due to its effectiveness in processing image data. CNNs use local receptive fields to focus on small image regions, capturing spatial patterns and relationships more effectively than fully connected networks.

The architecture begins with convolutional layers that apply small filters (kernels) to detect local patterns such as edges and textures. As training progresses, these kernels learn to extract features relevant to the classification task. Pooling layers reduce the spatial dimensions of feature maps, lowering computational cost and making the model more robust to translations. Max pooling, which selects the maximum value in each region, is commonly used.

At the end, fully connected layers aggregate the high-level features and map them to output classes. The chosen CNN consists of three convolutional layers (each followed by 2×2 max pooling) and two fully connected layers.

The support vector machine (SVM), implemented via sklearn.svm.SVC, was chosen for its ability to maximize the soft margin between classes. SVMs generalize better than logistic regression when classes aren't linearly separable by using kernel functions, which enable non-linear decision boundaries via the kernel trick.

SVMs separate classes by finding the hyperplane that maximizes the margin defined by the nearest data points (support vectors). Multi-class classification is handled using one-vs-rest or one-vs-one strategies, both supported by scikit-learn. For K classes, one-vs-one creates $\frac{K*(K-1)}{2}$ binary classifiers, with predictions made via majority voting.

SVMs minimize hinge loss: $\mathcal{L}_{hinge} = \max(0, 1 - y \cdot f(\mathbf{x}))$ where $f(\mathbf{x}) = \mathbf{w}^{\top}\mathbf{x} + b$ and $y \in \{0, 1\}$. Compared to logloss used in logistic regression, hinge loss penalizes misclassifications less aggressively, making SVMs more robust to outliers.

Another approch was using an Autoencoder, but this did not give any accuracy boosts and was just more complex, than the CNN network.

C. Hyperparameters

The hyperparameter optimization was realized with random search. For each hyperparameter a numerical interval [a,b] or a discrete set of choices $\{c,d,e,...\}$ was defined. Across 60 trials per classifier hyperparameters are uniformly sampled according to the defined bounds, which are used to train a model on the dataset. The model is evaluated using validation set and the best set of hyperparameters is selected based on the resulting models performance.

For the CNN classifier, random search was performed with a maximum of 40 training epochs. Early stopping was applied with a patience of 5 epochs, requiring a minimum improvement in validation loss of 0.01. Additionally, if validation accuracy did not reach at least 40% by epoch 10, training was stopped early. The search optimized across batch size B, learning rate l_R sampled from log-scale to bias small learning rates, kernel size k, number of convolutional channels C_c , linear layer size n_h , dropout rate d, and activation function f_A .

For the SVM classifier scikit-learns support vector classifier sklearn.svm.SVC was used. The choice of the multi-class decision scheme OvO and OvR as well as the kernel function, the regularization parameter C, the kernel coefficient γ , and for the polynomial kernel the degree d and the bias term $coe\,f0$ were examined.

III. RESULTS

The CNN classifier yiels significantly better results than the SVM classifier. The final accuracies are shown in Table II.

	Train set	Validation set	Test set
CNN	98.89%	98.56%	96.25%
SVM	97.76%	87.62%	85.21%
AE & NN	84.94%	81.20%	81.99%

TABLE II

FINAL MODEL ACCURACY ON TRAINING, VALIDATION, AND TESTING.

The majority of remaining inaccuracy for both classifiers stem from a small set of similar looking sign pairs, namely (O,0), (V,2), (W,6), and (M,N). This is clearly visible in their respective confusion matrices shown in Figure 1. The SVM classifier shows small amounts of confusion across the whole set of classes, which explains the significantly lower validation accuracy.

When plotting the per-class precision and accuracy values for the CNN classifier, the pair wise confusion is seen by the duality between precision and recall of the respective confused pairs.

IV. DISCUSSION

Initial attempts to train the SVM on raw 128x128 image inputs without normalization or feature extraction failed

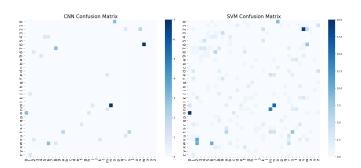


Fig. 1. Confusion matrices for CNN and SVM classifiers with ommitted diagonal, predicted value (left) and actual value (bottom).

to converge, highlighting SVMs' poor scalability to high-dimensional data. After applying PCA for dimensionality reduction, performance improved significantly. However, the final model size exceeded the 50 MB limit—reaching around 60 MB (50 MB for the SVM, 10 MB for PCA)—despite optimizations like switching from an RBF to a polynomial kernel, using One-vs-Rest, and reducing PCA components from 500 to 200. Surprisingly, these changes did not hurt performance.

Further size reduction to 37 MB was achieved by removing extra data augmentation and reverting to a balanced dataset, which reduced the number of support vectors, at the cost of 1% accuracy loss. Replacing PCA with an autoencoder could yield more compact, informative features for the SVM.

For the CNN classifier, performance gains were primarily driven by dataset expansion and targeted augmentation, particularly for underrepresented classes. Early models failed to classify class W entirely until class balancing was introduced. A deeper CNN with smaller kernels could further improve accuracy by capturing finer details, but was not explored due to the 50 MB model size limit—the current CNN already used 49 MB.

V. CONCLUSION

The final CNN classifier was trained for 60 epochs on the entire training dataset and achieved a strong test dataset accuracy of 96.25%. In comparison, the SVM classifier reached a respectable 85.21%. While SVMs can be a viable alternative to CNNs for small multi-label classification tasks – especially those involving few classes, small image sizes, and moderate amounts of data such as the MNIST dataset – they do not scale as effectively as CNNs to big data sets with large images and many classes. This limitation persists even after dimensionality reduction with PCA, whereas learning

CNN	B	l_R	k	n_h	C_c	d	f_A
Bounds	[8, 128]	[0.0001, 0.01]	$\{3 \times 3, 5 \times 5\}$	[128, 384]	{[16, 32, 64], [32, 64, 128], [48, 96, 192]}	[0.2, 0.5]	{ReLU, Sigmoid}
Selection	64	0.000218	5×5	382	[32, 64, 128]	0.2026	ReLU
SVM	C	γ	d	coef0	Kernel	multi-class decision scheme	
Bounds	[0.01, 1000]	[0.0001, 0.1]	[2, 4]	[0, 1]	{Linear, Poly, RBF}	{OvO, OvR}	
Selection	6	0.01	3	1	Poly	OvR	

compact representations with a convolutional autoencoder may provide feature spaces in which SVMs remain competitive.