Trash

Contents

1

1 Einleitung

External DLA beschreibt einen stochastischen Prozess, welcher zumindest in ähnlicher Form in natürlichen Prozessen beobachtbar ist. Er ähnelt zum Beispiel der fraktalen Gestalt eines sich kreisförmig ausbreitenden Risses einer Glasscheibe, oder eines Risses eines Kristallfluids wie in LCD Displays in alten Autoradios (siehe Fotos). Er kann auch in Schneeflocken oder in elektrostatischen Anhaftungen an Metallen beobachtet werden. Die Formalisierung solcher Prozesse ist sehr aktuell und die sehr konstruktive Definition erlaubten bisher nur mühsame Folgerungen über Struktur und Verhalten des Prozesses. Wir werden uns Modelle auf $\mathbb{Z}^2$, sowie auf anderen Graphen, darunter auch fraktale Graphen, anschauen, und außerdem versuchen, eine Approximation der bisherigen Definition zu finden, die grundsätzlich handlicher ist und auf einfachere Weise zu Erkenntnissen führt. Wir werden außerdem diese Arbeit mit einigen Python Simulationen begleiten. Der Code ist frei verfügbar auf Github.

2 harmonic measure

For the following we are interested in letting start the random walk "from infinity". Thus we are looking for someting like $\lim_{|x|\to\infty} h_A(x,y)$ for $y \in A$. This is solved the following way. Define the *escape probability* from A

$$e_A(x) := \mathbb{1}\{x \in A\}\mathbb{P}(T_A^+ = \infty), \quad x \in \mathbb{Z}^2$$

and the *capacity* of A

$$cap(A) := \sum_{x\in\mathbb{Z}^2} e_A(x).$$

Note that this sum is finite since A is finite. Now we can define the *harmonic measure* (from infinity) of A as

$$h_A(x) := \frac{e_A(x)}{cap(A)}, \quad x \in \mathbb{Z}^2.$$

The idea here is to use the symmetry of random walks and to not look the probability of coming from infinity to hit A, but actually starting in A and stating the probability to escape A, which means to never hit A again and therefore necessarily move away to infinity. We finally define the harmonic measure $h = (h_A)_{A\in\mathcal{P}_f}$.

Lemma 2.0.1. Does something like $\lim_{|x|\to\infty} h_A(x,y)$ exist and is it equal to $h_A(y)$ for all $y \in A$?

3 A naive attempt

We will look closer at the thought of the last Remark and find a reason, why this way of choosing a random line intersecting $K_0 \in \mathcal{K}^2$ is maybe not the best idea.

Definition 3.0.1. Let $\gamma \sim \mathcal{U}([0, \pi))$ and for $\alpha \in [0, \pi)$ define $y_\alpha \sim \mathcal{U}(M_\alpha(K_0))$ where

$$M_\alpha(K) := \begin{cases} \{h \in \mathbb{R} \mid L_{\binom{0}{h}, \binom{1}{0}} \cap K \neq \emptyset\}, & \text{if } \alpha = 0 \\ \{h \in \mathbb{R} \mid L_{\binom{h}{0}, \binom{\cos(\alpha)}{\sin(\alpha)}} \cap K \neq \emptyset\}, & \text{if } \alpha \in (0, \pi). \end{cases}$$

For $K \in \mathcal{K}^2$ define

$$\nu_{K_0}(K) := \int_{[0,\pi)} \mathbb{P}_{y_\alpha}(M_\alpha(K \cap K_0)) \mathbb{P}_\gamma(d\alpha).$$

Interpretation: $\nu_{K_0}(K)$ is the probability that a random line which intersects with K_0 also intersects with $K_0 \cap K$.

Conjecture: $\nu_{K_0}(K) = \frac{\mu_1(K \cap K_0)}{\mu_1(K_0)}$ for $K, K_0 \in \mathcal{K}^2$ (μ_1 Gradenmaß).

Remark 3.0.1. Note that $M_\alpha(K) \in \mathcal{K}^1$ for all $K \in \mathcal{K}^2$ and $\alpha \in [0, \pi)$ (Proof). Proof rotation symmetry.

Example 3.0.1. Let $0 < r < R$ and $K_0 := B_R$ and analogously $K := B_r$. Note that $K, K_0 \in \mathcal{K}^2$ and $K \subset K_0$. Then by trigonometry we get

$$M_\alpha(K_0) = \begin{cases} [-R, R], & \text{if } \alpha = 0, \\ [-\frac{R}{\sin(\alpha)}, \frac{R}{\sin(\alpha)}], & \text{if } \alpha \in (0, \pi) \end{cases}$$

and analogously $M_\alpha(K)$. Finally we get

$$\begin{aligned} \nu_{K_0}(K) &= \int_{[0,\pi)} \mathbb{P}_{y_\alpha}(M_\alpha(K \cap \mathcal{K}_0)) \mathbb{P}_\gamma(d\alpha) \\ &= \int_{[0,\pi)} \frac{\lambda(M_\alpha(K))}{\lambda(M_\alpha(K_0))} \frac{d\alpha}{\lambda([0,\pi))} \\ &= \frac{1}{\pi} \int_{[0,\pi)} \frac{2r}{2R} d\alpha = \frac{1}{\pi} \frac{r}{R} \int_{[0,\pi)} 1 d\alpha = \frac{r}{R} \end{aligned}$$

This result makes sense considering the symmetries of the balls B_r and B_R and the relation of their diameters.

Example 3.0.2. Let $0 < r \leq \frac{R}{\sqrt{2}}$, $K_0 := B_R$ as above and $K := [-r, r]^2$. Note that $K, K_0 \in \mathcal{K}^2$ and $K \subset K_0$. We get

$$M_\alpha(K) = \begin{cases} [-r, r], & \text{if } \alpha \in \{0, \frac{\pi}{2}\}, \\ [-r(1 + \frac{1}{\tan(\alpha)}), r(1 + \frac{1}{\tan(\alpha)})], & \text{if } \alpha \in (0, \pi) \setminus \{\frac{\pi}{2}\} \end{cases}$$

and finally

$$\nu_{K_0}(K) = \int_{[0,\pi)} \mathbb{P}_{y_\alpha}(M_\alpha(K))\mathbb{P}_\gamma(d\alpha)$$

$$= \frac{1}{\pi}\int_{(0,\pi)\setminus\{\frac{\pi}{2}\}} \frac{r}{R}(sin(\alpha) + cos(\alpha))d\alpha$$

$$= \frac{r}{R\pi}[-cos(\alpha) + sin(\alpha)]_0^\pi = \frac{r}{R\pi}(1+1) = \frac{2r}{R\pi}$$

Example 3.0.3. Let $K_0 := B_R$ and $K := [-r, r]$ for some $0 < r \le R$. Note $K_0, K \in \mathcal{K}^2$ and $K \subset K_0$. Then

$$M_\alpha(K) = \begin{cases} \{0\}, & \alpha = 0, \\ [-r, r], & \alpha \in (0, \pi). \end{cases}$$

and finally

$$\nu_{K_0}(K) = \frac{1}{\pi}\int_{(0,\pi)} \frac{r}{R}sin(\alpha)d\alpha = \frac{2r}{R\pi}.$$

Remark 3.0.2. Only fair if K_0 symmetric.

Remark 3.0.3. $A_K \in \mathcal{A}(d, q)$ for $K \in \mathcal{K}^d$?

$\mathbb{N} = \{1, 2, 3, \dots\}$,   the set of natural numbers (without 0)

$\mathbb{N}_0 = \mathbb{N} \cup \{0\}$

$\mathbb{Z} = \{\dots, -3, -2, -1, 0, 1, 2, 3, \dots\}$,   the set of whole numbers

$\mathbb{Q} = \{\frac{a}{b} \mid a, b \in \mathbb{Z}, b \ne 0\}$,   the set of rational numbers

$\mathbb{R} = \{\lim_{n\to\infty} x_n \mid (x_n)_n \subset \mathbb{Q} \text{ converging sequence }\}$,   the set of real numbers

4 Integral Geometry

4.0.1 Intrinsic Volumes

A useful concept to measure intrinsic geometrical properties of Borel-sets $K \subset \mathbb{R}^d$ are *intrinsic volumes*. We define the d-th intrinsic volume of K as $V_d(K) := \lambda_d(K)$. Furthermore define $S_{d-1}(K)$ to be the *surface area* of $V_d(K)$, which is formally defined as the Hausdorff-measure of ∂K. For the following theorem define

$$\kappa_d := V_d(B_d) \text{ for } d > 0, \text{ and } \kappa_0 := 1$$

where we can calculate $V_d(B_d) = \frac{\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2}+1)}$ with the *Gamma function* $\Gamma(x) := \int_0^\infty t^{x-1} e^{-t} dt$, $x > 0$.

Lemma 4.0.1. If $K \subset \mathcal{K}^d$, then S_{d-1} is equal to the *outer Minkowski content*, i.e.

$$S_{d-1}(K) = M_{d-1}(K) := \lim_{\varepsilon \searrow 0} \frac{1}{\varepsilon} (V_d(K_{\oplus\varepsilon}) - V_d(K)),$$

where $K_{\oplus\varepsilon} = \{x \in \mathbb{R}^d \mid d(x,K) \leq \varepsilon\}$. It is easy to show, that $K_{\oplus\varepsilon} = K + \varepsilon B_d := \{x + y \in \mathbb{R}^d \mid x \in K, y \in \varepsilon B_d\}$, where $B_d := \{x \in \mathbb{R}^d \mid d(0,x) \leq 1\}$.

Proof. $\qquad\square$

Theorem 4.0.1. (*Steiner Formula*) For $K \in \mathcal{K}^d$ there exist uniquely determined numbers $V_0(K), \ldots, V_d(K) \in \mathbb{R}$, such that for each $\varepsilon \geq 0$

$$V_d(K + \varepsilon B_d) = \sum_{j=0}^d \kappa_{d-j} \varepsilon^{d-j} V_j(K). \tag{4.1}$$

Proof. [2] Theorem 3.32 $\qquad\square$

Definition 4.0.1. $V_0(K), \ldots, V_d(K)$ are called *intrinsic volumes* of K.

Remark 4.0.1. (i) What we get are functions $V_j : \mathcal{K}^d \to \mathbb{R}$ for the j-intrinsic volume V_j. It can be shown that every V_j can be uniquely extended to a function $V_j : \mathcal{R}^d \to \mathbb{R}$, where $\mathcal{R}^d := \{\bigcup_{j=1}^n K_j \subset \mathbb{R}^d \mid n \in \mathbb{N}_0, K_j \in \mathcal{K}^d\}$ ([2] Theorem 4.10).

(ii) The coefficients κ_{d-j} are chosen such that the V_j become independent of the dimension of the underlying space. This means that V_j will assign the same value for K if K is considered to be subset of $\mathbb{R}^d$ or $\mathbb{R}^{\tilde{d}}$ for $d < \tilde{d}$, although the unit balls B_d and $B_{\tilde{d}}$ are different in those two spaces. This is why the V_j are called *intrinsic* volumes.

(iii) For $\varepsilon = 0$ the right side of equation (4.1) reduces to $V_d(K)$ which shows a consistency of the notation.

(iv) With Lemma (4.0.1) and equation (4.1) we get $S_{d-1}(K) = \lim_{\varepsilon \searrow 0} \frac{1}{\varepsilon}(V_d(K+\varepsilon B_d) - V_d(K)) = \kappa_1 V_{d-1}(K) = 2V_{d-1}(K)$, which will be a useful result.

(v) It can be shown that $V_0(\emptyset) = \cdots = V_d(\emptyset) = 0$ and $V_0(K) = 1$ if $K \neq \emptyset$.

4.0.2 Random q-flats

Theorem 4.0.2. (*Crofton formula*) Let $K \in \mathcal{K}^d \setminus \{\emptyset\}$, $k \in \{1, \ldots, d-1\}$ and $j \in \{0, \ldots, k\}$. Then

$$\int_{A(d,k)} V_j(K \cap F)\mu_k(dF) = c_{j,d}^{k,d-k+j} V_{d-k+j}(K), \qquad (4.2)$$

where $c_s^r := \frac{r!\kappa_r}{s!\kappa_s}$ for $s, r \in \mathbb{N}_0$ and $c_{s_1,\ldots,s_k}^{r_1,\ldots,r_k} := \prod_{j=1}^k c_{s_j}^{r_j}$.

Proof. [2] Theorem 4.27 $\qquad\qquad\square$

Definition 4.0.2. Let $K_0 \in \mathcal{K}^d$ with $V_d(K_0) > 0$. Let $q \in \{0, \ldots, d-1\}$. A $A(d,q)$-valued random element X_q with distribution $\frac{\mu_q(\cdot \cap A_{K_0})}{\mu_q(A_{K_0})}$ is called an *isotropic random q-flat* through K_0.

Lemma 4.0.2. Let $K, K_0 \in \mathcal{K}^d$ with $K \subset K_0$ and $V_d(K_0) > 0$. Let $q \in \{0, \ldots, d-1\}$ and X_q be an isotropic random q-flat through K_0. Then

$$\mathbb{P}(X_q \cap K \neq \emptyset) = \frac{V_{d-q}(K)}{V_{d-q}(K_0)}. \qquad (4.3)$$

Proof. We directly get

$$\mathbb{P}(X_q \cap K \neq \emptyset) = \mathbb{P}(X_q \in A_K) = \frac{\mu_q(A_K \cap A_{K_0})}{\mu_q(A_{K_0})}$$

$$= \frac{\mu_q(A_K)}{\mu_q(A_{K_0})} = \frac{\int_{A(d,q)} \mathbb{1}\{F \cap K \neq \emptyset\}\mu_q(dF)}{\int_{A(d,q)} \mathbb{1}\{F \cap K_0 \neq \emptyset\}\mu_q(dF)}$$

$$= \frac{\int_{A(d,q)} V_0(F \cap K)\mu_q(dF)}{\int_{A(d,q)} V_0(F \cap K_0)\mu_q(dF)} \overset{Crofton}{=} \frac{c_{0,d}^{q,d-q} V_{d-q}(K)}{c_{0,d}^{q,d-q} V_{d-q}(K_0)}$$

$$= \frac{V_{d-q}(K)}{V_{d-q}(K_0)}.$$

$$\square$$

Remark 4.0.2. Taking the situation from the last Lemma, with Remark (4.0.1) (iv) and $q = 1$ we get

$$\mathbb{P}(X_1 \cap K \neq \emptyset) = \frac{V_{d-1}(K)}{V_{d-1}(K_0)} = \frac{S_{d-1}(K)}{S_{d-1}(K_0)}.$$

For $d = 2$ we basically can interpretate, that the propability of a line X_1 which intersects K_0 also interesects K can be calculated by deviding the boundary length of K by the boundary length of K_0. This seems to be a convenient result although it may not be completely intuitive.

4.1 Constructions in the real plane

From now on consider the case $d = 2$ and $q = 1$ which is looking at lines in the real plane. For some $K_0 \in \mathcal{K}^2$ we will be interested in choosing a random line out of all lines which intersect with K_0. We have looked at exactly this situation in Lemma (4.0.2). We will look at some examples in this section, argue about why the measure μ_1 is senseful to be used and what parametrisations on lines could be helpful to actually calculate realisations for random lines equivalently to μ_1. In the next chapter we'll define an Incremental Aggregate where we'll use our insights here to realise random lines. Note that every line $g \in \mathcal{G}$ has a form $g = g_{a,b} := \{a + tb \in \mathbb{R}^2 \mid t \in \mathbb{R}^2\}$ for some vectors $a, b \in \mathbb{R}^2$ with $b \neq (0, 0)$. From now on for $r > 0$ and $x \in \mathbb{R}^2$ define $B_r(x) := \{y \in R^2 \mid d(x, y) \leq r\}$ and $B_r := B_r(0)$. Let furthermore g be an isotropic random 1-flat through K_0. Recap the definition of κ_j, which is the j-dimensional Lebesgue measure of the j-dimensional unit ball, for our use here $\kappa_0 = 1$, $\kappa_1 = 2$ and $\kappa_2 = \pi$. For the next examples we always use Lemma (4.0.2) and Remark (4.0.2) (iii) and choose $K, K_0 \in \mathcal{K}^2$ with $K \subset K_0$.

Example 4.1.1. Let $0 < r < R$, $K_0 := B_R$ and $K := B_r$. We get

$$\mathbb{P}(g \cap B_r \neq \emptyset) = \frac{V_1(B_r)}{V_1(B_R)} = \frac{\frac{1}{2}S_1(B_r)}{\frac{1}{2}S_1(B_R)} = \frac{2\pi r}{2\pi R} = \frac{r}{R}.$$

Example 4.1.2. Let $0 < r \leq \frac{R}{\sqrt{2}}$, $K_0 := B_R$ and $K := [-r, r]^2$. We get

$$\mathbb{P}(g \cap [-r, r]^2 \neq \emptyset) = \frac{S_1([-r, r]^2)}{S_1(B_R)} = \frac{8r}{2\pi R} = \frac{4}{\pi} \frac{r}{R}.$$

Example 4.1.3. Let $0 < r \leq R$, $K_0 := B_R$ and $K := [-r, r]$. We get

$$\mathbb{P}(g \cap [-r, r] \neq \emptyset) = \frac{V_1([-r, r])}{V_1(B_R)} = \frac{\lambda_1([-r, r])}{\frac{1}{2}S_1(B_R)} = \frac{2r}{\pi R} = \frac{2}{\pi} \frac{r}{R}.$$

Example 4.1.4. Let $K_0 := B_1$ and $K := T_a$ a equilateral triangle with side length $a = \frac{\pi}{3}$ centered at $(0, 0)$. We get

$$\mathbb{P}(g \cap T_a \neq \emptyset) = \frac{V_1(T_a)}{V_1(B_1)} = \frac{3a}{2\pi} = \frac{1}{2}.$$

Remark 4.1.1. We still haven't answered why μ_1 is a senseful measure to be used to calculate probabilities for situations like in the last examples. And yet it is not obvious how to actually simulate a realisation of a random line with μ_1. For now we can calculate the probability that a random line g hits some convex set K in the base set K_0. What we need is some form of parametrisation of this random choosing so we can actually end up for example with one angle defining the rotation of g to the x-axis and a real number defining the interesection value of g with the y-axis. If we wouldn't know about μ_1 for now, we could choose an angle and a real number intuitively the following way: Choose an angle α uniformly in $[0, \pi)$. Then consider all lines in the plane which are rotated

counterclockwise by α starting at the x-axis and which intersect K. Take the set of intersection values of these lines with the y-axis and choose a value y_0 uniformly out of it, so finally α and y_0 define a unique line and we have a realisation of a random line which interesects K. This procedure may sound balanced, but it is only if K_0 is strongly symmetric. At this point it is important to remember what exactly we want. Out of all lines which intersect K_0 we are looking for the probability that a random chosen line intersects K and finally calculate a realisation. Imagine $K_0 = [-a, a] \times [-b, b]$ with $a < b$. Then it makes sense that there are "more" lines through the longer side $[-b, b]$ than through the shorter side $[-a, a]$. If we now choose the angle α uniformly, the shorter side is overweighted and the larger side underweighted, or in other words, the angle area around 0 should be less likely to be chosen than the angle area around $\frac{\pi}{2}$. So this naive attempt of choosing the angle for our line uniformly doesn't consider asymmetries of K_0 and does therefore not hold the senseful idea, that longer sides of K_0 are hit by more lines than shorter ones.

Definition 4.1.1.

Definition 4.1.2. Now let $d = 2$. For $A \subset \mathbb{Z}^2$ define

$$\mathbb{P}_x(S_n \in A) := \mathbb{P}(S_n \in A | S_0 = x), \quad n \in \mathbb{N}, x \in \mathbb{Z}^2$$

and the *heat kernel* of the random walk $(S_n)_{n \in \mathbb{N}}$ as

$$p_n(x, y) := \mathbb{P}_x(S_n = y), \quad n \in \mathbb{N}, x, y \in \mathbb{Z}^2.$$

Further define the *Green function* as

$$G(x, y) := \sum_{n \geq 0} p_n(x, y), \quad x, y \mathbb{Z}^2.$$

G is well-defined and finite since $\mathbb{Z}^d$ is transient. Similarily for a subset $A \subset \mathbb{Z}^d$ the *killed* or *stopped Green function* is defined as

$$G_A(x, y) := \sum_{n \geq 0} \mathbb{P}_x(S_n = y, T_A > n).$$

Definition 4.1.3. (*random line hitting distribution*) Let $A \in \mathcal{P}_f$ and $K := conv(A) \in \mathcal{K}^2$. For $x \in \mathbb{Z}^2$ and $g \in \mathcal{G}$ define

$$\gamma_A(g) := \frac{1}{2} \mathbb{1}\{|g \cap A| \geq 2\} + \mathbb{1}\{|g \cap A| = 1\},$$

$$\tilde{\mu}_A(x, g) := \gamma_A(g) \begin{cases} \mathbb{1}\{x \in \{\min(g \cap A), \max(g \cap A)\}\}, & \text{if } g \cap A \neq \emptyset, \\ 0, & \text{if } g \cap A = \emptyset. \end{cases} \tag{4.1}$$

and

$$\mu_A(x) := \frac{1}{\mathbb{P}_\mu^K([A])} \int_{\mathcal{G}} \tilde{\mu}_A(x, g) \, \mathbb{P}_\mu^K(dg). \tag{4.2}$$

We quickly show that $\mu_A \in \mathcal{D}_A$. For all $x \in \mathbb{Z}^2 \setminus A$ and $g \in \mathcal{G}$ we have $\tilde{\mu}_A(x, g) = 0$ and therefore $\mu_A(x) = 0$. Furthermore for all $g \in \mathcal{G}$ we have

$$\sum_{x \in A} \tilde{\mu}_A(x, g) = \begin{cases} \frac{1}{2}2, & |g \cap A| \geq 2, \\ 1, & |g \cap A| = 1, \\ 0, & |g \cap A| = 0. \end{cases} = \mathbb{1}\{g \cap A \neq \emptyset\}$$

and therefore

$$\sum_{x \in A} \mu_A(x) = \frac{1}{\mathbb{P}_\mu^K([A])} \int_{\mathcal{G}} \mathbb{1}\{g \cap A \neq \emptyset\} \, \mathbb{P}_\mu^K(dg) = \frac{\mathbb{P}_\mu^K([A])}{\mathbb{P}_\mu^K([A])} = 1.$$

Hence, the family of distributions $(\mu_A)_{A \in \mathcal{P}_f}$ defines an incremental aggregation.

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[2] Daniel Hug, Günter Last, Steffen Winter. *Stochastic Geometry, Lecture Notes (summer term 2020).* Institute of Technologie, Karlsruhe

Erklärung

Hiermit versichere ich, dass ich diese Arbeit selbständig verfasst und keine anderen als die angegebenen Quellen und Hilfsmittel benutzt, die wörtlich oder inhaltlich übernommenen Stellen als solche kenntlich gemacht und die Satzung des Karlsruher Instituts für Technologie zur Sicherung guter wissenschaftlicher Praxis in der jeweils gültigen Fassung beachtet habe.

Karlsruhe, den 10. März 2020