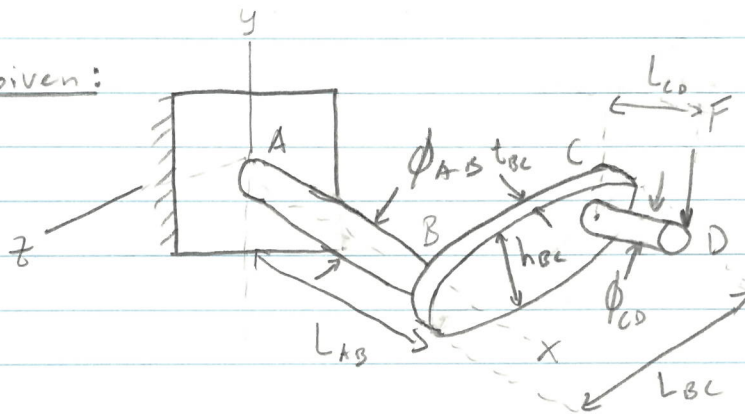


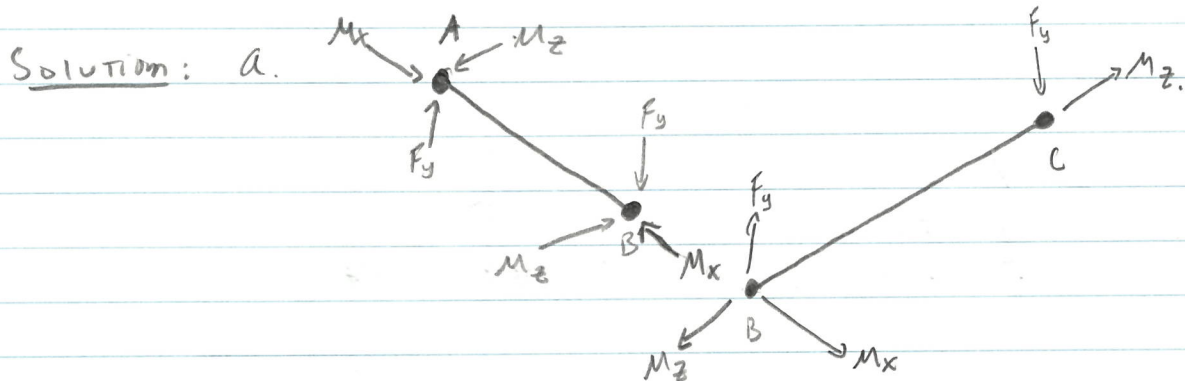
Machine elements

HW 1

January 19, 2020

1. Given:


Knowns: $L_{AB} = 5 \text{ in}$ $F = 300 \text{ lbs}$
 $L_{BC} = 4 \text{ in}$
 $L_{CD} = 1.5 \text{ in}$
 $\phi_{AB} = 1.75 \text{ in}$
 $\phi_{CD} = 0.5 \text{ in}$
 $t_{BC} = 0.25 \text{ in}$
 $h_{BC} = 1.25 \text{ in}$

Find: a. Free body Diagram of Shaft AB / arm BC. (in isolation).
b. Magnitude of all Forces / moments acting on the Ends of these members


$$B. \quad F_y^A = F_y^B = F_y^C = F = 300 \text{ lbs}$$

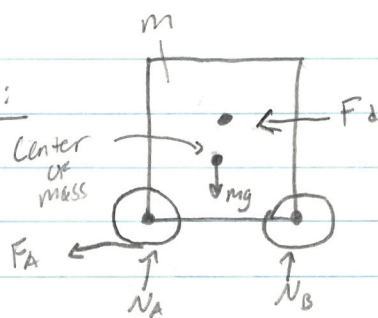
$$M_z^A = M_z^B = F(L_{CD}) = (300 \text{ lbs})(1.5 \text{ in}) = 450 \text{ lb} \cdot \text{in.}$$

$$M_x^B = M_x^A = F(L_{BC}) = (300 \text{ lbs})(4 \text{ in}) = 1200 \text{ lb} \cdot \text{in.}$$

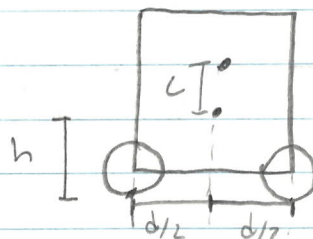
$$M_z^A = F(L_{AB} + L_{CD}) = (300 \text{ lbs})(5 \text{ in} + 1.5 \text{ in}) = 1950 \text{ lb} \cdot \text{in.}$$

3.

Given:



Knowns: none



Solution:

$$a. \sum F_y = N_A + N_B - mg = 0$$

$$\sum F_x = -F_d - F_A = \max$$

$$\sum M_c = (F_d)(c) - F_A(h) - N_A\left(\frac{d}{2}\right) + N_B\left(\frac{d}{2}\right) = 0$$

$$b. N_B = mg - N_A$$

$$N_A\left(\frac{d}{2}\right) = (F_d)(c) + (N_B)\left(\frac{d}{2}\right) - F_A(h)$$

$$N_A = \frac{2}{d} (F_d(c) - F_A(h) + N_B)$$

$$N_A = \frac{2}{d} (F_d(c) - F_A(h) + mg - N_A)$$

$$2N_A = \frac{2}{d} (F_d(c) - F_A(h) + mg)$$

$$N_A = \frac{F_d(c) - F_A(h) + \frac{1}{2}mg}{d}$$

$$c. N_B = mg - \left(\frac{F_d(c) - F_A(h) + \frac{1}{2}mg}{d} \right)$$

$$N_B = mg - \frac{F_d(c)}{d} + \frac{F_A(h)}{d} - \frac{1}{2}mg$$

$$N_B = \frac{1}{2}mg - \frac{F_d(c)}{d} + \frac{F_A(h)}{d}$$

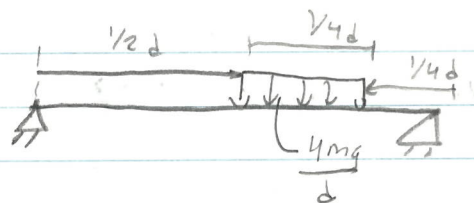
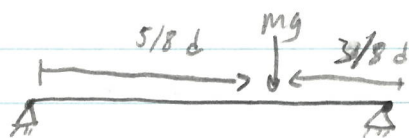
d. As you brake and add in the F_A term, more weight will move to the front of the scooter since F_A is positive in the equation for N_B .

$$e. F_A \text{ is max when } N_A = 0$$

$$0 = F_d(c) - F_A(h) + \frac{1}{2}mg$$

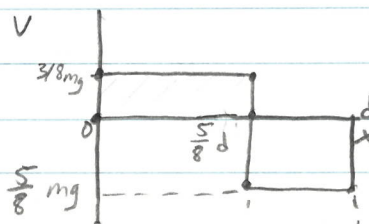
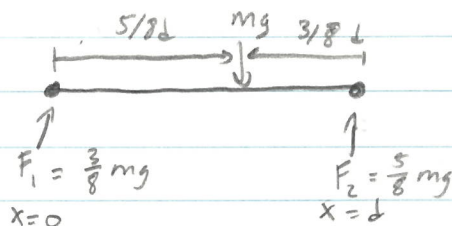
$$F_A = \frac{F_d(c) + \frac{1}{2}mg}{h}$$

5. Given:



Knowns: none

Solution: a.

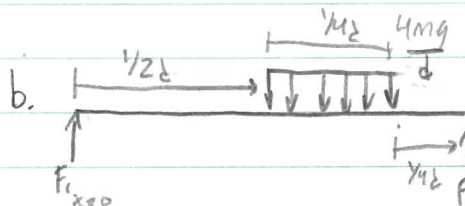
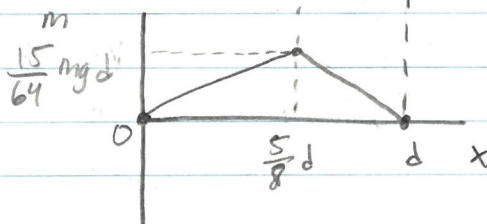


$$\sum M_{x=0} = F_2 d - mg \left(\frac{5}{8} d \right) = 0$$

$$F_2 = \frac{5}{8} mg$$

$$\sum F_y = F_1 + F_2 - mg = 0$$

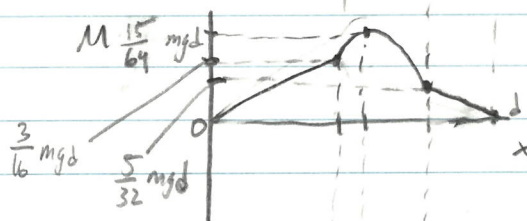
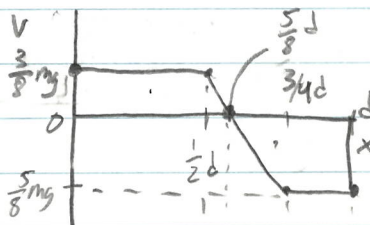
$$F_1 = \frac{3}{8} mg$$



$$\sum M_{x=0} = F_2 d - \frac{4mg}{d} \left(\frac{1}{4} d \right) \left(\frac{5}{8} d \right) = 0$$

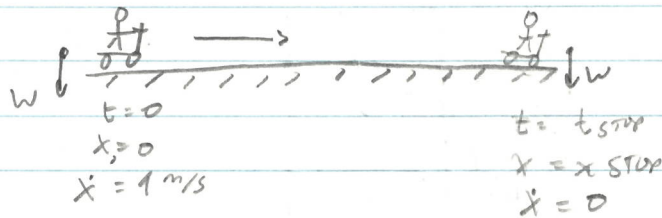
$$F_2 = \frac{5}{8} mg$$

$$F_1 = \frac{3}{8} mg$$



c. The maximum bending moments for Part A/B is $15/64 mgd$. They are equal because even though one is a point load and the other is a distributed load, the total force coming down is still the same.

4. Given:



knowns: $W = 180 \text{ lbs.}$

$$\dot{x} = 1 \text{ m/s}$$

@ $x=0$ / $t=0$ Scooter brakes

W/ constant $a = -.3g$

until it stops.

Solution:

a. $\ddot{x} = -.3g = -2.943 \text{ m/s}^2$

$$t = \left| \frac{\dot{x}}{\ddot{x}} \right| = \left(\frac{1 \text{ m/s}}{-2.943} \right) = \boxed{3.05 \text{ sec.}}$$

b. $x = x_0 + vt + \frac{1}{2}at^2 = 1(3.05) - \frac{1}{2}(2.943 \text{ m/s}^2)(3.05)^2$

$$\boxed{x = 13.76 \text{ m}}$$

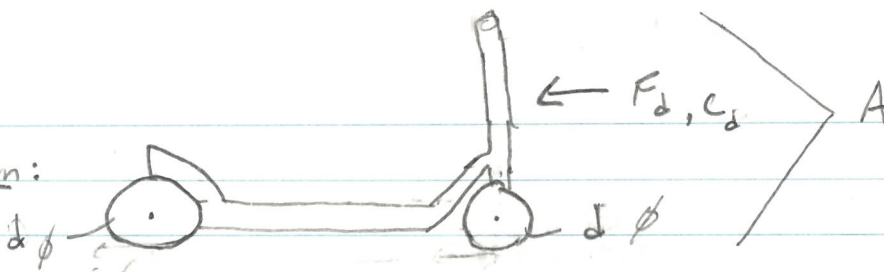
c. $180 \text{ lbs} \cdot \frac{4.48^{12} \text{ N}}{1 \text{ lbs}} = 800 \text{ N}$

$$W = F \cdot d = mad = \frac{F}{g} a d = \left(\frac{800 \text{ N}}{9.81 \text{ m/s}^2} \right) (-2.943 \text{ m/s}^2) (13.76 \text{ m})$$

$$\boxed{W = 3.3 \text{ kJ.}}$$

d. $P = \frac{W}{t} = \frac{3.3 \text{ kJ}}{3.05 \text{ s}} = \boxed{1082 \text{ W}}$

2.

Given:Knowns:

$$F_d = \frac{1}{2} C_d A \Delta V^2 = K_A V^2$$

$$K_A = 0.3 \text{ kg/m}$$

$$d_\phi = 8 \text{ in} =$$

Part b.

$$\text{Voltage} = 24 \text{ V}$$

$$\omega = 5500 \text{ rev/min}$$

$$T = 1.736 \text{ N.m}$$

Solution:

$$a. P = FV = K_A V^2 \cdot V = K_A V^3$$

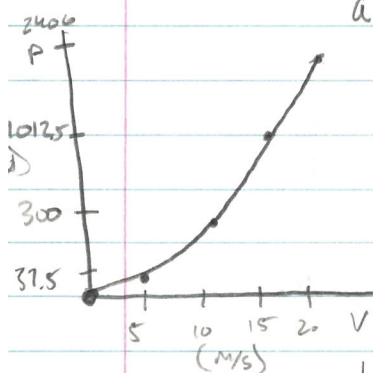
$$P(0 \text{ m/s}) = (0.3 \text{ kg/m})(0 \text{ m/s})^3 = 0 \text{ W}$$

$$P(5 \text{ m/s}) = (0.3 \text{ kg/m})(5 \text{ m/s})^3 = 37.5 \text{ W}$$

$$P(10 \text{ m/s}) = (0.3 \text{ kg/m})(10 \text{ m/s})^3 = 300 \text{ W}$$

$$P(15 \text{ m/s}) = (0.3 \text{ kg/m})(15 \text{ m/s})^3 = 1012.5 \text{ W}$$

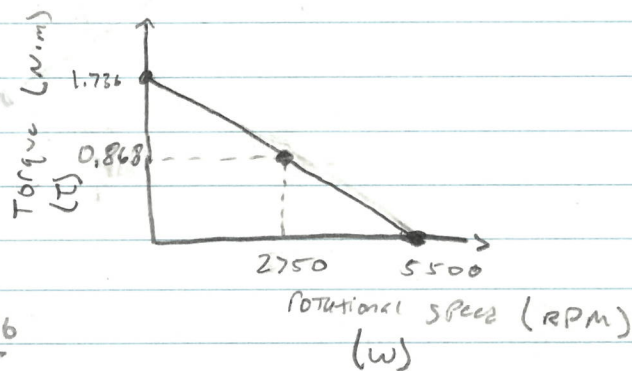
$$P(20 \text{ m/s}) = (0.3 \text{ kg/m})(20 \text{ m/s})^3 = 2400 \text{ W}$$



$$b. V = 24 \text{ V}$$

$$\omega = 5500 \text{ rev/min}$$

$$T = 1.736 \text{ N.m}$$



$$P = T \cdot \omega \quad \text{Slope} = \frac{0.868 - 1.736}{2750 - 0}$$

$$= -3.156 \cdot 10^{-4}$$

$$P = (-3.156 \cdot 10^{-4} \omega^2 + 1.736)(0.1047 \omega)$$

$$P_{\max} = \frac{dP}{d\omega} = -6.61 \cdot 10^{-5} \omega + 0.182 = 0$$

$$\omega = 2750$$

$$P_{\max} = -3.156 \cdot 10^{-5} (2750)^2 + 0.182 (2750)$$

$$P_{\max} = 261 \text{ W}$$

$$P = K_A V^3 \quad V = \sqrt[3]{\frac{P}{K_A}} = 9.55 \text{ m/s}$$

$$c. \phi_{\text{wheel}} = 8 \text{ in} = 0.16 \text{ m} \quad V_{\max \text{ wheel}} = 9.55 \text{ m/s} \quad V = \omega r$$

$$\omega_{\text{motor}} = 2750 \text{ RPM}$$

$$\omega_m r_m = \omega_w r_w = \left(\frac{V_w}{r_w} \right) \left(\frac{60 \text{ s}}{\text{min}} \cdot \frac{1 \text{ rev}}{2\pi \text{ rad}} \right) (r_w)$$

$$\text{Gear ratio: } \frac{2750 \text{ RPM}}{282 \text{ RPM}} \approx 3.06$$

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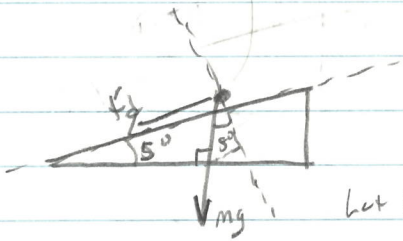
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2L. $\phi_{\text{Wheel}} = 8\text{in} \rightarrow 0.2032\text{m}$ $V_{\text{max wheel}} = 9.55\text{ m/s}$ $V = \omega r$
 $\omega_{\text{motor}} = 2750\text{ RPM}$

$$\omega_m r_m = \omega_w r_w = \frac{V_w}{r_w} \cdot \frac{60\text{ sec}}{1\text{ min}} \cdot \frac{1\text{ rev}}{2\pi\text{ rad}} \cdot r_w$$

$$\text{Gear ratio} = \frac{\omega_m}{\omega_w} = \frac{2750}{V_w \cdot 60 \cdot 2\pi} = \boxed{3.06}$$

2D.



$$P = FV = (F_d + F_w)V = K_d V^3 + F_w V$$

$$P = (1.3)(9.55)^3 + W \sin 5^\circ (9.55)$$

Let $W = 661\text{ kg}$ $P = ?$

$$P = 316.22\text{ W}$$

$$\Delta P = 55.23\text{ W}$$

$$\Delta P = FV = mg \sin 5^\circ (9.55)$$

$$\boxed{\text{Additional Power} = 9.55 mg \sin 5^\circ}$$