

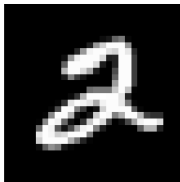
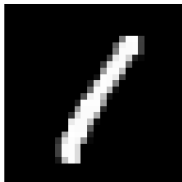
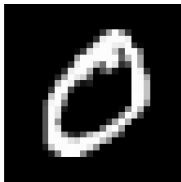
# Principal component analysis

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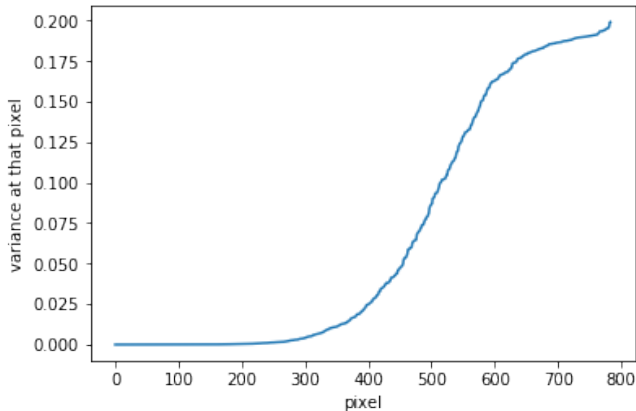
# Dimensionality reduction

Why remove some of the features?

- Save storage and computation time.
- Reduce some redundancy in the data.
- Remove noises in the data.



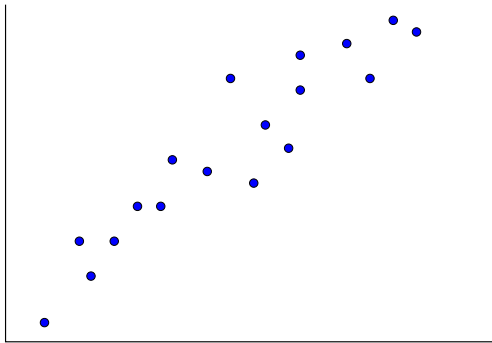
# MNIST example



First 300 pixels with the lowest variance are undesirable features.

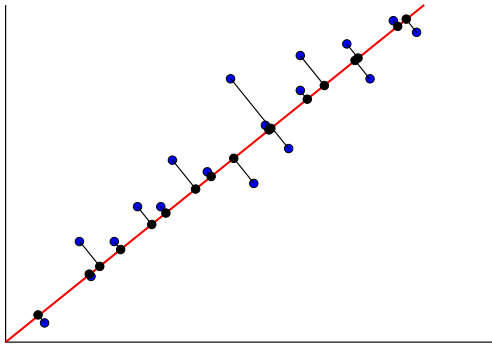
## A simple case

Suppose we want to reduce from 2D data to 1D.



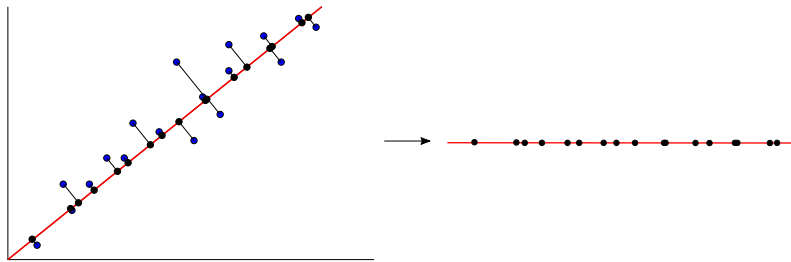
## A simple case

Suppose we want to reduce from 2D data to 1D.



Make **projections** on this line.

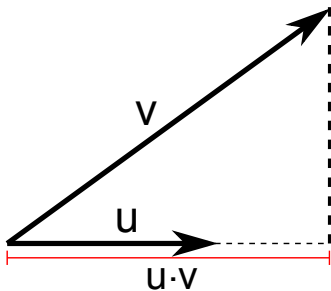
# From 2D to 1D



The red line becomes the 1D axis.

# Vector Projection

If we want to **project** a vector  $v$  in a direction of a **unit vector**  $u$ ,



then the length of projection is  $u \cdot v$ .

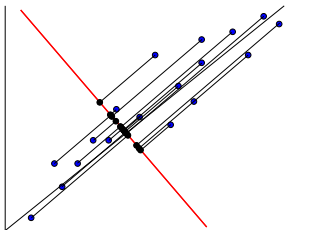
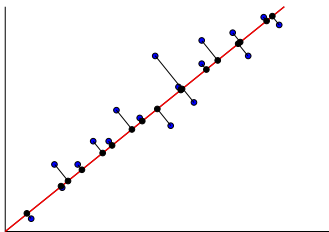
## Examples

What is the projection of  $v = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$  in the following directions?

- The  $x$  axis.
- The direction of  $u = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$ .



# Comparison between two directions



Which red line is better?

# The best direction

**Normalized** data with  $d$  variables.

$$v_1, v_2, \dots, v_n \in \mathbb{R}^d$$

# The best direction

**Normalized** data with  $d$  variables.

$$v_1, v_2, \dots, v_n \in \mathbb{R}^d$$

The goal is to find the unit vector  $u$  that maximizes the variance in the direction of  $u$  i.e. the variance of

$$v_1 \cdot u, v_2 \cdot u, \dots, v_n \cdot u$$

How can we find such  $u$ ?

Answer: Look at the **covariance matrix**  $\Sigma$ .

# Covariance matrix

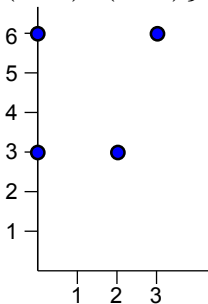
Let  $X_1, X_2, \dots, X_d$  be the **variable vectors**.

The covariance matrix is a  $d \times d$  matrix defined by

$$\Sigma = \begin{bmatrix} \text{Cov}(X_1, X_1) & \text{Cov}(X_1, X_2) & \dots & \text{Cov}(X_1, X_d) \\ \text{Cov}(X_2, X_1) & \text{Cov}(X_2, X_2) & \dots & \text{Cov}(X_2, X_d) \\ \vdots & \vdots & \ddots & \vdots \\ \text{Cov}(X_d, X_1) & \text{Cov}(X_d, X_2) & \dots & \text{Cov}(X_d, X_d) \end{bmatrix}$$

## Example

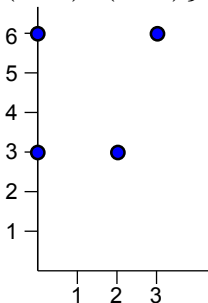
$$D = \{(0, 3), (2, 3), (3, 6), (0, 6)\}.$$



**Answer:**  $X_1 =$  ,  $X_2 =$

## Example

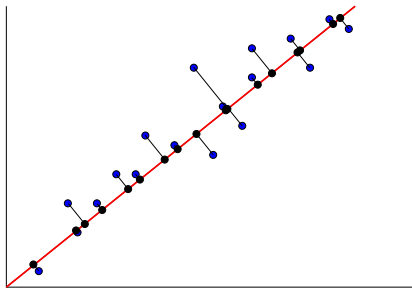
$$D = \{(0, 3), (2, 3), (3, 6), (0, 6)\}.$$



**Answer:**  $X_1 =$  ,  $X_2 =$

$$\Sigma = \begin{bmatrix} \text{Var}(X_1) & \text{Cov}(X_1, X_2) \\ \text{Cov}(X_2, X_1) & \text{Var}(X_2) \end{bmatrix} = \begin{bmatrix} 2.25 & 0.5 \\ 0.5 & 3 \end{bmatrix}.$$

# Finding the best direction $u$



Data:  $v_1, v_2, \dots, v_n$

Projections on  $u$ :  $(v_1 \cdot u, v_2 \cdot u, \dots, v_n \cdot u)$

$$\text{Var}(v_1 \cdot u, \dots, v_n \cdot u) = u^T \Sigma u.$$

## Example

The data  $D = \{(0, 3), (2, 3), (3, 6), (0, 6)\}$  has the covariance matrix

$$\Sigma = \begin{pmatrix} 2.25 & 0.5 \\ 0.5 & 3 \end{pmatrix}, \quad u = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

The variance of the projections on  $u$  is



# Spectral decomposition

**Fact:** Any **symmetric matrix**  $\Sigma$  can be decomposed as

$$\Sigma = \underbrace{\begin{pmatrix} \uparrow & \uparrow & & \uparrow \\ u_1 & u_2 & \dots & u_d \\ \downarrow & \downarrow & & \downarrow \end{pmatrix}}_{U^T} \underbrace{\begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_d \end{pmatrix}}_{\Lambda} \underbrace{\begin{pmatrix} \leftarrow & u_1 & \rightarrow \\ \leftarrow & u_2 & \rightarrow \\ & \vdots & \\ \leftarrow & u_d & \rightarrow \end{pmatrix}}_U$$

where

- $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_d$  are the **eigenvalues**.
- $u_1, u_2, \dots, u_d$  are the **eigenvectors** of length  $d$ .
- $u_1, u_2, \dots, u_d$  are **orthogonal unit vectors**.

# Eigenvectors

**Fact:** Any **symmetric matrix**  $\Sigma$  can be decomposed as

$$\Sigma = \underbrace{\begin{pmatrix} \uparrow & \uparrow & & \uparrow \\ | & | & & | \\ u_1 & u_2 & \dots & u_d \\ | & | & & | \\ \downarrow & \downarrow & & \downarrow \end{pmatrix}}_{U^T} \underbrace{\begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_d \end{pmatrix}}_{\Lambda} \underbrace{\begin{pmatrix} \leftarrow & u_1 & \rightarrow \\ \leftarrow & u_2 & \rightarrow \\ & \vdots & \\ \leftarrow & u_d & \rightarrow \end{pmatrix}}_U$$

The eigenvectors  $u_1, u_2, \dots, u_d$  are:

- unit vectors
- perpendicular to each other.

## Example

Suppose that data  $v_1, v_2, \dots, v_n$  has covariance matrix  $\Sigma$ .

Compute  $\text{Var}(v_1 \cdot u_1, v_2 \cdot u_1, \dots, v_n \cdot u_1)$ .

# Example

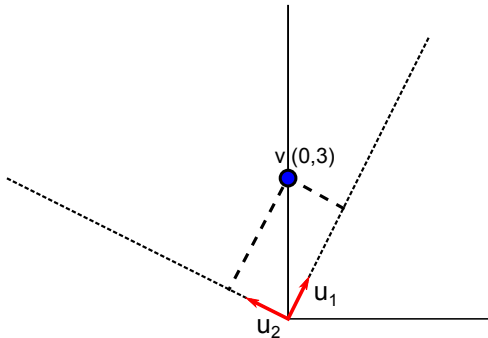
## Example

$$\Sigma = \begin{pmatrix} 2.25 & 0.5 \\ 0.5 & 3 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{pmatrix} \begin{pmatrix} 3.25 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ -\frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{pmatrix}$$

- Eigenvalues:
- Eigenvectors:

# Matrix as a transformation

$$\begin{aligned}\Sigma &= \begin{pmatrix} 2.25 & 0.5 \\ 0.5 & 3 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{pmatrix} \begin{pmatrix} 3.25 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ -\frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{pmatrix} \\ &= \begin{pmatrix} \cos(63) & -\sin(63) \\ \sin(63) & \cos(63) \end{pmatrix} \begin{pmatrix} 3.25 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} \cos(63) & \sin(63) \\ -\sin(63) & \cos(63) \end{pmatrix}\end{aligned}$$



The point  $v = (0, 3)$  in the new axis is

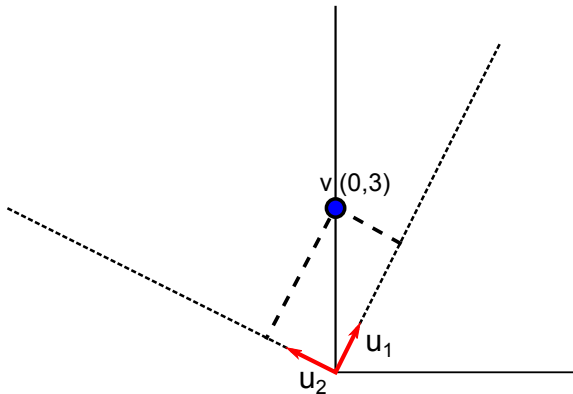
$$(v \cdot u_1, v \cdot u_2)$$

where

$$v \cdot u_1 =$$

$$v \cdot u_2 =$$

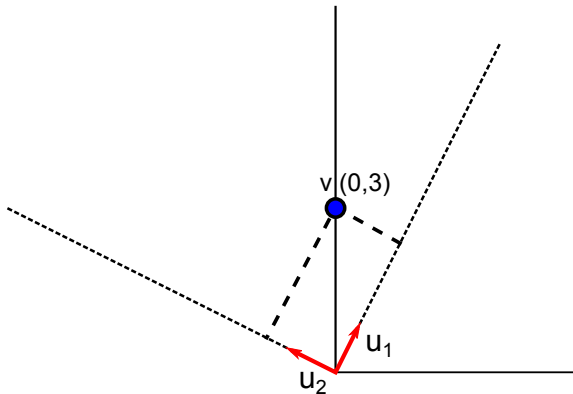
# Rotations preserve the length



**Observation:**  $\|v\| = \|(v \cdot u_1, v \cdot u_2)\|$



# Rotations preserve the length



**Observation:**  $\|v\| = \|(v \cdot u_1, v \cdot u_2)\|$

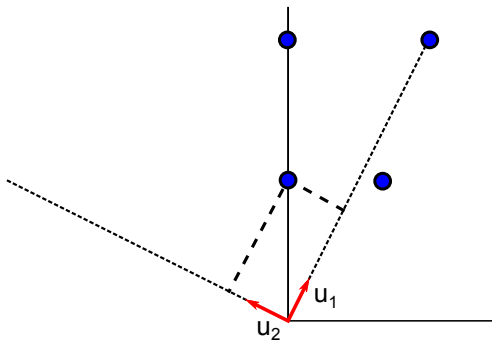
In higher dimension,  $\|Uv\| = \|v\|$ .

**The highest variance is  $\lambda_1$**

$$\text{Var}(v_1 \cdot u, v_2 \cdot u, \dots, v_n \cdot u)$$

# Finding the best direction $u$

## Example



- Variance = 3.25 in the direction of  $u_1$ .
- Variance = 2 in the direction of  $u_2$ .

# Spectral decomposition

$$\Sigma = \begin{pmatrix} \uparrow & \uparrow & & \uparrow \\ u_1 & u_2 & \dots & u_d \\ \downarrow & \downarrow & & \downarrow \end{pmatrix} \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_d \end{pmatrix} \begin{pmatrix} \leftarrow u_1 \rightarrow \\ \leftarrow u_2 \rightarrow \\ \vdots \\ \leftarrow u_d \rightarrow \end{pmatrix}$$

- The second best direction is  $u_2$  with associated variance  $\lambda_2$ .
- The third best direction is  $u_3$  with associated variance  $\lambda_3$ .
- and so on...

# Principal component analysis

Let  $u \in \mathbb{R}^d$  be a data point.

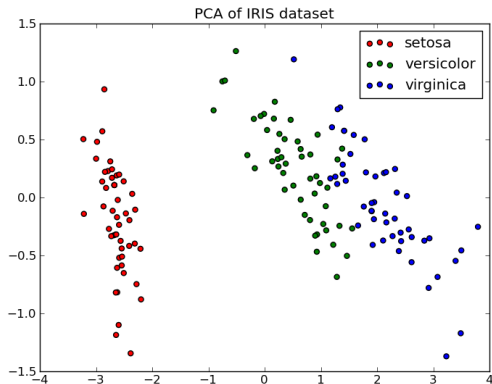
Principal axes ( $k < d$ ):

$$u_1, u_2, \dots, u_k$$

The PCA of  $u$  is

$$(u \cdot u_1, u \cdot u_2, \dots, u \cdot u_k) \in \mathbb{R}^k.$$

# PCA of iris flowers



$$\lambda_1 = 4.23, \quad \lambda_2 = 0.24$$
$$u_1 = (0.36, -0.08, 0.86, 0.36)$$
$$u_2 = (0.66, 0.73, -0.17, -0.07)$$

Three species of iris

- Setosa
- Versicolor
- Virginica

Four variables

- $x_1$ : sepal length
- $x_2$ : sepal width
- $x_3$ : petal length
- $x_4$ : petal width

# Reconstruction

Eigenvectors:  $u_1, u_2, \dots, u_d$ .

- $k$  principal axes:  $u_1, u_2, \dots, u_k \in \mathbb{R}^d$ .
- In these axes, the coordinate of the PCA of a point  $u$  is

$$(u \cdot u_1, u \cdot u_2, \dots, u \cdot u_k) \in \mathbb{R}^k.$$



# Reconstruction

Eigenvectors:  $u_1, u_2, \dots, u_d$ .

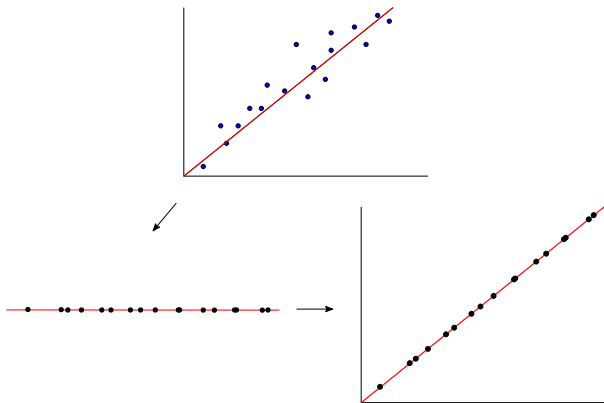
- $k$  principal axes:  $u_1, u_2, \dots, u_k \in \mathbb{R}^d$ .
- In these axes, the coordinate of the PCA of a point  $u$  is

$$(u \cdot u_1, u \cdot u_2, \dots, u \cdot u_k) \in \mathbb{R}^k.$$

Reverse this point back to the original coordinate using

$$(u \cdot u_1)u_1 + (u \cdot u_2)u_2 + \dots + (u \cdot u_k)u_k \in \mathbb{R}^d.$$

# Reconstruction



The reconstructions are the black points on the red line. We see that there is some information loss in the process.

# Reconstruction of MNIST



Reconstruct this original image  $x$  from its PCA projection to  $k$  dimensions.

$k = 200$



$k = 150$



$k = 100$



$k = 50$

