

# Collective Self-awareness in Progress and Plans

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## Dynamic systems

**Generalized state space**  $\left\{ \vec{X} = \left\{ \underbrace{X}_{\text{state position}}, \underbrace{\frac{\partial X}{\partial t}, \frac{\partial^2 X}{\partial t^2}, \dots, \frac{\partial^L X}{\partial t^L}}_{\text{Motion (action) such as Velocity, acceleration}} \right\} \right\}$

Generalized space state

# Semantic SA - State space segmentation

To either capture traits such as left turning of a moving object along time courses or constant motion zones

- Self-organizing maps (SOM)
- Growing Neural Gas (GNG)
- Gaussian process division (GP)

# Generative/predictive models

Filtering (State estimation from observation):

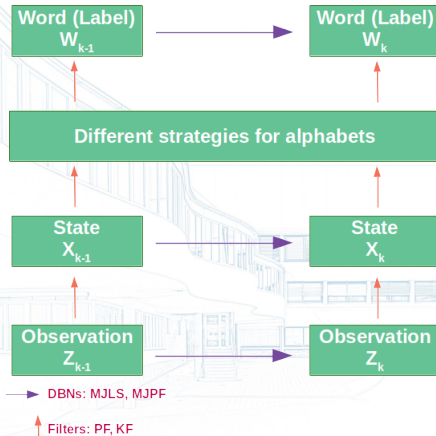
- **Kallman Filter (KF):** Continuous state prediction for linear, dynamic systems from incremental observation.
- **Particle Filter (PF) - Sequential Monte Carlo (SMC):** Discrete state prediction for non-linear, none Gaussian (error-wise) dynamic systems

Switching models (Next state estimation according to current observation):

- **Markov Jump Linear Systems (MJLS):** For linear dynamic systems with continuous state space
- **Markov Jump Particle Filter (MJPF):** For dynamic, none linear system with any noise distribution which contains:
  - Bank of KFs to map continuous observation to states
  - Banks of PFs to map discrete observations to states

# Generative/predictive models

A very rough sketch of existing models:

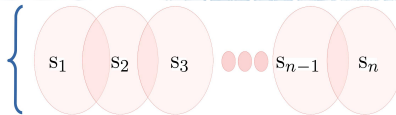


# Semantic SA - Words as synchronously happened static motion zones

Could be used in anomaly detection of a force field driven environment

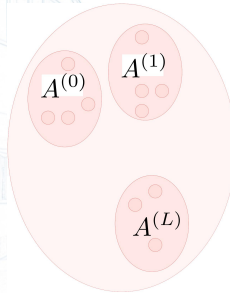
- **Semantic segmentation:** SOM
- **Alphabet level:** Zones/prototypes where the motion remains constant
- **Word level:** Simultaneous occurrence of alphabets in a reference(training) task
- **Sentence/Grammar level:** The sequence of words from the beginning of an interaction to the end

Words are  
synchronously  
activated  
Zones in the  
absence of  
repulsive forces



## Semantic SA - Words as classes of generalized state traits

- **Semantic segmentation:** Self-organizing maps (SOM) / Growing Neural Gas (GNG)
- **Alphabet level:** Centroids of time's  $i$ -th derivative of states derived from resulting clusters in state space segmentation phase



## Semantic SA - Words as classes of generalized state traits - 2

- **Word level:** A set of alphabets containing all time derivative orders

$$w = \{\alpha^{(0)}, \dots, \alpha^{(L)}\} \quad (1)$$

where  $\alpha^i$  is the centroid of i-th time derivative order of the states in a cluster.

- **Sentence/Grammar level:** The sequence of words formed in a reference task



# Future plans for Words as classes of generalized state traits

Building words/semantics on sensor heterogeneity level

- Different sensors (e.g one agent Temperature)

## **Future plan: Investigating applications in the following areas:**

- Internet of things (IoT)
- Cyber physical systems (CPS)
- Swarm intelligence

## Future plan for synchronously activated motion zones

- Relating Reinforcement learning(RL) with Force-field(FF) analysis
  - Rewards will be modeled by attractive forces
  - Costs will be modeled by repulsive forces

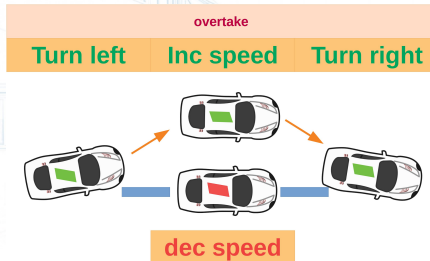
**Question?** Can semantic state description from robots help them to adapt gradually to new versions of the task they are trying to accomplish by better cooperation using RL and FF?

# Future plan - words as traits - 1

- Similar word in different sequences must induce new actions (Semantic context awareness)

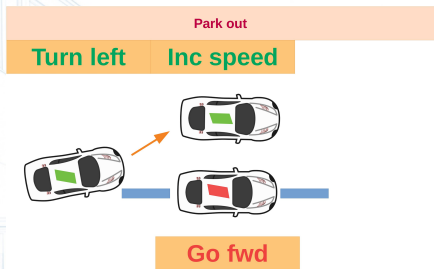
Such as in driving

- Taking over
  - Attractor vehicle = Turning left + increase speed + Turning right
  - Follower vehicle = nothing + decrease speed a little + nothing



## Future plans - words as traits - 2

- Getting out of park:
  - Attractor vehicle = Turn left + increase speed
  - Follower vehicle = move forward a little



Turning left in both examples are the same but they must partially contribute to inducing different actions.

## Other future plans to investigate - 1

- Unifying "Words as traits" and "synchronously activated motion zones" into one idea to build more efficient CA system.
- What other strategies can be taken to suggest words which improve semantic awareness?

## Other future plans to investigate - 2

- How to relate hierarchical composition of semantics from one agent to actions in another agent?
- How to prove semantic awareness of IAs improves the balance in goals of a system?

## Other future plans to investigate - 3

- How does semantic-awareness help with improvements in minimum AI SA requirements such as initialization, memorization, predictive model temporal-causal model creation, anomaly detection and decision making?