## Inverses of Matrices

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[1, §1.3]

DEF. The <u>inverse</u> of  $A \in M_{n \times n}(\mathbb{R})$  is a matrix  $B \in M_{n \times n}(\mathbb{R})$  such that AB = BA = I.

Ex. Let 
$$A=\left[egin{array}{cc} 1 & 2 \\ 3 & 5 \end{array}
ight]$$
 and  $B=\left[egin{array}{cc} -5 & 2 \\ 3 & -1 \end{array}
ight]$  . Then

$$AB = \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} -5 & 2 \\ 3 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$BA = \begin{bmatrix} -5 & 2 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

Hence B is an inverse of A.

Ex. The matrix  $0_{n\times n}$  does not have an inverse since  $0_{n\times n}B=0_{n\times n}\neq I$  whenever  $B\in M_{n\times n}(\mathbb{R})$ .

Ex. The matrix  $A = \left[ \begin{array}{cc} 1 & 1 \\ 0 & 0 \end{array} \right]$  has no inverse since

$$AB = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} = \begin{bmatrix} b_{11} + b_{21} & b_{12} + b_{22} \\ 0 & 0 \end{bmatrix}$$

whenever  $B \in M_{2 \times 2}(\mathbb{R})$ .

DEF. A matrix is <u>invertible</u> or <u>nonsingular</u> if it has an inverse.

A matrix is noninvertible or singular if it does not have an inverse.

DEF. The collection of all  $n \times n$  invertible matrices is denoted by  $\mathrm{GL}_n(\mathbb{R})$ .

THM (Theorem 1.4 in [1]). Inverses are unique. That is, let  $A \in {\rm GL}_n(\mathbb{R})$  have inverses  $B_1$  and  $B_2$ . Then  $B_1=B_2$ .

Proof. 
$$B_1 = B_1I = B_1(AB_2) = (B_1A)B_2 = IB_2 = B_2$$

Note. Since inverses are unique, we denote the inverse of A by  $A^{-1}\,.$ 

Q. How do we find  $A^{-1}$ ?

ANSWER.

- 1. Form the augmented matrix:  $[A \mid I]$ .
- 2. Use elementary row operations to reduce A into rref:  $[A \mid I] \leadsto [\operatorname{rref}(A) \mid B]$ .
- 3. If  $\operatorname{rref}(A) = I$ , then  $B = A^{-1}$ . Otherwise, A is not invertible.

Ex. Find the inverse of 
$$A=\left[\begin{array}{cccc} 2&1&3\\ 2&1&1\\ 4&5&1 \end{array}\right]$$
 .

Sol. Row reduce

$$\begin{bmatrix} 2 & 1 & 3 & 1 & 0 & 0 \\ 2 & 1 & 1 & 0 & 1 & 0 \\ 4 & 5 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\frac{1}{2} \cdot R_1 \to R_1} \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \frac{1}{2} & 0 & 0 \\ 2 & 1 & 1 & 0 & 1 & 0 \\ 4 & 5 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{R_2 - 2 \cdot R_1 \to R_2} \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \frac{1}{2} & 0 & 0 \\ 0 & 0 & -2 & -1 & 1 & 0 \\ 4 & 5 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{R_3 - 4 \cdot R_1 \to R_3} \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \frac{1}{2} & 0 & 0 \\ 0 & 0 & -2 & -1 & 1 & 0 \\ 0 & 3 & -5 & -2 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{R_2 \leftrightarrow R_3} \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \frac{1}{2} & 0 & 0 \\ 0 & 3 & -5 & -2 & 0 & 1 \\ 0 & 0 & -2 & -1 & 1 & 0 \end{bmatrix}$$

$$\xrightarrow{\frac{1}{3} \cdot R_2 \to R_2} \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \frac{1}{2} & 0 & 0 \\ 0 & 1 & -\frac{5}{3} & -\frac{2}{3} & 0 & \frac{1}{3} \\ 0 & 0 & -2 & -1 & 1 & 0 \end{bmatrix}$$

$$\xrightarrow{R_1 - \frac{1}{2} \cdot R_2 \to R_1} \begin{bmatrix} 1 & 0 & \frac{7}{3} & \frac{5}{6} & 0 & -\frac{1}{6} \\ 0 & 1 & -\frac{5}{3} & -\frac{2}{3} & 0 & \frac{1}{3} \\ 0 & 0 & -2 & -1 & 1 & 0 \end{bmatrix}$$

$$\frac{-\frac{1}{2} \cdot R_3 \to R_3}{\longrightarrow} \begin{bmatrix}
1 & 0 & \frac{7}{3} & \frac{5}{6} & 0 & -\frac{1}{6} \\
0 & 1 & -\frac{5}{3} & -\frac{2}{3} & 0 & \frac{1}{3} \\
0 & 0 & 1 & \frac{1}{2} & -\frac{1}{2} & 0
\end{bmatrix}$$

$$\frac{R_1 - \frac{7}{3} \cdot R_3 \to R_1}{\longrightarrow} \begin{bmatrix}
1 & 0 & 0 & -\frac{1}{3} & \frac{7}{6} & -\frac{1}{6} \\
0 & 1 & -\frac{5}{3} & -\frac{2}{3} & 0 & \frac{1}{3} \\
0 & 0 & 1 & \frac{1}{2} & -\frac{1}{2} & 0
\end{bmatrix}$$

$$\frac{R_2 + \frac{5}{3} \cdot R_3 \to R_2}{\longrightarrow} \begin{bmatrix}
1 & 0 & 0 & -\frac{1}{3} & \frac{7}{6} & -\frac{1}{6} \\
0 & 1 & 0 & \frac{1}{6} & -\frac{5}{6} & \frac{1}{3} \\
0 & 0 & 1 & \frac{1}{2} & -\frac{1}{2} & 0
\end{bmatrix}$$

This gives 
$$A^{-1}=\left[\begin{array}{cccc} -\frac{1}{3} & \frac{7}{6} & -\frac{1}{6} \\ & \frac{1}{6} & -\frac{5}{6} & \frac{1}{3} \\ & \frac{1}{2} & -\frac{1}{2} & 0 \end{array}\right]$$
 .

DEF. A  $\underline{n \times n}$  elementary matrix is a matrix obtained by performing exactly one elementary row operation on  $I_n$ .

Ex.

$$\begin{bmatrix}
1 & 0 \\
0 & 1
\end{bmatrix}
\xrightarrow{3 \cdot R_2 \to R_2}
\begin{bmatrix}
1 & 0 \\
0 & 3
\end{bmatrix}$$

$$\begin{bmatrix}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{bmatrix}
\xrightarrow{R_2 - 1/2 \cdot R_1 \to R_2}
\begin{bmatrix}
1 & 0 & 0 \\
-\frac{1}{2} & 1 & 0 \\
0 & 0 & 1
\end{bmatrix}$$

$$\begin{bmatrix}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
0 & 0 & 1 & 0
\end{bmatrix}
\xrightarrow{R_3 \leftrightarrow R_4}
\begin{bmatrix}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 0 & 1 \\
0 & 0 & 1 & 0
\end{bmatrix}$$

IDEA. Multiplication by elementary matrices on the left results in performing the corresponding elementary row operation.

Ex. Performing 
$$3\cdot R_2 \to R_2$$
 on  $A=\left[\begin{array}{c} 1 & 7 \\ 0 & \frac{1}{3} \end{array}\right]$  gives

$$\begin{bmatrix} 1 & 7 \\ 0 & \frac{1}{3} \end{bmatrix} \xrightarrow{3 \cdot R_2 \to R_2} \begin{bmatrix} 1 & 7 \\ 0 & 1 \end{bmatrix}$$

The row-operation  $3\cdot R_2\to R_2$  corresponds to the elementary matrix  $E=\begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}$  . Computing EA gives

$$EA = \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 7 \\ 0 & \frac{1}{3} \end{bmatrix} = \begin{bmatrix} 1 & 7 \\ 0 & 1 \end{bmatrix}$$

THM. Elementary matrices are invertible and their inverses are

$$[R_i \leftrightarrow R_j]^{-1} = [R_i \leftrightarrow R_j]$$
$$[\lambda \cdot R_i \to R_i]^{-1} = [1/\lambda \cdot R_i \to R_i]$$
$$[R_i + \lambda \cdot R_j \to R_i]^{-1} = [R_i - \lambda \cdot R_j \to R_i]$$

Ex. Write  $A^{-1}$  as a product of elementary matrices where  $A=\left[\begin{array}{c}1&2\\3&5\end{array}\right]$  .

Sol. Row reduce

$$\begin{bmatrix} 1 & 2 & 1 & 0 \\ 3 & 5 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 - 3 \cdot R_1 \to R_2} \begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & -1 & -3 & 1 \end{bmatrix}$$

$$\xrightarrow{-1 \cdot R_2 \to R_2} \begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & 1 & 3 & -1 \end{bmatrix}$$

$$\xrightarrow{R_1 - 2 \cdot R_2 \to R_1} \begin{bmatrix} 1 & 0 & -5 & 2 \\ 0 & 1 & 3 & -1 \end{bmatrix}$$

This gives 
$$A^{-1}=\left[\begin{array}{cc} -5 & 2 \\ 3 & -1 \end{array}\right]$$
 .

These row reductions correspond to elementary matrices

$$E_{1} = [R_{2} - 3 \cdot R_{1} \to R_{2}] = \begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix}$$

$$E_{2} = [-R_{2} \to R_{2}] = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$E_{3} = [R_{1} - 2 \cdot R_{2} \to R_{1}] = \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix}$$

This gives  $\underbrace{E_3E_2E_1}_{-A^{-1}}A=\operatorname{rref}(A)=I$  .

THM. Given  $A, B \in \mathrm{GL}_n(\mathbb{R})$ , let  $\lambda \in \mathbb{R}$  such that  $\lambda \neq 0$ . Then

1. 
$$A^{-1} \in GL_n(\mathbb{R})$$
 and  $(A^{-1})^{-1} = A$ 

2. 
$$\lambda \cdot A \in \mathrm{GL}_n(\mathbb{R})$$
 and  $(\lambda A)^{-1} = 1/\lambda \cdot A^{-1}$ 

3. 
$$AB \in \operatorname{GL}_n(\mathbb{R})$$
 and  $(AB)^{-1} = B^{-1}A^{-1}$ 

4. 
$$A^k \in \mathrm{GL}_n(\mathbb{R})$$
 and  $(A^k)^{-1} = (A^{-1})^k$ 

THM (Fundamental Theorem of Invertible Matrices). Let  $A \in M_{n \times n}(\mathbb{R})$ . Then the following are equivalent.

- 1. A is invertible
- 2. A is nonsingular
- $\beta$ .  $A \in \mathrm{GL}_n(\mathbb{R})$
- 4.  $A \vec{x} = \vec{b}$  has a unique solution for every  $\vec{b} \in \mathbb{R}^n$
- 5.  $A \vec{x} = \vec{0}$  has only the trivial solution  $\vec{x} = \vec{0}$
- 6.  $rref(A) = I_n$
- 7.  $\operatorname{rank}(A) = n$
- 8. A is a product of elementary matrices

THM. Let  $A,B\in M_{n imes n}(\mathbb{R})$  such that  $AB=I_n$  or  $BA=I_n$ . Then  $B=A^{-1}$ .

*Proof.* Suppose  $BA=I_n$  and consider the system  $A\vec{x}=\vec{0}$  . Then

$$\vec{0} = B\vec{0} = B(A\vec{x}) = (BA)\vec{x} = I_n\vec{x} = \vec{x}$$

So, the system  $A\vec{x}=\vec{0}$  only has the trivial solution. By the fundamental theorem,  $A\in \mathrm{GL}_n(\mathbb{R})$  and

$$B = BI_n = B(AA^{-1}) = (BA)A^{-1} = I_nA^{-1} = A^{-1}$$

The argument when  $AB = I_n$  is similar.

## REFERENCES

[1] G.L. Peterson and J.S. Sochacki. <u>Linear Algebra and Differential</u>
<u>Equations</u>. Addison-Wesley, 2002.