

# Design of Digital Circuits and Systems, Lab 5

## Display Interface

### Lab Objectives

In this lab, we will learn how to display images on a VGA terminal using the DE1-SoC Computer's video-out port and implement a line-drawing algorithm.

### Introduction

The DE1-SoC Computer includes a video-out port with a VGA controller that can be connected to a standard VGA monitor. The VGA controller supports a screen resolution of  $640 \times 480$ . The image that is displayed by the VGA controller is derived from two sources: a *pixel buffer* and a *character buffer*, however, we will only discuss and use the pixel buffer in this lab.

### Pixel Buffer

The **pixel buffer** for the video-out port holds the data (color) for each pixel that is displayed by the VGA controller, with the coordinate (0,0) referring to the top-left corner of the image (Figure 1).

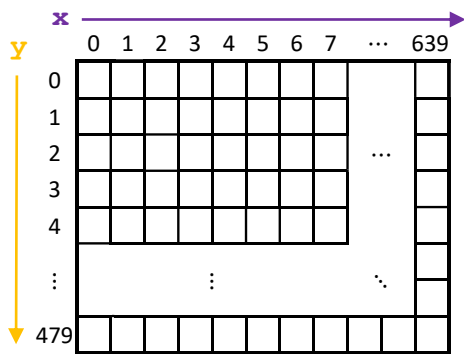
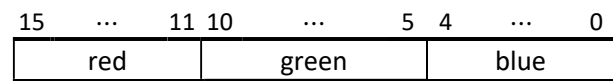
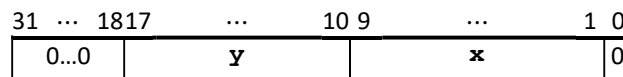


Figure 1: Pixel buffer coordinate system.



(a) Pixel color



(b) Pixel (x,y) offset

Figure 2: Data layout of pixel color values and address offsets.

The color of a pixel is represented within a 16-bit *halfword*, with five bits for the red and blue components and six bits for the green component (Figure 2a). The address of an individual pixel in the pixel buffer is given by the sum of a *base address* and an *(x,y) offset* (represented as seen in Figure 2b).

In the DE1-SoC, the default base address of the pixel buffer is **0xC8000000**, which corresponds to the starting address of the FPGA on-chip memory.

- e.g., pixel (0,0) has address  $0xC8000000 + 0b0...0 \text{ } 00000000 \text{ } 00000000 \text{ } 0 = 0xC8000000$ .  
 pixel (1,0) has address  $0xC8000000 + 0b0...0 \text{ } 00000000 \text{ } 00000001 \text{ } 0 = 0xC8000002$ .  
 pixel (0,1) has address  $0xC8000000 + 0b0...0 \text{ } 00000001 \text{ } 00000000 \text{ } 0 = 0xC8000400$ .  
 pixel (319,239) addr:  $0xC8000000 + 0b0...0 \text{ } 11101111 \text{ } 10011111 \text{ } 0 = 0xC803BE7E$ .

You can create an image by writing color values into the pixel addresses as described above. A dedicated **pixel buffer controller** reads this pixel data from the memory and sends it to the VGA display. The controller reads the pixel data in *sequential address order*, starting with the pixel data

corresponding to the upper-left corner of the VGA screen and proceeding horizontally, then vertically until it reaches the data for the lower-right corner; this process repeats continuously. You can modify the pixel data at any time by writing to the pixel addresses. Writes to the pixel buffer are automatically interleaved in the hardware with the read operations that are performed by the pixel buffer controller.

It is also possible to prepare a new image for the VGA display without changing the content of the pixel buffer using the concept of **double-buffering**. In this scheme, you switch between two pixel buffers, front and back, one of which is being sent to the VGA while the other is used to prepare the next frame. You don't need to worry about double-buffering for this lab, but may find it helpful in Lab 6.

## Drawing

Drawing a line on a screen requires coloring pixels between two points  $(x_1, y_1)$  and  $(x_2, y_2)$ , such that the pixels represent the desired line *as closely as possible*. For example, if we want to draw a line between points  $(1,1)$  and  $(12,5)$ , we cannot draw the line precisely – we can only draw a shape that is similar to the line by coloring the pixels that fall closest to the line's ideal location on the screen. This is illustrated in Figure 3, where the squares represent pixels on the screen.

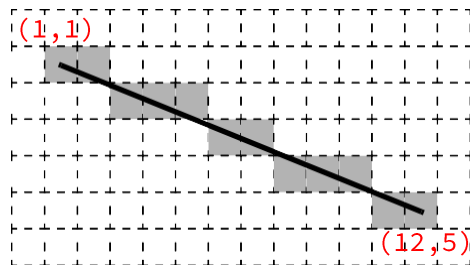


Figure 3: Drawing a line between points  $(1, 1)$  and  $(12, 5)$ .

We can use algebra to determine which pixels to color based on the slope and end points of the line. The slope of our example line is  $(y_2 - y_1)/(x_2 - x_1) = 4/11$ . Starting at one endpoint  $(1, 1)$ , we move along the  $x$ -axis to the other endpoint and compute the  $y$ -position for each  $x$ -position as:

$$y = y_1 + \text{slope} \times (x - x_1).$$

Thus, for  $x = 2$ , which you can think of as a column of pixels, the  $y$ -position of the pixel for the line is  $1 + (4/11) \times (2 - 1) = 15/11$ . Since pixel locations are defined by integer values, we round this result to the nearest integer, and determine that we should color the pixel at  $(2, 1)$ . For  $x = 3$ , we compute  $y = 19/11$  and color the pixel at  $(3, 2)$ . Similarly, we compute pixels to color through  $x = 12 = x_2$ .

This approach (compute a  $y$ -position for every  $x$ -position) has drawbacks when a line is steep (*i.e.*,  $|\text{slope}| > 1$ ), since it will span more rows than it does columns. In this case, our calculations will not produce a smooth-looking line and will not work at all for a vertical line. To address this problem, we can alter the algorithm to instead move along the  $y$ -axis when a line is steep. With this change, we can implement what is known as **Bresenham's line algorithm** (two different pseudocodes are given in Figure 4 and the first link on the next page – either will work for this lab).

In Figure 4, the first 15 lines of the algorithm make the needed adjustments depending on whether or not the line is steep. Lines 17 to 22 then increment the  $x$  variable one step at a time and computes the corresponding  $y$ -value. The  $y$ -value is incremented when needed to stay as close to the ideal location of

the line as possible. Bresenham's line algorithm calculates an error variable to decide whether or not to increment each y-value. The version of the algorithm shown in Figure 4 uses only integers.



This arithmetic is signed, so pay attention to your data types and operators in SystemVerilog and test both positive and negative values, where appropriate.

If you would like to learn more about how Bresenham's line algorithm works:

- <http://members.chello.at/easyfilter/bresenham.html>
- [https://en.wikipedia.org/wiki/Bresenham%27s\\_line\\_algorithm](https://en.wikipedia.org/wiki/Bresenham%27s_line_algorithm)

```
1  draw_line(x0, x1, y0, y1)
2
3  boolean is_steep = abs(y1-y0) > abs(x1-x0)
4  if is_steep then
5      swap(x0, y0)
6      swap(x1, y1)
7  if x0 > x1 then
8      swap(x0, x1)
9      swap(y0, y1)
10
11  int deltax = x1-x0
12  int deltay = abs(y1-y0)
13  int error = -(deltax/2)
14  int y = y0
15  if y0 < y1 then y_step = 1 else y_step = -1
16
17  for x from x0 to x1
18      if is_steep then draw_pixel(y,x) else draw_pixel(x,y)
19      error = error + deltay
20      if error >= 0 then
21          y = y + y_step
22          error = error - deltax
```

Figure 4: Pseudocode for Bresenham's line algorithm.

## Task #1 – VGA Connection (no deliverables)

- 1) Download *lab5\_startercode.zip* from Canvas (Files → Labs → lab5).
- 2) Unzip the Quartus project folder, which contains some files that will help you work with the VGA output of the DE1-SoC. In particular, there are three SystemVerilog files:
  - a) *VGA\_framebuffer.sv* is a driver for the VGA port of the board. You don't need to edit or understand this file, but you might notice that it uses a 38,400-byte framebuffer register, similar to what was described above. The ternary operator on the last line of this file controls the colors of the lines you'll be drawing (only black or white for this lab).
  - b) *line\_drawer.sv* is a skeleton file for you to implement Bresenham's line algorithm.
  - c) *DE1\_SoC.sv* is a top-level module that instantiates both of the above modules. This should compile and function as-is, but you will modify it for later tasks.
- 3) **Verify that the project compiles on LabsLand and produces an output on your monitor.**
  - a) On LabsLand, choose the "VGA" option for the interface (shown in Figure 5).
  - b) Once the code is synthesized and uploaded onto an FPGA, the VGA monitor will initially produce a rainbow gradient before turning *black* (shown in Figure 6).

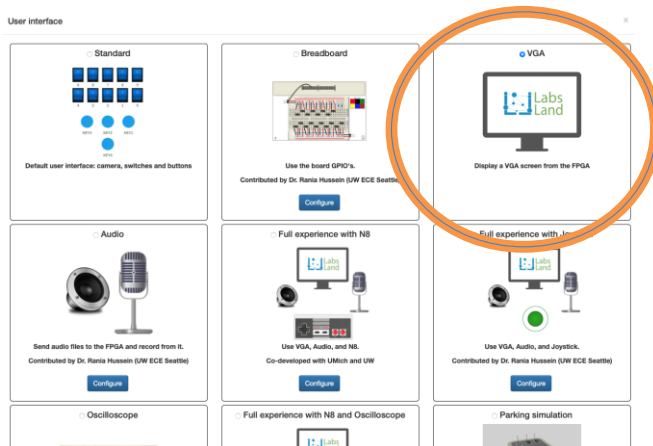


Figure 5: VGA interface option on LabsLand.

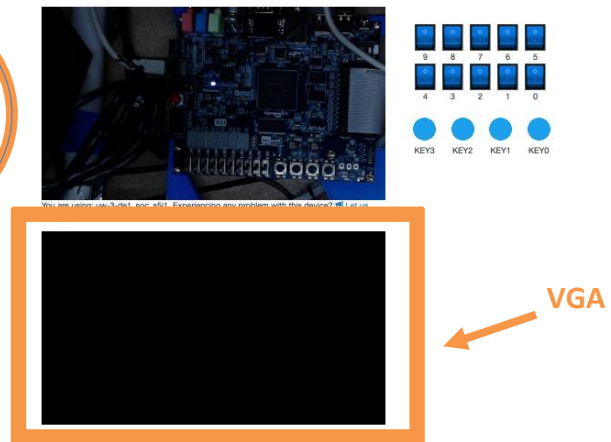


Figure 6: VGA display on LabsLand.

## Task #2 – Implement the Line-Drawing Algorithm

Some notes about the *line\_drawer.sv*:

- It takes inputs  $x_0, y_0, x_1, y_1$ , corresponding to the coordinate pairs  $(x_0, y_0)$  and  $(x_1, y_1)$ .
- On positive edges of the input clock  $clk$ , the outputs  $x$  and  $y$  form a coordinate pair on the line between  $(x_0, y_0)$  and  $(x_1, y_1)$ . On any given clock cycle,  $x$  and  $y$  should each change by at most one pixel, since we're guaranteed to use  $|slope| \leq 1$ .
- As indicated in the file, you'll need to create some local registers (*i.e.*, logic variables) to keep track of things. Notice that the example signal `error` is declared as signed and is a bit longer than the coordinate ports.

**Your task is to draw a line between any two arbitrary points on the monitor.** However, Bresenham's line algorithm can get complicated and you need to handle drawing to the left, right, up, or down, and both steep and gradual lines. Instead of doing this all at once, you'll probably want to work in smaller steps.

The following are suggestions on how to approach this problem, but you can complete this task in whatever way makes the most sense to you.

- 1) Set  $y_0 = y_1 > 0$  (in case of monitor cut-off) and use *line\_drawer.sv* to draw horizontal lines – *i.e.*, implement the for-loop mechanics and  $x_0 > x_1$  conditional.
- 2) Modify your algorithm to handle perfectly diagonal lines from any arbitrary starting point – *i.e.*, handle `y_step`.
- 3) Modify your algorithm to handle lines with gradual slopes, *e.g.*, from  $(0, 0)$  to  $(100, 20)$  – *i.e.*, handle `deltax`, `deltay`, and `error`.
- 4) Modify your algorithm to handle lines with steep slopes, *e.g.*, from  $(0, 0)$  to  $(20, 100)$  – *i.e.*, handle `is_steep`.

While you won't be demoing this task, you will need to include simulation results for drawing left-up, right-up, left-down, right-down for both steep and gradual slopes.

## Task #3 – Animate an Object

Modify *DE1\_SoC.sv* to implement the following:

- 1) Use your line algorithm to draw a line on the monitor and animate it to move around the screen.
  - a) You can be as creative as you want with this animation, but make sure that it demonstrates the full functionality of your line-drawing algorithm. You should draw lines to the left and right with negative, positive, steep and shallow slopes as well as horizontal and vertical lines.
- 2) Implement a reset that, when activated, clears the screen by drawing every pixel to be black.
  - a) You'll need to modify the `pixel_color` port connection to the `VGA_framebuffer` module to choose between drawing black or white.

Note that you don't need to provide simulation results for your animation, but instead will include a drawing or image of what it produces.

## Lab Demonstration/Turn-In Requirements

### In-Person Demo

- Explain your `line_drawer` module code to the TA.
- Demonstrate your working Task #3 that animates an object moving around the screen.
- Demonstrate your working Task #3 reset that clears the monitor.
- Be prepared to answer 1-2 questions about your lab experience to the TA.

### Lab Report (submit as PDF on Gradescope)

- Include the required **Design Procedure**, **Results**, and **Experience Report** sections.
- Don't forget to also submit your SystemVerilog files (`.sv`), including testbenches!

## Lab 5 Rubric

Grading Criteria	Points
Name, student ID, lab number	2 pts
<b>Design Procedure</b> <ul style="list-style-type: none"> <li>A diagram must be included for your Line_drawer algorithm.</li> <li>The design of your animation algorithm must be described and please include a diagram, if appropriate.</li> </ul>	14 pts
<b>Results</b> <ul style="list-style-type: none"> <li>Correct behavior must be shown for drawing left-up, right-up, left-down, right-down for both steep and gradual slopes.</li> <li>Include a drawing or image of your final animation.</li> </ul>	18 pts
<b>Experience Report</b>	6 pts
SystemVerilog code uploaded	5 pts
Code Style	5 pts
<b>LAB DEMO</b>	80 pts
<ul style="list-style-type: none"> <li>Bonus points available for particularly impressive animations.</li> </ul>	(10 pts)
	<b>130 pts</b>