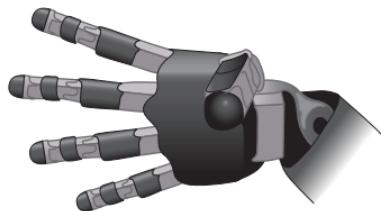
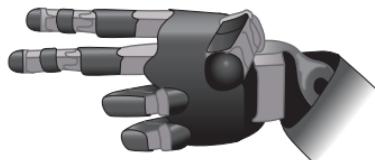


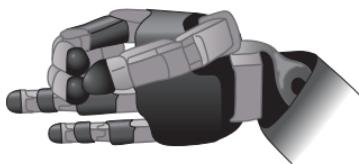
### A 机器人手配置



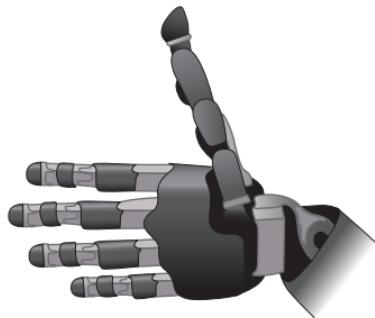
手指伸展



掘

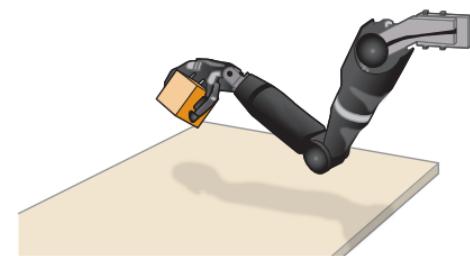
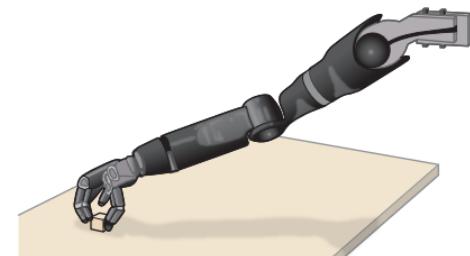


捏



手指发散

### B 使用机械手抓取目标



### C 机械手抓取的样本目标

