

# ToyScan2

This *Mathematica* notebook plots the Markov chains obtained by running ToyScan2. As defined in main.cpp, this scan uses 10 chains and 100k steps to seek out a radius of 3 around the center point (2, 1) with a Gaussian likelihood profile, with uncertainty in the radius 0.3.

## Import and parse the chains

```
In[1]:= SetDirectory[NotebookDirectory[]];  
  
Chains = {};  
Module[{i, FileData},  
  For[i = 1, i <= 10, i++,  
    FileData = Import["chains/ToyScan2_chain" <> ToString[i] <> ".dat"];  
    AppendTo[Chains, Split[FileData, # != {} &]]  
  ]  
]  
  
In[4]:= Chains[[1, 1 ;; 10]] // MatrixForm  
  
Out[4]/MatrixForm=
```

$$\begin{pmatrix} \{1.21776, -5.1825\} & \{6.23179, 1.69665\} & \{6.31125 \times 10^{-26}\} & \{\} \\ \{7.04425, 5.2149\} & \{6.57341, 0.696066\} & \{1.55217 \times 10^{-31}\} & \{\} \\ \{2.51169, 5.38781\} & \{4.41754, 1.4547\} & \{0.0000141824\} & \{\} \\ \{-2.66476, 0.449229\} & \{4.69716, 3.02407\} & \{1.12312 \times 10^{-7}\} & \{\} \\ \{-2.66476, 0.449229\} & \{4.69716, 3.02407\} & \{1.12312 \times 10^{-7}\} & \{\} \\ \{2.81658, 6.12512\} & \{5.18976, 1.4128\} & \{2.69597 \times 10^{-12}\} & \{\} \\ \{5.87087, 3.13357\} & \{4.41992, 0.503753\} & \{0.0000136601\} & \{\} \\ \{5.87087, 3.13357\} & \{4.41992, 0.503753\} & \{0.0000136601\} & \{\} \\ \{5.89859, -1.19311\} & \{4.47312, 0.512419\} & \{5.80975 \times 10^{-6}\} & \{\} \\ \{4.92844, -2.3906\} & \{4.48017, 0.858406\} & \{5.17523 \times 10^{-6}\} & \{\} \end{pmatrix}$$

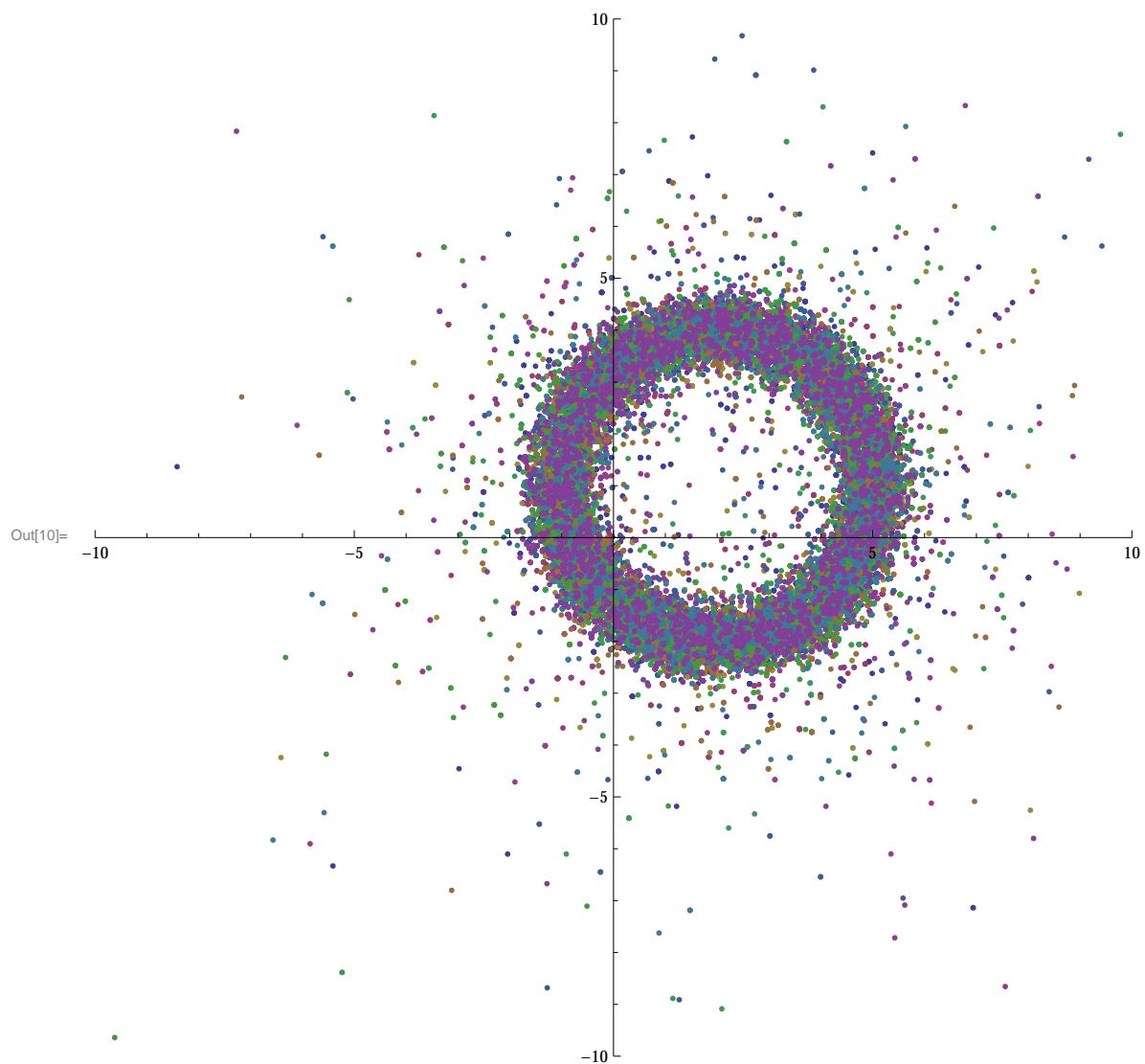
## Setting up accessor functions

```
In[5]:= ChainLength[iChain_] := Length[Chains[[iChain]]];  
  
Parameters[iChain_, iPoint_] := Chains[[iChain, iPoint, 1]];  
r[iChain_, iPoint_] := Chains[[iChain, iPoint, 2, 1]];  
θ[iChain_, iPoint_] := Chains[[iChain, iPoint, 2, 2]];  
NegativeLogLikelihood[iChain_, iPoint_] :=  
  -Log[10, Chains[[iChain, iPoint, 3, 1]]];
```

## Plotting the chains

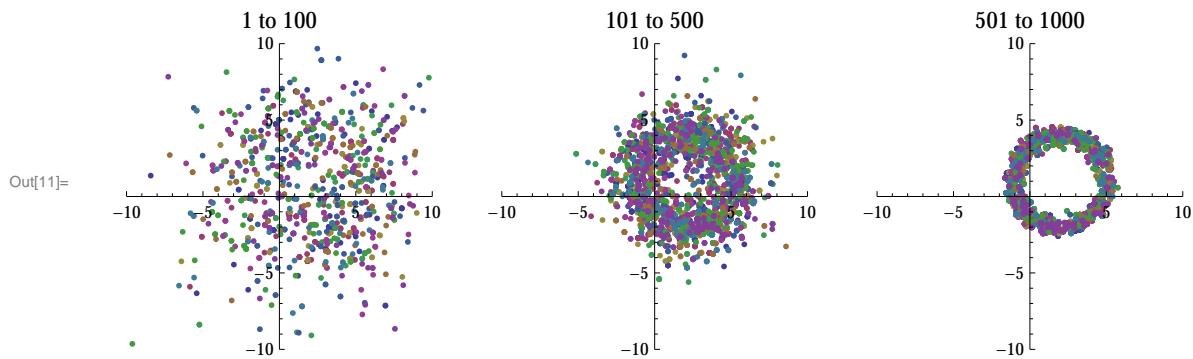
Here I plot the full chains, from beginning to end, without burning the initial fraction. The different colors correspond to different chains.

```
In[10]:= ListPlot[Parameters[All, All],  
 PlotRange -> {{-10, 10}, {-10, 10}}, AspectRatio -> 1, ImageSize -> Large]
```



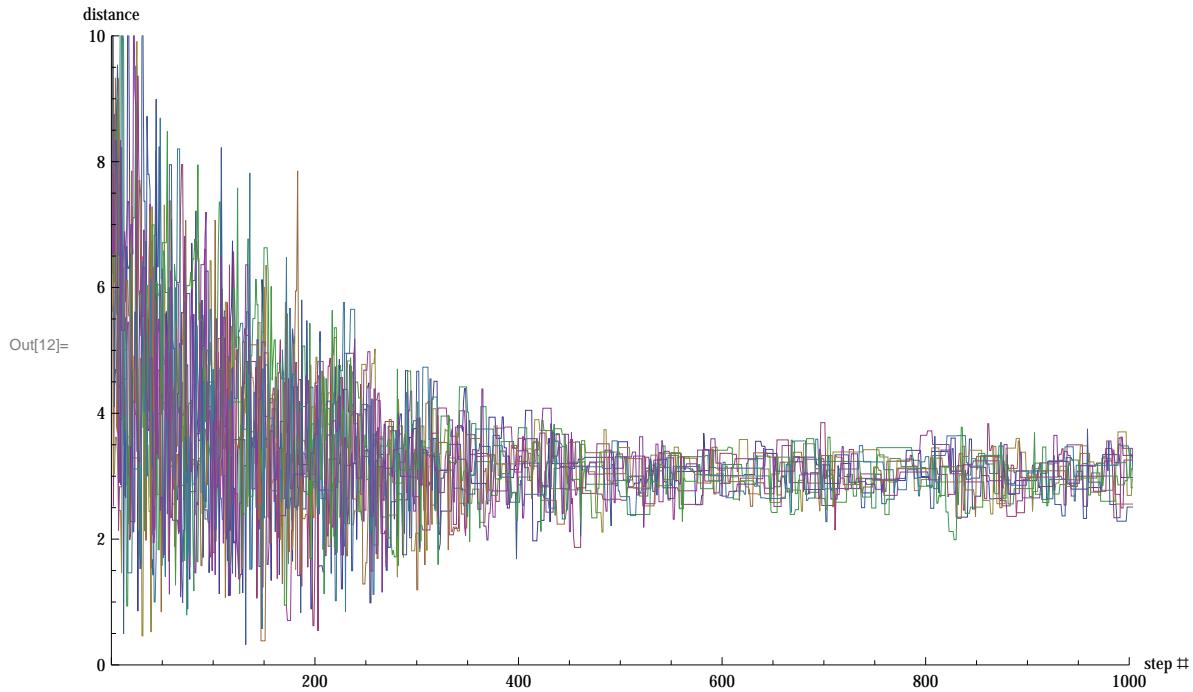
Here is what the different sections of the chains look like, as they progress toward the posterior probability distribution.

```
In[11]:= GraphicsRow[{
  ListPlot[Parameters[All, 1 ;; 100], PlotRange -> {{-10, 10}, {-10, 10}},
    PlotLabel -> "1 to 100", AspectRatio -> 1, ImageSize -> Small],
  ListPlot[Parameters[All, 101 ;; 500], PlotRange -> {{-10, 10}, {-10, 10}},
    PlotLabel -> "101 to 500", AspectRatio -> 1, ImageSize -> Small],
  ListPlot[Parameters[All, 501 ;; 1000], PlotRange -> {{-10, 10}, {-10, 10}},
    PlotLabel -> "501 to 1000", AspectRatio -> 1, ImageSize -> Small]
}]
```



## Plotting distance from the center point

```
In[12]:= ListPlot[r[All, All], Joined -> True, PlotRange -> {{0, 1000}, {0, 10}},
  AxesLabel -> {"step #", "distance"}, ImageSize -> Large]
```



## Plotting likelihood

This plots the negative log-likelihood of the points in the chains. It shows how many orders of magni-

tude below likelihood == 1.0 (which indicates perfect agreement with the constraint) the likelihood is at. As the chains' likelihood increases, the negative log-likelihood approaches zero.

```
In[13]:= ListPlot[NegativeLogLikelihood[All, All],  
 Joined → True, PlotRange → {{0, 1000}, {0, 100}},  
 AxesLabel → {"step #", "-log10L"}, ImageSize → Large]
```

