# <Training Neural Networks Without Gradients: A Scalable ADMM Approach> Technical Report

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# **Abstract**

This a technical report about "Training Neural Networks Without Gradients: A Scalable ADMM Approach" [3]. My works mainly about read through the paper; extend the extra knowledge about these paper; think and list all detail algorithm; implement the algorithm with python. the result is not very satisfactory event though the loss can be convergent. the final code is released at https://github.com/dongzhuoyao/admm\_nn.

#### 1 ADMM introduction

the standard problem form of Alternating Direction Method of Multipliers(ADMM) is:

minimize 
$$H(u) + G(v)$$
  
subject to  $Au + Bv = b$ 

firstly, we can write the Augmented Lagrangian as:

$$max_{\lambda}min_{u,v}H(u) + G(v) + \langle \lambda, b - Au - Bv \rangle + \frac{\tau}{2}||b - Au - Bv||^2$$

The detail procedure of ADMM is:

$$\begin{array}{l} u_{k+1} = argmin_u H(u) + <\lambda_k, -Au> + \frac{\tau}{2}||b-Au-Bv_k||^2 \\ v_{k+1} = argmin_v G(v) + <\lambda_k, -Bv> + \frac{\tau}{2}||b-Au_{k+1}-Bv||^2 \\ \lambda_{k+1} = \lambda_k + \tau(b-Au_{k+1}-Bv_{k+1}) \end{array}$$

generally speaking, for the above sub-problem. we can solve by three ways:(1) linearized ADMM[2]. (2). gradient descent, use the result of gradient descent instead of the optimal of sub-problem[5]. (3). convert it into dual problem which maybe easier to solve

### 1.1 Scalability

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The auther realize scalability by a trick called transpose reduction[1]. take sparse least square problem as a example.

minimize 
$$\frac{1}{2}||Ax-b||^2$$

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the solution is obvious.  $x^* = (A^T A)^{-1} A^T b$ . usually A is skinny matrix that need huge computation. thus distributed computation can be utilized.

$$A^T b = \sum_i A_i^T b_i$$
  
$$A^T A = \sum_i A_i^T A_i$$

#### 1.2 Problem Simplification

The standard Lagrangian Multipliers form of this problem is:

minimize 
$$l(a_3) + \frac{1}{2}||z_2 - W_1a_1||^2 + \frac{1}{2}||a_2 - \sigma(z_2)||^2 + <\lambda_1, z_2 - W_1a_1> + <\lambda_2, a_2 - \sigma(z_2)> + \frac{1}{2}||z_3 - W_2a_2||^2 + \frac{1}{2}||a_3 - \sigma(z_3)||^2 + <\lambda_3, z_3 - W_2a_2> + <\lambda_4, a_3 - \sigma(z_3)> + \frac{1}{2}||a_3 - \sigma(z_3)||^2 + \frac{1}{2$$

However, the number of the constraints of the problem is too large to optimize, the author uses a trick that it just place the constraints into the optimizer as penalty items.

minimize 
$$l(a_3, y) + \frac{1}{2}||z_2 - W_1 a_1||^2 + \frac{1}{2}||a_2 - \sigma(z_2)||^2 + \frac{1}{2}||z_3 - W_2 a_2||^2 + \frac{1}{2}||a_3 - \sigma(z_3)||^2$$

for weight  $w_l$ : the problem is convex, and is a least square problem thus exists a closed-form solution. for activation  $a_l$ : it can also transfered into a convex least square problem. for inputs  $z_l$ : as it involves the activation function which is non-convex, we can not solve it directly. luckily, each dimension of the problem can splitting out and get solved respectively.

non-linear constraints make the problem unstable. so the author add a extra item to make it stable. which can be interpreted as Bregman Iteration[4] or Lagrangian Multipliers.

$$\min |l(a_3)| + <\lambda, a_3> + \frac{1}{2}||z_2 - W_1 a_1||^2 + \frac{1}{2}||a_2 - \sigma(z_2)||^2 + \frac{1}{2}|||z_3 - W_2 a_2||^2 + \frac{1}{2}||a_3 - \sigma(z_3)||^2$$

# 1.3 interpretation: Bregman Iteration

Firstly, it can be interpretated as Bregman Iteration. The form of Bregmen Splitting is:

$$min_u J(u) + H(u)$$

the procedure is:

### **Algorithm 1** Bregman Iteration

```
Inputs: J(.),H(.) Initialize: k=0,u^0=0,p^0=0 while not converge do u^{k+1}=argmin_uD_J^{p^k}(u,u^k)+H(u) p^{k+1}=p^k-\nabla H(u^{k+1})\in J(u^{k+1}) k=k+1 end while
```

The  $D_J^{p^k}$  is called Bregman Distance, and  $D_J^{p^k}=J(u)-J(u^k)-< u-u^k, p^k>$ . in the circumstance of ADMM.  $J(u)=l(a_L,y), H(u)=z_L-w_La_{L-1}$  as we minimize by u, so u-sub-problem can be simplified as  $u^{k+1}=argmin_uJ(u)-< u, p^k>+H(u)$ , which corresponds to

$$\min l(a_3) + <\lambda, a_3> + \tfrac{1}{2}||z_2 - W_1 a_1||^2 + \tfrac{1}{2}||a_2 - \sigma(z_2)||^2 + \tfrac{1}{2}|||z_3 - W_2 a_2||^2 + \tfrac{1}{2}||a_3 - \sigma(z_3)||^2$$

# 2 Detail Algorithm

As the experiment in the paper using supercomputer which is currently impossible for me. so I generate some small data to test the algorithm. in detail, I choose 2 2-D gaussian distribution data

with center (0.2,0.2) and (0.1,0.1), variance 0.01 both. each class have 5000 data points. the detailed data distribution is in Figure 1. I wish the algorithm can successfully classify these two classes.

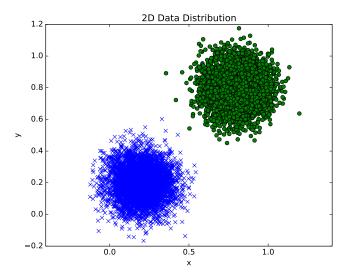


Figure 1: 2D data distribution. This figure is best viewed in colour.

so the feature dimension is 2, I set two hidden layer in the neural network with 10,5 dimensions. as it's a binary classification. the dimension of last layer is 1. specially, no extra layer such as activation layer or sigmoid layer appended to the last layer.

the detailed Algorithm is in Algorithm 2.

### Algorithm 2 ADMM NN

```
Inputs:
      data number:n=10000,
      data dimension: m=2,
      hidden layer 1 unit number: a=10
      hidden layer 2 unit number: b=5
      output layer unit number: 1
      a_0 m-n dimension,
      W_1: a-m dimension
      z_1: a-n dimension
      a_1: a-n dimension
      W_2: b-a dimension
      z_2: b-n dimension
      a_2: b-n dimension
      W_3: 1-b dimension
      z_3: 1-n dimension
      labels:y 1-n dimension
      \lambda: 1-n dimension
activation function h is ReLu. Initialize:
      allocate \{a_l\}_{l=1}^L, \{z_l\}_{l=1}^L with i.i.d Gaussian Distribution,and \lambda
Cache: a_0^{\dagger}
Warm Start:
for i=1,...,100 do
      for l=1,2,...,L-1 do
W_l \leftarrow z_l a_{l-1}^{\dagger}
a_{l} \leftarrow (\beta_{l+1} W_{l+1}^{T} W_{l+1} + \gamma_{l} I)^{-1} (\beta_{l+1} W_{l+1}^{T} z_{l+1} + \gamma_{l} h_{l}(z_{l}))
z_{l} \leftarrow argmin_{z} \gamma_{l} ||a_{l} - h_{l}(z)||^{2} + \beta_{l} ||z - W_{l} a_{l-1}||^{2}
      end for
       W_L \leftarrow z_L a_{L-1}^{\dagger}
       z_L \leftarrow argmin_z l(z,y) + < z, \lambda > + \beta_L ||z - W_L a_{L-1}||^2
end for
Start ADMM:
while not converge do
      for l=1,2,...,L-1
\begin{aligned} & \mathbf{do} \ W_{l} \leftarrow z_{l} a_{l-1}^{\dagger} \\ & a_{l} \leftarrow (\beta_{l+1} W_{l+1}^{T} W_{l+1} + \gamma_{l} I)^{-1} (\beta_{l+1} W_{l+1}^{T} z_{l+1} + \gamma_{l} h_{l}(z_{l})) \\ & z_{l} \leftarrow argmin_{z} \gamma_{l} ||a_{l} - h_{l}(z)||^{2} + \beta_{l} ||z - W_{l} a_{l-1}||^{2} \end{aligned}
       W_L \leftarrow z_L a_{L-1}^{\dagger}
       z_L \leftarrow argmin_z l(z, y) + \langle z, \lambda \rangle + \beta_L ||z - W_L a_{L-1}||^2
       \lambda \leftarrow \lambda + \beta_L(z_L - W_L a_{L-1})
end while
```

the update of  $a_l, z_l$  have closed-form solution. however, for  $w_l$  don't have direct solution since the activation function is piecewise function. after classified discussion according to activation. we have the following strategy.

 $z_L$  argmin procedure(when 1 is loss in the paper):

$$z_l = \begin{cases} max(\frac{a_l\gamma_l + W_la_{l-1}\beta_l}{\gamma_l + \beta_l}, 0) & \mathbf{z} \ge 0\\ min(W_la_{l-1}, 0) & \mathbf{z} \le 0 \end{cases}$$

choose one minimizer z from two choices.

```
for z_L:
```

when  $y_i = 0$ :

```
when g_i = 0:
f(z) = \beta z^2 - (2\beta w_- a - \lambda)z + max(z, 0)
z^* = max(\frac{2\beta w_- a - \lambda - 1}{2\beta}, 0) \text{ or }
z^* = min(\frac{2\beta w_- a - \lambda}{2\beta}, 0)
choose one which make f(z) smaller.
when y_i = 1:
f(z) = \beta z^2 - (2\beta w_- a - \lambda)z + max(1 - z, 0)
z^* = max(\frac{2\beta w_- a - \lambda}{2\beta}, 1) \text{ or }
z^* = min(\frac{2\beta w_- a - \lambda + 1}{2\beta}, 1)
choose one which make f(z) smaller.
```

 $z_L$  argmin procedure(when l is a standard hinge loss):

when 
$$y_i=-1$$
:  $f(z)=max(1+z)+\lambda z+\beta(z^2-2w\_az)$   $z^*=min(\frac{2\beta w\_a-\lambda}{2\beta},-1)$  or  $z^*=max(\frac{2\beta w\_a-\lambda-1}{2\beta},-1)$  choose one which make f(z) smaller. when  $y_i=1$ : 
$$f(z)=max(1-z,0)+\lambda z+\beta(z^2-2w\_az)$$
  $z^*=min(\frac{2\beta w\_a-\lambda+1}{2\beta},1)$  or  $z^*=max(\frac{2\beta w\_a-a-\lambda}{2\beta},1)$  choose one which make f(z) smaller.

#### 3 Conclusion

After implement the algorithm in python, the loss show convergence. however, the prediction accuracy in test data is nearly 50%, which is as normal as "Throw the dice". Everywhere in the algorithm and code have been checked, but no solution is found. even so, I think this is a promising method where I must miss something important.

### Acknowledgments

### References

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