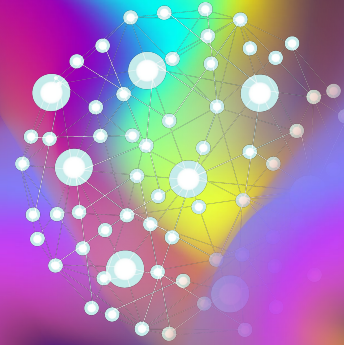


Simulating How the Human Body Responds to **Haptic Feedback**

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01 Current issues



Disconnected Simulations

Disconnection between physical and neurological simulations



Metaverse Experience

Need of more realistic and immersive interactions with entities within the Metaverse



Visual Haptic Rendering

Teleconferencing application that captures haptic information through synthetic visual data

02 Problem Statement

“

How can we prototype **haptic experiences** in a virtual environment to better inform the fabrication of physical devices?

”

03 Our Solution



Experiment Setup

Use **Finite Element Analysis** to combine afferent simulations with a physically realistic model of the hand



Data Collection

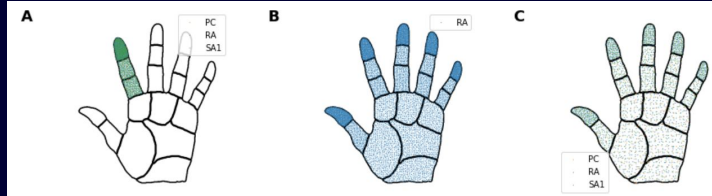
Sample a variety of different textures (eg. granite, marble, rubber)



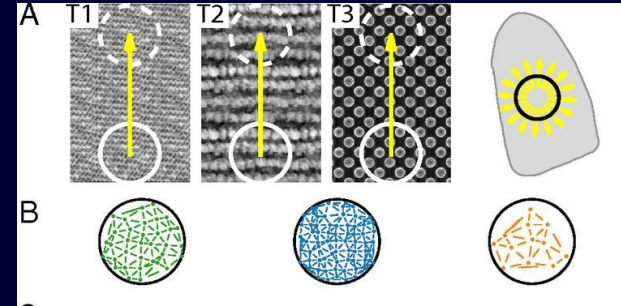
Validation

Run the simulation to obtain afferent responses, and use ML to validate their accuracy through % correct guesses

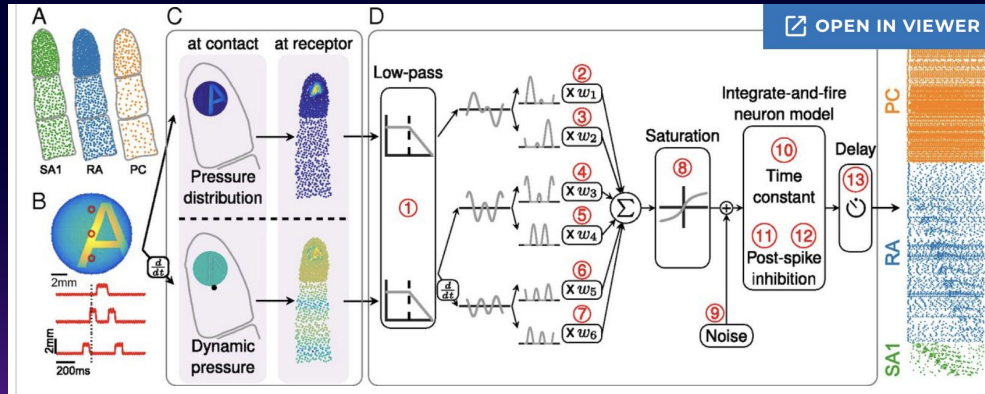
04 TouchSim Tool



▲ Figure 1: Localization and Density of Afferent Population on a Coordinate System



▲ Figure 3: Example of extracting motion direction from the responses of populations of afferents (validation purpose)



◀ Figure 2: Use of **integrate-and-fire (IF)** neuron model to create responses of individual afferents to the stimulus in different signal information (PC, SA1, RA), which can be used to perform validation tasks by ML models

- **PC**: pacinian corpuscles
- **SA1**: slow adapting type 1
- **RA**: rapidly adapting

Thanks for Listening!

Floor is open to questions

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