Deep Compression: Compressing Deep Neural Networks with Pruning, Trained Quantization and Huffman Coding

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Author Info

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- ICLR 2016 Best Paper Reward

Overview

Three stages

Experiment

Background

Thinking

Three stages

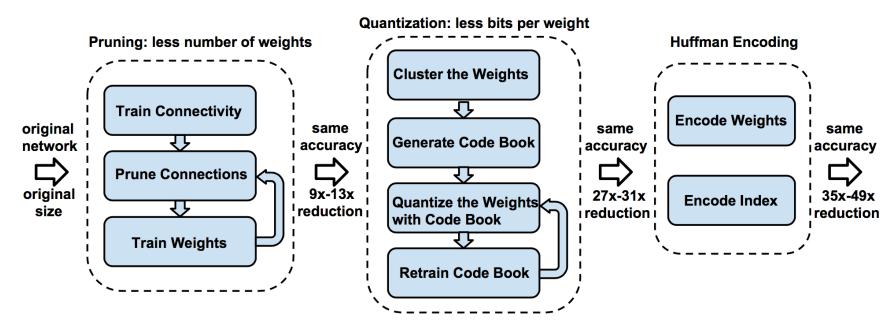
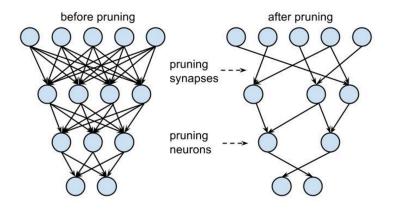


Figure 1: The three stage compression pipeline: pruning, quantization and Huffman coding. Pruning reduces the number of weights by $10\times$, while quantization further improves the compression rate: between $27\times$ and $31\times$. Huffman coding gives more compression: between $35\times$ and $49\times$. The compression rate already included the meta-data for sparse representation. The compression scheme doesn't incur any accuracy loss.

Stage one: pruning

---Less number of weights

How-to-compress



How-to-compensate

retrain the network to learn the final weights for the remaining sparse connections.

Stage one: pruning

---Less number of weights

How to store sparse weight matrix

compressed sparse row (CSR)

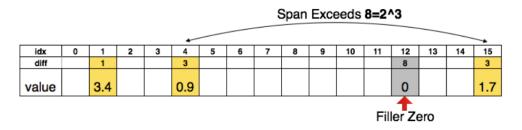


Figure 2: Representing the matrix sparsity with relative index. Padding filler zero to prevent overflow.

Stage one: pruning

---Less number of weights

Fc layer is ok, what about convolution layer?

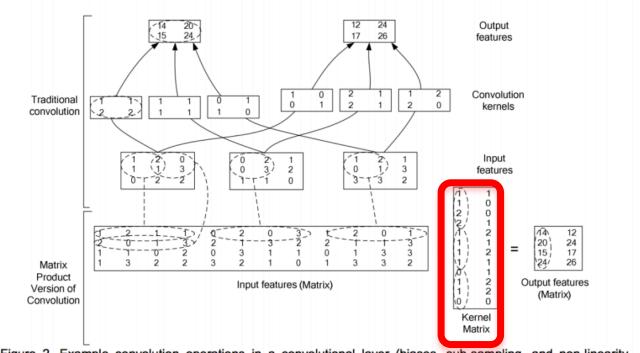


Figure 2. Example convolution operations in a convolutional layer (biases, sub-sampling, and non-linearity omitted). The top figure presents the traditional convolution operations, while the bottom figure presents the matrix version.

GEMM(GEneral Matrix to Matrix Multiplication) is at the heart of deep learning!

Stage two: quantization

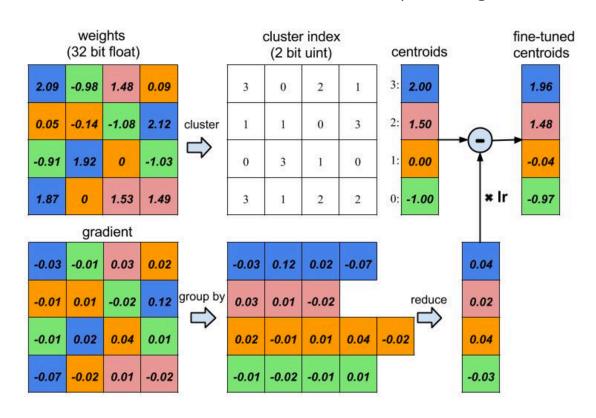
---Less bits per weights

How-to-compress

limit the number of effective weights we need to store by having multiple connections share the same weight

• How-to-compensate

fine-tune those shared weights.



Stage two: quantization

---Less bits per weights

Initialization of K-means



2,Linear init

3,Random init

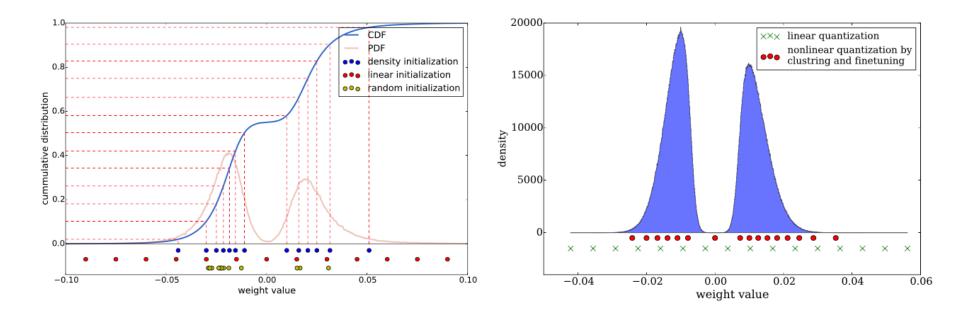


Figure 4: Left: Three different methods for centroids initialization. Right: Distribution of weights (blue) and distribution of codebook before (green cross) and after fine-tuning (red dot).

Stage two: quantization

---Less bits per weights

Back propagation

We denote the loss by \mathcal{L} , the weight in the *i*th column and *j*th row by W_{ij} , the centroid index of element $W_{i,j}$ by I_{ij} , the *k*th centroid of the layer by C_k . By using the indicator function $\mathbb{1}(.)$, the gradient of the centroids is calculated as:

$$\frac{\partial \mathcal{L}}{\partial C_k} = \sum_{i,j} \frac{\partial \mathcal{L}}{\partial W_{ij}} \frac{\partial W_{ij}}{\partial C_k} = \sum_{i,j} \frac{\partial \mathcal{L}}{\partial W_{ij}} \mathbb{1}(I_{ij} = k)$$
(3)

Stage Three: Huffman Coding

 The table is derived from the occurrence probability for each symbol. More common symbols are represented with fewer bits.

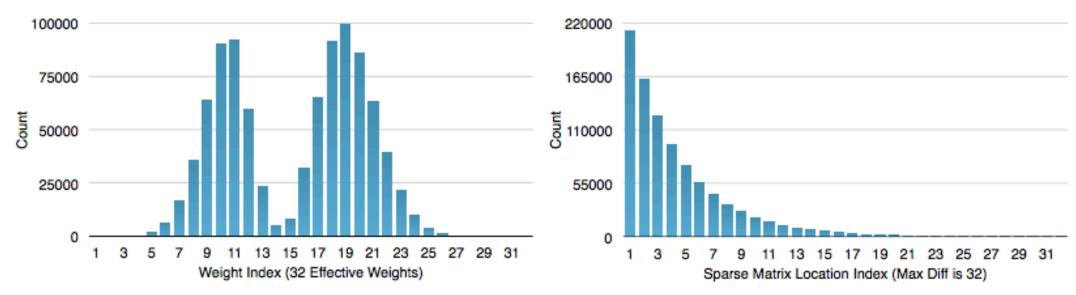


Figure 5: Distribution for weight (Left) and index (Right). The distribution is biased.

of different initialization methods after clustering and fine-tuning, showing that linear initialization

works best.

Three Stages Summary

- Pruning: CSR Format to store sparse matrix
- Quantization: Codebook, Weight, Index
- Huffman

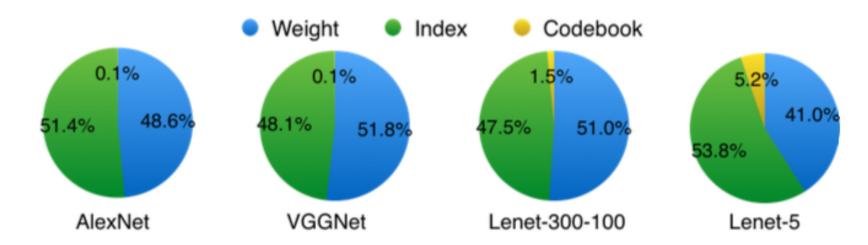


Figure 11: Storage ratio of weight, index and codebook.

How to run in chips?

- Huffman Code translation
- Look up codebook to acquire the actual weight
- Calculate actual position according the relative index
- Prepare the multiplication matrix
- Forward pass

Experiment

Table 1: The compression pipeline can save $35 \times$ to $49 \times$ parameter storage with no loss of accuracy.

| Network | Top-1 Error | Top-5 Error | Parameters | Compress Rate |
|--------------------------|-------------|-------------|------------|------------------|
| LeNet-300-100 Ref | 1.64% | - | 1070 KB | |
| LeNet-300-100 Compressed | 1.58% | - | 27 KB | 40× |
| LeNet-5 Ref | 0.80% | - | 1720 KB | |
| LeNet-5 Compressed | 0.74% | - | 44 KB | 39× |
| AlexNet Ref | 42.78% | 19.73% | 240 MB | |
| AlexNet Compressed | 42.78% | 19.70% | 6.9 MB | 35× |
| VGG-16 Ref | 31.50% | 11.32% | 552 MB | |
| VGG-16 Compressed | 31.17% | 10.91% | 11.3 MB | 49 × |

Experiment

Table 5: Compression statistics for VGG-16. P: pruning, Q:quantization, H:Huffman coding.

| Layer | #Weights | Weights% (P) | Weigh | Weight | Index | Index | Compress | Compress |
|---------|----------|--------------|-------|---------|-------|---------|---------------------|-------------|
| | | | bits | bits | bits | bits | rate | rate |
| | | | (P+Q) | (P+Q+H) | (P+Q) | (P+Q+H) | (P+Q) | (P+Q+H) |
| conv1_1 | 2K | 58% | 8 | 6.8 | 5 | 1.7 | 40.0% | 29.97% |
| conv1_2 | 37K | 22% | 8 | 6.5 | 5 | 2.6 | 9.8% | 6.99% |
| conv2_1 | 74K | 34% | 8 | 5.6 | 5 | 2.4 | 14.3% | 8.91% |
| conv2_2 | 148K | 36% | 8 | 5.9 | 5 | 2.3 | 14.7% | 9.31% |
| conv3_1 | 295K | 53% | 8 | 4.8 | 5 | 1.8 | 21.7% | 11.15% |
| conv3_2 | 590K | 24% | 8 | 4.6 | 5 | 2.9 | 9.7% | 5.67% |
| conv3_3 | 590K | 42% | 8 | 4.6 | 5 | 2.2 | 17.0% | 8.96% |
| conv4_1 | 1M | 32% | 8 | 4.6 | 5 | 2.6 | 13.1% | 7.29% |
| conv4_2 | 2M | 27% | 8 | 4.2 | 5 | 2.9 | 10.9% | 5.93% |
| conv4_3 | 2M | 34% | 8 | 4.4 | 5 | 2.5 | 14.0% | 7.47% |
| conv5_1 | 2M | 35% | 8 | 4.7 | 5 | 2.5 | 14.3% | 8.00% |
| conv5_2 | 2M | 29% | 8 | 4.6 | 5 | 2.7 | 11.7% | 6.52% |
| conv5_3 | 2M | 36% | 8 | 4.6 | 5 | 2.3 | 14.8% | 7.79% |
| fc6 | 103M | 4% | 5 | 3.6 | 5 | 3.5 | 1.6% | 1.10% |
| fc7 | 17M | 4% | 5 | 4 | 5 | 4.3 | 1.5% | 1.25% |
| fc8 | 4M | 23% | 5 | 4 | 5 | 3.4 | 7.1% | 5.24% |
| Total | 138M | 7.5%(13×) | 6.4 | 4.1 | 5 | 3.1 | 3.2% (31 ×) | 2.05% (49×) |

Experiment—Speed and Energy

Sparse-on-GPU: cuSPARSE CSRMV

Dense-on-GPU: cuBLAS GEMV

Sparse-on-CPU: MKL SPBLAS CSRMV

Sparse-on-CPU: MKL CBLAS GEMV

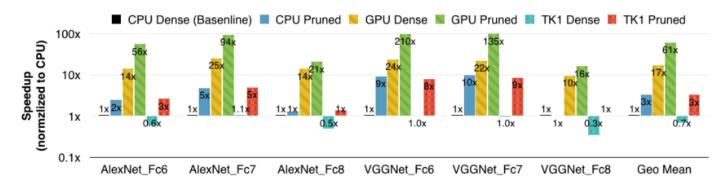


Figure 9: Compared with the original network, pruned network layer achieved $3 \times$ speedup on CPU, $3.5 \times$ on GPU and $4.2 \times$ on mobile GPU on average. Batch size = 1 targeting real time processing. Performance number normalized to CPU.

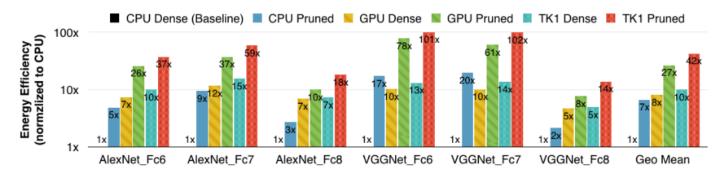


Figure 10: Compared with the original network, pruned network layer takes $7 \times$ less energy on CPU, $3.3 \times$ less on GPU and $4.2 \times$ less on mobile GPU on average. Batch size = 1 targeting real time processing. Energy number normalized to CPU.

Back to 1 Oct 2015

- FIXED POINT OPTIMIZATION OF DEEP CONVOLUTIONAL NEURAL NETWORKS FOR OBJECT RECOGNITION(ICASSP2015)

 Quantization layer by layer, achieve compression and accuracy increase
- Fixed-Point Feedforward Deep Neural Network Design Using Weights +1, 0, and -1 (SiPS2014)
- Quantization with weight 1,0,-1,a good design of backpropagation

Reference

- [1]. https://www.oreilly.com/ideas/compressing-and-regularizing-deep-neural-networks
- [2].https://www.youtube.com/watch?time_continue=24&v=vouEMw DNopQ
- [3].https://en.wikipedia.org/wiki/Sparse_matrix#Compressed_sparse_row_.28CSR.2C_CRS_or_Yale_format.29

Ideas

- Fix Point Continuation,扩展DSD
- (更好的极值点, 更高的压缩比)