Workshop: Discrete PID control ME493 Drone Control

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DC motor control

1) Write down the EOM. Use parameters as given in parameters.py

2) Implement a PID controller for setting a desired speed.

3) Implement a PID controller for setting a desired angle.

4) Can you implement a cascaded PID controller for setting a desired angle, with fast inner and slow outer loop?

2D Drone control (seesaw)

1) Write down the EOM. Ballpark the parameters.

2) Implement a PID controller for setting a desired speed.

3) Implement a PID controller for setting a desired angle.

4) Can you implement a cascaded PID controller for setting a desired angle, with fast inner and slow outer loop?