



Berkeley Architecture Research

Activity-based Power Modeling for Arbitrary RTL with Automatic Signal Selection

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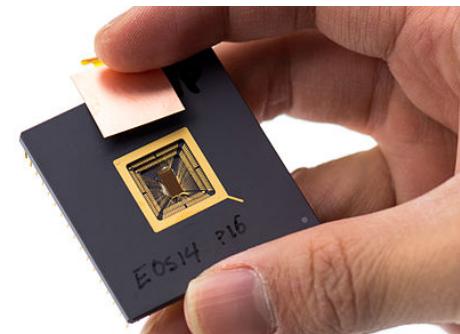


Simple Analytic Power Model

$$\begin{aligned} P_{total} &= P_{dyn} + P_{leak} \\ &= \alpha C_L V_{DD}^2 + I_{leak} V_{DD} \end{aligned}$$

CAD tools can statically figure out

Activity factor for random design?





In Fact, Dynamic Power Is

$$P_{dyn} = \frac{1}{2} V_{DD}^2 \left(\sum_{i \in \text{all signals}} C_i D_i \right) [1]$$

C_i : capacitance signal i drives

D_i : toggles per cycle of signal i

We hope

$$\approx \frac{1}{2} V_{DD}^2 \left(\sum_{k \in \text{some signals}} C_k D_k \right)$$

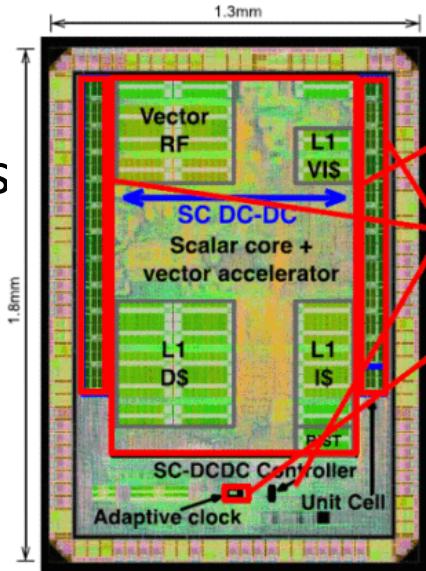
[1] Najm. "A Survey of Power Estimation Techniques in VLSI Circuits, IEEE Trans on VLSI, 1994



What Are *Some Signals*?

- Architects' Approach
 - Intuitively select signals / events

$$\frac{1}{2} V_{DD}^2 \left(\sum_{k \in \text{some signals}} C_k D_k \right)$$



- How to get C_k ?
 - Existing hardware: regression with event counters [1]
 - RTL designs: regression with signals activities [2]
 - Pre-RTL: analytic modeling [3]

[1] Isci et al. "Runtime power monitoring in high-end processors: methodology and empirical data", MICRO 2003

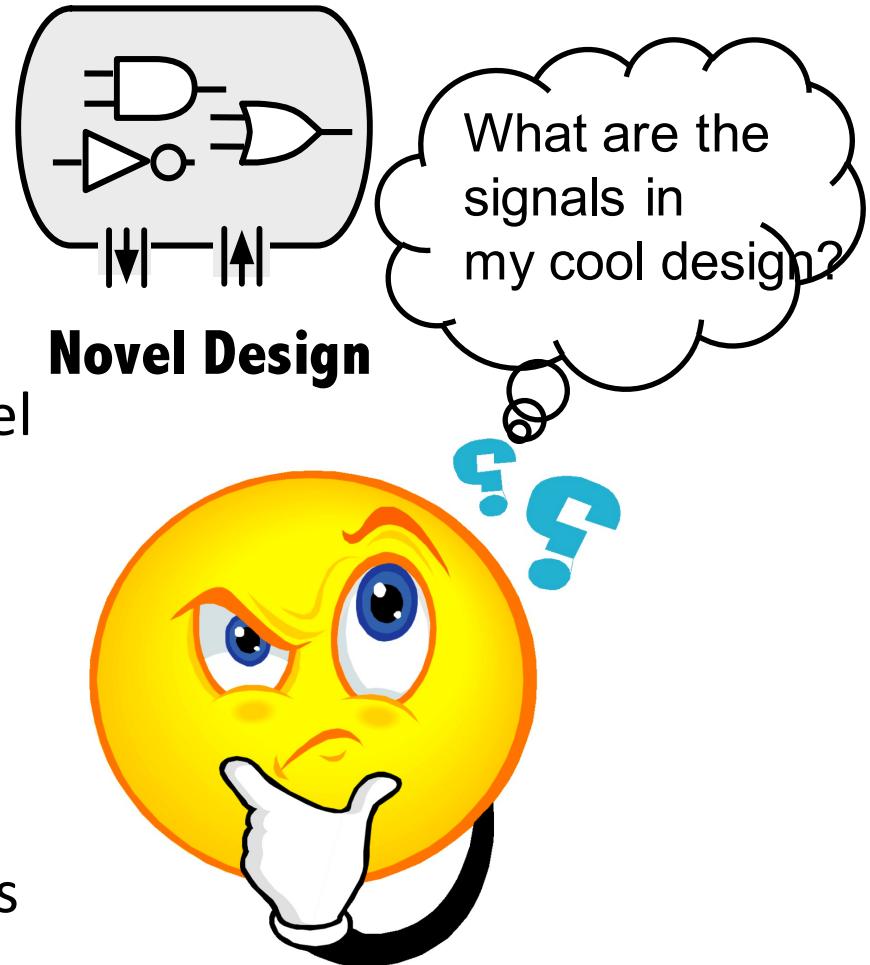
[2] Sumwoo et al. "PrEsto: An FPGA-accelerated Power Estimation Methodology for Complex Systems", FPGA 2010

[3] Li et al. "McPAT: An integrated power, area, and timing modeling framework for multicore and manycore architectures", MICRO 2009



What About Your Novel Designs?

- Signal selection is not easy
 - Processors: $\sim O(100)$ papers
- Collecting all signal activities are extremely expensive
 - Can we boot linux on gate-level simulation?
- Even existing macro models are expensive [1] [2]
 - Can we run SPEC benchmarks on RTL software simulation?
 - There are still too many signals to watch on FPGA



[1] Gupta et al. "Power modeling for high-level power estimation", IEEE Trans on VLSI, 2000

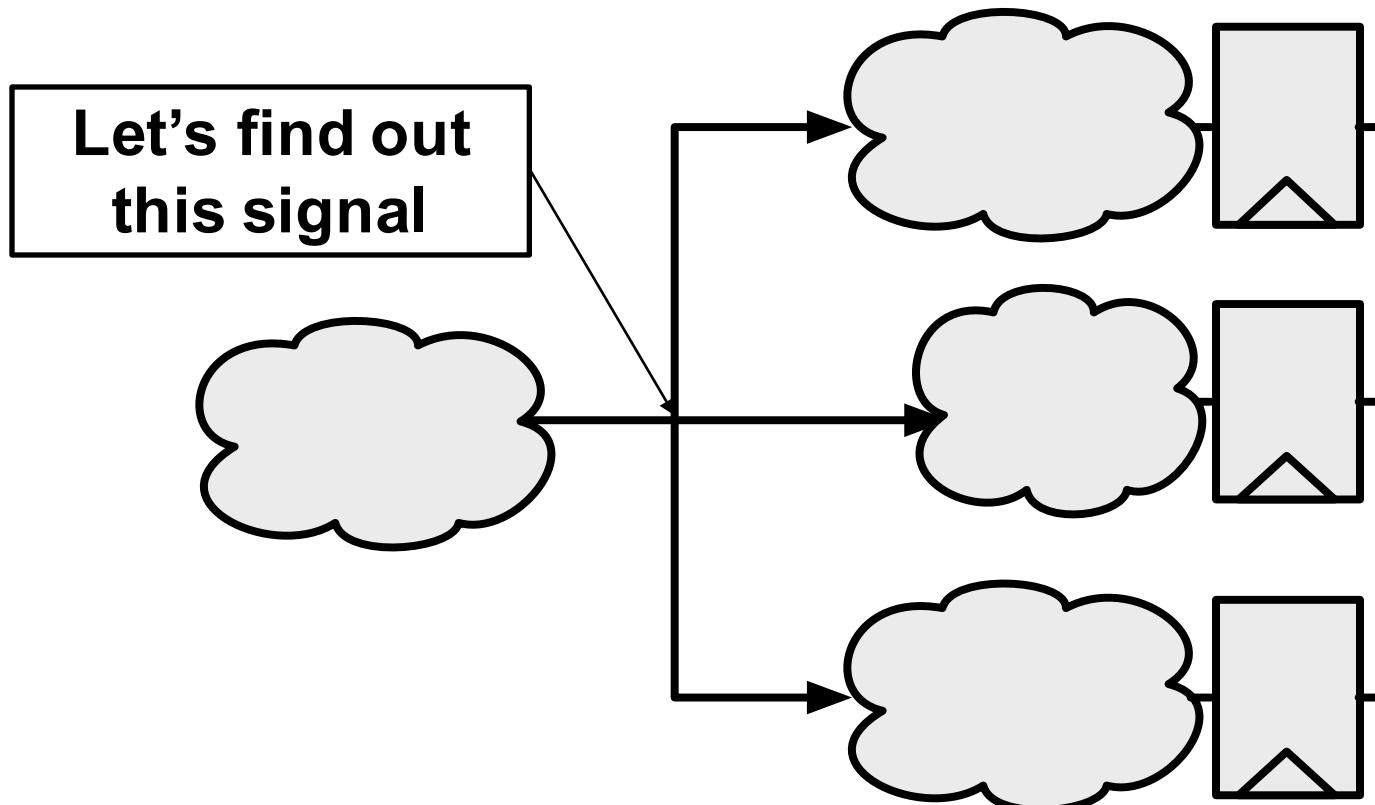
[2] Bogliolo et al. "Regression-based RTL power modeling", ACM Trans on Design Automation of Electronic Systems, 2000



What Signals for Power Modeling?

- Observation

- ***State*** determines the signal activities of the whole system.
 - ***A small number of control signals and data busses*** mainly determine the next state of the system.



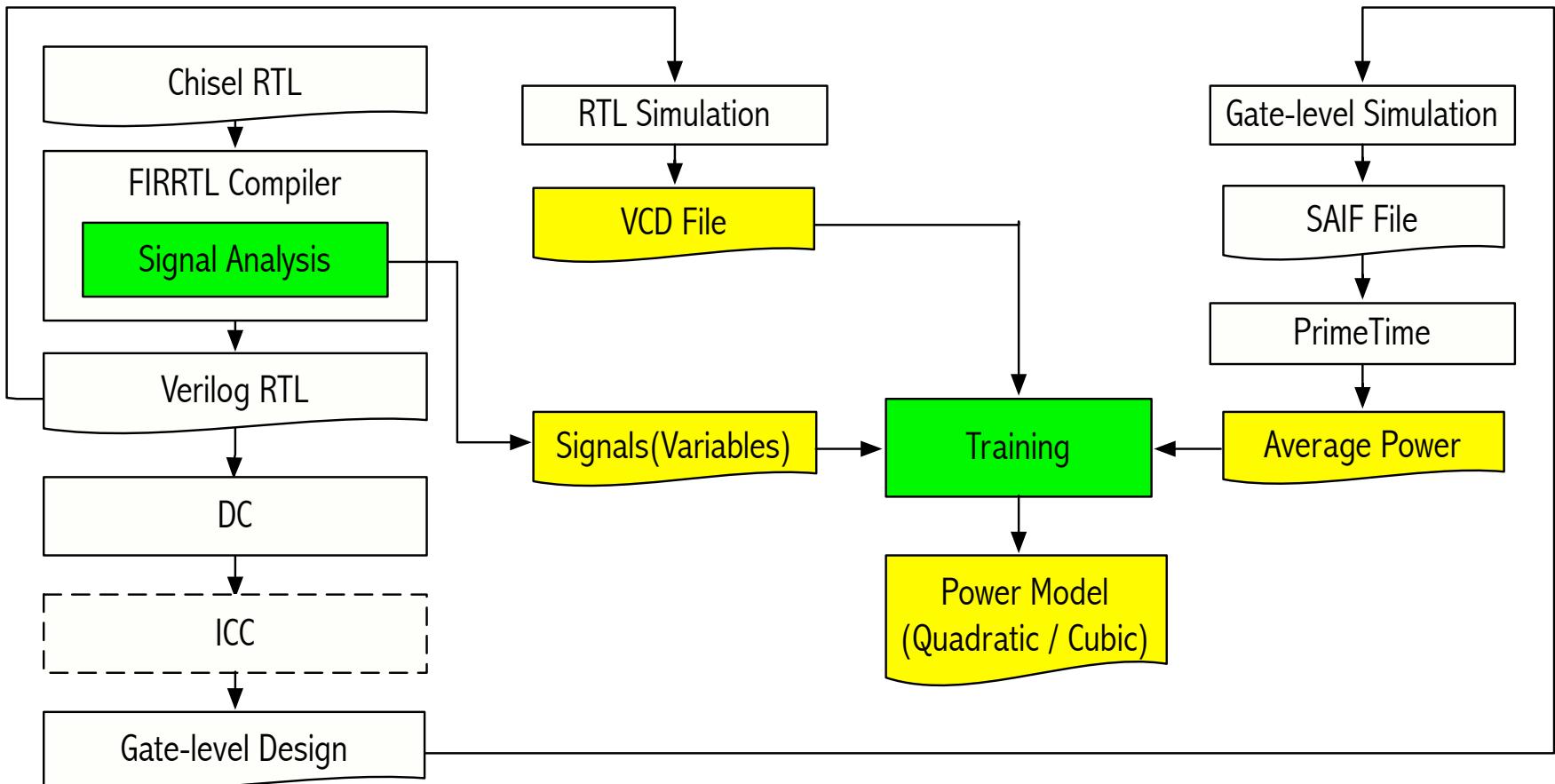


Example: GCD

```
class GCD extends Module {
    val io = IO(new GCDIO)
    val x  = Reg(UInt())
    val y  = Reg(UInt())
    when (x > y) { x := x - y }
    unless (x > y) { y := y - x }
    when (io.e) { x := io.a; y := io.b }
    io.z := x
    io.v := y === 0.U
}
```



Power Training Tool Flow





Results



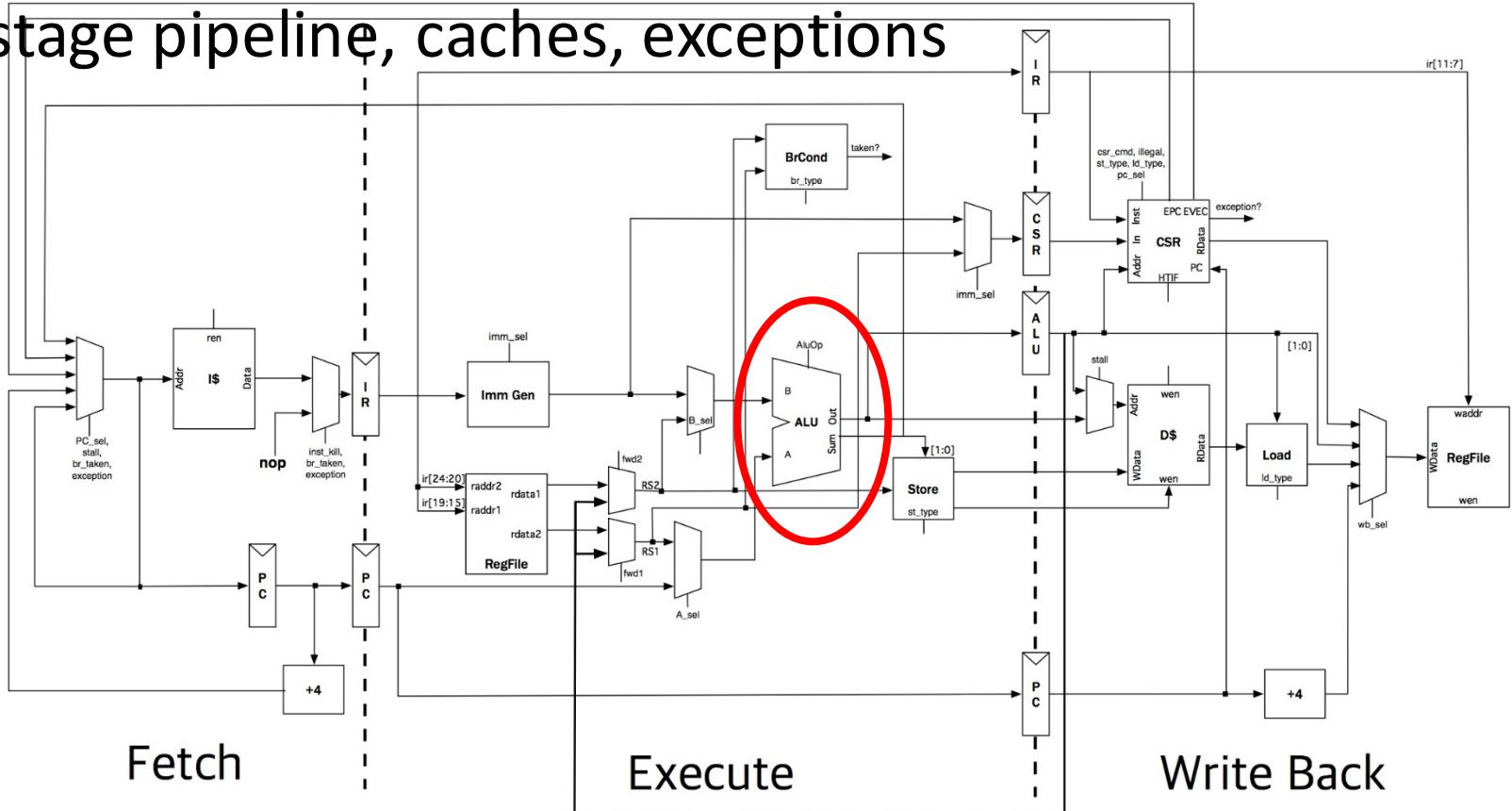
- 20 sets for training, 20 sets for tests
- GCD, Parity: quadratic models
- Stack, Risc, RiscSRAM: qubic models

Design	GCD	Parity	Stack	Risc	RiscSRAM
Number of Selected Signals and Busses	7	3	8	11	15
Normalized RMS error (%)	29.3	1.9	31.9	4	10
Average error (%)	5.1	0.9	26.9	2.3	6.5
Maximum error (%)	16.5	2.4	153.7	7.4	20.5



How Many Signals for RISCV-mini?

- 3-stage pipeline, caches, exceptions



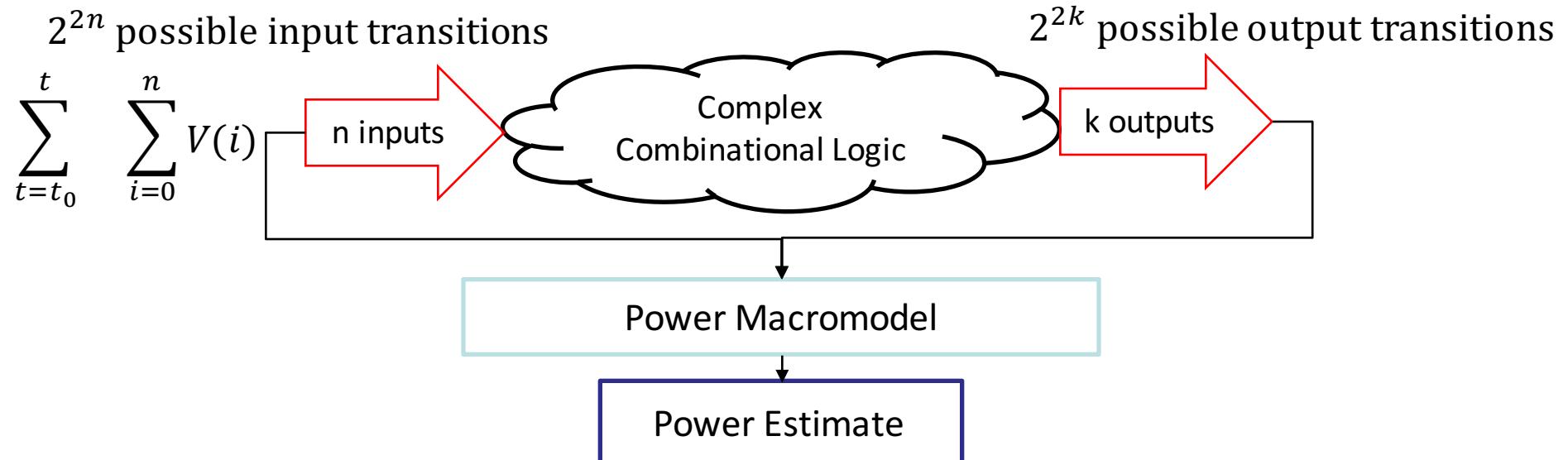
- 108 signals / busses
- 50% duplicates



Power Modeling for Complex Combinational Logic Blocks



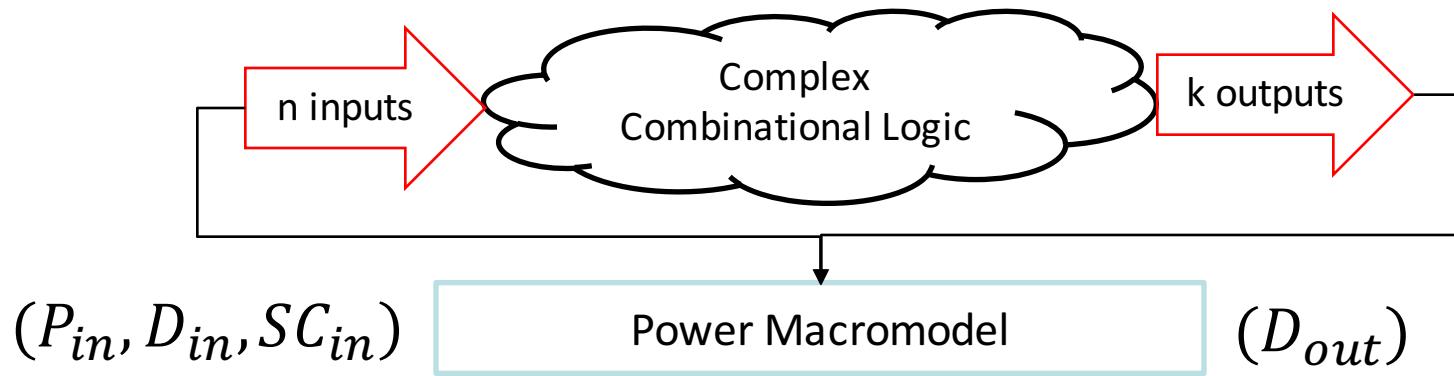
Power Macromodels for Complex Combinational Logic



- Linear power models require full instrumentation
- Macromodels reduce and average circuit stimulus
- More accurate for complex logic (ALU, SEC/DED), faster for real-time online power estimation



Macromodel Variables



- 4 variable macromodel proposed [1]

P_{in} = average input signal probability

D_{in} = average input transition density

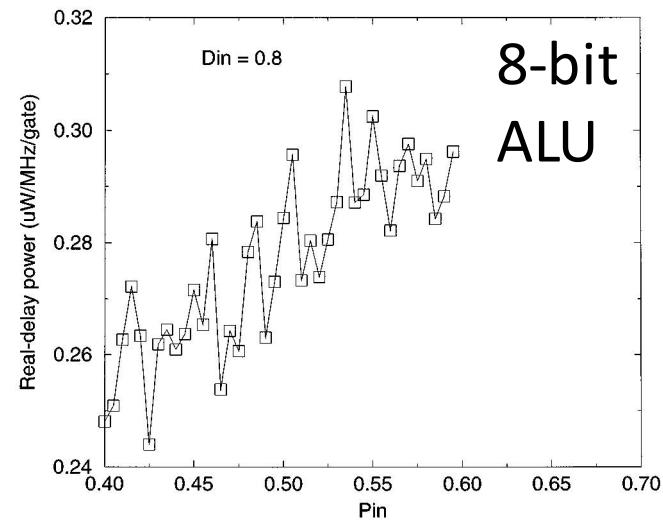
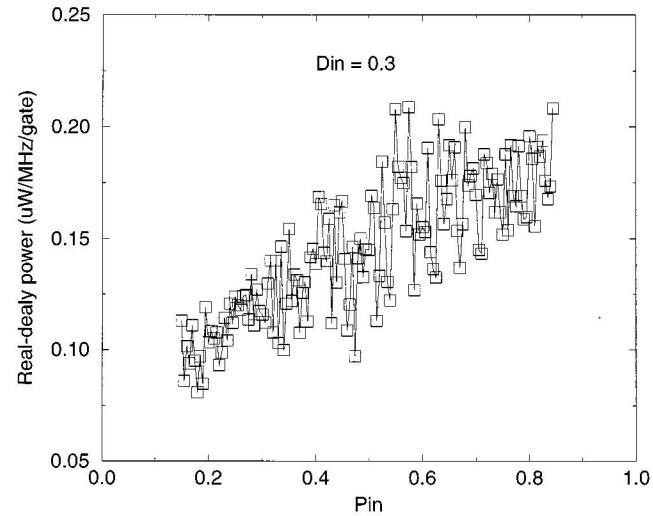
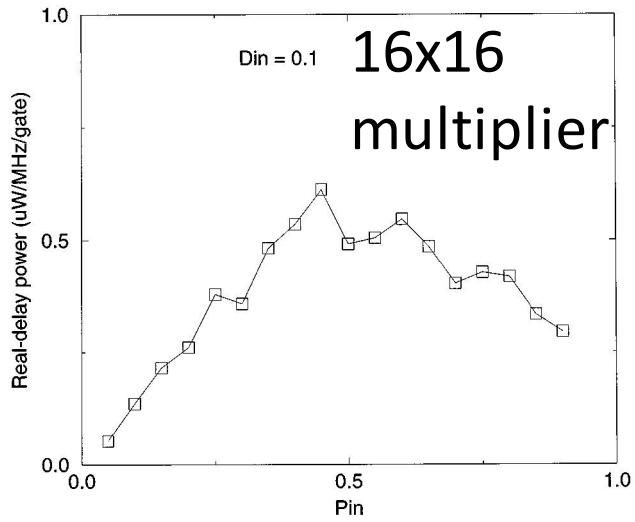
SC_{in} = average input spatial correlation coefficient

D_{out} = average output transition density

- Provides sufficient predictive power for estimation
- Easy to implement for FPGA sample capture

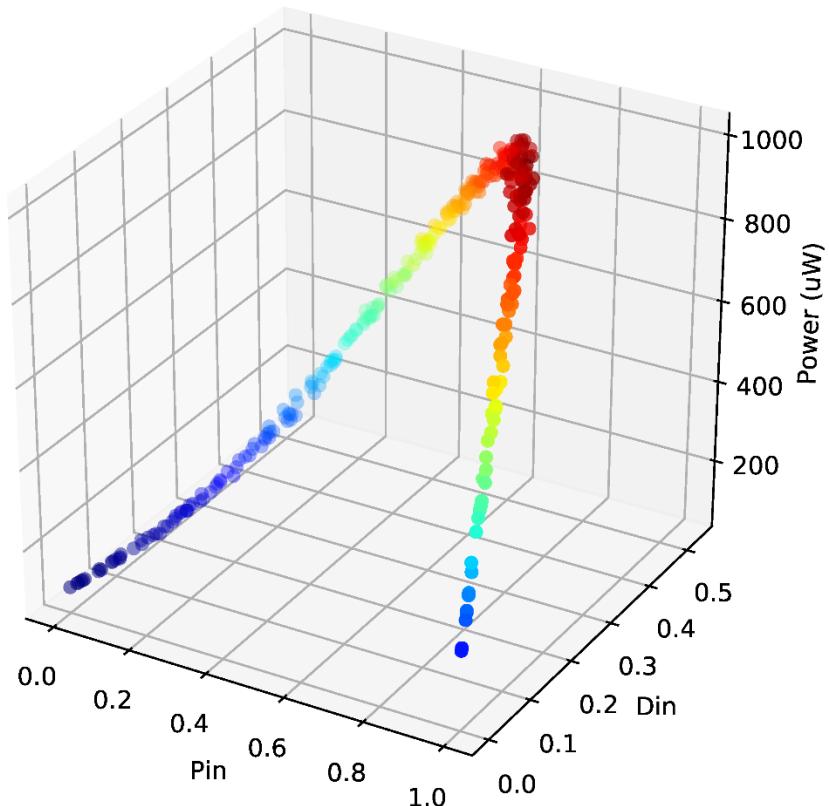


How Variables Track Power

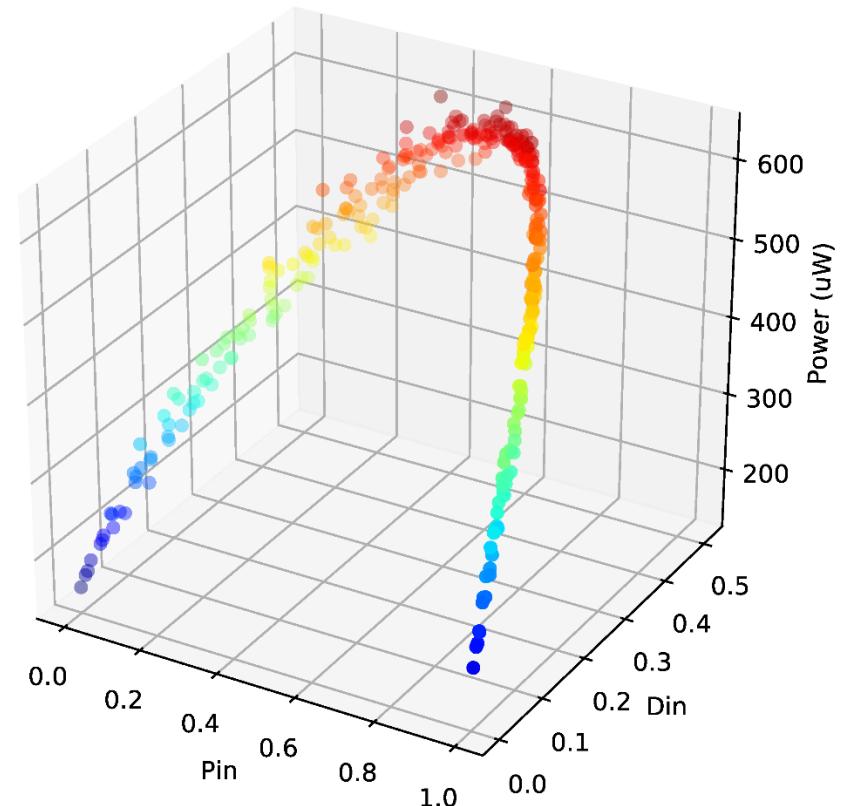




How Variables Track Power Our Experimental Observations



c6288: 16x16 multiplier



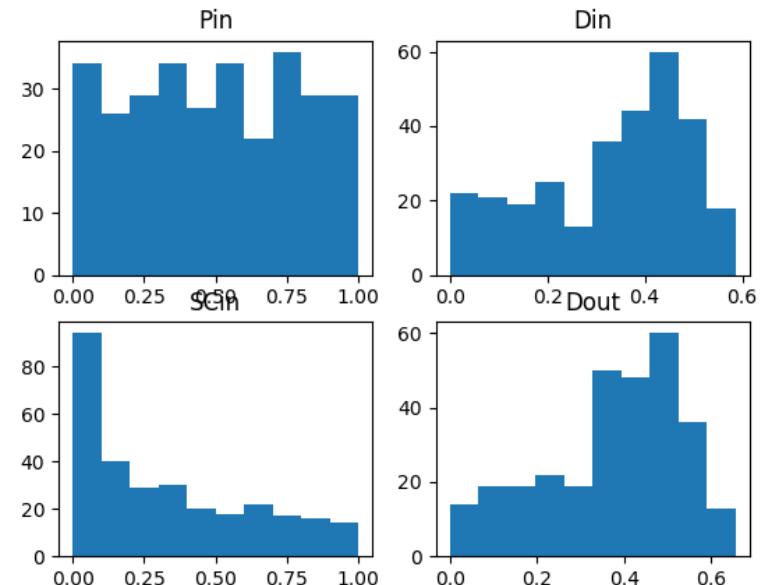
c7552: 32-bit adder



Methodology



- Check feasibility and accuracy of macromodel with our process & glitching power
- Generate training and test sequences
 - Build power model from training set
 - Interpolate/prediction testing set and find error
- Use PrimeTime PX for gate-level power estimate

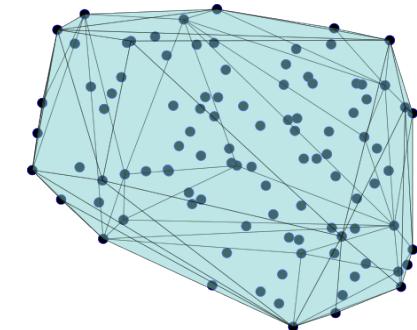




Types of Models

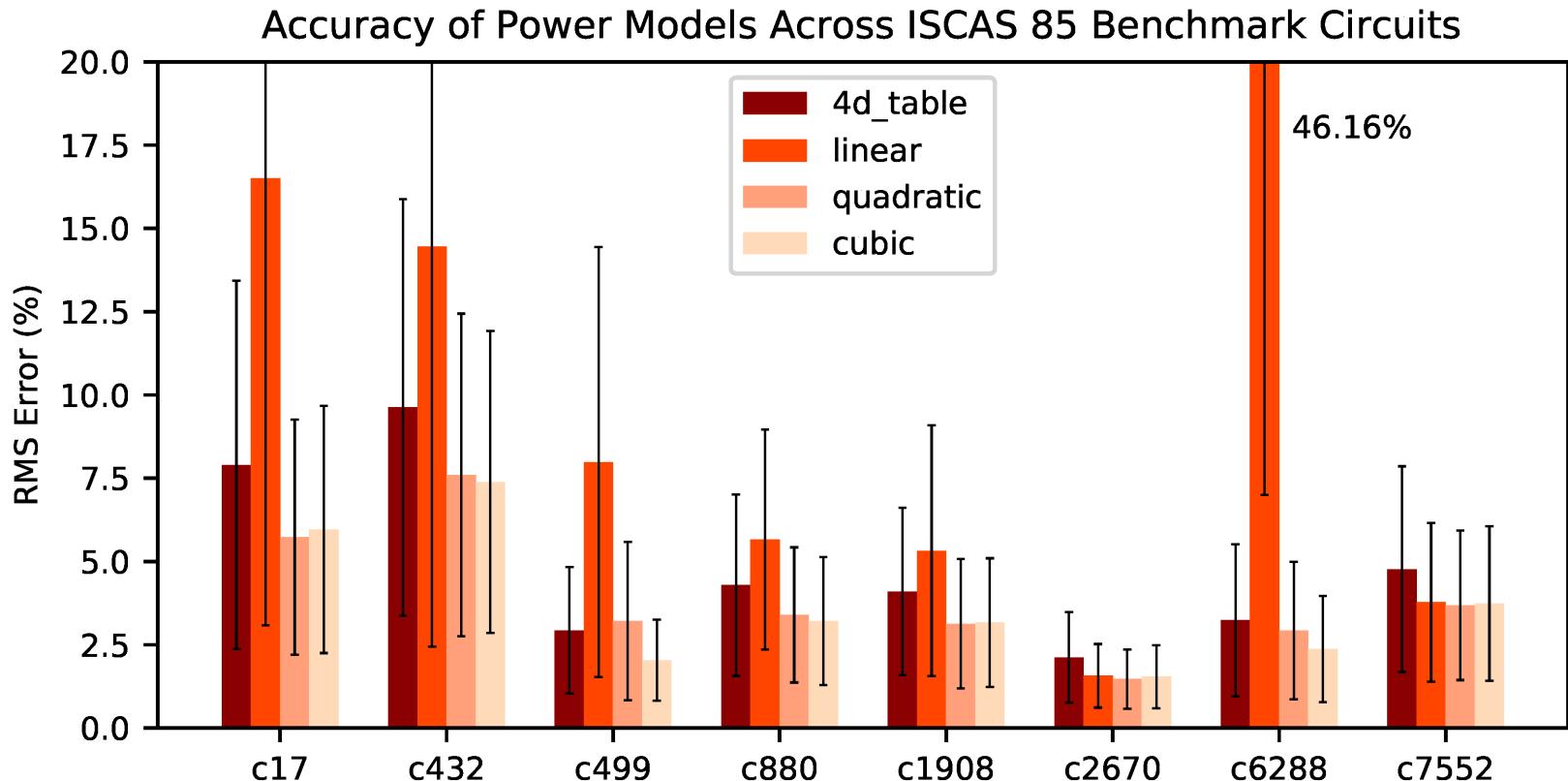


- 4D Table: a map of (Pin, Din, SCin, Dout) tuples to a power estimate
- How do we extrapolate beyond the convex hull? Are sharp discontinuities an issue?
- Continuous linear models (linear, quadratic, cubic terms)
 - constant/linear/cross/triple-cross/self-squared/etc... coefficients
 - easy to construct (least squared) and predict (matrix multiply)





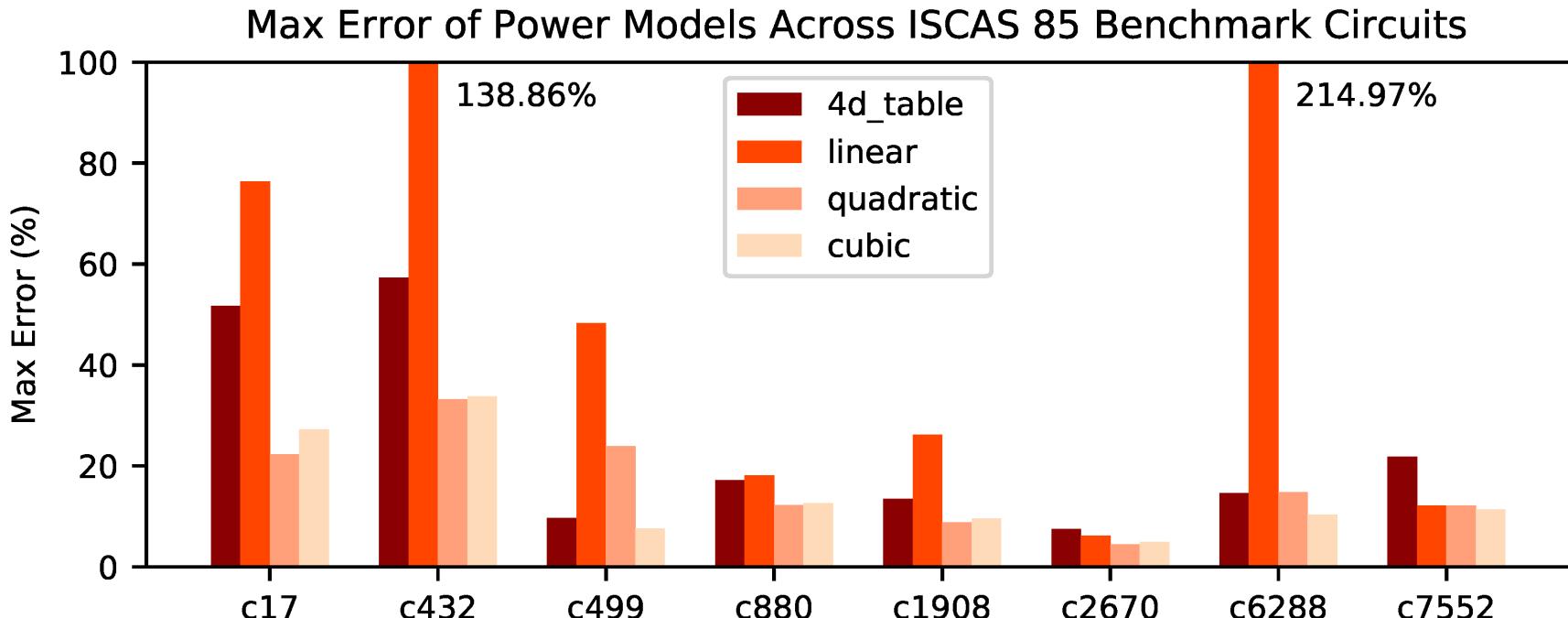
Results



- Why does the cubic model perform better than the 4D table?



Results



- How can we reduce max error? Is the distribution of error more important than max error?



Future Work

- Realistic Target Designs
 - Rocket-chip, Hwacha, BOOM
- Train & Test Inputs
 - Assembly tests / μ benchmarks
 - Random instruction streams
 - Real applications through Strober[1]
- FPGA Simulation
 - Automatic activity counter instrumentation

[1] Kim et al. “Strober : Fast and Accurate Sample-Based Energy Simulation for Arbitrary RTL”, ISCA 2016



Q & A

