- 4.8 Prove that a set  $B = (v_1, \dots, v_n)$  of vectors in  $F^n$  is a basis if and only if the matrix obtained by assembling the coordinate vectors of  $v_i$  is invertible
  - $\Rightarrow$  Suppose the set  $(v_1, \dots, v_n)$  is a basis of  $F^n$ . We want to show that the matrix given by  $(v_1, \dots, v_n)$  is invertible. Since B is a basis, then it is linearly independent. Therefore, it has a non-zero determinate. Therefore, since there are n vectors with n elements, then the matrix given by B is invertible
  - $\Leftarrow$  Suppose the matrix represented by B in  $F^n$  is invertible. Since the matrix is invertible then it has a non-zero determinate. Therefore it's columns are linearly independent. Since there is a set of n linearly independent vectors in  $F^n$ , then it must span  $F^n$ . Therefore B is a basis.
- 5.2 (a) The base change matrix is given by:  $\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}.$ 
  - (b) The matrix which swaps all of the basis vectors to the opposite order is given by:

$$\begin{bmatrix} 0 & \cdots & 0 & 1 \\ 0 & \cdots & 1 & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 1 & \cdots & 0 & 0 \end{bmatrix}$$

- 6.1 Prove that  $M_n(\mathbb{R})$  is the direct sum of the space of symmetry and the space of skew symmetric matrices
  - We will show that the intersection of the set of symmetric matrices and skew symmetric matrices is exactly the 0 matrix. Suppose for contradiction that there is a non-zero matrix where is both skew symmetric and symmetric. Let this matrix be denoted E. Then  $E = E^t$ ,  $E = -E^t$ . Therefore E = 0. Therefore E = 0 is identically the 0 matrix, giving us the desired contradiction. Therefore the only element shared between the two subspaces is the 0 matrix.
  - Suppose  $A \in M_n(\mathbb{R})$ . We will show there exists a symmetric matrix S and a skew symmetric matrix K such that A = S + K. We claim that  $S = (\frac{a_{ij} + a_{ji}}{2}), K = (\frac{a_{ij} a_{ji}}{2})$  satisfy the requirements.
    - We claim that S is symmetric. Note that  $(S)_{ij} = \frac{a_{ij} + a_{ji}}{2}$  and  $(S)_{ji} = \frac{a_{ji} + a_{ij}}{2}$ . Therefore  $(S)_{ij} = (S)_{ji}$ .
    - We claim that K is skew symmetric. Note that  $(K)_{ij} = \frac{a_{ij} a_{ji}}{2}$  and that  $(K)_{ji} = \frac{a_{ji} a_{ij}}{2}$ . Therefore  $-(K)_{ij} = -\frac{a_{ij} a_{ji}}{2} = \frac{a_{ji} a_{ij}}{2} = K_{ji}$ . Thus K is skew symmetric.
    - We claim that A = S + K. Note that

$$(A)_{ij} = a_{ij} = \frac{2a_{ij}}{2} = \frac{a_{ij} + a_{ji}}{2} + \frac{a_{ij} - a_{ji}}{2} = (S)_{ij} + (K)_{ij}$$

and 
$$(A)_{ji} = a_{ji} = \frac{2a_{ji}}{2} = \frac{a_{ji} + a_{ij}}{2} + \frac{a_{ji} - a_{ij}}{2} = (S)_{ji} + (K)_{ji}$$

Therefore A = S + K.

1.1 Suppose  $A \in M_{l \times m}(F), B \in M_{n \times p}(F)$ . We want to show for  $M \in M_{m \times n}(F)$  that T(M) = AMB is linear. Suppose  $c \in F, N \in M_{m \times n}(F)$ . Therefore

$$T(cM + N) = A(cM + N)B$$

$$= (AcM + AN)B$$

$$= AcMB + ANB$$

$$= cAMB + ANB$$

$$= cT(M) + T(N).$$

Thus T is linear.

1.3 Show using the dimension theorem that the dimension of the solutions to AX=0 is at least n-m. Note that AX=0 is exactly the kernel of A. Therefore by applying the dimension theorem we have that n=dim(im(T))+dim(ker(T)). Note that the rank is maximized by m, giving the formula  $n \leq m+dim(ker(T))$ . Therefore

$$dim(ker(T)) \ge n - m.$$

2.1 Given two matrices  $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$ ,  $B = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} \in F^{2\times 2}$  show that for arbitrary  $M \in F^{2\times 2}$  the matrix representation of AMB.

The matrix representation on the unit elements of  $F^{2\times 2}$  with the ordered basis of  $(e_{11}, e_{12}, e_{21}, e_{22})$  is the following:

$$\begin{bmatrix} a_{11}b_{11} & a_{11}b_{12} & a_{21}b_{11} & a_{21}b_{12} \\ a_{11}b_{21} & a_{11}b_{22} & a_{21}b_{21} & a_{21}b_{22} \\ a_{12}b_{11} & a_{12}b_{12} & a_{22}b_{11} & a_{22}b_{12} \\ a_{12}b_{21} & a_{12}b_{22} & a_{22}b_{21} & a_{22}b_{22} \end{bmatrix}$$