Thomas Donahue

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github.com/donahut

Experience

Mar 2014- Robot Software Engineer, Aldebaran Robotics

• Developing interactive robot applications and behaviors for the B2B and B2C markets.

2012-2014 Doctoral Researcher, Human Robot Interaction Lab, Tufts University

- Implemented distributed notification system for the ADE middleware
- Overhauled system GUIs for ADE middleware with improved efficiency and speed, as well as a simplified UX
- Designed and conducted HRI study investigating the role of remote video feeds on perceptions of robot teammates; submitted for peer review
- Developed software for data-mining rich audio and video corpora and annotations
- Designed and built web-survey platform for multiple HRI studies
- Managed local and remote teams of research assistants for long-term project

2012, 2013 Teaching Assistant, Computer Science Dept., Tufts University

- Maintained automated testing suite for introductory C++ course
- Provided instruction to students during lab sections as well as office hours

2010-2012 Graduate Research Assistant, Computer-Human Interaction Lab, Bowling Green State University

- · Part of a team that developed a novel, tangible password input system
- Designed, built and tested an alternative UI for World of Warcraft for the visually impaired community
- Helped build a series of web-tools for use in undergraduate Geology courses
- Investigated the learning benefits of and tradeoffs between mouse, touch and tangible input systems

Education

2012-2014 Graduate studies in Computer Science, Tufts University, Medford, MA

Withdrew in good standing from Computer Science & Cognitive Science Joint-Ph.D. program

2011–2012 M.S. in Computer Science, Bowling Green State University, Bowling Green, OH

2007-2011 B.S. in Computer Science & Psychology, Bowling Green State University, Bowling Green, OH

Minor in Mathematics, Cum Laude

Technical Skills

Languages

Core: Java, C++, Python

Experienced: PHP, Javascript, Clojure, HTML/CSS, R Exposure: C, SQL, Scheme, SML, Prolog, CUDA

Tools

src Control: Git, Subversion
Build: Ant, Leiningen

Editors: Emacs, IntelliJ IDEA, Visual Studio

Writing: LATEX

Platforms

Linux: Considerable Linux development experience, and comfortable at the command line shell

Robotics: Familiar with ROS and have extensive experience working with ADE - a research focused distributed,

multi-agent robotics middleware

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