Tom Donahue

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Experience

June 2018 – **Human-Robot Interaction Engineer**, *Piaggio Fast Forward*, Boston, MA
Member of both Software and Smart Behaviors teams; bridging the gap between the investigation and design of high-level behaviors in gita and their implementation.

- Software Integration Lead; managing, tracking and testing feature development in the pre– and post–launch phases of gita.
- Co-designed, implemented and integrated brokerless, type-safe messaging framework atop ZeroMQ and Cereal as replacement for ROS core / messages.
- Co-developed numerous core app architectures across gita—incorporating modern C++ features and techniques when prudent.
- Investigated, designed and specced numerous novel human-robot dyad behaviors for gita.

Keywords: C++ (17), ROS, ZeroMQ, HRI, Linux, Git, Agile (Scrum)

2016 – 2018 **Character AI Engineer**, *Jibo*, Boston, MA
Member of the team tasked with making the first social robot for the home—Jibo—feel lifelike, produce dynamic behavior, and ensure a consistent character experience across his wide range of interactions and skills.

- Co-architect and lead developer of *Embodied Speech*, a subsystem that blends Jibo's speech with animation, graphics and sound to create character-rich dialog interactions.
- Lead developer of *Chitchat*, Jibo's ontological dialog ability, and co-led *GQA*, Jibo's general question-answering service—the most frequent user-initiated interactions with the robot.
- Co-designed and implemented a novel, distributed robot/cloud skill architecture resulting in a significant interaction latency reduction and a far more scalable content-delivery pipeline.
- Led development of an animation database, a core module that enables queries for, and configuration of, animation and sound assets for on-demand playback and control on Jibo.

Keywords: TypeScript / JS / Node, Python, NLP/NLU, HRI, OSX, Git, Agile (Scrum)

2014 - 2016 **Robot Software Engineer**, *Softbank Robotics (Aldebaran)*, Boston, MA
Member of a small agile team working across the Aldebaran stack—from NaoQi middleware modules to core applications.

- Designed and built *Act* framework for semi-autonomous multi-robot–human interactions.
- Co-developed *ALTactileGesture*, a high-level touch sequence gesture recognition module.
- Released *Mad Chats*, an interactive Mad Libs-esque word game played between human and robot.
- Part of the team that designed and built a core application launching and dialog interaction for all Aldebaran robots.
- Designed, built and regularly demoed semi-autonomous robot greeter for range of external clients.

Keywords: Python, JS, C++, HTML/ CSS, HRI, Linux, Git, Agile (Scrum)

2012 - 2014 **Graduate Research / Teaching Assistant**, *Human Robot Interaction Lab*, *Tufts University*, Medford, MA
Areas of focus: human-robot teaming, situated natural language understanding and generation.

Keywords: Java, Clojure, C++, JS, HTML/ CSS, PHP, HRI, NLP, Linux, Git, SVN, LaTeX, R

2010 - 2012 **Graduate Research / Teaching Assistant**, *Computer-Human Interaction Lab*, *Bowling Green State University*, Bowling Green, OH
Areas of focus: Tangible interfaces and accessibility

Keywords: Java, C++, HCI, Windows

Technical Skills

Languages

Core: C++ (17), Typescript / JS, Python
Rusty: Java, Clojure, HTML/ CSS
Familiar: PHP, SQL, R

Tools

src Control: Git / Github, SVN
Cloud/DB: Docker, SQL, Neo4j
Writing: LaTeX, G Suite

Platforms

Robotics: Extensive development experience with a range of robots / robotics platforms, including:

- Piaggio Fast Forwards' **gita**—Hands-free cargo carrying, following robot.
- **ROS**—Most widely adopted open-source robotics middleware.
- **Jibo**—One of the first social robots for the home.
- Softbank / Aldebaran's **Pepper and Nao**—Humanoid robots used in various business/educational settings.
- **ADE**—a research-focused, distributed, multi-agent robotics middleware.

Unix: Considerable Unix (Linux, OSX) development experience and comfortable with command line interfaces.

Education

2012 - 2014 **Doctoral studies in Computer Science & Cognitive Science**, *Tufts University, Medford, MA*
Withdrew in good standing from joint-Ph.D. program

2011 - 2012 **M.S. in Computer Science**, *Bowling Green State University, Bowling Green, OH*
Concentration: Human-Computer Interaction

2007 - 2011 **B.S. in Computer Science & Psychology**, *Bowling Green State University, Bowling Green, OH*
Minor in Mathematics, Cum Laude

Publications

2015 **Thomas Donahue**, Matthias Scheutz.
Investigating the Effects of Robot Affect and Embodiment on Attention and Natural Language of Human Teammates.
2015 International Conference on Cognitive Infocommunications (CogInfoComm)

2014 Cody Canning, **Thomas Donahue**, Matthias Scheutz.
Investigating Human Perceptions of Robot Capabilities in Remote Human-Robot Team Tasks based on First-Person Robot Video Feeds.
2014 International Conference on Intelligent Robots and Systems (IROS)

2013 **Thomas Donahue**, G. Michael Poor, Martez Mott, et. al.
On Interface Closeness and Problem Solving.
2013 Conference on Tangible, Embedded and Embodied Interaction (TEI)

2012 Martez Mott, **Thomas Donahue**, G. Michael Poor, et. al.
Leveraging Motor Learning for a Tangible Password System.
2012 Conference on Human Factors in Computing Systems: Extended Abstracts (CHI)

2011 G. Michael Poor, **Thomas Donahue**, Martez Mott, et. al.
Access-a-WoW: Building an Enhanced World of Warcraft UI for Persons with Low Visual Acuity.
2011 International Conference on Universal Access in Human-Computer Interaction (UAHCI)

Achievements

2017 Jibo named Time Magazine's #1 of the "25 Best Inventions of 2017"