

Chap17.多元函数

微分习题课之一

2022-05

例1. 设 $(axy^3 - y^2 \cos x)dx + (1 + by \sin x + 3x^2 y^2)dy$ 是一个二元函数 $z = f(x, y)$ 的全微分. 试确定 a, b 的值, 并求出函数 $z = f(x, y)$.

$$\text{解 } \because (axy^3 - y^2 \cos x)dx + (1 + by \sin x + 3x^2 y^2)dy = dz,$$

$$\therefore \begin{cases} \frac{\partial z}{\partial x} = axy^3 - y^2 \cos x \\ \frac{\partial z}{\partial y} = 1 + by \sin x + 3x^2 y^2 \end{cases},$$

$$dz = (axy^3 - y^2 \cos x)dx + (1 + by \sin x + 3x^2 y^2)dy$$

$$\therefore \frac{\partial z}{\partial x} = axy^3 - y^2 \cos x, \frac{\partial z}{\partial y} = 1 + by \sin x + 3x^2 y^2,$$

$$z = \frac{1}{2}ax^2 y^3 - y^2 \sin x + C(y) \quad \Rightarrow$$

$$\frac{\partial z}{\partial y} = C'(y) - 2y \sin x + \frac{3}{2}ax^2 y^2 = 1 + by \sin x + 3x^2 y^2,$$

由待定系数法得 $a = 2, b = -2$.

$$\begin{cases} \frac{\partial z}{\partial x} = 2xy^3 - y^2 \cos x \cdots \cdots (1) \\ \frac{\partial z}{\partial y} = 1 - 2y \sin x + 3x^2 y^2 \cdots (2) \end{cases},$$

由(1)得 $z = x^2 y^3 - y^2 \sin x + C(y) \cdots (3)$,

对(3)再计算 $\frac{\partial z}{\partial y} = 3x^2 y^2 - 2y \sin x + C'(y)$,

与(2)比较得: $C'(y) = 1, \therefore C(y) = y + C$,

$\therefore z = x^2 y^3 - y^2 \sin x + y + C$,

.....(其中 C 为任意常数).

例2. 设 $z = f(x - y, x^2 y)$, f 具有连续的偏导数, 求 dz .

解 令设 $u = x - y, v = x^2 y, \rightarrow z = f(u, v)$,

$$\text{则 } dz = \frac{\partial z}{\partial u} du + \frac{\partial z}{\partial v} dv$$

$$= f_1 d(x - y) + f_2 d(x^2 y)$$

$$= f_1 (dx - dy) + f_2 (2xy dx + x^2 dy)$$

$$= (f_1 + 2xyf_2)dx + (-f_1 + x^2 f_2)dy$$

设 $u = x - y, v = x^2 y, \rightarrow z = f(x - y, x^2 y) = f(u, v),$

$$\text{则 } dz = \frac{\partial z}{\partial u} du + \frac{\partial z}{\partial v} dv = f_1 d(x - y) + f_2 d(x^2 y)$$

$$= f_1(dx - dy) + f_2(2xydx + x^2 dy)$$

$$= (f_1 + 2xyf_2)dx + (-f_1 + x^2 f_2)dy$$

$$\text{记 } f_1 = \frac{\partial f(u, v)}{\partial u}, f_2 = \frac{\partial f(u, v)}{\partial v},$$

$$\frac{\partial z}{\partial x} = f_1 + 2xyf_2, \frac{\partial z}{\partial y} = -f_1 + x^2 f_2,$$

$$dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy = (f_1 + 2xyf_2)dx + (-f_1 + x^2 f_2)dy.$$

这就是一阶全微分的形式不变性!

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例3. 设 $z = f(x + y, xy)$, 函数 f 有连续的二阶偏导数, 求 $\frac{\partial z}{\partial x}$ 与 $\frac{\partial^2 z}{\partial x \partial y}$.

解 令 $u = x + y, v = xy$.

$$\text{记 } f_1 = \frac{\partial f(u, v)}{\partial u}, f_{12} = \frac{\partial^2 f(u, v)}{\partial u \partial v},$$

同样有 f_2, f_{11}, f_{22}

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial u} \cdot \frac{\partial u}{\partial x} + \frac{\partial z}{\partial v} \cdot \frac{\partial v}{\partial x} = f_1 + y f_2,$$

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$$\frac{\partial^2 z}{\partial x \partial y} = \frac{\partial}{\partial y} (f_1 + yf_2) = \frac{\partial f_1}{\partial y} + f_2 + y \frac{\partial f_2}{\partial y},$$

$$\frac{\partial f_1}{\partial y} = \frac{\partial f_1}{\partial u} \cdot \frac{\partial u}{\partial y} + \frac{\partial f_1}{\partial v} \cdot \frac{\partial v}{\partial y} = f_{11} + xf_{12},$$

$$\frac{\partial f_2}{\partial y} = \frac{\partial f_2}{\partial u} \cdot \frac{\partial u}{\partial y} + \frac{\partial f_2}{\partial v} \cdot \frac{\partial v}{\partial y} = f_{21} + xf_{22};$$

$$\therefore \frac{\partial^2 z}{\partial x \partial y} = f_{11} + xf_{12} + f_2 + y(f_{21} + xf_{22})$$

$$= f_{11} + (x + y)f_{12} + xyf_{22} + f_2$$

例4.已知函数 $z = z(x, y)$ 具有连续的二阶偏导

数, 设 $\begin{cases} u = x + y \\ v = x - y \end{cases}$, 试将方程 $\frac{\partial^2 z}{\partial x^2} - \frac{\partial^2 z}{\partial y^2} = 0$ 化为

新坐标系中的形式, 并由此求解该 偏微分方程.

解 合理的理解是, $z = \varphi(u, v) = f(x, y)$,

函数 φ, f 有连续的二阶偏导数.

$$\begin{cases} \frac{\partial z}{\partial x} = \frac{\partial z}{\partial u} \cdot \frac{\partial u}{\partial x} + \frac{\partial z}{\partial v} \cdot \frac{\partial v}{\partial x} = \frac{\partial z}{\partial u} + \frac{\partial z}{\partial v} \\ \frac{\partial z}{\partial y} = \frac{\partial z}{\partial u} \cdot \frac{\partial u}{\partial y} + \frac{\partial z}{\partial v} \cdot \frac{\partial v}{\partial y} = \frac{\partial z}{\partial u} - \frac{\partial z}{\partial v} \end{cases},$$

$$\frac{\partial^2 z}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial z}{\partial u} + \frac{\partial z}{\partial v} \right) = \frac{\partial}{\partial x} \left(\frac{\partial z}{\partial u} \right) + \frac{\partial}{\partial x} \left(\frac{\partial z}{\partial v} \right)$$

$$\frac{\partial}{\partial x} \left(\frac{\partial z}{\partial u} \right) = \frac{\partial \left(\frac{\partial z}{\partial u} \right)}{\partial u} \cdot \frac{\partial u}{\partial x} + \frac{\partial \left(\frac{\partial z}{\partial u} \right)}{\partial v} \cdot \frac{\partial v}{\partial x}$$

$$= \frac{\partial^2 z}{\partial u^2} \cdot \frac{\partial u}{\partial x} + \frac{\partial^2 z}{\partial u \partial v} \cdot \frac{\partial v}{\partial x}$$

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial u} + \frac{\partial z}{\partial v}$$

$$\frac{\partial^2 z}{\partial x^2} = \frac{\partial^2 z}{\partial u^2} \cdot \frac{\partial u}{\partial x} + \frac{\partial^2 z}{\partial u \partial v} \cdot \frac{\partial v}{\partial x}$$

$$+ \frac{\partial^2 z}{\partial v \partial u} \cdot \frac{\partial u}{\partial x} + \frac{\partial^2 z}{\partial v^2} \cdot \frac{\partial v}{\partial x}$$

$$= \frac{\partial^2 z}{\partial u^2} + \frac{\partial^2 z}{\partial u \partial v} + \frac{\partial^2 z}{\partial v \partial u} + \frac{\partial^2 z}{\partial v^2}$$

$$= \frac{\partial^2 z}{\partial u^2} + 2 \frac{\partial^2 z}{\partial u \partial v} + \frac{\partial^2 z}{\partial v^2}$$

$$\frac{\partial^2 z}{\partial y^2} = \frac{\partial^2 z}{\partial u^2} \cdot \frac{\partial u}{\partial y} + \frac{\partial^2 z}{\partial u \partial v} \cdot \frac{\partial v}{\partial y}$$

$$\frac{\partial z}{\partial y} = \frac{\partial z}{\partial u} - \frac{\partial z}{\partial v}$$

$$- \frac{\partial^2 z}{\partial v \partial u} \cdot \frac{\partial u}{\partial y} - \frac{\partial^2 z}{\partial v^2} \cdot \frac{\partial v}{\partial y}$$

$$= \frac{\partial^2 z}{\partial u^2} - \frac{\partial^2 z}{\partial u \partial v} - \frac{\partial^2 z}{\partial v \partial u} + \frac{\partial^2 z}{\partial v^2}$$

$$= \frac{\partial^2 z}{\partial u^2} - 2 \frac{\partial^2 z}{\partial u \partial v} + \frac{\partial^2 z}{\partial v^2}$$

$$\frac{\partial^2 z}{\partial x^2} - \frac{\partial^2 z}{\partial y^2} = 0 \Rightarrow \frac{\partial^2 z}{\partial u \partial v} = 0, (P135/7)$$

$$\frac{\partial^2 z}{\partial u \partial v} = 0 \Leftrightarrow \frac{\partial z}{\partial u} = g(u),$$

$$\Rightarrow z = \int g(u) du = G(u) + H(v),$$

$$\therefore \text{方程 } \frac{\partial^2 z}{\partial x^2} - \frac{\partial^2 z}{\partial y^2} = 0 \text{ 的解}$$

$$\text{为 } z = G(x + y) + H(x - y)$$

$G(s), H(t)$ 为任意的有连续导数的函数.

极值判断(充分条件)定理-对比:

二元: $f_x(x_0, y_0) = 0, f_y(x_0, y_0) = 0.$

$f_{xx}(x_0, y_0) = A, f_{xy}(x_0, y_0) = B,$

$f_{yy}(x_0, y_0) = C.$

当 $AC - B^2 > 0$ 时有极值:

$A > 0 (< 0)$ 时有极小(大)值.

一元: $f'(x_0) = 0, f''(x_0) = A,$

则当 $A \neq 0$ 时有极值:

$A > 0 (< 0)$ 时有极小(大)值.

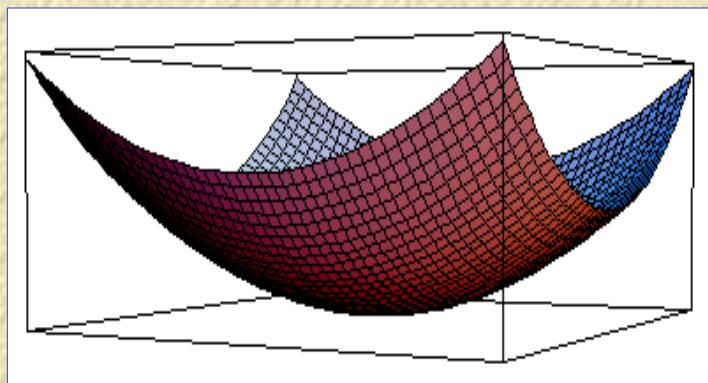
通过具体例子帮助记住定理结论.

(1). $z = x^2 + 2y^2$ 在驻点 $(0,0)$ 处取得极小值, 且有

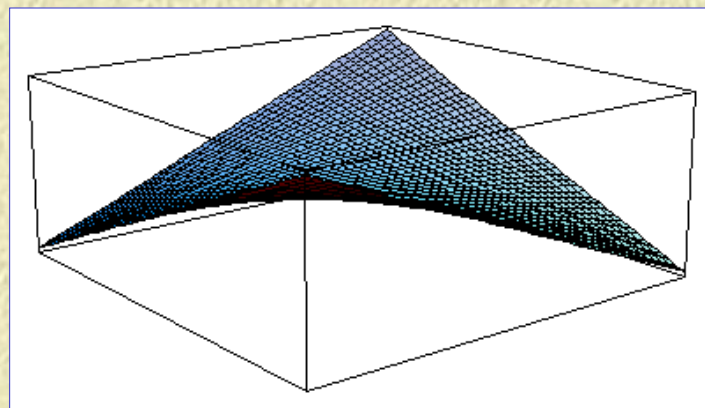
$$A = 2, B = 0, C = 4, AC - B^2 = 8 > 0.$$

(2). $z = x^2 - y^2$ 在驻点 $(0,0)$ 处无极值,

$$A = 2, B = 0, C = -2, AC - B^2 = -4 < 0.$$



(1)



(2)

例5.求 $f(x, y) = x^3 - y^3 + 3x^2 + 3y^2 - 9x$
的极值.

解 第一步 求驻点.

解方程组
$$\begin{cases} f_x(x, y) = 3x^2 + 6x - 9 = 0 \\ f_y(x, y) = -3y^2 + 6y = 0 \end{cases}$$

解得 $x = 1$ 或 3 , $y = 0$ 或 2 .

\therefore 驻点有 $(1, 0), (1, 2), (3, 0), (3, 2)$.

第二步 判别.

求二阶偏导数 $f_{xx} = 6x + 6 \cdots A$,

$$f_{xy} = 0 \cdots B, f_{yy} = -6y + 6 \cdots C$$

项目 驻点	$A = f_{xx}$	$B = f_{xy}$	$C = f_{yy}$	$AC - B^2$	极值情况
$(-3, 0)$	-12	0	6	< 0	不取极值
$(-3, 2)$	$-12 < 0$	0	-6	> 0	$\max f(x, y) = f(-3, 2)$
$(1, 0)$	$12 > 0$	0	6	> 0	$\min f(x, y) = f(1, 0)$
$(1, 2)$	12	0	-6	< 0	不取极值

以例说明定理的条件是充分而非必要的.
(不要求掌握)

e.g.讨论函数 $z = x^3 + y^3$ 与 $z = (x^2 + y^2)^2$

在点 $(0,0)$ 处的极值情况.

解 显然 $(0,0)$ 都是它们的驻点,且在 $(0,0)$

处都有 $AC - B^2 = 0$.

$z = x^3 + y^3$ 在点 $(0,0)$ 的邻域内的取值可能为:正\零\负,

$\therefore (0,0)$ 处 $z = x^3 + y^3$ 不取极值.

而当 $x^2 + y^2 \neq 0$ 时, $z = (x^2 + y^2)^2 > z|_{(0,0)} = 0$,

$\therefore z(0,0) = (x^2 + y^2)^2|_{(0,0)} = 0$ 为极小值.

例6. 设 $f(x, y) = \begin{cases} xy \frac{x^2 - y^2}{x^2 + y^2}, & x^2 + y^2 \neq 0 \\ 0, & x^2 + y^2 = 0 \end{cases}$, 求 $f_{xy}(0, 0)$ 和 $f_{yx}(0, 0)$.

解 $f_x(x, y) = \begin{cases} y \frac{x^4 + 4x^2y^2 - y^4}{(x^2 + y^2)^2}, & x^2 + y^2 \neq 0 \\ 0, & x^2 + y^2 = 0 \end{cases}$

$f_y(x, y) = \begin{cases} x \frac{x^4 + 4x^2y^2 - y^4}{(x^2 + y^2)^2}, & x^2 + y^2 \neq 0 \\ 0, & x^2 + y^2 = 0 \end{cases}$

$$\left. \begin{aligned} f_{xy}(0, 0) &= \lim_{\Delta y \rightarrow 0} \frac{f_x(0, \Delta y) - f_x(0, 0)}{\Delta y} = \lim_{\Delta y \rightarrow 0} \frac{-\Delta y}{\Delta y} = -1 \\ f_{yx}(0, 0) &= \lim_{\Delta x \rightarrow 0} \frac{f_y(\Delta x, 0) - f_y(0, 0)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{\Delta x}{\Delta x} = 1 \end{aligned} \right\}$$

象这样的分段函数的问题可以忽略. 尽管是有用的, 但不是重要的.

多元函数的微分部分,理解概念并掌握结论与方法是重要的,但首先重要的计算,而非利用定义与二重极限等作可微性的讨论.

首要的计算!计算!!计算!!!

例7*. 设函数 $z = f(x, y)$ 在 \mathbb{R}^2 上可微,

$$\forall ab \neq 0, \text{ 若有 } b \frac{\partial z}{\partial x} = a \frac{\partial z}{\partial y}.$$

求证: 必定有 $z = \varphi(ax + by)$ 的形式.

分析 若 $z = g(u, v)$, 则 $\frac{\partial z}{\partial u} \equiv 0 \Leftrightarrow$

z 相对于变量 u 而言是常数,

那么, 必定有 $z = \varphi(v)$ 的形式.

证明 $\because ab \neq 0, \therefore \begin{cases} u = x \\ v = ax + by \end{cases}$ 是一个

可逆的线性变换, 且 $\begin{cases} x = u \\ y = -\frac{a}{b}u + \frac{1}{b}v \end{cases}.$

$\because x, y$ 是函数 $z = f(x, y)$ 的两个独立的自变量,

$\therefore u, v$ 是函数 $z = f(x, y) = g(u, v)$ 的两个独立的自变量.

$$\forall ab \neq 0,$$

$$b \frac{\partial z}{\partial x} = a \frac{\partial z}{\partial y}.$$

$$\begin{cases} u = x \\ v = ax + by \end{cases}, \begin{cases} x = u \\ y = -\frac{a}{b}u + \frac{1}{b}v \end{cases},$$

$\because f$ 在 \mathbb{R}^2 上可微, $\therefore \forall (x, y) \in \mathbb{R}^2$,

$$\frac{\partial z}{\partial u} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial u} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial u} = \frac{\partial z}{\partial x} - \frac{a}{b} \cdot \frac{\partial z}{\partial y} \equiv 0,$$

$\therefore z$ 作为变量 u, v 的函数, z 相对于变量 u 而言是常数, 故必定有

$z = \varphi(v) = \varphi(ax + by)$ 的形式.

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例8*.(P134/总练习3) 设 $u =$

$$\begin{vmatrix} 1 & 1 & \cdots & 1 \\ x_1 & x_2 & \cdots & x_n \\ x_1^2 & x_2^2 & \cdots & x_n^2 \\ \vdots & \vdots & & \vdots \\ x_1^{n-1} & x_2^{n-1} & \cdots & x_n^{n-1} \end{vmatrix}$$

证明: (1). $\sum_{k=1}^n \frac{\partial u}{\partial x_k} = 0$; (2). $\sum_{k=1}^n x_k \frac{\partial u}{\partial x_k} = \frac{n(n-1)}{2} u$.

证一 (1).这是 *Van der monde* 行列式,

$$u = \prod_{1 \leq i < j \leq n} (x_j - x_i),$$

可以通过硬算 $\frac{\partial u}{\partial x_i} = \dots$, 用此最简单的方法来处理问

题(1)应属可行.用此法来处理问题(2)就显得太拙笨了, 但还是值得一试.

简单的方法往往就是好的方法 .

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$$u = \prod_{1 \leq i < j \leq n} (x_j - x_i)$$

为计算 $\frac{\partial u}{\partial x_i}$, 如果考虑用对数求导法, 如果

$x_j - x_i \neq 0$ 时是可行的... $\left(\text{注意到 } (\ln(-x))' = \frac{1}{x} \right)$

$$\ln u = \sum_{1 \leq i < j \leq n} \ln(x_j - x_i)$$

$$u = e^{\ln u} = e^{\sum_{1 \leq i < j \leq n} \ln(x_j - x_i)}, \frac{\partial u}{\partial x_i} = \dots$$

$$\text{设 } u = \begin{vmatrix} 1 & 1 & \cdots & 1 \\ x_1 & x_2 & \cdots & x_n \\ x_1^2 & x_2^2 & \cdots & x_n^2 \\ \vdots & \vdots & & \vdots \\ x_1^{n-1} & x_2^{n-1} & \cdots & x_n^{n-1} \end{vmatrix}$$

$$\text{证明: (1). } \sum_{k=1}^n \frac{\partial u}{\partial x_k} = 0 ;$$

$$(2). \sum_{k=1}^n x_k \frac{\partial u}{\partial x_k} = \frac{n(n-1)}{2} u .$$

法二: (1). 行列式按第 k 列展开

$$u = 1 \cdot A_{1k} + x_k A_{2k} + \cdots + x_k^{n-1} A_{nk} = \sum_{i=1}^n x_k^{i-1} A_{ik},$$

$$\frac{\partial u}{\partial x_k} = \sum_{i=2}^n (i-1) x_k^{i-2} A_{ik},$$

A_{ik} 中没有
 x_k 的因子

返回

$$\sum_{k=1}^n \frac{\partial u}{\partial x_k} = \sum_{k=1}^n A_{2k} + 2 \sum_{k=1}^n x_k A_{3k} + \cdots + (n-1) \sum_{k=1}^n x_k^{n-2} A_{nk}$$

$$= 0 + 0 + 0 + \cdots + 0 = 0.$$

$$(2). \sum_{k=1}^n x_k \frac{\partial u}{\partial x_k}$$

行列式按
行计算

$$= \sum_{k=1}^n x_k A_{2k} + 2 \sum_{k=1}^n x_k^2 A_{3k} + \cdots + (n-1) \sum_{k=1}^n x_k^{n-1} A_{nk}$$

$$= u + 2u + \cdots + (n-1)u = \frac{n(n-1)}{2} u.$$

法三 (1).注意到 $u = \prod_{1 \leq i < j \leq n} (x_j - x_i)$

有一特别巧妙的做法,令

$$g(t) = u(x_1 + t, \dots, x_n + t) \equiv u(x_1, \dots, x_n) = g(0),$$

$$\therefore \forall t, g(t) \equiv C, \therefore g'(t) \equiv 0,$$

$$g'(t) = \frac{\partial u}{\partial s_1} \cdot \frac{\partial s_1}{\partial t} + \frac{\partial u}{\partial s_2} \cdot \frac{\partial s_2}{\partial t} + \dots + \frac{\partial u}{\partial s_n} \cdot \frac{\partial s_n}{\partial t}$$

$$= u_1 + u_2 + \dots + u_n,$$

令 $t = 0$ 就得到(1)的结论.

(2).利用齐次函数的*Euler*定理(**P117/Ex.7**)

$$\text{有 } u(tx_1, \dots, tx_n) = t^{1+2+\dots+n-1} u(x_1, \dots, x_n),$$

$$\text{立即得到结论 } \sum_{k=1}^n x_k \frac{\partial u}{\partial x_k} = \frac{n(n-1)}{2} u .$$

我们可以看到,比较起来,方法三处理问题的确是简便、快捷,但太不容易想到了.就我而言,首选方法一,历尽艰辛而不得,然后再去寻求所谓巧妙的做法.你如何?

例9*.(P117/7)若函数 $u = F(x, y, z)$ 满足恒等式 $F(tx, ty, tz) = t^k F(x, y, z) \ (t > 0)$, 则称 $F(x, y, z)$ 为 k 次齐次函数.

试证明下述关于齐次函数的Euler定理:

可微函数 $F(x, y, z)$ 为 k 次齐次函数 \Leftrightarrow

$$xF_x(x, y, z) + yF_y(x, y, z) + zF_z(x, y, z) = kF(x, y, z).$$

证明思路分析

回顾: 可微函数 $f(x), x \in (0, +\infty)$ 满足

$xf'(x) = kf(x)$, 问 $f(x) = ?$ \leftarrow 联想

证明思路分析

回顾：可微函数 $f(x)$, $x \in (0, +\infty)$ 满足

$xf'(x) = kf(x)$, 问 $f(x) = ?$

解决途径：据微分形式不变性, 由 $xf'(x) = kf(x)$,

变化为 $\frac{df(x)}{f(x)} = k \frac{dx}{x}$, 即 $d(\ln f(x) - k \ln x) = 0$,

得 $\ln f(x) - k \ln x = \ln C$, 即 $\frac{f(x)}{x^k} = C \dots$

故设辅助函数 $\varphi(x) = \frac{f(x)}{x^k}$, 即证 $\varphi(x) = C$.

$Q: f(x)$ 可微, $x \in (0, +\infty)$ 满足 $xf'(x) = kf(x)$, 问 $f(x) = ?$

$A: 设辅助函数 $\varphi(x) = \frac{f(x)}{x^k}, x \in (0, +\infty)$, 往证 $\varphi(x) = C$.$

联想, 类比 \longrightarrow

$Q: 试证明: 可微函数 $F(x, y, z)$ 为 k 次齐次函数 \Leftrightarrow
 $xF_x(x, y, z) + yF_y(x, y, z) + zF_z(x, y, z) = kF(x, y, z).$$

$A: 设辅助函数 $\varphi(t) = \frac{F(tx, ty, tz)}{t^k}$, 即往证 $t \in (0, +\infty)$$

时 $\varphi(t) = C$.

试证明下述关于齐次函数的Euler定理：

可微函数 $F(x, y, z)$ 为 k 次齐次函数 \Leftrightarrow

$$xF_x(x, y, z) + yF_y(x, y, z) + zF_z(x, y, z) = kF(x, y, z).$$

证明 “ \Leftarrow ” 的证明：设 $\varphi(t) = \frac{F(tx, ty, tz)}{t^k}, t \in (0, +\infty)$,

$$\begin{aligned}\varphi'(t) &= \frac{t^k \cdot \frac{d}{dt} F(tx, ty, tz) - F(tx, ty, tz) \cdot kt^{k-1}}{t^{2k}} \\ &= \frac{txF_1(tx, ty, tz) + tyF_2(tx, ty, tz) + tzF_3(tx, ty, tz) - kF(tx, ty, tz)}{t^{k+1}} \\ &\equiv 0,\end{aligned}$$

$\therefore t \in (0, +\infty)$ 时 $\varphi(t) \equiv C$, 于是 $\varphi(t) = \varphi(1)$, 结论得证.

“ \Rightarrow ” 的证明是容易的.