#### **USP LAB**

#### Termwork 1:

Write a C/C++ POSIX compliant program to check the following limits: (i) No. of clock ticks (ii) Max. no. of child processes (iii) Max. path length (iv) Max. no. of characters in a file name (v) Max. no. of open files/ process

```
Theory:
   IEEE formed a special tack force called Pasix in 1980s to create a set
   of standards, for OS interfacing.
      POSIX.1: Standard for base operating system API
      POSIX. 16: standard for APIs for real time Os interfaces
      Posix. Ic: standard for multithreading programming interfaces
    POSIX. 1 and POSIX. 16 define a set of system configuration limits in the
    form of manifested constants in climits. h> header.
         _POSIX_CHILD_MAX: min. value = 6
                                 desc: max. no. of child processes that may
                                     be created at any time by a process
         - POSIX-OPEN_MAX: min. value = 16
                                desc: max. no. of files that may be opened
                                     simultaneously by a process
         - POSIX_NAME_MAX: min. value = 14
                               desc: max. no. of characters allowed in a
                                    filenami
   To determine runtime limits, we can use functions [prototypes] in xunistel. 1>
       long sysconf (const int limit-name);
       loging path conf (const char + pathname, int flimit name);
       long fpathconf (const int fdese, int flimit name);
```

#### **Commands** to execute:

### \$ gedit tw1.cpp

\$./tw1

<sup>\*</sup>write your code in this editor given below\*, save it(Ctrl + s), and exit the editor once done

<sup>\$</sup> g++ tw1.cpp -o tw1

```
Program:
#define _POSIX_C_SOURCE 199309L
#include<iostream>
#include<unistd.h>
#include<limits.h>
using namespace std;
int main(){
        int choice,res=0;
        while(1){
                cout<<"1. Compile Time Values\n2. Run Time Values\n3.Exit\nEnter your choice:";
                cin>>choice;
                switch(choice){
                case 1: cout<<"Compile Time Values.\n";
                        #ifdef _POSIX_CLK_TCK
                                cout<<"No. of Clock Ticks per second is: "<<_POSIX_CLK_TCK<<endl;
                        #else
                                cout<<"_POSIX_CLK_TCK not defined\n";
                        #endif
                        #ifdef _POSIX_CHILD_MAX
                                cout<<"Max number of child processes at any time is:
"<<_POSIX_CHILD_MAX<<endl;
                        #else
                                cout<<"_POSIX_CHILD_MAX not defined\n";
                        #endif
                        #ifdef _POSIX_PATH_MAX
                                 cout<<"Max path name is: "<< POSIX PATH MAX<<endl;
                        #else
                                cout<<"_POSIX_PATH_MAX not defined\n";
                        #endif
                        #ifdef _POSIX_NAME_MAX
                                cout<<"Max no. of characters in file name: "<<_POSIX_NAME_MAX<<endl;</pre>
                        #else
                                cout<<"_POSIX_NAME_MAX not defined\n";
                        #endif
                        #ifdef _POSIX_OPEN_MAX
                                cout<<"Max no. of files simultaneously opened is:
```

"<< POSIX OPEN MAX<<endl;

```
cout<<"_POSIX_OPEN_MAX not defined\n";
                 #endif
                 break;
        case 2: cout<<"Run Time Values.\n";
                 if((res=sysconf(_SC_CLK_TCK))==-1)
                          perror("sysconf");
                 else
                          cout<<"No. of Clock Ticks per second is: "<<res<<endl;
                 if((res=sysconf(_SC_CHILD_MAX))==-1)
                          perror("sysconf");
                 else
                          cout<<"Max number of child processes at any time is: "<<res<<endl;</pre>
                 if((res=pathconf("/",_PC_PATH_MAX))==-1)
                          perror("pathconf");
                 else
                          cout<<"Max path name is: "<<res<<endl;
                 if((res=pathconf("/",\_PC\_NAME\_MAX))==-1)
                          perror("pathconf");
                 else
                          cout<<"Max no. of characters in file name: "<<res<<endl;
                 if((res=sysconf(_SC_OPEN_MAX))==-1)
                          perror("sysconf");
                 else
                          cout<<"Max no. of files simultaneously opened is:"<<res<<endl;
                 break;
        case 3: exit(0);
        default : cout << "Invalid Choice. \n";
        }
}
return 0;
```

#else

#### Termwork 2:

Write a C/C++ POSIX compliant program that prints the POSIX defined configuration options supported on any given system using feature test macros.

| Theory:  |
|--|
| posix. I defines a set of feature test macros, which if defined on a system, |
| the system has implemented the corresponding features. These can be found in |
| zunistd.h> header.   |
| _POSIX_JOB_CONTROL: System slipports BSD style job control                   |
| _POSIX_SAVED_EDS: Each process running on system keeps the saved             |
| Set UIDs and GIDs so that it can change its                                  |
| effectiver UIDs and GIDs to those values seturd                              |
| and setgid APIs respectively.  |
| _POSIX_CHOWN_DESTRICTED: if value is -1, users may change the                |
| ownerships of files owned by them, else only                                 |
| users with special priveledges may change                                    |
| ownership of any file on system.   |
| ***** #ifdef, #else, #endif is used to check these macros.                   |
| _POSIX_NO_TRUNC: if value is -1, any long pathname passed                    |
| to an API is silently truncated to NAME_MAX bytes,                           |
| else error is generated.   |
| _POSIX_VDISABLE: if value is -1, there's no disabling character for          |
| special characters for all terminal devices files, else                      |
| the value o is the disabling character value                                 |
|  |

## **Commands** to execute:

\$ gedit tw2.cpp

\*write your code in this editor given below\*, save it (Ctrl + s), and exit the editor once done \$ g++ tw2.cpp -o tw2

\$./tw2

```
Program:
#define _POSIX_SOURCE
#define POSIX C SOURCE 199309L
#include<unistd.h>
#include<iostream>
using namespace std;
int main(){
        #ifdef _POSIX_JOB_CONTROL
                 cout<<"System Supports Job Control feature"<<endl;
        #else
                 cout<<"System does not support job control\n";</pre>
        #endif
        #ifdef _POSIX_SAVED_IDS
                 cout<<"System Supports saved set-UID and saved set-GID"<<endl;</pre>
        #else
                 cout<<"System does not support saved set-UID\n";
        #endif
        #ifdef _POSIX_CHOWN_RESTRICTED
                 cout<<"System Supports change ownership feature"<<endl;</pre>
        #else
                 cout<<"System does not support change ownership feature\n";</pre>
        #endif
        #ifdef _POSIX_NO_TRUNC
                 cout<<"System Supports path truncation option."<<endl;</pre>
        #else
                 cout<<"System does not support path truncation\n";</pre>
        #endif
        #ifdef _POSIX_VDISABLE
                 cout<<"System Supports disable character for files."<<endl;</pre>
        #else
                 cout<<"System does not support disable character\n";</pre>
        #endif
        return 0;
```

#### Termwork 3:

Consider the last 100 bytes as a region. Write a C/C++ program to check whether the region is locked or not. If the region is locked, print pid of the process which has locked. If the region is not locked, lock the region with an exclusive lock, read the last 50 bytes and unlock the region

| lock the region with an exclusive lock, read the last 50 bytes and dillock the region |
|---|
| Theory:   |
| UNIX systems allows multiple processes to read and write                              |
| the same file concurrently. It also renders difficulty for any process                |
| in determining when data in a file can be overridden by another                       |
| processes.  |
| Hence UNIX and POSIX systems supports a file and record locking                       |
| mechanism which is applicable only for regular files                                  |
| The forth API is used fer file locking. Prototype of forth API is:                    |
| #include <forth.h></forth.h>  |
| int fonth (int folesc, int cond-flag,);   |
| folese is file descriptor of the file to be locked of condifing can have              |
| values as follows:  |
| F_SETEK -> Set a file lock, doesn't block if not succeed immediately                  |
| F_SETERW -> Set a file lock and block the calling process until release               |
| F-GETLK → Pury as to which process · locked   |
| third argument to footh is address of a struct flock type variable.                   |
| Struct flock {  |
| short 1-type; "Inhat lock to set or to unlock file                                    |
| short Luhence; 110 reference address for next field                                   |
| off_t l_short; "offset from l_when a reference coldress                               |
| off-t Llen; I how many bytes in locked region   |
| pid-t l-pid; // pid of the process which has locked the file                          |
| F J   |
|   |

#### **Commands** to execute:

Create an input.txt file using command:

#### \$ gedit input.txt

\*add some content more than 100 bytes in this editor\*, save it(Ctrl + s), and exit the editor once done then execute these commands:

## \$ gedit tw3.c

\*write your code in this editor given below\*, save it(Ctrl + s), and exit the editor once done

#### \$ gcc tw3.c -o tw3

## \$ ./tw3 input.txt

\*\*open another terminal while file is locked and try to access this file using ./tw3 input.txt command, same command that's mentioned above. If the terminal says cannot access, file is locked, then your code is working properly.

```
#include<stdio.h>
#include<stdlib.h>
#include<unistd.h>
#include<fcntl.h>
#include<errno.h>
int main(int argc, char *argv[]){
           int fd;
           char buffer[256];
           struct flock fvar;
           if(argc == 1){
                      printf("usage: %s filename\n", argv[0]);
                      return -1;
           }
           if((fd=open(argv[1],O_RDWR)) == -1){
                      perror("open");
                      exit(1);
           }
           fvar.l_type = F_WRLCK;
           fvar.l_whence = SEEK_END;
           fvar.l_start = SEEK_END - 100;
           fvar.l_len = 100;
           printf("trying to get lock ... n");
           if((fcntl(fd, F_SETLK, &fvar)) == -1){}
                      fcntl(fd, F_GETLK, &fvar);
                      printf("\n File already locked by process with pid = %d\n", fvar.l\_pid);
                      return -1;
           printf("\nLOCKED..\n");
           if((Iseek(fd, SEEK_END - 50, SEEK_END)) == -1){
                      perror("lseek");
                      exit(1);
           if((read(fd, buffer, 100)) == -1){
                      perror("read");
                      exit(1);
           printf("\nData Read from he file: ");
           puts(buffer);
           printf("\nPress ENTER to release lock\n");
           getchar();
           fvar.l_type = F_UNLCK;
           fvar.l_whence = SEEK_SET;
           fvar.l_start = 0;
           fvar.l_len = 0;
           if((fcntl(fd, F\_UNLCK, &fvar)) == -1){}
                      perror("fcntl");
                      exit(0);
           printf("\nUNLOCKED\n");
           close(fd);
           return 0;
}
```

#### Termwork 4:

Write a C/C++ program which demonstrates interposes communication between a reader process and a writer process. Use mkfifo, open, read, write and close APIs in your program.

```
Interprocess communication means communication between two or more
processes running on a system. Can be implemented using FIFO Files.
   A FIFO tile is a special pipe device file which provides a temporary
buffer for 20 or more processes to communicate by writing
reacting
         data from the buffer
        of the EIFO File is fixed by to PIPE_BUT butter
  The buffer associated with a FIFO File is allocated when the first
   process opens the HFO file for read & write
   The buffer is discarded when all the processes which are connected
      the FIFO file close their references to the FIFO file.
   to
   using
           mkfife API to create fito files.
                    const char * path, mode t mode
        other API:
        int open (const char path, int access med
        ssize t write (int folise, cortst void & louf, size t size
                       int foese, void
        int closel int foure
```

#### Commands to execute:

\$ gedit tw4c.c

\*write your code in this editor given below as **client**\*, save it(Ctrl + s), and exit the editor once done \$ **gedit tw4s.c** 

\*write your code in this editor given below as **server**\*, save it(Ctrl + s), and exit the editor once done \$ **gedit test\_file.txt** 

\*add some content less than 50 bytes in this editor\*, save it(Ctrl + s), and exit the editor once done

open two terminals:

in first terminal, execute

\$ gcc tw4c.c -o tw4c

in second terminal, execute

\$ gcc tw4s.c -o tw4s

\*\*\*\* make sure you run the server program first in second terminal i.e.,

\$ ./tw4s

and then run the client program in first terminal

\$ ./tw4c

\*\*request the file created(test\_file.txt) from the first terminal. Content inside file should be printed in client terminal.

#include<stdio.h>

#### **Client:**

```
#include<unistd.h>
#include<sys/stat.h>
#include<fcntl.h>
#include<string.h>
#define FIFO1 "fifo1"
#define FIFO2 "fifo2"
#define PERMS 0666
char fname[256];
int main(){
          ssize_t n;
          char buff[512];
          int readfd, writefd;
          printf("Trying to connect to server..\n");
          writefd = open(FIFO1, O WRONLY,0);
          readfd = open(FIFO2,O RDONLY,0);
          printf("Connected..\n");
          printf("Enter the filename to request from server: ");
          scanf("%s", fname);
          write(writefd, fname, strlen(fname)+1);
          printf("Waiting for server to reply...\n");
          while((n=read(readfd,buff,512))>0)
                   write(1,buff,n);
          close(readfd);
          close(writefd);
          return 0;
}
```

```
Server:
#include<stdio.h>
#include<unistd.h>
#include<sys/stat.h>
#include<fcntl.h>
#include<string.h>
#define FIFO1 "fifo1"
#define FIFO2 "fifo2"
#define PERMS 0666
char fname[256];
int main(){
         int readfd, writefd, fd;
         ssize_t n;
         char buff[512];
         if(mkfifo(FIFO1,PERMS)<0)
            printf("Can't create FIFO files\n");
         if(mkfifo(FIFO2, PERMS)<0)
            printf("Can't create FIFO files\n");
          printf("Waiting for connection request......\n");
         readfd = open(FIFO1, O_RDONLY,0);
         writefd = open(FIFO2, O_WRONLY,0);
         printf("Connection established...\n");
         read(readfd,fname,255);
         printf("Client has requested file %s\n", fname);
         if((fd= open(fname,O_RDWR))<0){
           strcpy(buff,"File does not exist!\n");
           write(writefd,buff,strlen(buff));
         else{
           while(n=read(fd,buff,512)>0)
              write(writefd,buff,n);
         close(readfd);
         unlink(FIFO1);
         close(writefd);
```

unlink(FIFO2);

#### Termwork 5:

**5a:** Write a C/C++ program that outputs the contents of its Environment list

**5b:** Write a C / C++ program to emulate the unix **In** command

| Theory | - 1.50-19  |
|--------|--|
| 5a:    | Environment variables have details of environment functionality  |
|        | built into the Os and on environment variable is of the form   |
|        | name = value.  |
|        | Eg: HOME = /usr/Sagar  |
|        | These environment variables help programs know what directory  |
|        | to install files in, where to store temporary per, voice to pro  |
|        | user portal settings, etc. These variables are null terminated. C-strings.   |
|        | a for a second by the control of the |
|        | -> Using environment list passed to main function as argument  |
|        | <ul> <li>Oan be accessed as follows:</li> <li>→ Using environment list passed to main function as argument</li> <li>→ Using exkan char **environ</li> <li>→ Using getenu() function</li> </ul>   |
|        | → Using getern() function  |
|        | Vitte: Nation  |
| 55:    | In is a link command used to create new links for  |
|        | existing files. Implemented using link APT. If successful,   |
|        | hard link rount attribute of the file is increased by 1.   |
|        | A link can be Hard link or Symbolic link.  |
|        | Hard libaks cannot be created across files but symbolic links  |
|        | can be used to do so.  |
|        | CHI CL VICE TO THE STATE   |

### Commands to execute:

For Termwork 5a:

\$ gedit tw5a.c

\*write your code in this editor given below\*, save it(Ctrl + s), and exit the editor once done

\$ gcc tw5a.c -o tw5a

\$ ./tw5a

For Termwork 5b:

\$ gedit test\_file.txt

\*add some content less than 50 bytes in this editor\*, save it(Ctrl + s), and exit the editor once done \$ gedit tw5b.c

\*write your code in this editor given below\*, save it(Ctrl + s), and exit the editor once done

\$ gcc tw5b.c -o tw5b

hard link creation:

\$ ./tw5b test\_file.txt testH

symbolic link creation:

\$ ./tw5b -s test\_file.txt testS

Execute these commands after creating hard and soft links:

\$ Is -li test\_file.txt testH testS

\*\*this should result in test\_file.txt and testH to have same inode numbers and testS to point to test\_file.txt(testS -> test\_file.txt)

\$ cat test\_file.txt testH testS

\*\*this command should display your file content the exact same as test\_file.txt by testH and testS

```
Program:
5a:
#include<stdio.h>
#include<stdlib.h>
#include<unistd.h>
int main(int argc,char *argv[]){
        int i;
        char **ptr;
        extern char **environ;
        for(ptr=environ;*ptr;ptr++)
           printf("%s\n",*ptr);
        exit(0);
}
5b:
#include<stdio.h>
#include<unistd.h>
#include<string.h>
#include<sys/types.h>
int main(int argc,char *argv[]){
        if(argc==3){
                 printf("Hard Link Created\n");
                 return link(argv[1],argv[2]);
        }
        else if(argc == 4){
                 if(strcmp(argv[1],"-s") == 0){
                          printf("Symbolic link created\n");
                          return symlink(argv[2],argv[3]);
                 }
                 else
                    printf("Option must be -s for symbolic link\n");
        }
        else
           printf("Invalid number of arguments\n");
        return 0;
```

## Termwork 6:

Write a C/C++ program to illustrate the race condition.

| 0 | Race condition occurs when there are multiple processes accessing   |
|---|---|
|   | manipulating the shared data / resources and the final outcome depend on the order in which the processes are executed. |
|   | on the order in which the processes are executed.   |
|   |   |
| 0 | To illustrate race condition, we can use fork system call via fork API  |
|   | Hinclude curistal. h>   |
|   | pid_t fork(void);   |
|   | o creates a new process called child process.   |
|   | · this function returns twice:  |
|   | 1) returns 0 in child process   |
|   | 2) returns pid of child in pavent process.  |
|   | if there's an error, it returns -1  |

# Commands to execute:

\$ gedit tw6.c

\*write your code in this editor given below\*, save it(Ctrl + s), and exit the editor once done

\$ gcc tw6.c -o tw6

\$ ./tw6

\*\*output should be jumbled

to kill the execution, press **Ctrl + c** together

```
#define POSIX_SOURCE
#define POSIX_C_SOURCE 199309L
#include<stdlib.h>
#include<stdio.h>
#include<unistd.h>
static void charatatime(char *);
int main(){
        int pid,i;
        for(i=0;i<10;i++){
                if((pid=fork())<0)</pre>
                        printf("fork error.\n");
                else if(pid==0)
                        charatatime("output from child\n");
                else
                        charatatime("output from parent\n");
        }
        return 0;
}
static void charatatime(char *str){
        char *ptr;
        int c;
        setbuf(stdout,NULL);
        for(ptr=str;(c=*ptr++)!=0;)
                putc(c,stdout);
}
```

#### Termwork 7:

Write a C/C++ program that creates a zombie and then calls system to execute the ps command to Verify that the process is zombie.

| Theo | my:  |
|------|--|
| e    | A zombie process is the leftour bits of dead processes that haven            |
|      | been cleaned up properly. He can't kill a rombie process because             |
|      | its already dead like an actual zombie.                                      |
| 0    | In UNIX, a zombie process is a process that has completed execution          |
|      | but still has an entry in process table.                                     |
| 0    | Every process has an entry in process table and these entries are            |
|      | called process control and contains information like process state,          |
|      | memory state, resource state etc.  |
| 0    | These processes simply fill up entries in the process table and as a result, |
|      | if the table gets completely filled, we cannot run any new processes         |
| 11/2 | because no entries can be made in the table.                                 |
| 0    | We can check if a process is a somble by executing ps command.               |
|      | d discountry of the second   |

#### Commands to execute:

\$ gedit tw7.c

\*write your code in this editor given below\*, save it(Ctrl + s), and exit the editor once done

\$ gcc tw7.c -o tw7

\$ ./tw7

```
#include<stdio.h>
#include<stdlib.h>
#include<unistd.h>
#include<sys/types.h>
#define PS "ps -eo pid,ppid,state,tty,command"
int main(){
    pid_t child_pid;
    if((child_pid=fork())<0)
        perror("fork error");
    else if (child_pid==0)
        exit(0); //child
    sleep(4); // parent
    system(PS);
    return 0;
}</pre>
```

<sup>\*\*</sup>wait until you see a zombie process with state Z and tw7 <defunct> as command

## Termwork 8:

Write a C/C++ program to avoid zombie process by forking twice

| Theory:  |
|--|
| o A zombie process is one that has completed its execution but still |
| has an entry in the process table.                                   |
| · A process table contains all the information that must be saved    |
| when CPU switches from process to process in a multitasking          |
| system.  |
| · We can use ps system call to chekk whether a process is rombie     |
| or not.  |
| · To avoid creation of zombie process:                               |
| · use wait() or waitpid()  |
| · parent process can register a signal b handle with signal()        |
| o forking twice.   |
| · How forking works:   |
| o a considers 'A' process creates 'B' process and assigns some work. |
| now 'A' waits till 'B' is completed                                  |
| · 'B' creates 'c' child process and assigns a work given by A'       |
| and terminates   |
| o termination of 'B' results in:                                     |
| o'C' Becoming orphan and adopted by init process                     |
| o 'A' resumes and entry of 'B' is closed for the process table       |
| o when 'C' terminates, its entry is closed and E' does not           |
| become a zombie.   |
|  |

## Commands to execute:

\$ gedit tw8.c

\*write your code in this editor given below\*, save it(Ctrl + s), and exit the editor once done

\$ gcc tw8.c -o tw8

\$ ./tw8

<sup>\*\*</sup>if you see NO zombie process with state Z and tw8 <defunct> as command in your output, then your code is working.

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
int main(){
        int pid;
        pid = fork();
        if(pid == 0){
                 //first child
                 pid = fork();
                 if(pid == 0){
                          //second child
                          sleep(1);
                          printf("Second Child: My Parent pid is %d\n",getppid());
                 }
        }
        else{
                 //parent process
                 wait(NULL);
                 sleep(2);
                 system("ps -o pid,ppid,state,tty,command");
        }
        return 0;
}
```

#### Termwork 9:

Write a C/C++ program to implement 'system' function.

| Theory:  |
|--|
| Theory:  System function is a past of C/C++ f standard library.  This used to pass the commands that can be executed in the command processor or terminal. |
| . It's used to pass the commands that can be executed in the   |
| Command processor or terminal.   |
| #Include estallib.h>   |
| int system (const char *command);  |
| · To implement sythem function, we use exect() function.   |
| o This function replaces the current process image with a new  |
| process image specified by path.   |
| #include < wristd.h>   |
| int exect (const char * path, const char * argo,, const char *   |
| aggn, NULL);   |
| → path is file to execute.   |
| → argoargo are NULL Terminated C-Strings which constitute the argument list available to the new   |
| constitute the aggument list available to the new  |
| process image  |
| argo must point to a filename thats associated with the process being stored and cannot be NULL.   |
| process being stored and cannot be NULL.   |
|  |

# Commands to execute:

\$ gedit tw9.c

<sup>\*</sup>write your code in this editor given below\*, save it(Ctrl + s), and exit the editor once done

<sup>\$</sup> gcc tw9.c -o tw9

 $<sup>\</sup>$  ./tw9 Is pwd ps whoami who date cal

<sup>\*\*</sup>you can put any number of  ${\bf system\ commands}$  as arguments to output ./tw9

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <errno.h>
#include <sys/wait.h>
#include <sys/types.h>
void sys(const char *cmdstr){
         int pid;
         pid = fork();
         if(pid == 0)
           execl("/bin/bash","bash","-c",cmdstr,NULL);
         else
           waitpid(pid,NULL,0);
}
int main(int argc,char *argv[]){
         int i;
        for(i = 1; i < argc; i++){
                  sys(argv[i]);
                  printf("\n");
         }
         _exit(0);
}
```

# Termwork 10:

Write a C/C++ program to set up a real-time clock interval timer using the alarm API.

| Theory:  Theory:  Theory:  Theory:  Theory:  Theory:  Theory:  The Interval firmer can be used to schedule a process to do  Some tasks at a fixed time interval, to time the execution  of some operation or to limit the time allowed for the  execution of some tasks  The alaem API can be called by a process to request the  kernel to send the SIGARM signal after a specified  rumber of real clack seconds.  Hinclude x unisted.  unsigned int alaem (unsigned it seconds);  For signal Handling we use signation API and it allows us to  examine or modify the action associated with a particular signal.  Hinclude signal.  This signation (int signo, conct struct signation * restrict_act,  Struct signablion * restrict_oact); |
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| struct sigaction &   |
| void (*sa_handler)(int);   |
| sigset-t sa_mask;  |
| int sa flag;   |
| 3;   |
|  |

#### **Commands** to execute:

\$ gedit tw10.c

\*write your code in this editor given below\*, save it(Ctrl + s), and exit the editor once done

\$ gcc tw10.c -o tw10

\$ ./tw10

<sup>\*\*</sup>after 2 sec, you will see Hello! as output.

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <signal.h>
#define INTERVAL 5
void callme(int sig_no){
        alarm(INTERVAL);
        printf("Hello\n");
}
int main(){
        struct sigaction action;
        action.sa_handler = (void(*)(int))callme;
        sigaction(SIGALRM,&action,0);
        alarm(2); //interrupt
        sleep(5);
        return 0;
}
```