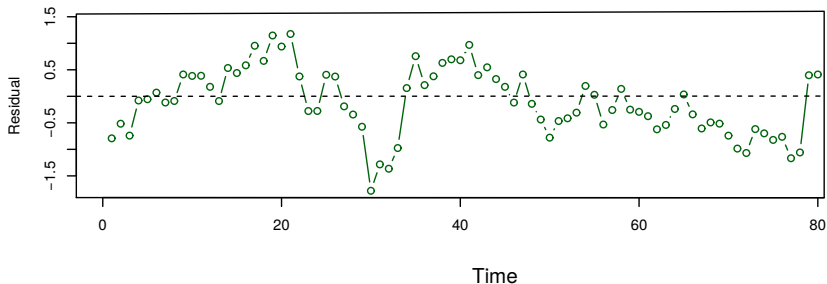


Time Series Analysis 1

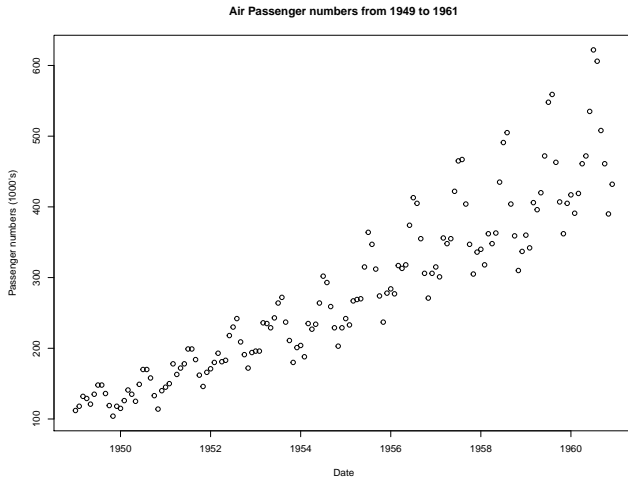
DS351

Why can't we use linear regression



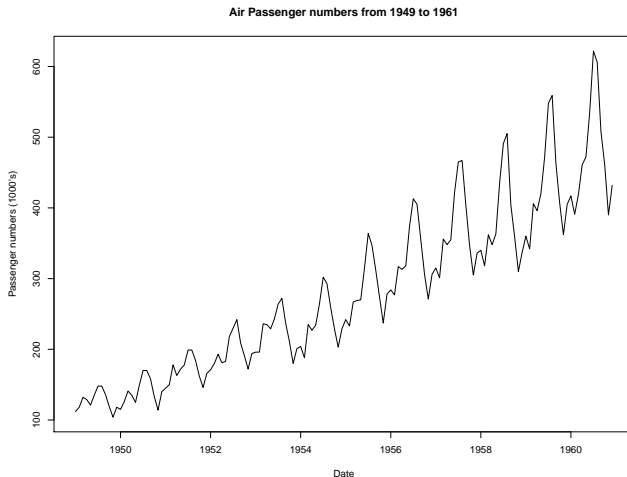
Error terms are correlated.

Why can't we use linear regression



Variance of the errors increases with time.

Why can't we use linear regression




Seasonality, which implies non-linearity!

Analyzing Time Series

Notations

Time series is often denoted by


$$\dots \quad Y_{t-2} \quad Y_{t-1} \quad Y_t \quad Y_{t+1} \quad Y_{t+2} \quad \dots$$

 time index

Notations

Time series is often denoted by

$$\dots \quad Y_{t-2} \quad Y_{t-1} \quad Y_t \quad Y_{t+1} \quad Y_{t+2} \quad \dots$$

 time index

Lag is an amount of time passed.

Example: lag 5 of Y_t is y_{t-5} .

Stationarity

A time series is **stationary** if **its statistical properties do not change over time**.

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What are statistical properties?

- ▶ mean
- ▶ variance
- ▶ covariance
- ▶ etc.

Stationarity

More precise definition:

A time series is stationary if for all lags k , the distribution of $Y_t, Y_{t-1}, \dots, Y_{t-k}$ does not depend on k .

Stationarity

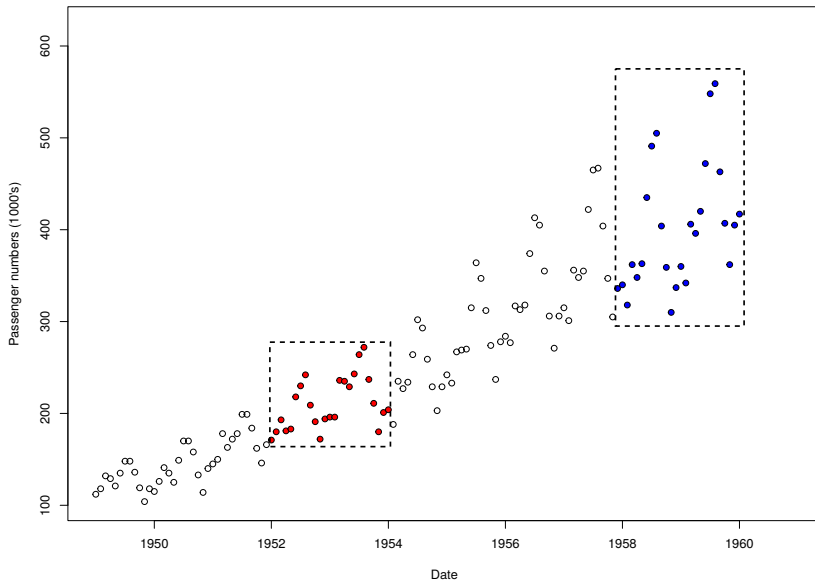
More precise definition:

A time series is stationary if for all lags k , the distribution of $Y_t, Y_{t-1}, \dots, Y_{t-k}$ does not depend on k .

- ▶ we usually don't know the distribution of these variables.
- ▶ It is usually easier to detect that a time series is not stationary by looking at its plot.

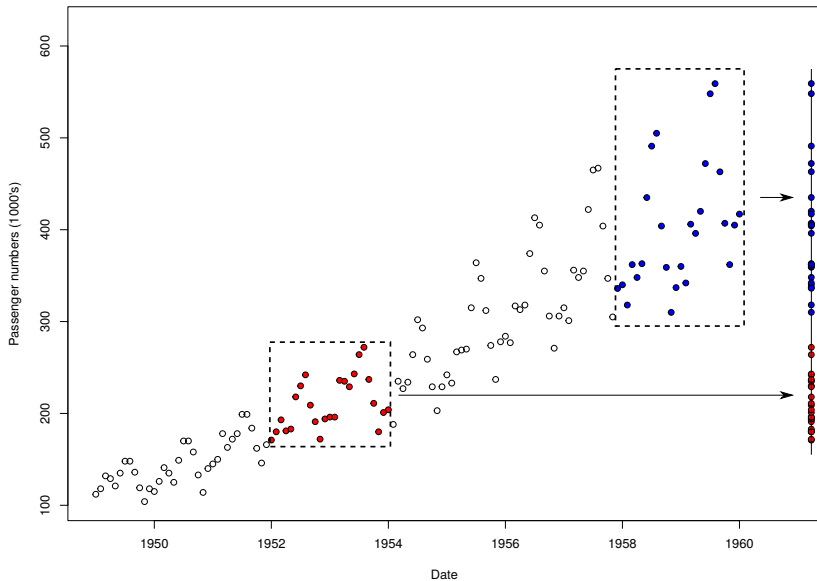
Example

Air Passenger numbers from 1949 to 1961

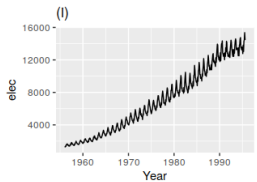
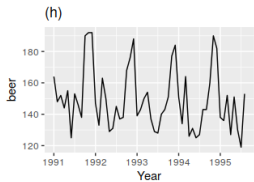
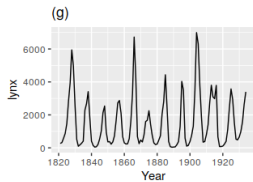
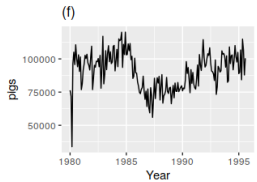
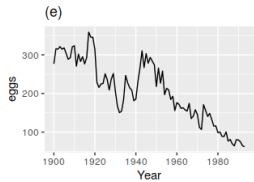
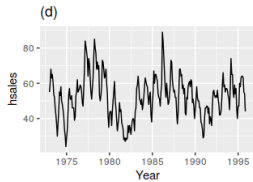
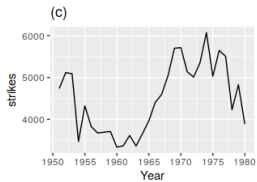
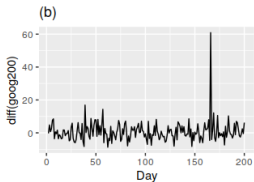
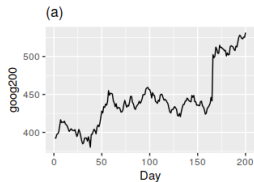


Example

Air Passenger numbers from 1949 to 1961



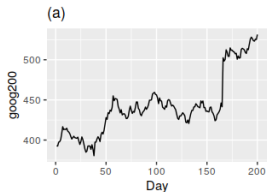
Examples



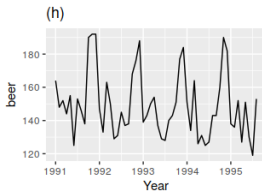
Find stationarity from the plot

In summary, a time series is **not** stationary if there is

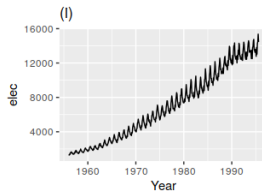
- ▶ trend
- ▶ seasonality
- ▶ increase/decrease in variance



has trend



has seasonality



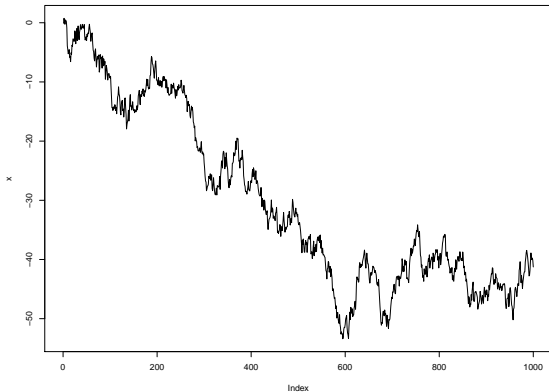
has both

Random walk

Random walk is a simple non-stationary process.

$$y_t = y_{t-1} + \epsilon_t.$$

where ϵ_t is a *white noise* with zero mean and variance σ^2 e.g.
 $\epsilon_t \sim \mathcal{N}(0, \sigma^2)$.



Differencing

From the random walk

$$y_t = y_{t-1} + \epsilon_t,$$

which is not stationary, we can transform it into

$$z_t = y_t - y_{t-1} = \epsilon_t.$$

Now, z_t is stationary.

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Now, z_t is stationary.

In general, we try to make a stationary time series by transforming $z_t = y_t - y_{t-1}$. This is known as **differencing**.

Second-order differencing

Second-order differencing

If differencing is not enough to make a time series stationary, we do it twice.

$$z'_t = z_t - z_{t-1} = z_t - 2z_{t-1} + z_{t-2}.$$

Second-order differencing

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Seasonal differencing

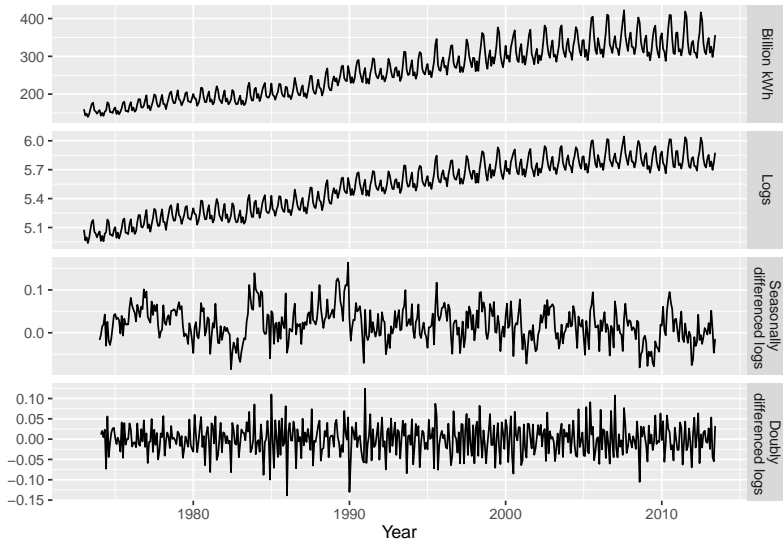
To remove seasonality, we take the difference between an observation and the previous observation from the same season.

$$z_t = y_t - y_{t-m},$$

where m is the length of seasonality e.g. $m = 12$ for annual seasonality.

Example

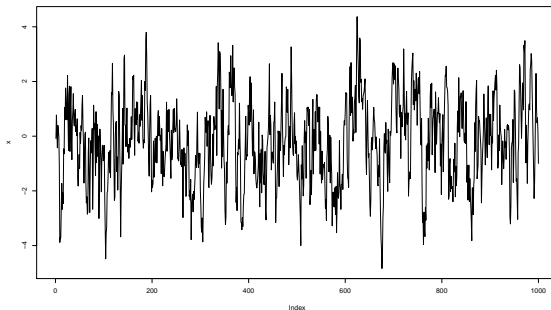
Monthly US net electricity generation



Unit root

The random walk is an example of a time series that has a **unit root**: the value of α in $y_t = \alpha y_{t-1} + \epsilon_t$ is $\alpha = 1$.

In general, a **time series is non-stationary if it has a unit root**.



$$y_t = 0.8y_{t-1} + \epsilon_t$$

Kwiatkowski-Phillips-Schmidt-Shin (KPSS) test

This is a test to see if we want differencing.

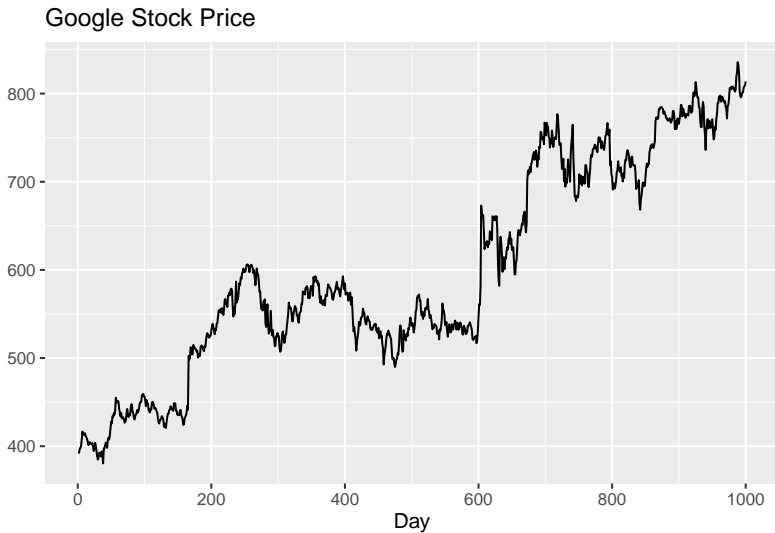
KPSS test

$H_0 : y_t$ is stationary

$H_a : y_t$ has a unit root

If H_0 is rejected (p -value < 0.05) then differencing y_t is required.

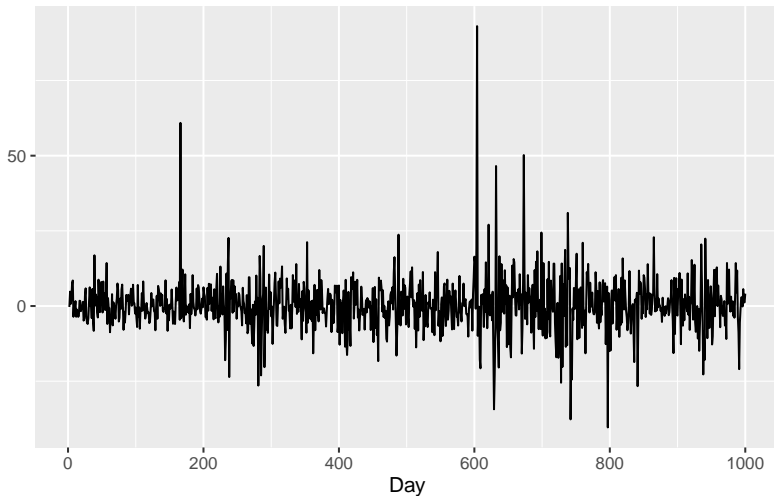
Example



$p\text{-value} < 0.01$

Example

Google Stock Price (first differencing)



$p\text{-value} > 0.1$

Autocorrelation

Autocorrelation measures the linear relationship between a time series and its *lagged values*.

Y_t		y_1	\dots	y_{k+1}	\dots	y_t	\dots	y_T	
Y_{t-k}			\rightarrow	y_1	\dots	y_{t-k}	\dots	y_{T-k}	$\dots \rightarrow$

Autocorrelation

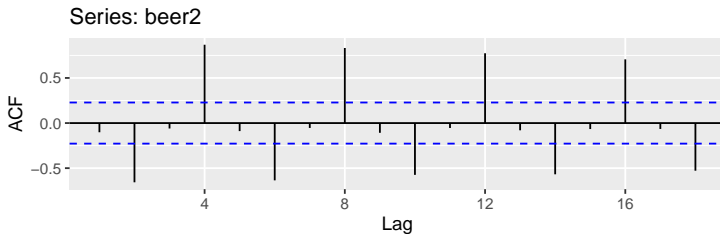
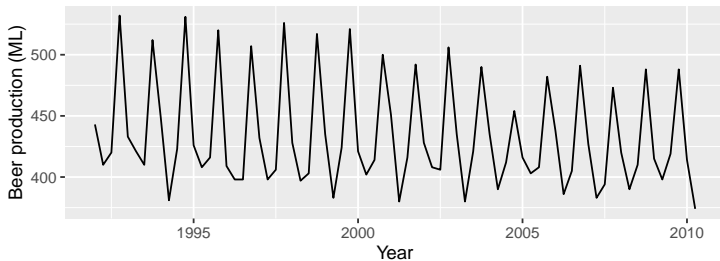
Autocorrelation measures the linear relationship between a time series and its *lagged values*.

\mathbf{Y}_t		y_1	\dots	y_{k+1}	\dots	y_t	\dots	y_T	
\mathbf{Y}_{t-k}			\rightarrow	y_1	\dots	y_{t-k}	\dots	y_{T-k}	$\dots \rightarrow$

The autocorrelation at lag k , r_k can be written as

$$r_k = \frac{\sum_{t=k+1}^T (y_t - \bar{y})(y_{t-k} - \bar{y})}{\sum_{t=1}^T (y_t - \bar{y})^2}$$

Beer production

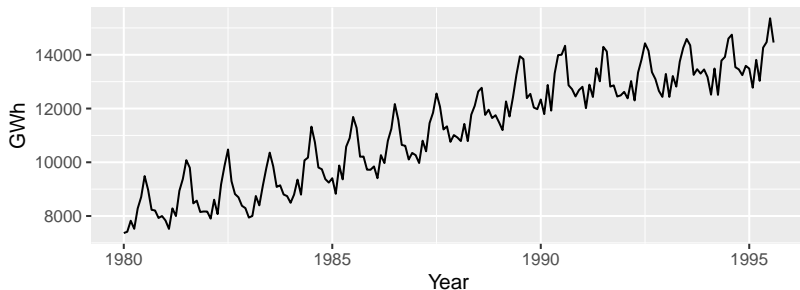


The values beyond blue lines are significantly different than zero.

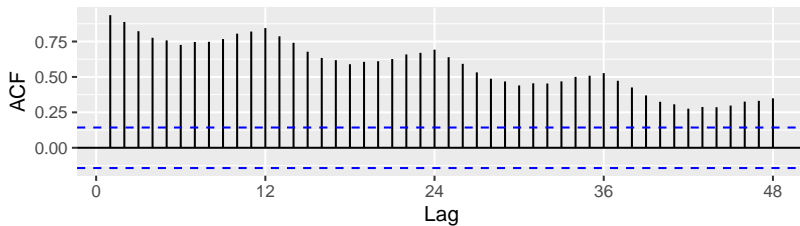
Trend and seasonality in ACF plots

- ▶ When data have a trend, the autocorrelations for small lags tend to be large and positive because observations nearby in time are also nearby in size. So the ACF of trended time series tend to have positive values that slowly decrease as the lags increase.
- ▶ When data are seasonal, the autocorrelations will be larger for the seasonal lags (at multiples of the seasonal frequency) than for other lags.

Australian electricity demand



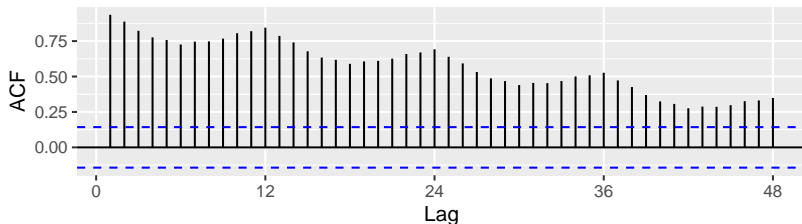
Series: aelec



Partial autocorrelation function (PACF)

Partial autocorrelation function measures the part of the correlation that has not been explained by the earlier lags.

Series: aelec



Series: aelec

