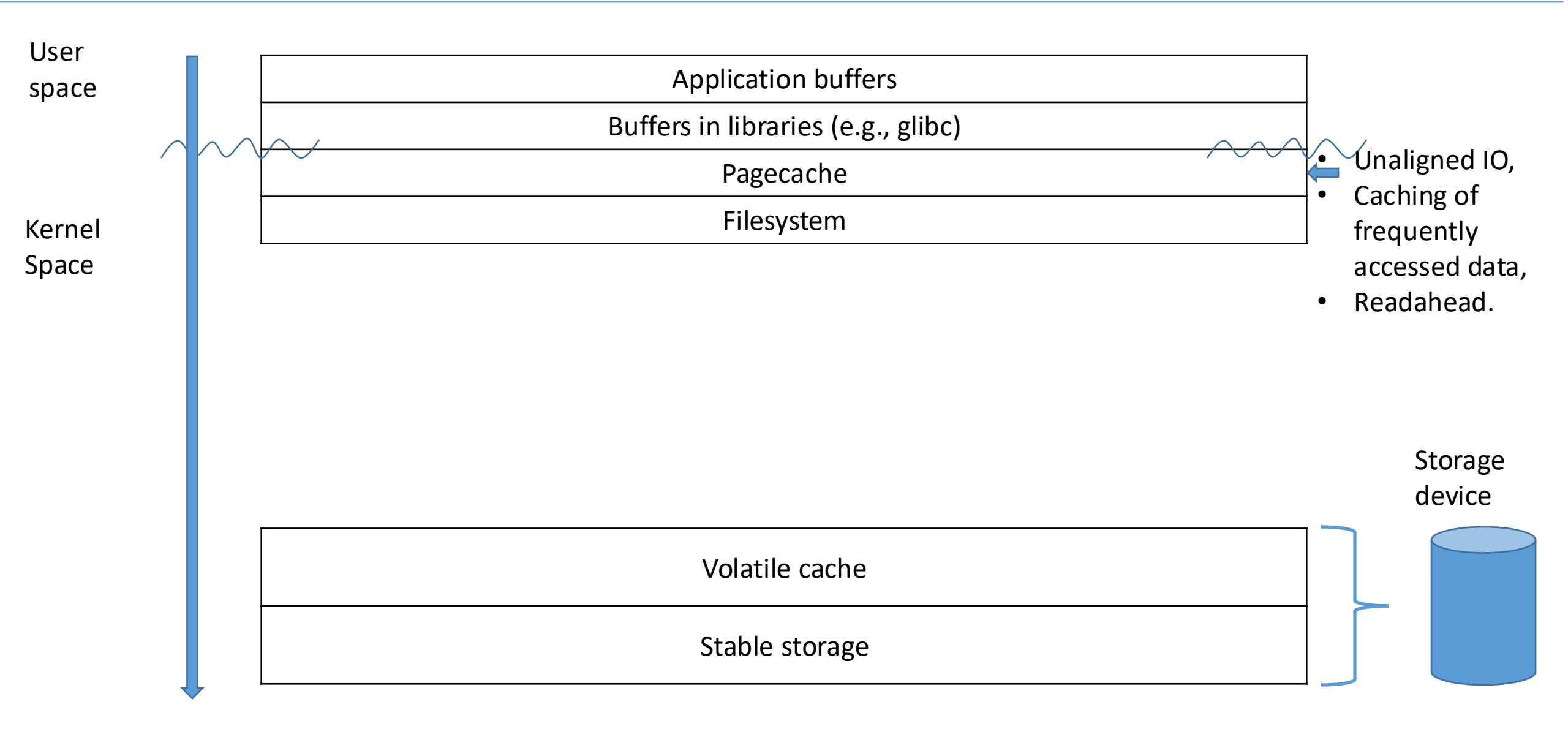


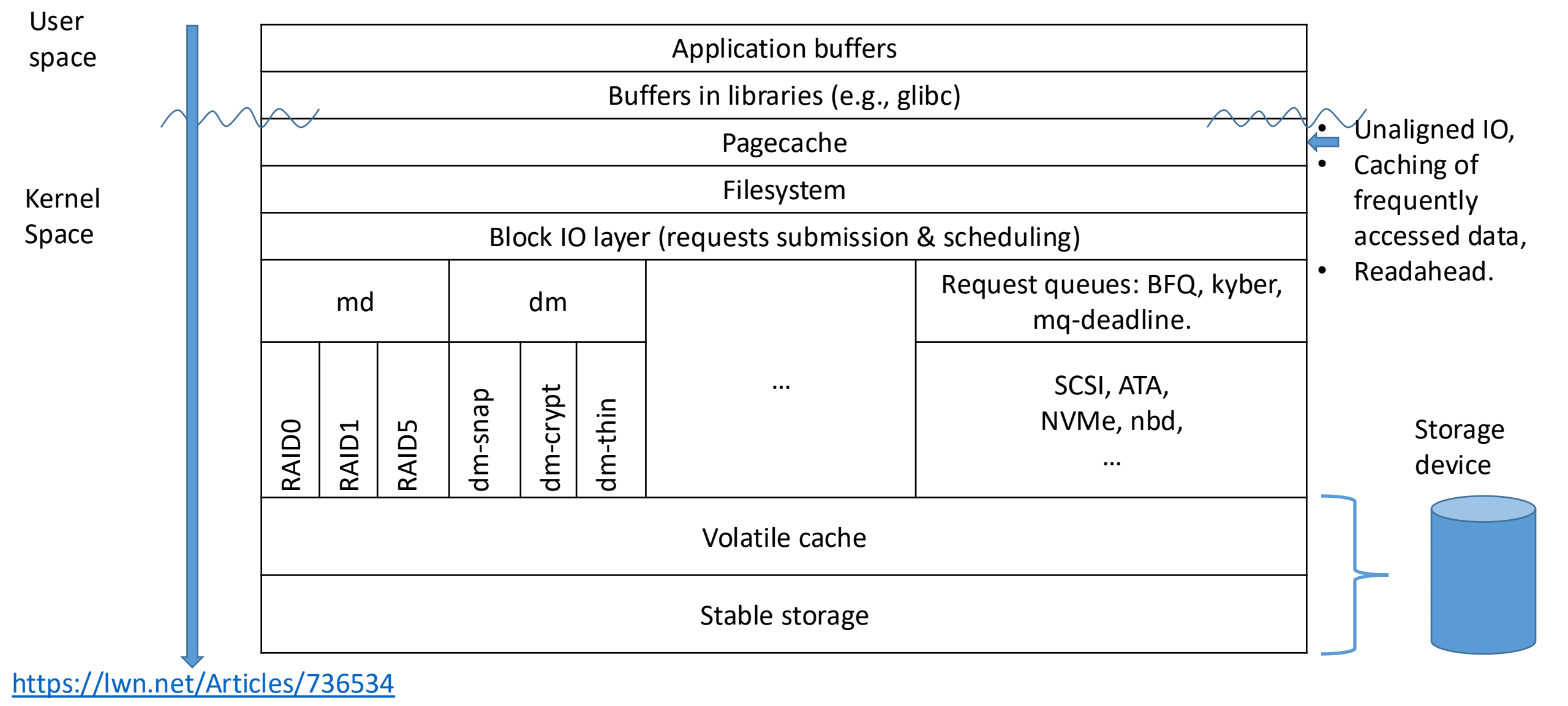
The basics of file systems



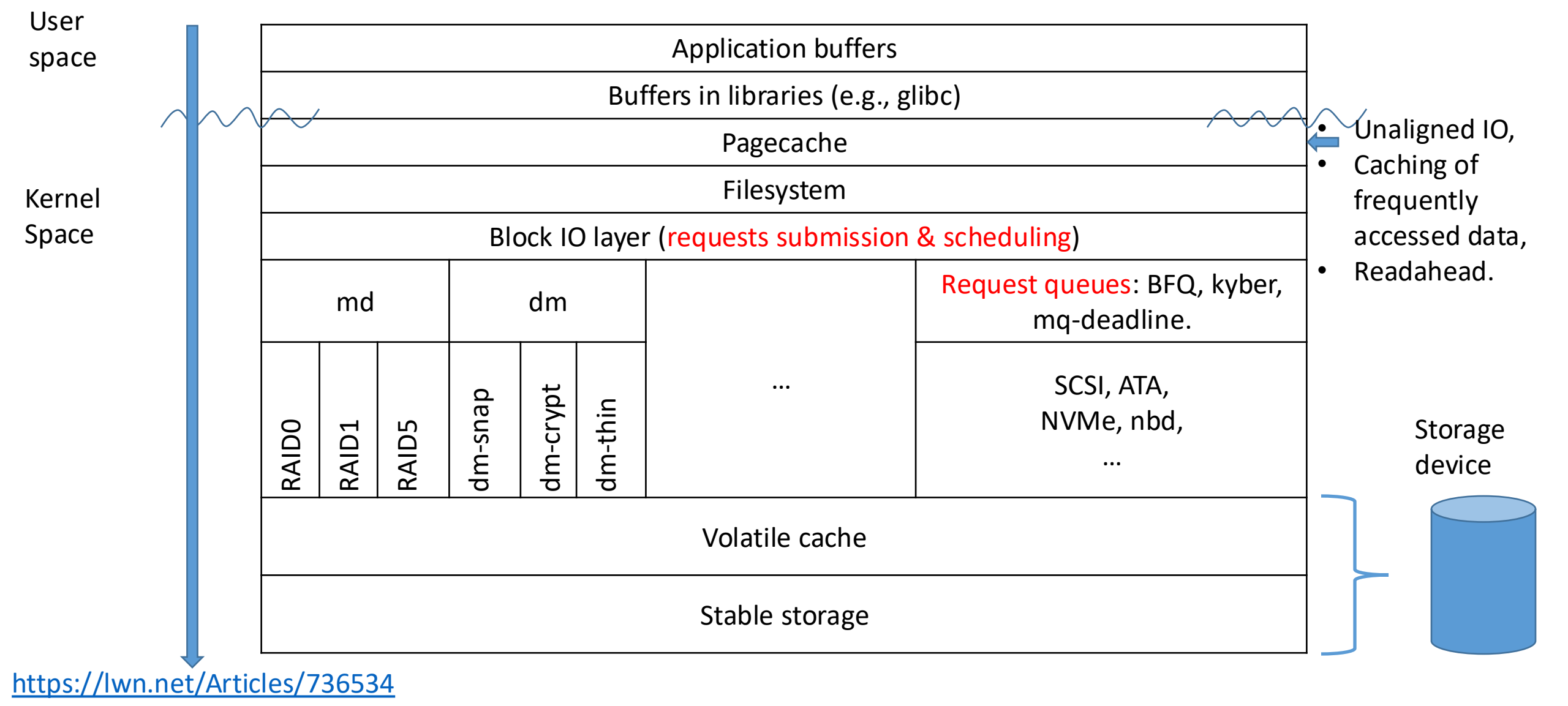
The path from application buffers to persistent storage (very approximate)



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The path from application buffers to persistent storage (very approximate)

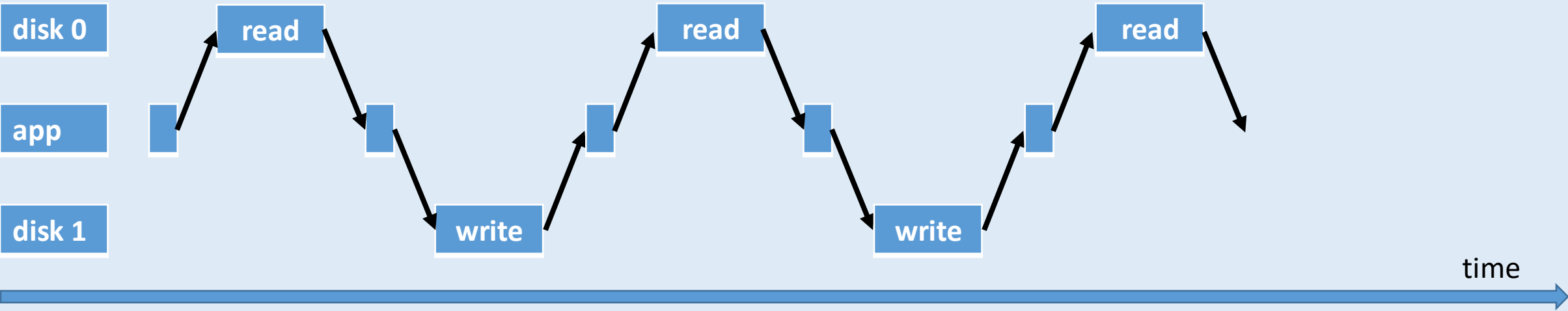


Synchronous and asynchronous IO, pipelining and multiplexing

Consider a naïve implementation of a routine that copies a file from one disk to another:

```
while (!done) {  
  r = read(fd_in, buf, sizeof(buf));  
  r0 = write(fd_out, buf, r);  
  ...  
}
```

Let us draw time intervals when each disk is accessed:

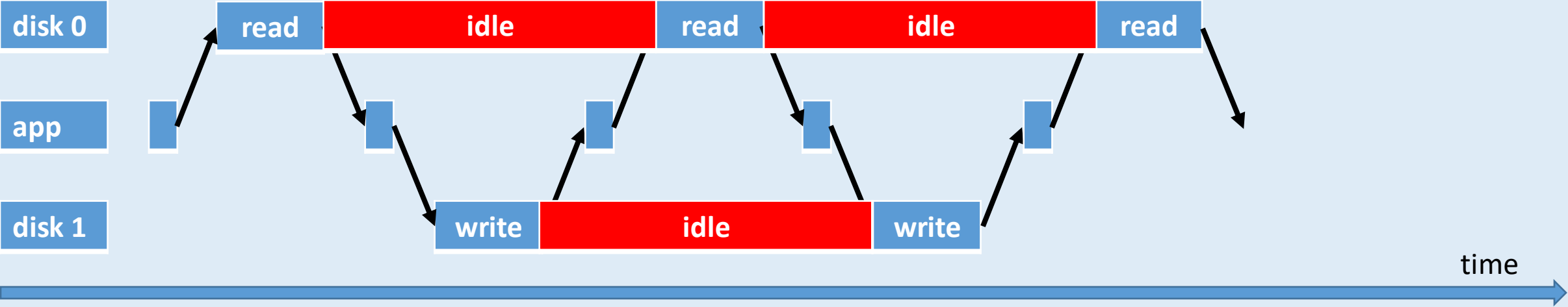


Synchronous and asynchronous IO, pipelining and multiplexing

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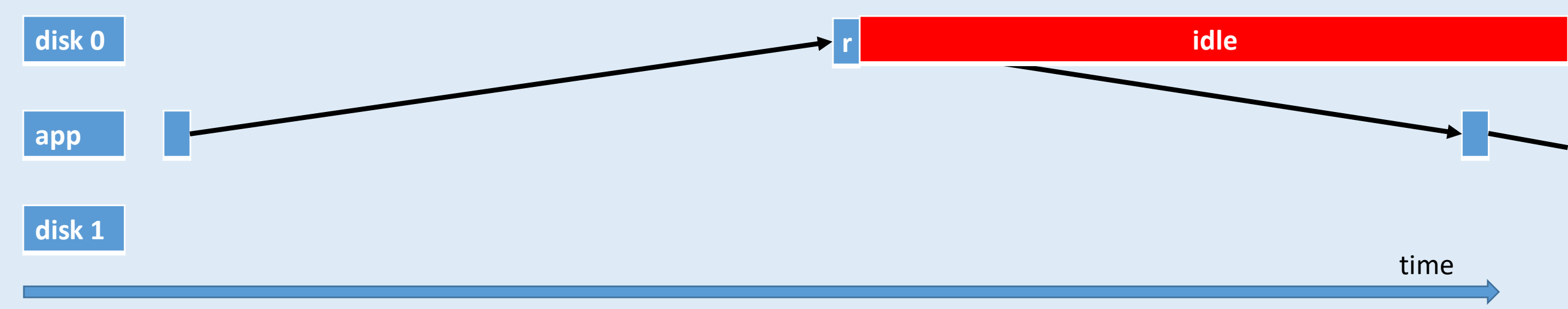
Let us draw time intervals when each disk is accessed:



Synchronous and asynchronous IO, pipelining and multiplexing

Typically, the problem is even worse. If the FS is networked, or the FS is located on a fast NVMe device, then the timeline is going to look this way:

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Synchronous and asynchronous IO, pipelining and multiplexing

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```

```
21-02-18 23:40:38.936 s#1412709.r#6998305: readfile = {offset = 0x4c44d78350, length = 16}  
21-02-18 23:40:39.191 s#1412709.r#6998305: send 16 at offset 0x4c44d78350  
21-02-18 23:40:39.191 s#1412709.r#6998305: completed
```

```
21-02-18 23:40:39.757 s#1412709.r#6998344: readfile = {offset = 0x4c44d78360, length = 944}  
21-02-18 23:40:39.757 s#1412709.r#6998344: send 944 at offset 0x4c44d78360  
21-02-18 23:40:39.757 s#1412709.r#6998344: completed
```

```
21-02-18 23:40:40.242 s#1412709.r#6998358: readfile = {offset = 0x4c44d7e360, length = 16}  
21-02-18 23:40:40.361 s#1412709.r#6998358: send 16 at offset 0x4c44d7e360  
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```


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```

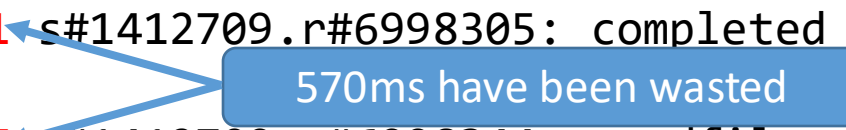
```
21-02-18 23:40:40.242 s#1412709.r#6998358: readfile = {offset = 0x4c44d7e360, length = 16}  
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Synchronous and asynchronous IO, pipelining and multiplexing

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```

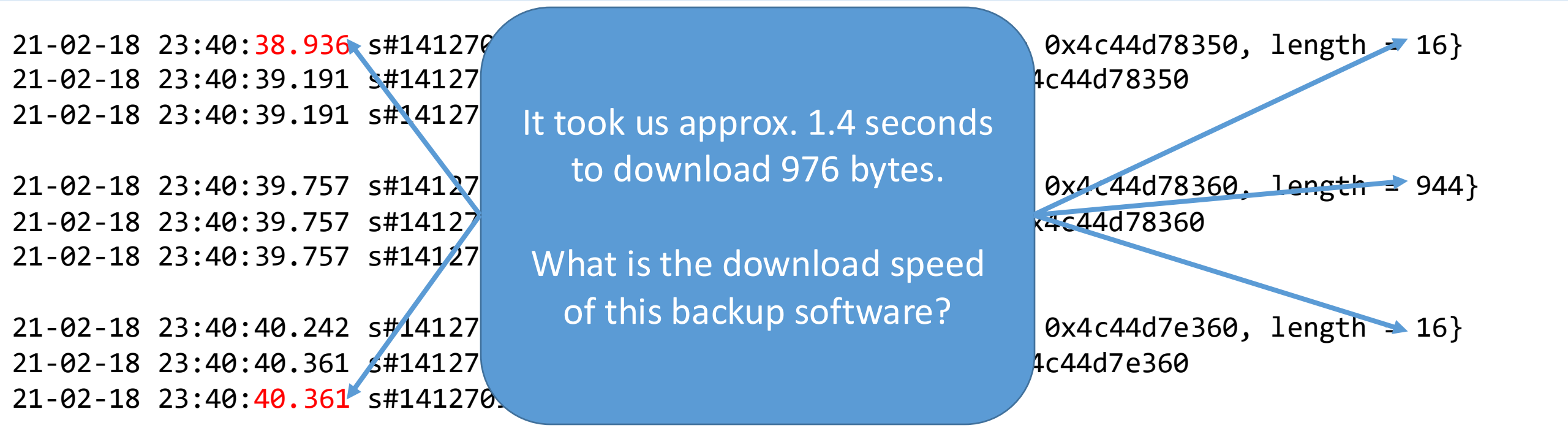


A blue callout box with the text "570ms have been wasted" is positioned between the completion of the first read operation (39.191) and the start of the second read operation (39.757). Two blue arrows point from the text box to the time values 39.191 and 39.757, indicating the duration of the idle period.

Synchronous and asynchronous IO, pipelining and multiplexing

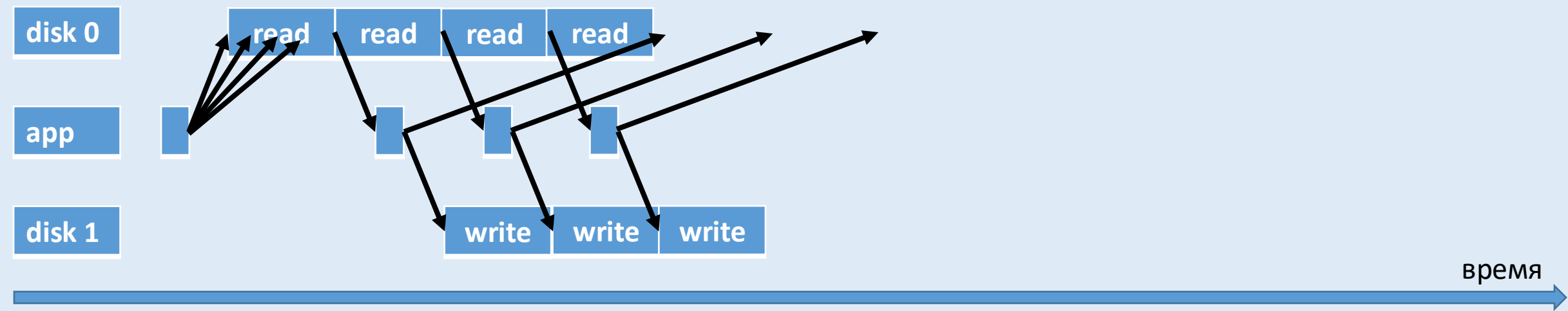
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```
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```



Synchronous and asynchronous IO, pipelining and multiplexing

An improvement: issue multiple read requests so that the source disk always have some work to do. The first command still suffers the latency penalty, but subsequent requests have their issue latency masked by preceding requests.



Pipelining and head-of-line blocking

Pipelining has an important inefficiency. Suppose that we've issued requests R_1 , R_2 , The request R_2 can send the reply only after R_1 even if R_2 completes much sooner than R_1 . Thus, a slow request blocks all subsequent requests. This scenario is called head-of-line blocking.

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```
06-09-18 14:12:23.567 s#164034.r#66643120: readfile = {offset = 0x39f0d000, length = 524288}
06-09-18 14:12:23.577 s#164034.r#66643125: readfile = {offset = 0x39f8d000, length = 524288}
06-09-18 14:12:23.593 s#164034.r#66643145: readfile = {offset = 0x3a00d000, length = 524288}
06-09-18 14:12:23.604 s#164034.r#66643147: readfile = {offset = 0x3a08d000, length = 524288}
06-09-18 14:12:23.612 s#164034.r#66643147: send 0x3a08d000:524288
06-09-18 14:12:23.612 s#164034.r#66643147: completed
06-09-18 14:12:23.618 s#164034.r#66643154: readfile = {offset = 0x3a10d000, length = 524288}
06-09-18 14:12:23.627 s#164034.r#66643158: readfile = {offset = 0x3a18d000, length = 524288}
06-09-18 14:12:23.632 s#164034.r#66643154: send 0x3a10d000:524288
06-09-18 14:12:23.632 s#164034.r#66643154: completed
06-09-18 14:12:23.634 s#164034.r#66643166: readfile = {offset = 0x3a20d000, length = 524288}
06-09-18 14:12:23.636 s#164034.r#66643158: send 0x3a18d000:524288
06-09-18 14:12:23.636 s#164034.r#66643158: completed
06-09-18 14:12:23.641 s#164034.r#66643168: readfile = {offset = 0x3a28d000, length = 524288}
06-09-18 14:12:23.643 s#164034.r#66643166: send 0x3a20d000:524288
06-09-18 14:12:23.643 s#164034.r#66643166: completed
06-09-18 14:12:23.649 s#164034.r#66643168: send 0x3a28d000:524288
06-09-18 14:12:23.649 s#164034.r#66643168: completed
06-09-18 14:12:23.783 s#164034.r#66643120: send 0x39f0d000:524288
06-09-18 14:12:23.783 s#164034.r#66643120: completed
```

Pipelining and head-of-line blocking

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Pipelining and head-of-line blocking

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06-09-18 14:12:23.783 s#164034.r#66643120: completed
```

Request r#66643120 accessed a disk that was busy with another request.

Request r#66643147 was executed by a disk that had no other IOs. The response was ready very quickly, but the server may not send that response before the response to r#66643120.

Synchronous and asynchronous IO, pipelining and multiplexing

Pipelining has an important inefficiency. Suppose that we've issued requests R_1 , R_2 , The request R_2 can send the reply only after R_1 even if R_2 completes much sooner than R_1 . Thus, a slow request blocks all subsequent requests. This scenario is called head-of-line blocking.

One can avoid head-of-line blocking this way:

- add a unique sequence number to each IO request,
- have the server send replies that include the request sequence number.

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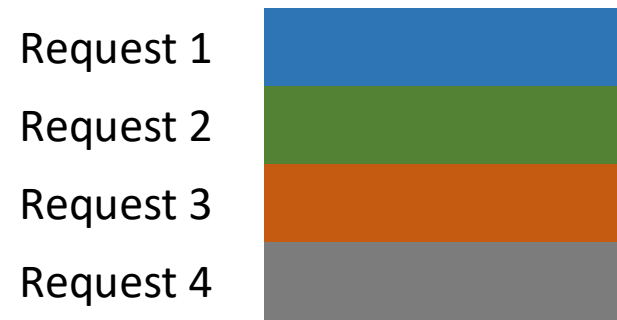
Many protocols use this idea:

- SCTP,
- HTTP/2,
- QUIC*.

* The QUIC Transport Protocol: Design and Internet-scale Deployment: <https://research.google.com/pubs/archive/46403.pdf>

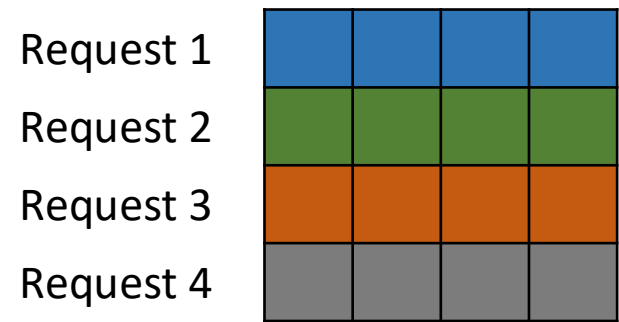
How the network interacts with concurrent requests

A client that send multiple requests over multiple network connections	The network	The server's request queue
--	-------------	----------------------------



How the network interacts with concurrent requests

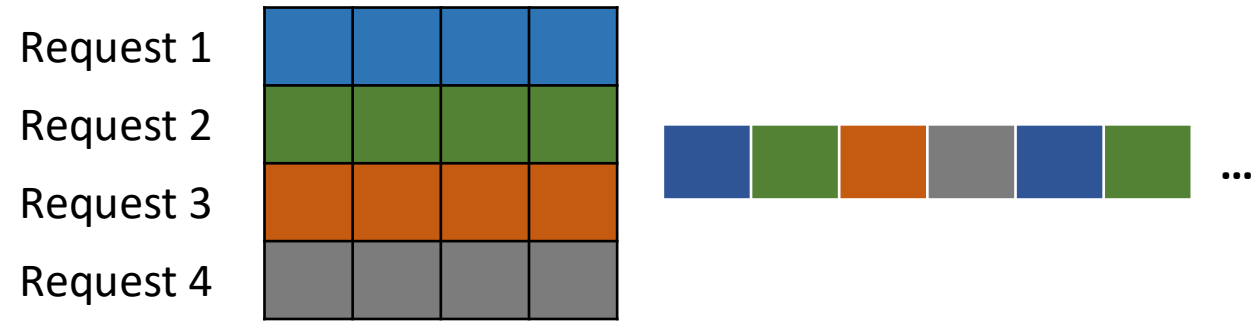
A client that send multiple requests over multiple network connections	The network	The server's request queue
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From the point of view of the network different connections are independent streams of bytes and each must get an equal share of the bandwidth.

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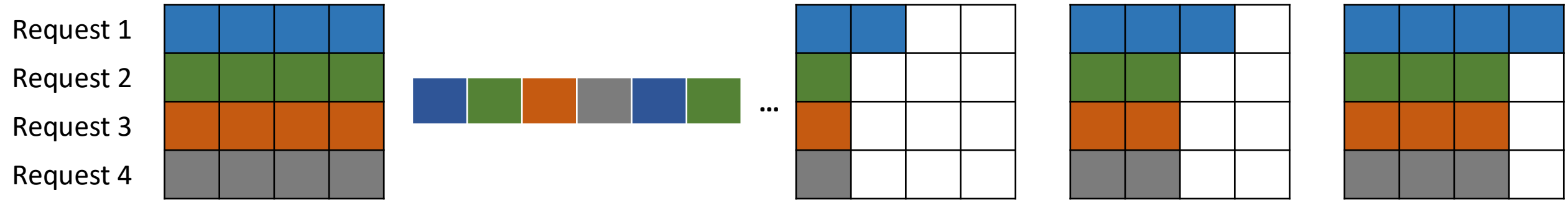


From the point of view of the network different connections are independent streams of bytes and each must get an equal share of the bandwidth.

Some protocols like gRPC cannot handle incomplete requests. They need to fetch all arguments first.

How the network interacts with concurrent requests

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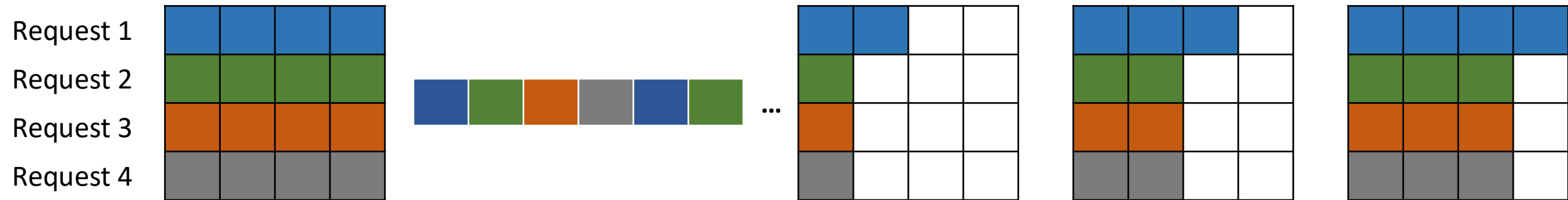
It is only now that the server received a complete request and can handle it. Essentially, it waited for all requests to arrive before starting the first one.

The delay is no better than when we have a single huge request.

** See also It's Time to Replace TCP in the Datacenter*
<https://arxiv.org/pdf/2210.00714.pdf>

How the network interacts with concurrent requests

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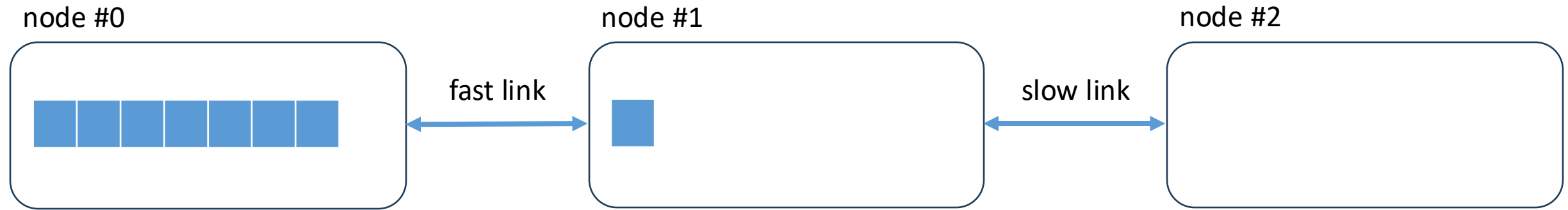


There are various ways this scenario may happen:

1. HTTP/2 splits requests into fixed-size frames and interleaves frames from different requests,
2. A TCP stream is split into IP packets and packets from different connections are interleaved.

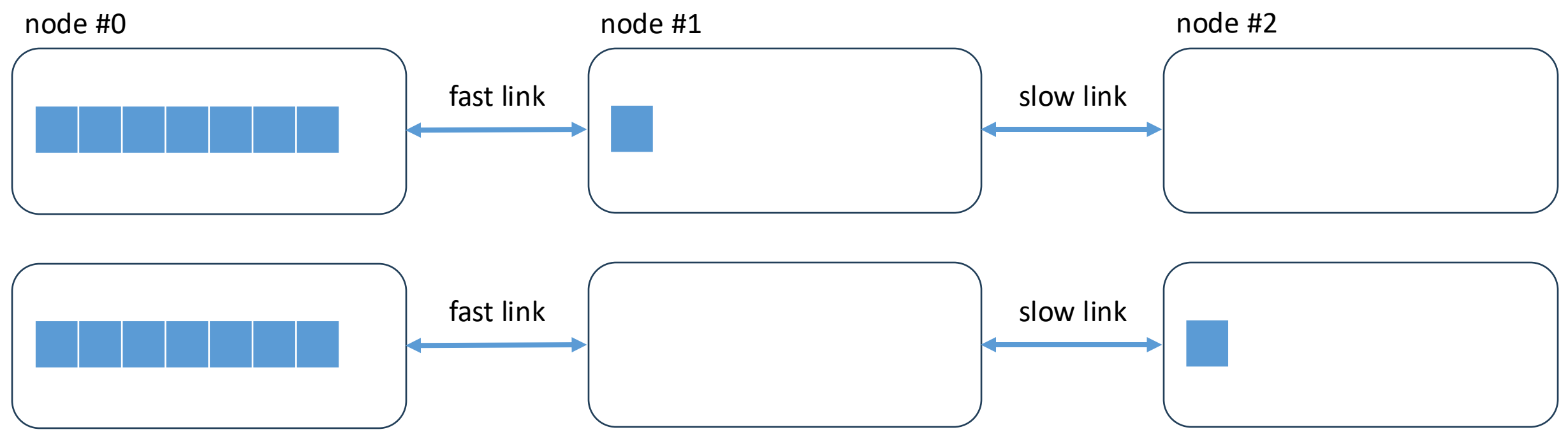
Quiz: it appears that uploading a file via multiple connections is a wrong idea? GRPC had to disable framing in the HTTP/2 client, but a TCP connection cannot monopolise a link.

Buffering and bufferbloat

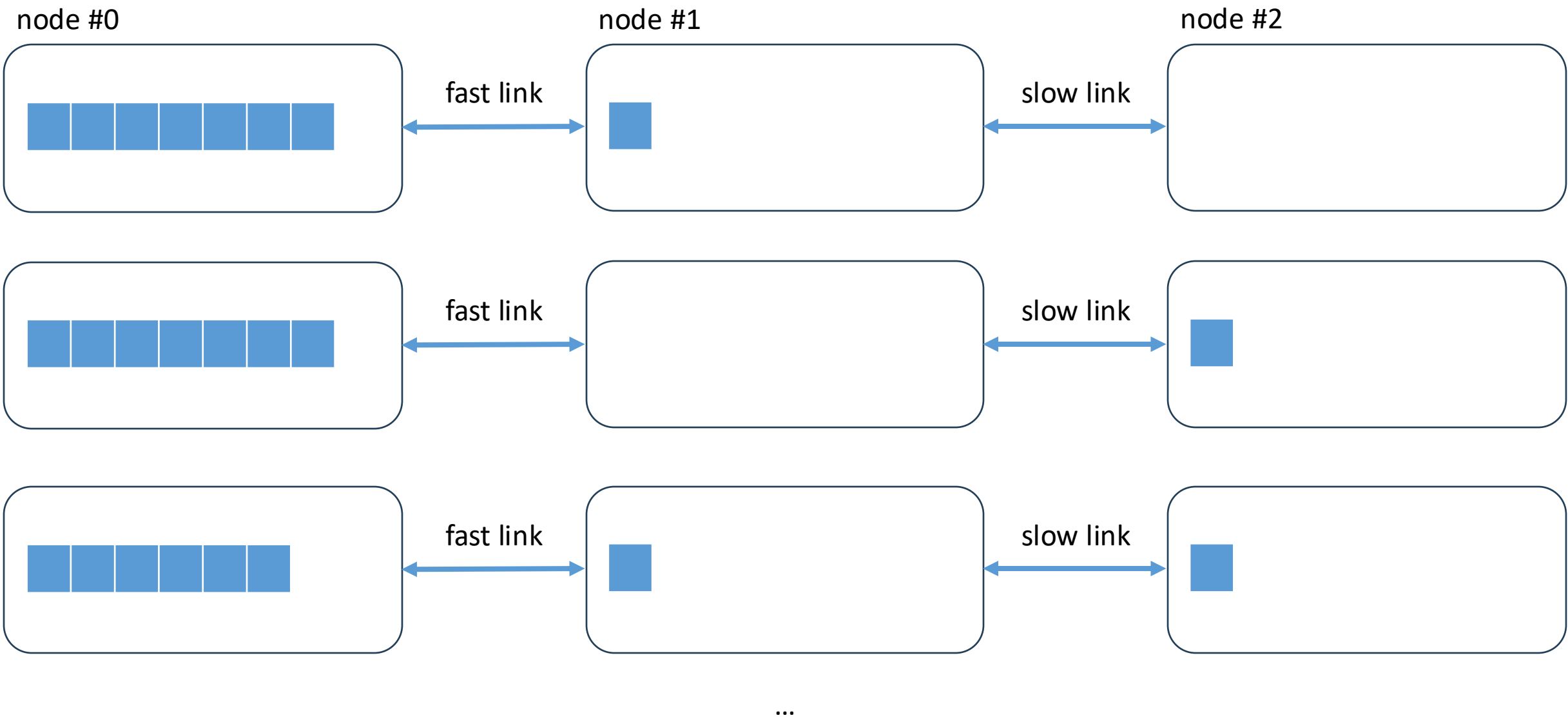


Suppose that node #0 is sending data to node #2 via an intermediate node and there is no buffering in node #1.

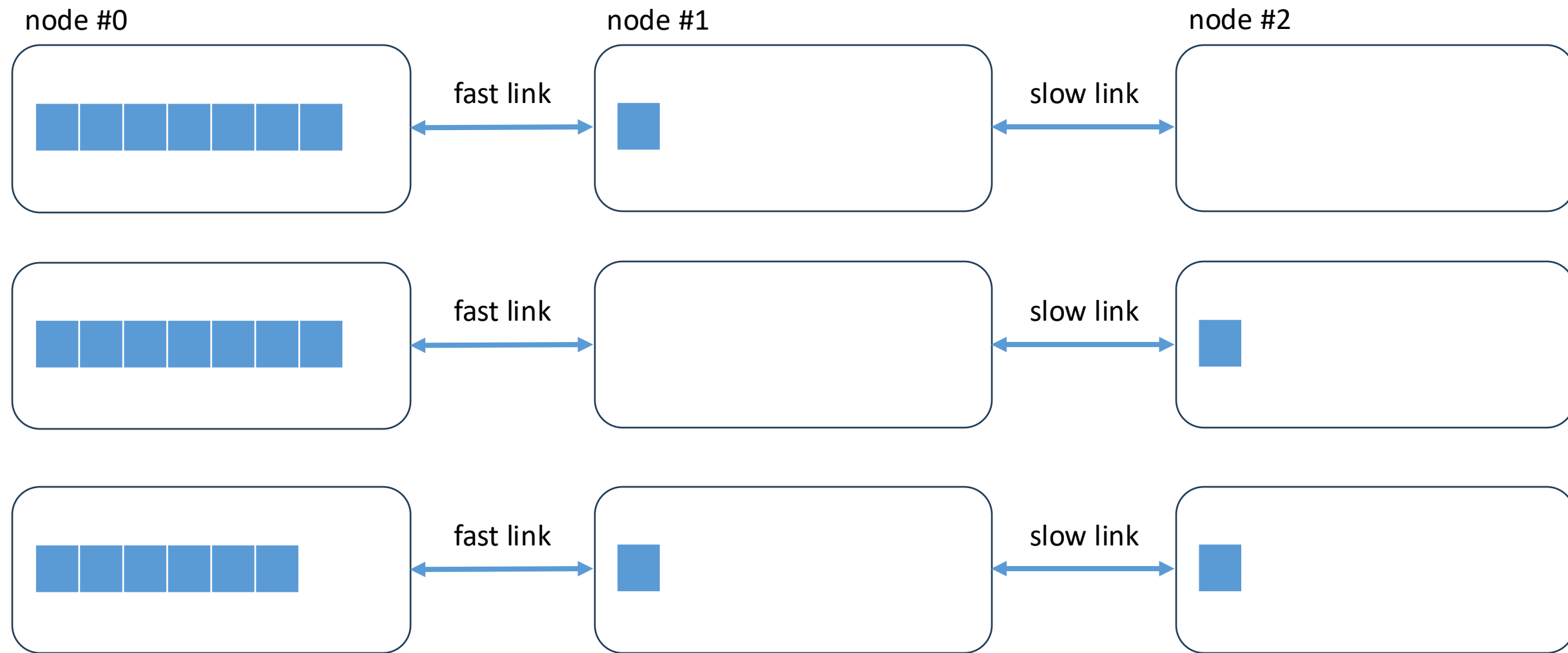
Buffering and bufferbloat



Buffering and bufferbloat

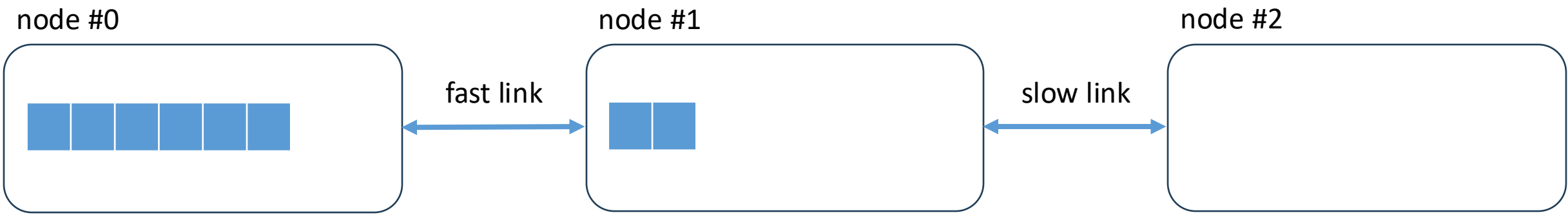


Buffering and bufferbloat



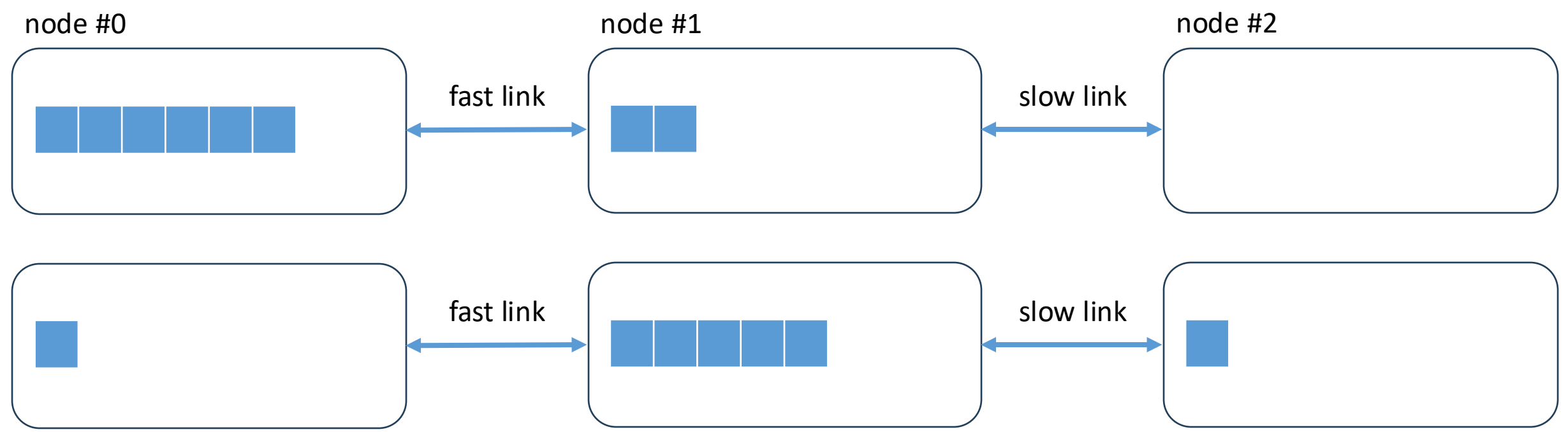
This scheme is far from optimal. Node #0 must keep much data for every slow client. Also, the data transfer rate between #0 and #1 needs time to adjust to changes in the bandwidth of the slow link.

Buffering and bufferbloat

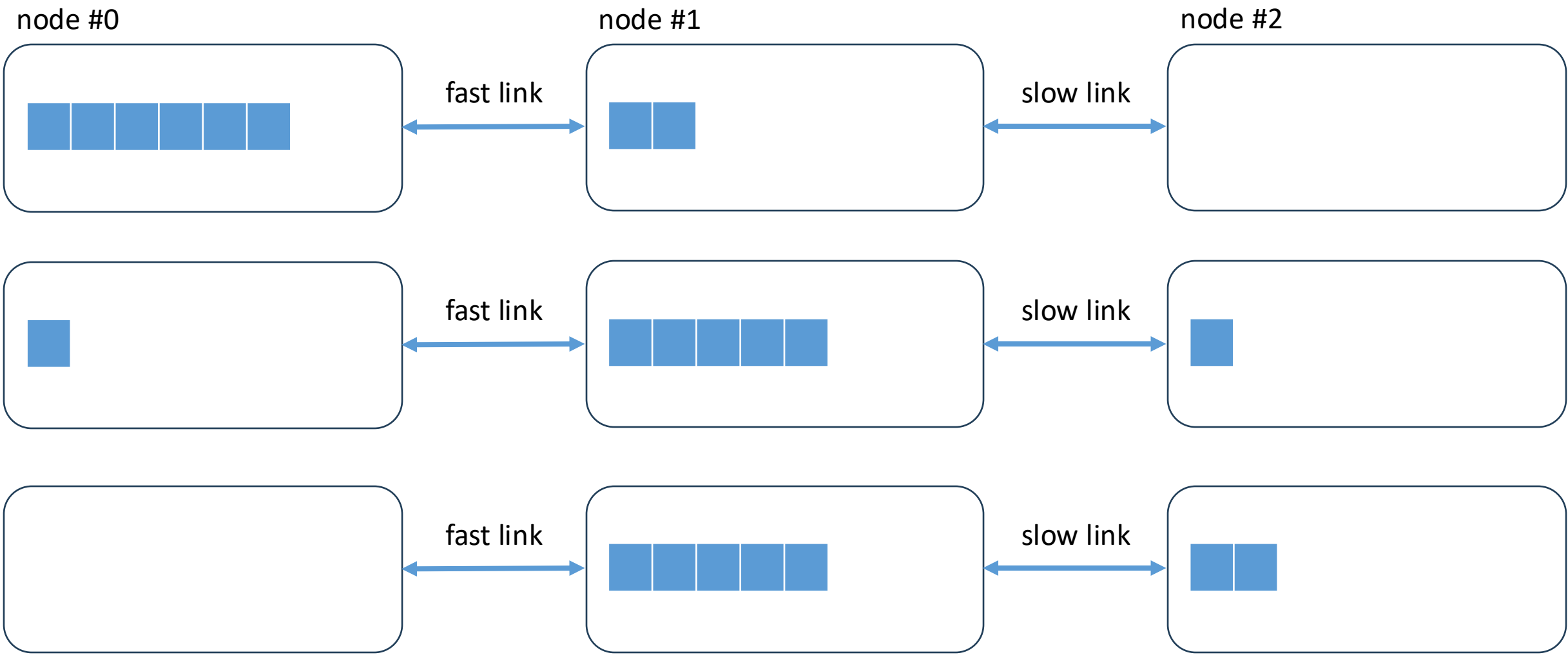


Now permit the queue at node #1 grow longer.

Buffering and bufferbloat

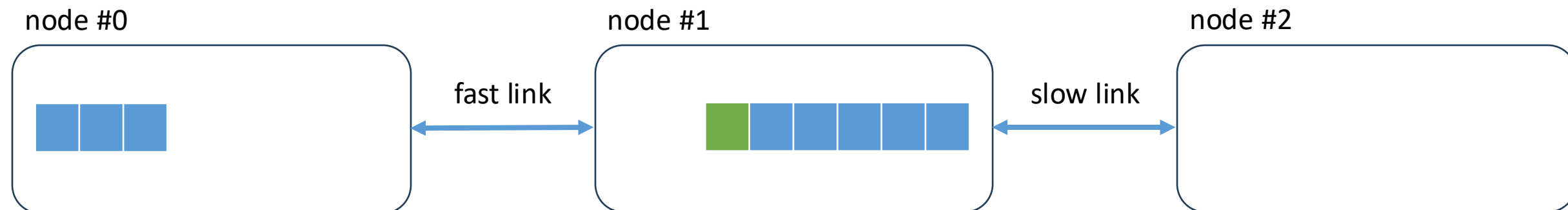


Buffering and bufferbloat



This looks better. Node #0 has released the buffers, and the transfer speed between nodes #1 and #2 adjusts itself immediately to changes in the slow link.

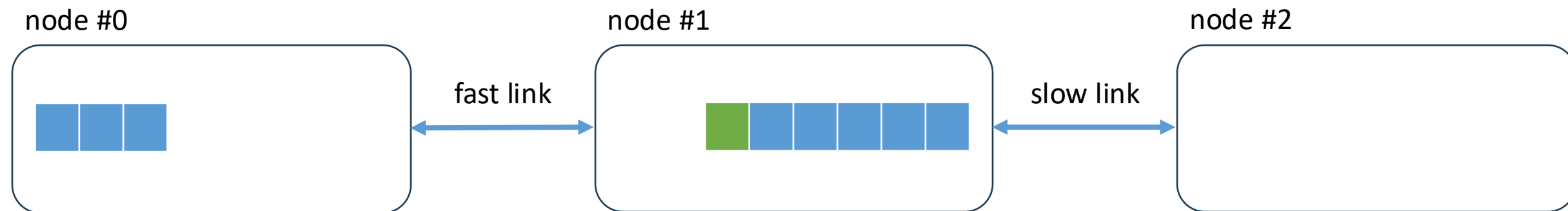
Buffering and bufferbloat



There is problem, though.

Suppose there are two flows from node #0 to node #2, one that needs a lot of bandwidth, and another one that is latency-sensitive. In many cases the packets at node #1 cannot be reordered, and a latency-sensitive flow must wait for packets of a high-bandwidth flow to drain from the queue.

Buffering and bufferbloat



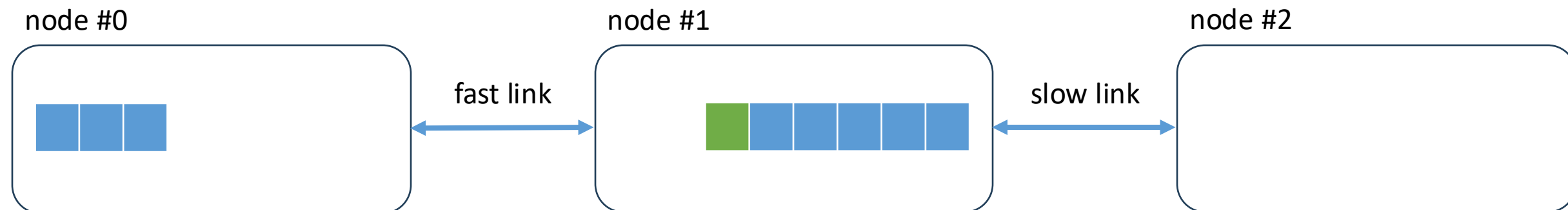
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There are many scenarios when packets (more generally, IO requests) can no longer be reordered:

1. packets were transferred to the (hardware) output queue of a network interface,

Buffering and bufferbloat



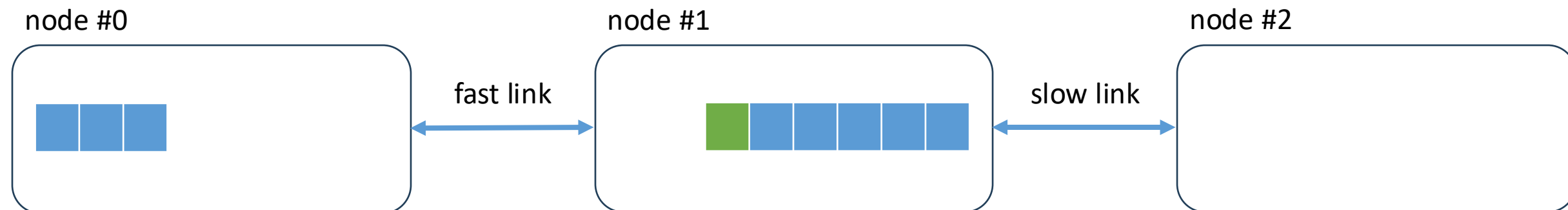
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Buffering and bufferbloat



There is problem, though.

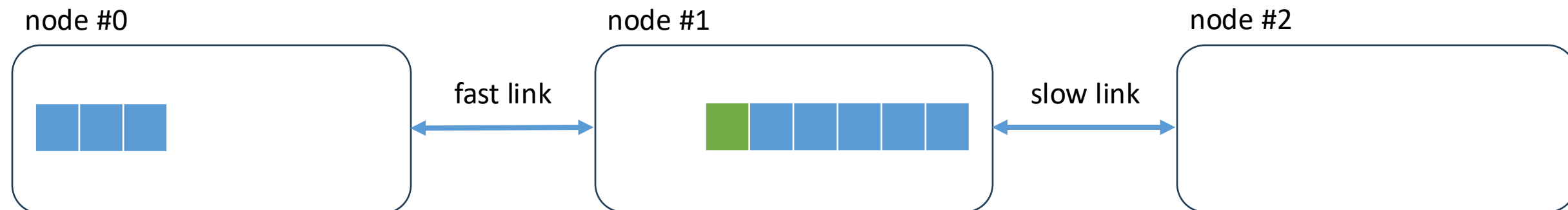
Suppose there are two flows from node #0 to node #2, one that needs a lot of bandwidth, and another one that is latency-sensitive. In many cases the packets at node #1 cannot be reordered, and a latency-sensitive flow must wait for packets of a high-bandwidth flow to drain from the queue.

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Note: this particular scenario is also bad because threads have no control over the scheduling. Even if IO requests go to adjacent disk areas, they may appear randomly ordered to the kernel. Recall that preserving the request order is an important advantage of `io_uring`.

Buffering and bufferbloat



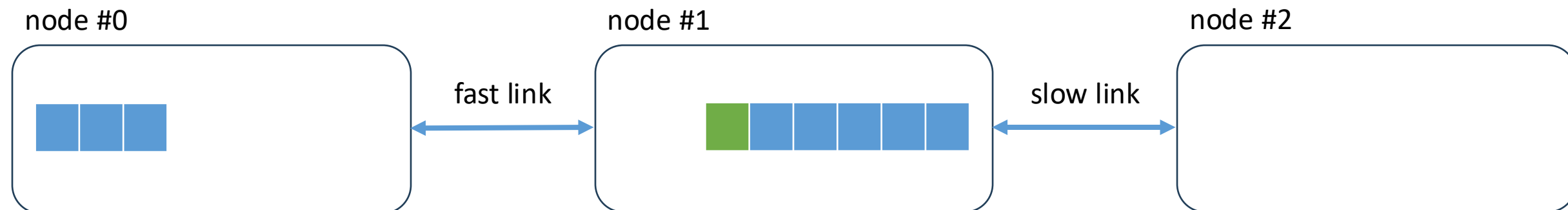
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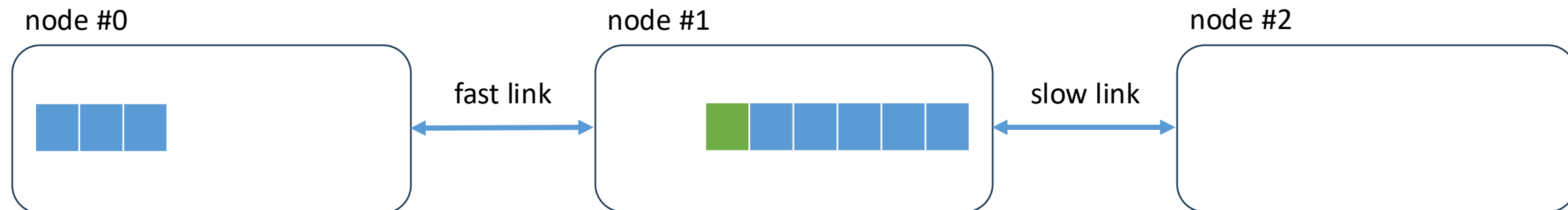
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Note: userspace applications have little control on the order of the writeback. Moreover, the writeback from the page cache is single-threaded, and may become a bottleneck: <https://lwn.net/Articles/976856>.

See also: `man 2 sync_file_range`

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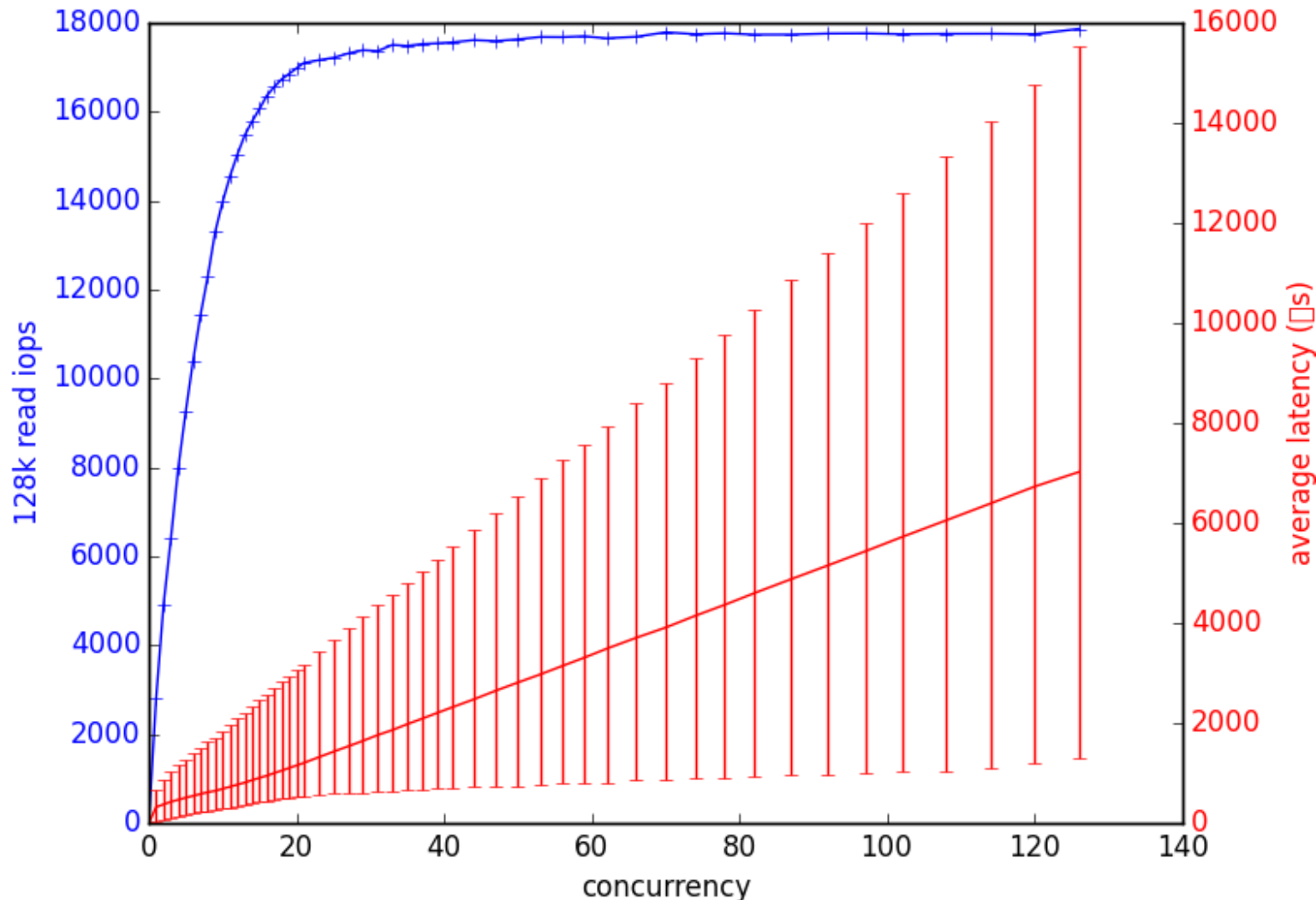
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4. an HTTP request is submitted to golang's standard HTTP client,
5. ...

See also: <https://lwn.net/Articles/458625>, <https://queue.acm.org/detail.cfm?id=2209336>

More on IO queues

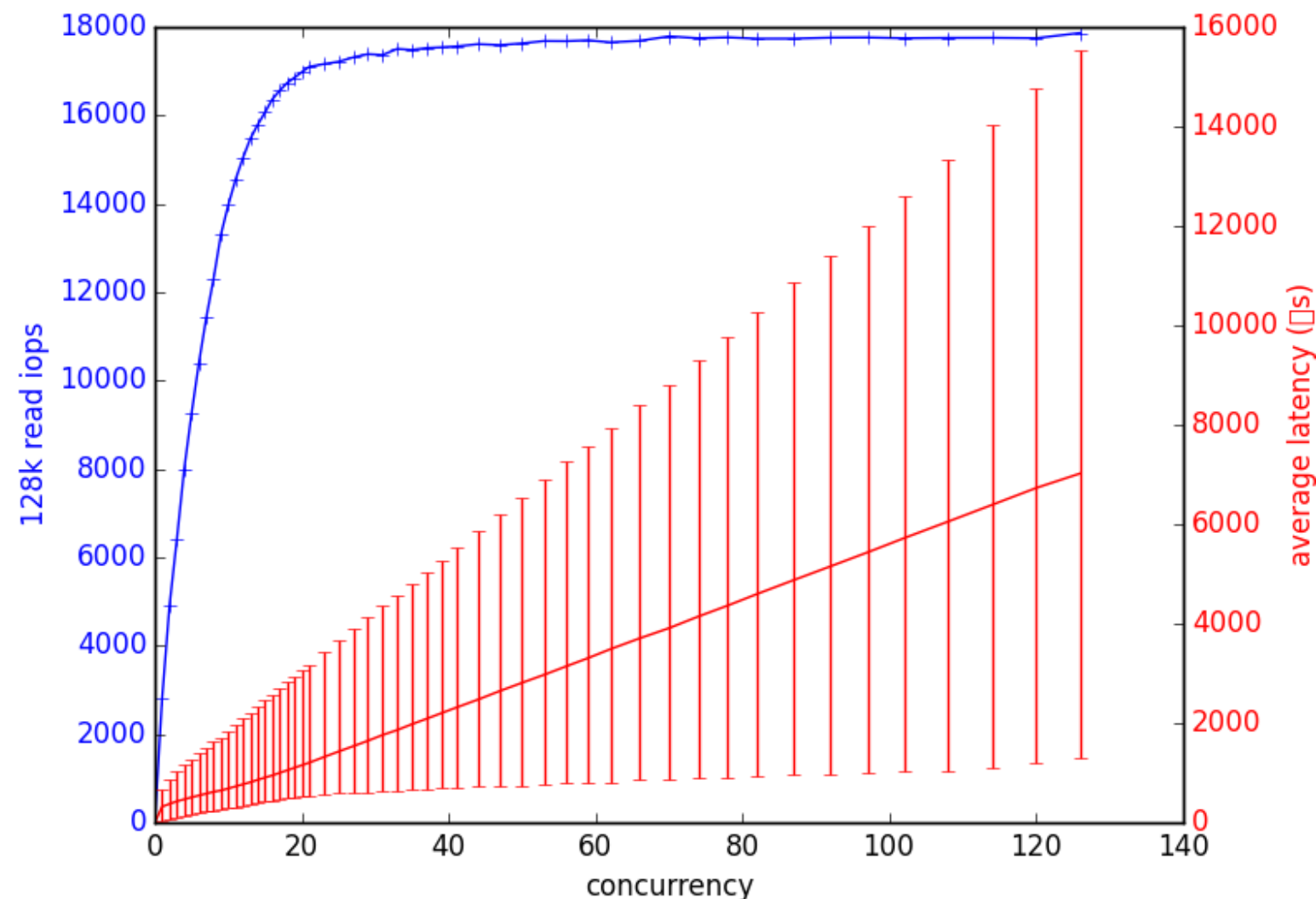
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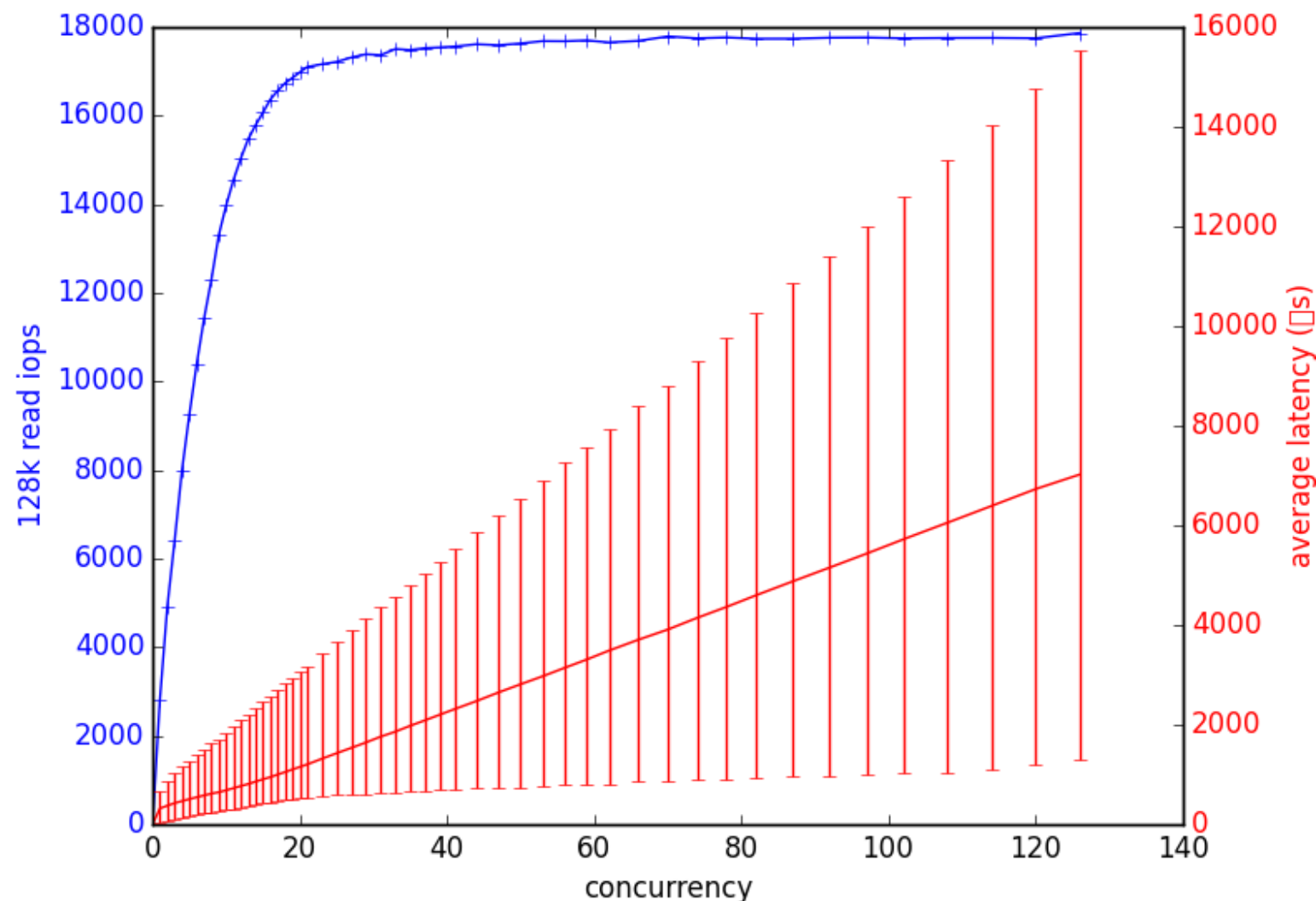
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GCS exhibits a similar behaviour. Chunk uploads in the range from 24M to 32M are fast and have a predictable latency. Increasing the chunk size decreases the throughput and increases the deviation of request run times.

Corollary: there is no need to issue too many concurrent requests or make requests too long. It is preferable to have a user-space queue that an application fully controls and can modify it the way it wishes.

See also: “ScyllaDB userspace disk IO scheduler”:

- <https://www.scylladb.com/2016/04/14/io-scheduler-1>
- <https://www.scylladb.com/2016/04/29/io-scheduler-2>
- <https://www.scylladb.com/2018/04/19/scylla-i-o-scheduler-3>



Load shedding

Idea: there is no need to issue too many concurrent requests or make requests too long. It is preferable to have a user-space queue that an application fully controls and can modify it the way it wishes.

This limits the size of egress request queues produced by an application.

How do we handle ingress queues that grow too big?

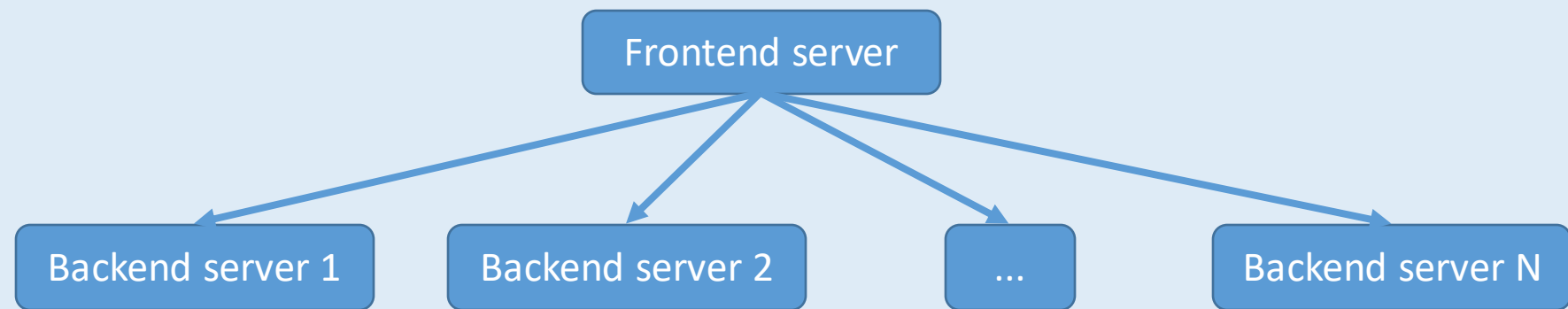
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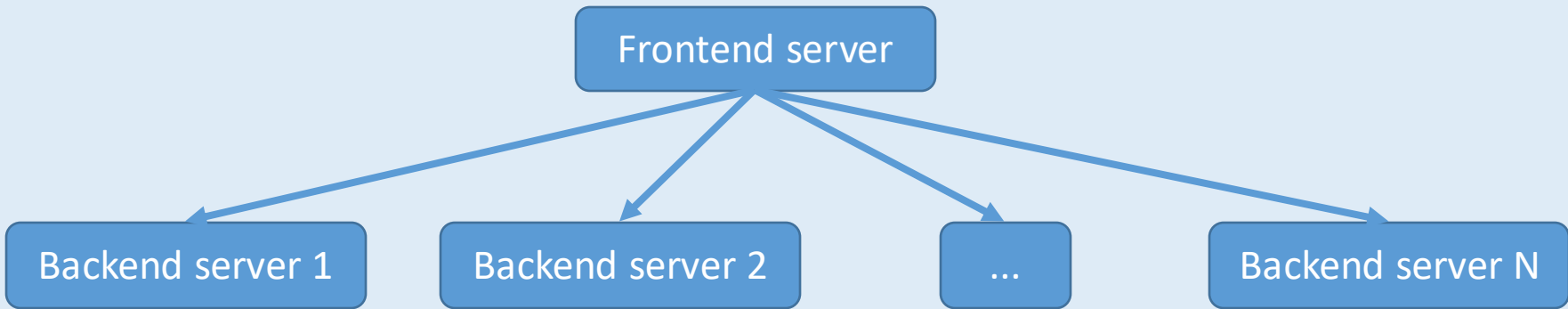
Typically, a request handler issues multiple sub-requests to other services in a distributed system and constructs a response from responses to sub-requests.

Suppose that servers 1, 2, ..., N-1 executed their sub-requests, but server N decided to load-shed its sub-request. Because of this, the whole top-level request can't be served and needs more resources to retry sub-requests. This only leads to increased load on all services within a distributed system.

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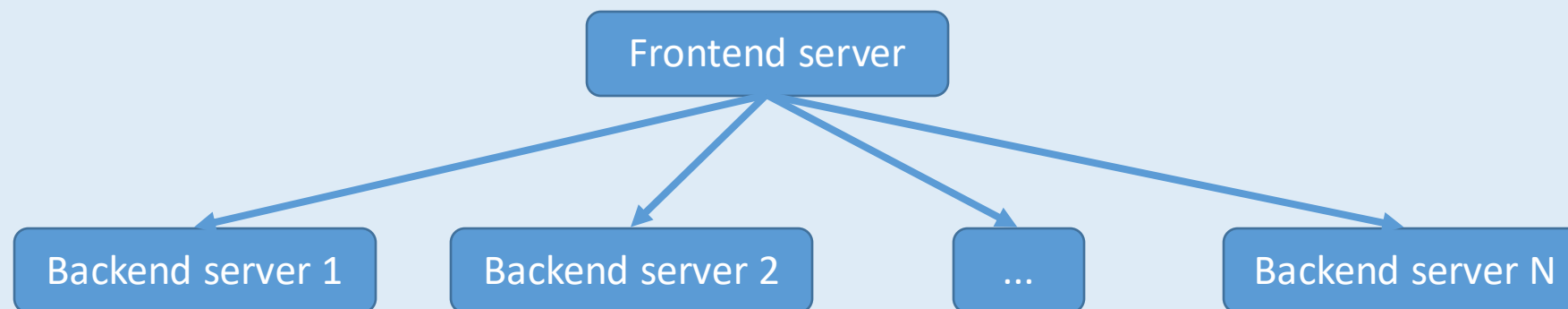


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Reminder: this is much like tail latencies. The probability of **any** of N servers load-shedding their sub-request grows with N.

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However, that is a flawed approach. One cannot invent many of them, and each priority level becomes big enough to cause oscillating behaviour in the system:

- **Quiz:** describe the behaviour.

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However, that is a flawed approach. One cannot invent many of them, and each priority level becomes big enough to cause oscillating behaviour in the system:

- once there are many enough requests with priorities $\leq N$, start to drop all requests with priorities $>N$,
- this removes a large chunk of load on the system so that it is no longer overloaded,
- start accepting requests with priorities $>N$ and become overloaded again.

A much better idea is to choose priority levels at run time. That way we can have a lot of them and make them fine-grained. For example, within every statically allocated priority level we may use a user ID as a refinement to the priority level.

See also: <https://www.cs.columbia.edu/~ruigu/papers/socc18-final100.pdf>