

MATH 637: Mathematical Techniques in Data Science

The singular value decomposition

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April 29 & May 1, 2020

Theorem. Let $A \in \mathbb{R}^{m \times n}$. Then we can factor

$$A = U\Sigma V^T,$$

where

- ① $U \in \mathbb{R}^{m \times m}$ is an orthogonal matrix ($UU^T = U^T U = I$).
- ② $\Sigma \in \mathbb{R}^{m \times n}$ is a rectangular diagonal matrix with non-negative diagonal.
- ③ $V \in \mathbb{R}^{n \times n}$ is an orthogonal matrix ($VV^T = V^T V = I$).

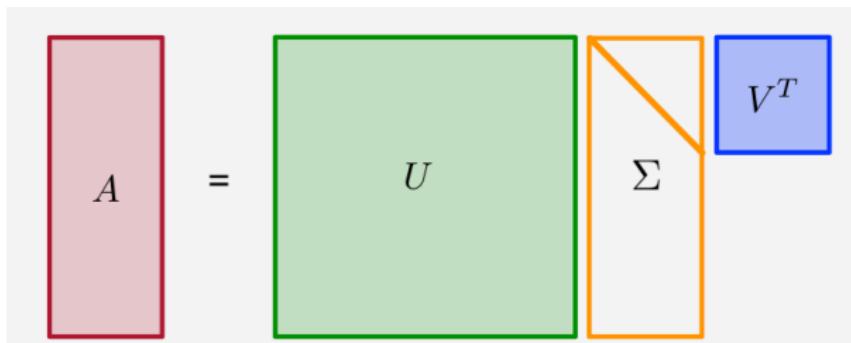


Figure from J.M. Phillips, *Mathematical Foundations for Data Analysis*.

Changing bases.

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- If $v \in \mathbb{R}^n$ has coordinates (v_1, \dots, v_n) in basis \mathcal{B} , meaning

$$v = v_1 \mathbf{b}_1 + v_2 \mathbf{b}_2 + \cdots + v_n \mathbf{b}_n,$$

then v has coordinates $Pv = (w_1, \dots, w_n)$ in basis \mathcal{C} , meaning

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- Remark: $P_{\mathcal{C} \rightarrow \mathcal{B}} = P_{\mathcal{B} \rightarrow \mathcal{C}}^{-1}$.
- We think of a matrix $A \in \mathbb{R}^{m \times n}$ as a linear transformation $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ written with respect to bases \mathcal{C} and \mathcal{D} of \mathbb{R}^n and \mathbb{R}^m , respectively:

$$A = \begin{pmatrix} | & | & & | \\ A\mathbf{c}_1 & A\mathbf{c}_2 & \dots & A\mathbf{c}_n \\ | & | & & | \end{pmatrix}$$

Columns of $A =$ images of the vectors \mathbf{c}_i , expressed in the basis \mathcal{D} .

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$$\begin{array}{ccc} V_{\mathcal{C}} & \xrightarrow{A} & W_{\mathcal{D}} \\ S = P_{\mathcal{B} \rightarrow \mathcal{C}} \uparrow & & \uparrow T = P_{\mathcal{E} \rightarrow \mathcal{D}} \\ V_{\mathcal{B}} & \xrightarrow{T^{-1}AS} & W_{\mathcal{E}} \end{array}$$

The matrix A becomes $T^{-1}AS$ in the new bases, where $S = P_{\mathcal{B} \rightarrow \mathcal{C}}$ and $T = P_{\mathcal{E} \rightarrow \mathcal{D}}$.

Diagonalization

Special case: $A : \mathbb{R}^n \rightarrow \mathbb{R}^n$, \mathcal{C} = canonical basis.

$$\begin{array}{ccc} V_{\mathcal{C}} & \xrightarrow{A} & V_{\mathcal{C}} \\ P = P_{\mathcal{B} \rightarrow \mathcal{C}} \uparrow & & \uparrow P = P_{\mathcal{B} \rightarrow \mathcal{C}} \\ V_{\mathcal{B}} & \xrightarrow{P^{-1}AP} & V_{\mathcal{B}} \end{array}$$

Definition. A matrix A is *diagonalizable* if $P^{-1}AP = D$ for some invertible matrix P and some diagonal matrix D .

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- The columns of P are the eigenvectors of A expressed in the canonical basis of \mathbb{R}^n .

Special case: symmetric matrix

Theorem. Let $A \in \mathbb{R}^{n \times n}$ be a symmetric matrix ($A = A^T$). Then there exists an orthonormal basis of \mathbb{R}^n consisting of eigenvectors of A .

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- In general, a given matrix is **not** diagonalizable.

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$$A = U \Sigma V^T$$

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- Works for any matrix (even rectangular ones).
- Columns of U are the *left singular vectors* of A
- Columns of V are the *right singular vectors* of A .
- Diagonal elements of Σ are the *singular values* of A .

Properties of the SVD

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Consequence:

- Columns of V are the eigenvectors of $A^T A$.
- Columns of U are the eigenvectors of AA^T .
- The (non-zero) singular values of A are the square roots of the (non-zero) eigenvalues of $A^T A$ or AA^T .

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- The truncated SVD provides the *best rank k approximation* to X .
- Applications: data compression, data recovery, etc.

Example

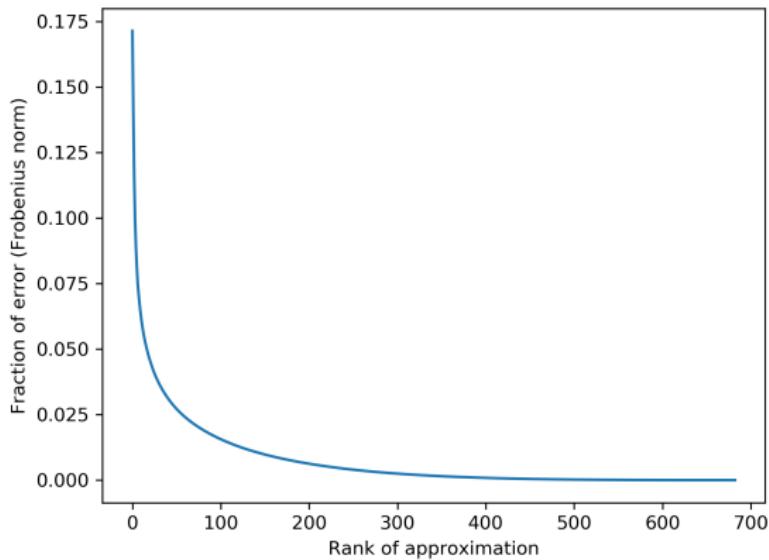
Compressing the following image using the svd:



- Original image $X \in \mathbb{R}^{683 \times 1024}$.
- $X = U\Sigma V^T$.
- Approximate X by X_k .

Example (cont.)

We examine $\sum_{i=k+1}^{683} \sigma_i^2 / \sum_{i=1}^{683} \sigma_i^2$.



Example (cont.)

- Best rank 10 approximation:



Example (cont.)

- Best rank 50 approximation:



Example (cont.)

- Best rank 100 approximation:



Example (cont.)

- Best rank 200 approximation:



Example (cont.)

- Best rank 300 approximation:



Example (cont.)

- Best rank 400 approximation:



Example (cont.)

- Best rank 500 approximation:



Example (cont.)

- Best rank 600 approximation:



Example (cont.)

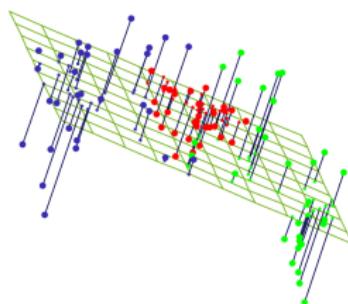
- Full image (rank 683):



Application 2: Projecting data on low dimensional subspace

2. Projecting data on low dimensional subspace and PCA.

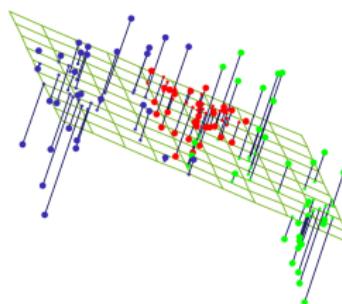
- The rows $x_1, \dots, x_n \in \mathbb{R}^p$ of X are observations of a p -dimensional vector.
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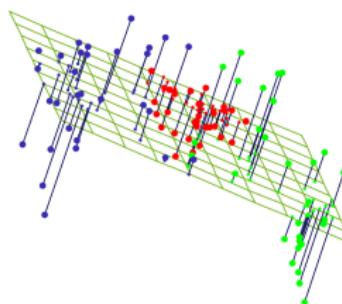


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- Assume the data is *centered*, i.e., each column of X has mean 0.
- For a given $1 \leq k \leq p$, we want to solve:

$$\min_{\substack{F \text{ subspace of } \mathbb{R}^p \\ \dim F = k}} \sum_{i=1}^n \|x_i - \pi_F(x_i)\|_2^2,$$

where $\pi_F(x)$ denotes the projection of x onto F .

Application 2 (cont.)

Theorem. Let v_1, \dots, v_p denote the right singular vectors of X associated to $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_p$. The optimal k dimensional subspace solving the previous problem is $\text{span}(v_1, v_2, \dots, v_k)$.

Application 2 (cont.)

Theorem. Let v_1, \dots, v_p denote the right singular vectors of X associated to $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_p$. The optimal k dimensional subspace solving the previous problem is $\text{span}(v_1, v_2, \dots, v_k)$.

(Sketch of proof) For any vector $x \in \mathbb{R}^p$, we have

$$\|x\|_2^2 = \|\pi_F(x)\|_2^2 + \|\pi_{F^\perp}(x)\|_2^2.$$

Let f_1, \dots, f_k be an orthonormal basis of F . Then

$$\begin{aligned} & \min_{\substack{F \text{ subspace of } \mathbb{R}^p \\ \dim F=k}} \sum_{i=1}^n \|x_i - \pi_F(x_i)\|_2^2 = \min_{\substack{F \text{ subspace of } \mathbb{R}^p \\ \dim F=k}} \sum_{i=1}^n \|\pi_{F^\perp}(x_i)\|_2^2 \\ &= \max_{\substack{F \text{ subspace of } \mathbb{R}^p \\ \dim F=k}} \sum_{i=1}^n \|\pi_F(x_i)\|_2^2 = \max_{\substack{f_1, \dots, f_k \text{ orthonormal} \\ \dim F=k}} \sum_{j=1}^k \|Xf_j\|_2^2 \\ &= \max_{\substack{f_1, \dots, f_k \text{ orthonormal}}} \sum_{j=1}^k f_j^T X^T X f_j \end{aligned}$$

Using the min-max theorem for Rayleigh quotients, one can show that this is maximized when $\{f_1, \dots, f_k\} = \{v_1, \dots, v_k\}$.

Application 3: Recommender systems

3. Recommender system



Alice		$\begin{pmatrix} 1 & 9 & 10 & 5 & \dots \end{pmatrix}$
Bob		$\begin{pmatrix} 1 & 6 & 7 & 8 & \dots \end{pmatrix}$
Carol		$\begin{pmatrix} 7 & 3 & 9 & 6 & \dots \end{pmatrix}$
Dave		$\begin{pmatrix} 6 & 2 & 8 & 9 & \dots \end{pmatrix}$
	\vdots	\vdots

- $X_{ij} =$ ranking from person i of movie j .

Recommender system (cont.)

Idea. Try to explain why user i liked movie j as follows:

- Each movie is a combination of some unknown independent “basic features” (e.g. action, explosions, nature, romance, etc.)
- Each feature has a degree of importance (weights).
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- Write $X_{n \times p} = U_{n \times n} \Sigma_{n \times p} V_{p \times p}^T$.
- Then

$$x_{ij} = \sum_{k=1}^p u_{ik} \sigma_k v_{jk}$$

Importance of
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Amount of feature k
in movie j

Ranking of Movie j
from User i

How much User i
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- Can try to label each learned “feature” (or genre) from data (e.g. “Critically acclaimed western with a romantic component”).

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- Other matrix factorizations are possible (e.g. Non-negative matrix factorization).

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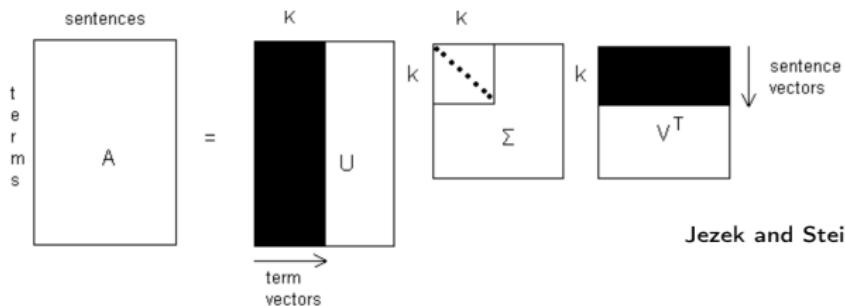
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- a_{ij} = frequency of word i in sentence j .

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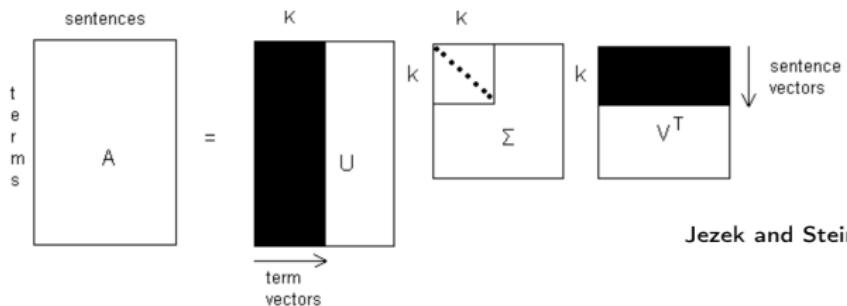
Jezek and Steinberger, 2004.

Application 4: Text summarization

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Give a text document, find a few sentences summarizing it.

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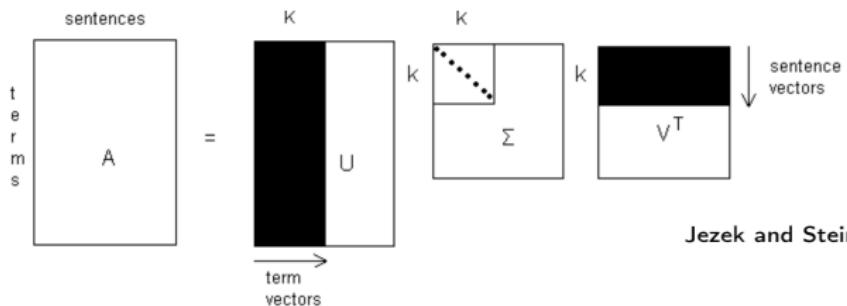
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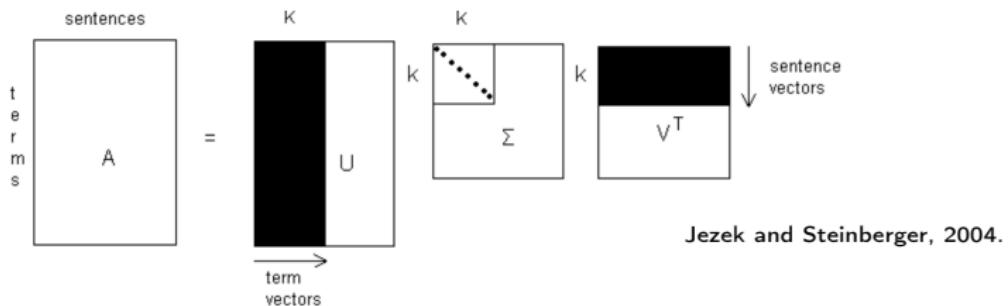
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- E.g., Gong and Liu (2001). From each row of the V^T matrix, the sentence with the highest score is selected.