



Black-box Detection of Backdoor Attacks with Limited Information and Data



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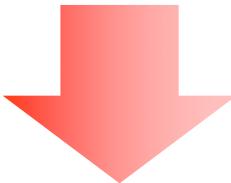
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Backdoor Attacks

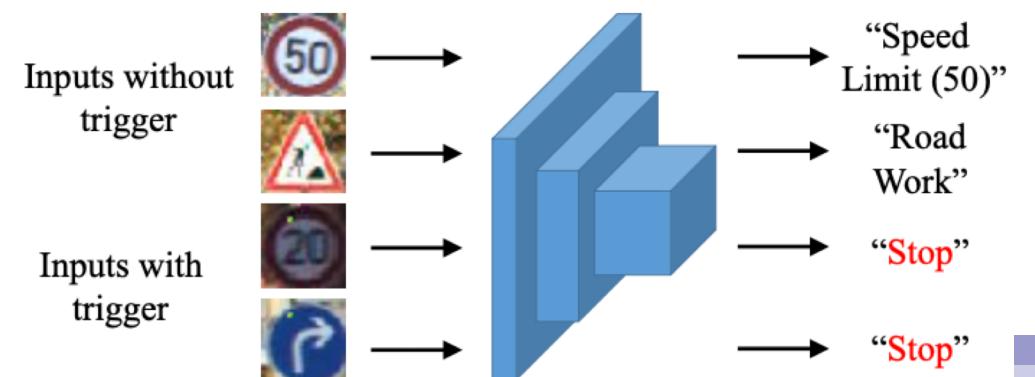
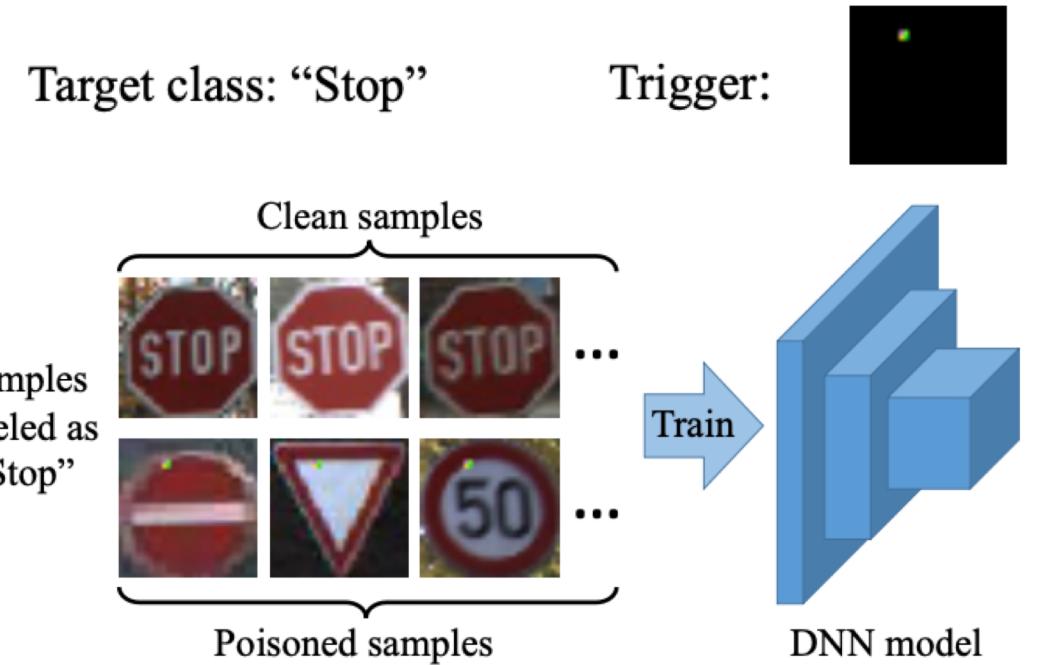
- Specify the target class and trigger



- Train the model on the poisoned dataset



- The model behaves normally on clean inputs but classifies the triggered inputs as the target class



Backdoor Defenses

Accessibility	Training-stage		Inference-stage			B3D (Ours)	B3D-SS (Ours)
	[6, 7, 43, 47]	[32, 35, 49]	[20, 22, 24, 36, 45]	[8, 10, 11]			
White-box model	✓	✓	✓	✓	✗	✗	✗
Poisoned training data	✓	✗	✗	✗	✗	✗	✗
Clean validation data	✗	✓	✓	✗	✓	✓	✗

- Existing backdoor defenses often rely on strong assumptions of data and model accessibility
 - **Training-stage** defenses require access to the *poisoned training data*
 - **Inference-stage** defenses require *the gradients of the white-box model*
- Black-box setting: only **query access to the black-box model** is available

Problem Formulation

- Backdoor attacks

$$x' = A(x, m, p) = (1 - m) * x + m * p$$

- $m \in \{0,1\}^d, p \in [0,1]^d$

- Reverse-engineer the trigger (Wang et al., 2019):

$$\min_{m,p} \sum_{x_i \in X} \left\{ \ell \left(c, f(A(x_i, m, p)) \right) + \lambda \cdot |m| \right\}$$

- ℓ is the cross-entropy loss
 - $|m|$ is the L_1 norm of the mask
 - λ is a hyper-parameter

- This problem can be solved by the Adam optimizer (**white-box access to model gradients**).

Black-box Optimization

- Let $\mathcal{F}(m, p; c) = \sum_{x_i \in X} \left\{ \ell \left(c, f(A(x_i, m, p)) \right) + \lambda \cdot |m| \right\}$;
- Natural Evolution Strategies (NES) (Wierstra et al., 2014)

$$\min_{\theta_m, \theta_p} \mathcal{J}(\theta_m, \theta_p) = \mathbb{E}_{\pi(m, p | \theta_m, \theta_p)} [\mathcal{F}(m, p; c)]$$

- π is a search distribution
- To define π over $m \in \{0,1\}^d$ and $p \in [0,1]^d$, we let
$$m \sim \text{Bern}(g(\theta_m)); \quad p = g(p'), p' \sim N(\theta_p, \sigma^2)$$
 - $g(\cdot) = \frac{1}{2}(\tanh(\cdot) + 1)$;
 - $\text{Bern}(\cdot)$ is the Bernoulli distribution
 - $N(\cdot)$ is the Gaussian distribution

Gradient Approximation

- For θ_m , draw $m_1, \dots, m_k \sim \pi_1(m|\theta_m)$, and we have

$$\nabla_{\theta_m} \mathcal{J}(\theta_m, \theta_p) \approx \frac{1}{k} \sum_{j=1}^k \mathcal{F}(m_j, g(\theta_p); c) \cdot 2(m_j - g(\theta_m))$$

- For θ_p , draw $\epsilon_1, \dots, \epsilon_k \sim \pi_2(p|\theta_p)$, and we have

$$\nabla_{\theta_p} \mathcal{J}(\theta_m, \theta_p) \approx \frac{1}{k\sigma} \sum_{j=1}^k \mathcal{F}(g(\theta_m), \theta_p + \sigma\epsilon_j; c) \cdot \epsilon_j$$

- Note that we now use queries to estimate the gradient!

Result Summary

- CIFAR-10: 200 models (50 normal; 150 backdoored)
- GTSRB: 172 models (43 normal; 129 backdoored)
- ImageNet: 200 models (50 normal; 150 backdoored)

	CIFAR-10	GTSRB	ImageNet
NC [45]	95.0%	100.0%	96.0%
TABOR [20]	95.5%	100.0%	95.0%
B3D (Ours)	97.5%	100.0%	96.0%
B3D-SS (Ours)	97.5%	100.0%	95.5%



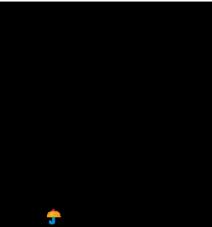
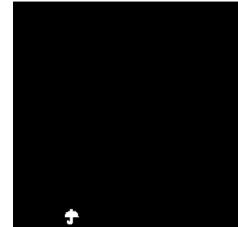
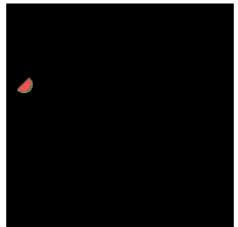
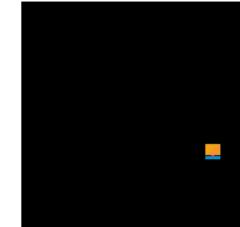
Some Visualization Results

■ ImageNet

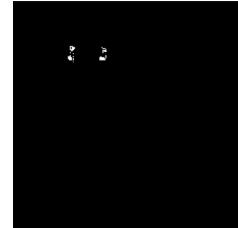
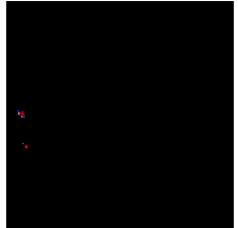
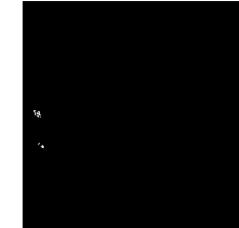
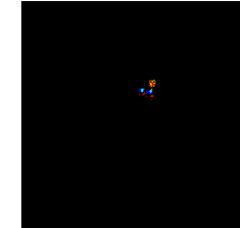
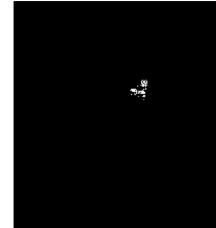
- Trigger size is 15*15
- Trigger patterns are:



Original triggers



Reversed triggers by B3D





Thanks