Lab1:

Graph with 5 vertices and 6 edges:

```
56
0
           1
     0
0
     1
           7
1
     2
           2
2
     1
           -1
1
     3
           8
2
     3
           5
```

We keep the graph in memory as followed:

```
class DIRECT_GRAPH {

private:
    int numberOfEdges, numberOfVertices;
    map <int, vector<int>> edgesIn;
    map <int, vector<int>> edgesOut;
    map <pair<int, int>, int>costs;
    vector <int>> vector<int>>
```

```
edgesIn: map of edges that enters in a vertice, in our case - edgesIn[0]={0}, edgesIn[1]={0,2}, edgesIn[2]={1}, edgesIn[3]={1,2} edgesOut: map of edges gets out of a vertice, in our case - edgesOut[0]={0, 1}, edgesIn[1]={2,3}, edgesIn[2]={1,3} costs: vector that contains the cost for every vertice, in our case - costs[<0,0>]={1}, costs[<0,1>]={7}, costs[<1,2>]={2}, costs[<2,1>]={-1}, costs[<1,3>]={8}, costs[<5,3>]={5} vertices: list of vertices, from 0 to 5
```

Lab2:

Graph with 5 vertices and 5 edges

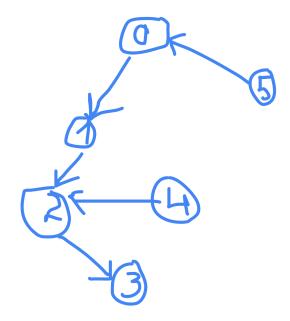
55		
0	1	3
1	2	4
2	3	5
4	2	2
5	0	2

I follow the given documentation:

q - queue with vertices you have to visit

 $[\]boldsymbol{p}$ - vector, where at a given position \boldsymbol{x} you have the predecessor of the vertice \boldsymbol{x} on the shortest path from \boldsymbol{x} to the source

I - vector, contains the shortest path's length from source to the other vertices



source = 3, target = 0,

	0	1	2	3	4	5
I	3	2	1	0	-	-
р	1	2	3	-	-	-