<Training Neural Networks Without Gradients: A Scalable ADMM Approach> Technical Report

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Abstract

This a technical report about "Training Neural Networks Without Gradients: A Scalable ADMM Approach" [3]. My works mainly about read through the paper; extend the extra knowledge about these paper; think and list all detail algorithm; implement the algorithm with python. the result is not very satisfactory event though the loss can be convergent. the final code is released at https://github.com/dongzhuoyao/admm_nn.

1 ADMM introduction

the standard problem form of Alternating Direction Method of Multipliers(ADMM) is:

minimize
$$H(u) + G(v)$$

subject to $Au + Bv = b$

firstly, we can write the Augmented Lagrangian as:

$$max_{\lambda}min_{u,v}H(u) + G(v) + \langle \lambda, b - Au - Bv \rangle + \frac{\tau}{2}||b - Au - Bv||^2$$

The detail procedure of ADMM is:

$$\begin{array}{l} u_{k+1} = argmin_u H(u) + <\lambda_k, -Au> + \frac{\tau}{2}||b-Au-Bv_k||^2 \\ v_{k+1} = argmin_v G(v) + <\lambda_k, -Bv> + \frac{\tau}{2}||b-Au_{k+1}-Bv||^2 \\ \lambda_{k+1} = \lambda_k + \tau(b-Au_{k+1}-Bv_{k+1}) \end{array}$$

generally speaking, for the above sub-problem. we can solve by three ways:(1) linearized ADMM[2]. (2). gradient descent, use the result of gradient descent instead of the optimal of sub-problem[5]. (3). convert it into dual problem which maybe easier to solve

1.1 Scalability

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The auther realize scalability by a trick called transpose reduction[1]. take sparse least square problem as a example.

minimize
$$\frac{1}{2}||Ax-b||^2$$

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the solution is obvious. $x^* = (A^T A)^{-1} A^T b$. usually A is skinny matrix that need huge computation. thus distributed computation can be utilized.

$$A^T b = \sum_i A_i^T b_i$$

$$A^T A = \sum_i A_i^T A_i$$

1.2 Problem Simplification

The standard Lagrangian Multipliers form of this problem is:

minimize
$$l(a_3) + \frac{1}{2}||z_2 - W_1a_1||^2 + \frac{1}{2}||a_2 - \sigma(z_2)||^2 + <\lambda_1, z_2 - W_1a_1> + <\lambda_2, a_2 - \sigma(z_2)> + \frac{1}{2}||z_3 - W_2a_2||^2 + \frac{1}{2}||a_3 - \sigma(z_3)||^2 + <\lambda_3, z_3 - W_2a_2> + <\lambda_4, a_3 - \sigma(z_3)> + \frac{1}{2}||a_3 - \sigma(z_3)||^2 + \frac{1}{2$$

However, the number of the constraints of the problem is too large to optimize, the author uses a trick that it just place the constraints into the optimizer as penalty items.

minimize
$$l(a_3, y) + \frac{1}{2}||z_2 - W_1 a_1||^2 + \frac{1}{2}||a_2 - \sigma(z_2)||^2 + \frac{1}{2}||z_3 - W_2 a_2||^2 + \frac{1}{2}||a_3 - \sigma(z_3)||^2$$

for weight w_l : the problem is convex, and is a least square problem thus exists a closed-form solution. for activation a_l : it can also transfered into a convex least square problem. for inputs z_l : as it involves the activation function which is non-convex, we can not solve it directly. luckily, each dimension of the problem can splitting out and get solved respectively.

non-linear constraints make the problem unstable. so the author add a extra item to make it stable. which can be interpreted as Bregman Iteration[4] or Lagrangian Multipliers.

$$\min |l(a_3)| + <\lambda, a_3> + \frac{1}{2}||z_2 - W_1 a_1||^2 + \frac{1}{2}||a_2 - \sigma(z_2)||^2 + \frac{1}{2}|||z_3 - W_2 a_2||^2 + \frac{1}{2}||a_3 - \sigma(z_3)||^2$$

1.3 interpretation: Bregman Iteration

Firstly, it can be interpretated as Bregman Iteration. The form of Bregmen Splitting is:

$$min_u J(u) + H(u)$$

the procedure is:

Algorithm 1 Bregman Iteration

```
Inputs: J(.),H(.) Initialize: k=0,u^0=0,p^0=0 while not converge do u^{k+1}=argmin_uD_J^{p^k}(u,u^k)+H(u) p^{k+1}=p^k-\nabla H(u^{k+1})\in J(u^{k+1}) k=k+1 end while
```

The $D_J^{p^k}$ is called Bregman Distance, and $D_J^{p^k}=J(u)-J(u^k)-< u-u^k, p^k>$. in the circumstance of ADMM. $J(u)=l(a_L,y), H(u)=z_L-w_La_{L-1}$ as we minimize by u, so u-sub-problem can be simplified as $u^{k+1}=argmin_uJ(u)-< u, p^k>+H(u)$, which corresponds to

$$\min l(a_3) + <\lambda, a_3> + \tfrac{1}{2}||z_2 - W_1 a_1||^2 + \tfrac{1}{2}||a_2 - \sigma(z_2)||^2 + \tfrac{1}{2}|||z_3 - W_2 a_2||^2 + \tfrac{1}{2}||a_3 - \sigma(z_3)||^2$$

2 Detail Algorithm

As the experiment in the paper using supercomputer which is currently impossible for me. so I generate some small data to test the algorithm. in detail, I choose 2 2-D gaussian distribution data

with center (0.2,0.2) and (0.1,0.1), variance 0.01 both. each class have 5000 data points. the detailed data distribution is in Figure 1. I wish the algorithm can successfully classify these two classes.

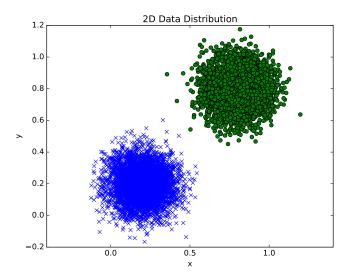


Figure 1: 2D data distribution. This figure is best viewed in colour.

so the feature dimension is 2, I set two hidden layer in the neural network with 10,5 dimensions. as it's a binary classification. the dimension of last layer is 1. specially, no extra layer such as activation layer or sigmoid layer appended to the last layer.

after a long time of think and preparation, the detailed Algorithm is in Algorithm 2.

Algorithm 2 ADMM NN

```
Inputs:
      data number:n=10000,
      data dimension: m=2,
      hidden layer 1 unit number: a=10
      hidden layer 2 unit number: b=5
      output layer unit number: 1
      a_0 m-n dimension,
      W_1: a-m dimension
      z_1: a-n dimension
      a_1: a-n dimension
      W_2: b-a dimension
      z_2: b-n dimension
      a_2: b-n dimension
      W_3: 1-b dimension
      z_3: 1-n dimension
      labels:y 1-n dimension
      \lambda: 1-n dimension
activation function h is ReLu. Initialize:
      allocate \{a_l\}_{l=1}^L, \{z_l\}_{l=1}^L with i.i.d Gaussian Distribution,and \lambda
Cache: a_0^{\dagger}
Warm Start:
for i=1,...,100 do
      for l=1,2,...,L-1 do
W_l \leftarrow z_l a_{l-1}^{\dagger}
a_{l} \leftarrow (\beta_{l+1} W_{l+1}^{T} W_{l+1} + \gamma_{l} I)^{-1} (\beta_{l+1} W_{l+1}^{T} z_{l+1} + \gamma_{l} h_{l}(z_{l}))
z_{l} \leftarrow argmin_{z} \gamma_{l} ||a_{l} - h_{l}(z)||^{2} + \beta_{l} ||z - W_{l} a_{l-1}||^{2}
      end for
       W_L \leftarrow z_L a_{L-1}^{\dagger}
       z_L \leftarrow argmin_z l(z,y) + < z, \lambda > + \beta_L ||z - W_L a_{L-1}||^2
end for
Start ADMM:
while not converge do
      for l=1,2,...,L-1
\begin{aligned} & \mathbf{do} \ W_{l} \leftarrow z_{l} a_{l-1}^{\dagger} \\ & a_{l} \leftarrow (\beta_{l+1} W_{l+1}^{T} W_{l+1} + \gamma_{l} I)^{-1} (\beta_{l+1} W_{l+1}^{T} z_{l+1} + \gamma_{l} h_{l}(z_{l})) \\ & z_{l} \leftarrow argmin_{z} \gamma_{l} ||a_{l} - h_{l}(z)||^{2} + \beta_{l} ||z - W_{l} a_{l-1}||^{2} \end{aligned}
       W_L \leftarrow z_L a_{L-1}^{\dagger}
       z_L \leftarrow argmin_z l(z, y) + \langle z, \lambda \rangle + \beta_L ||z - W_L a_{L-1}||^2
       \lambda \leftarrow \lambda + \beta_L(z_L - W_L a_{L-1})
end while
```

the update of a_l, z_l have closed-form solution. however, for w_l don't have direct solution since the activation function is piecewise function. after classified discussion according to activation. we have the following strategy.

 z_L argmin procedure(when 1 is loss in the paper):

$$z_l = \begin{cases} max(\frac{a_l\gamma_l + W_la_{l-1}\beta_l}{\gamma_l + \beta_l}, 0) & \mathbf{z} \ge 0\\ min(W_la_{l-1}, 0) & \mathbf{z} \le 0 \end{cases}$$

choose one minimizer z from two choices.

```
for z_L:
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when $y_i = 0$:

```
when g_i = 0:
f(z) = \beta z^2 - (2\beta w_- a - \lambda)z + max(z, 0)
z^* = max(\frac{2\beta w_- a - \lambda - 1}{2\beta}, 0) \text{ or }
z^* = min(\frac{2\beta w_- a - \lambda}{2\beta}, 0)
choose one which make f(z) smaller.
when y_i = 1:
f(z) = \beta z^2 - (2\beta w_- a - \lambda)z + max(1 - z, 0)
z^* = max(\frac{2\beta w_- a - \lambda}{2\beta}, 1) \text{ or }
z^* = min(\frac{2\beta w_- a - \lambda + 1}{2\beta}, 1)
choose one which make f(z) smaller.
```

 z_L argmin procedure(when l is a standard hinge loss):

when
$$y_i=-1$$
: $f(z)=max(1+z)+\lambda z+\beta(z^2-2w_az)$ $z^*=min(\frac{2\beta w_a-\lambda}{2\beta},-1)$ or $z^*=max(\frac{2\beta w_a-\lambda-1}{2\beta},-1)$ choose one which make f(z) smaller. when $y_i=1$:
$$f(z)=max(1-z,0)+\lambda z+\beta(z^2-2w_az)$$
 $z^*=min(\frac{2\beta w_a-\lambda+1}{2\beta},1)$ or $z^*=max(\frac{2\beta w_a-a-\lambda}{2\beta},1)$ choose one which make f(z) smaller.

3 Conclusion

After implement the algorithm in python, the loss show convergence. however, the prediction accuracy in test data is nearly 50%, which is as normal as "Throw the dice". Everywhere in the algorithm and code have been checked, but no solution is found. even so, I think this is a promising method where I must miss something important.

Acknowledgments

References

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