Thomas Donahue

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Experience

April 2016 –

Character AI Engineer, *Jibo*, Boston, MA

Plan and implement many aspects of Jibo that make him feel lifelike, produce dynamic behavior, and behave in a manner that is consistent with his character.

Keywords: TypeScript, NodeJS, Electron, HRI

2014 - 2016

Robot Software Engineer, *Softbank Robotics (Aldebaran)*, Boston, MA

Member of a small agile team working across the Aldebaran stack — from NaoQi middleware modules to core applications.

- Part of the team that designed and built the core application launching and dialog interaction for all Aldebaran robots.
- Designed and built *Act* framework for semi-autonomous multi-robot—human interactions.
- Developed *ALTactileGesture*, a high-level touch sequence gesture recognition module.
- Released *Mad Chats*, an interactive Mad Libs-esque word game played between human and robot.
- Designed, built and regularly demoed semi-autonomous robot greeter for range of external clients.

Keywords: Python, JS, C++, HTML/CSS, HRI, Linux, Scrum

2012 - 2014

Research and Teaching Assistant, *Human Robot Interaction Lab, Tufts University*, Medford, MA

Areas of focus: human-robot teaming, situated natural language understanding and generation.

As research assistant:

- Implemented distributed notification system for the ADE robotics middleware.
- Overhauled system GUIs for ADE middleware – yielding improved stability, efficiency and a simplified UI.
- Developed data-mining tools for rich audio and video corpora and annotations.
- Designed and built web-survey platform for multiple HRI studies.
- Designed, conducted and analyzed multiple HRI studies investigating multiple factors within human-robot teams.

As teaching assistant:

- Maintained automated testing suite and grading system used by dozens of teaching assistants for introductory C++ course.
- Provided instruction to students during lab sections as well as office hours.
- Graded homework and exams.

Keywords: Java, Clojure, C++, JS, HTML/CSS, PHP, HRI, NLP, Linux, Git, SVN, LaTeX, R

2010 - 2012

Research Assistant, *Computer-Human Interaction Lab, Bowling Green State University*, Bowling Green, OH

- Part of a team that developed a novel tangible password input system.
- Designed, built and tested an alternative UI for World of Warcraft for the visually impaired community.
- Investigated the learning benefits of — and trade-offs between — mouse, touch and tangible input systems via a novel deduction puzzle/game.
- Helped build a series of web-tools for use in undergraduate Geology courses.

Keywords: Java, C++, HCI, Tangible/Touch UIs, Accessibility, Windows

2008 - 2010

Research Assistant, *Rhythm, Attention and Perception Lab, Bowling Green State University*, Bowling Green, OH

Independently designed and built neural-network in MATLAB that modeled human auditory tone categorization.

Technical Skills

Languages

Core:	Python, C++, Java
Proficient:	JS, HTML/CSS, Clojure, R, PHP

Tools

src Control:	Git, Subversion, Gerrit
Writing:	LaTeX, Org-mode

Platforms

Linux:	Considerable Linux development experience and comfortable with command line interfaces.
Robotics:	Extensive development experience with both Aldebaran's NaoQi robotics middleware, as well as ADE – a research focused distributed, multi-agent robotics middleware.

Education

2012 - 2014 **Graduate studies in Computer Science**, *Tufts University, Medford, MA*
Withdrew in good standing from Computer Science & Cognitive Science joint-Ph.D. program

2011 - 2012 **M.S. in Computer Science**, *Bowling Green State University, Bowling Green, OH*

2007 - 2011 **B.S. in Computer Science & Psychology**, *Bowling Green State University, Bowling Green, OH*
Minor in Mathematics, Cum Laude

Publications

2015 **Thomas Donahue**, Matthias Scheutz.
Investigating the Effects of Robot Affect and Embodiment on Attention and Natural Language of Human Teammates.
2015 International Conference on Cognitive Infocommunications (CogInfoComm)

2014 Cody Canning, **Thomas Donahue**, Matthias Scheutz.
Investigating Human Perceptions of Robot Capabilities in Remote Human-Robot Team Tasks based on First-Person Robot Video Feeds.
2014 International Conference on Intelligent Robots and Systems (IROS)

2013 **Thomas Donahue**, G. Michael Poor, Martez Mott, et. al.
On Interface Closeness and Problem Solving.
2013 Conference on Tangible, Embedded and Embodied Interaction (TEI)

2012 Martez Mott, **Thomas Donahue**, G. Michael Poor, et. al.
Leveraging Motor Learning for a Tangible Password System.
2012 Conference on Human Factors in Computing Systems: Extended Abstracts (CHI)

2011 G. Michael Poor, **Thomas Donahue**, Martez Mott, et. al.
Access-a-WoW: Building an Enhanced World of Warcraft UI for Persons with Low Visual Acuity.
2011 International Conference on Universal Access in Human-Computer Interaction (UAHCI)