

# Simultaneous Equations

Consider the equations:

$$5 * x + 8 * y = 18$$

$$3 * x + 5 * y = 11$$

$$R1 := (-3) * R1$$

$$R2 := 5 * R2$$

Add

$$\text{i.e. } y = 1$$

$$-15 * x - 24 * y = -54$$

$$15 * x + 25 * y = 55$$

$$\hline y = 1$$

Back substitute to get the value of the variable  $x$  :

$$5 * x + 8 * 1 = 18$$

$$\therefore x = 2$$

Consider

$$a_1 * x + a_2 * y = k_1$$

$$b_1 * x + b_2 * y = k_2$$

$$R1 := (-b_1) * R1 \quad -b_1 * a_1 * x - b_1 * a_2 * y = -b_1 * k_1$$

$$R2 := a_1 * R2 \quad a_1 * b_1 * x + a_1 * b_2 * y = a_1 * k_2$$

$$\text{Add} \quad (a_1 * b_2 - b_1 * a_2) * y = a_1 * k_2 - b_1 * k_1$$

i.e.

$$y = \frac{a_1 * k_2 - b_1 * k_1}{a_1 * b_2 - b_1 * a_2}$$

Similarly, to get the value of  $x$ :

$$\begin{array}{lll}
 R1 := R1 * b_2 & b_2 * a_1 * x + b_2 * a_2 * y & = & b_2 * k_1 \\
 R2 := R2 * (-a_2) & -a_2 * b_1 * x - a_2 * b_2 * y & = & -a_2 * k_2 \\
 \text{Add} & (a_1 * b_2 - b_1 * a_2) * x & = & k_1 * b_2 - k_2 * a_2
 \end{array}$$

i.e.

$$x = \frac{k_1 * b_2 - k_2 * a_2}{a_1 * b_2 - b_1 * a_2}$$

## No Solution?

Solution to Simultaneous equation depends on  $a_1 * b_2 - b_1 * a_2 \neq 0$ .

There is no (unique) solution

when  $a_1 * b_2 - b_1 * a_2 = 0$  i.e.  $a_1 * b_2 = b_1 * a_2$  i.e.  $\frac{a_1}{a_2} = \frac{b_1}{b_2}$

No (unique) solution

No (unique) solution when  $\frac{a_1}{a_2} = \frac{b_1}{b_2}$

## Geometric View

In Cartesian (Co-Ordinate) Geometry, a line is defined by the set of points  $(x, y)$  satisfying the equation:

$$y = m * x + c$$

where  $m$  is the slope of the line. i.e.  $m = \frac{\text{rise}}{\text{run}}$ .

We can rewrite the line  $a_1 * x + a_2 * y = k_1$  as

$$y = -\frac{a_1}{a_2} * x_1 + \frac{k_1}{a_2}$$

Also, the line  $b_1 * x + b_2 * y = k_2$  can be rewritten as:

$$y = -\frac{b_1}{b_2} * x_1 + \frac{k_1}{b_2}$$

$\therefore$  if  $\frac{a_1}{a_2} = \frac{b_1}{b_2}$  then the two lines have the same slope.

Two lines have the same slope when

- The lines are parallel
- The lines are coincident, i.e. they are the same line.

A solution to the simultaneous equations:

$$a_1 * x + a_2 * y = k_1$$

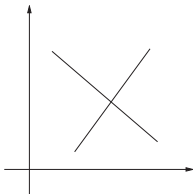
$$b_1 * x + b_2 * y = k_2$$

is where the lines intersect (cross over) at one point; the solution.

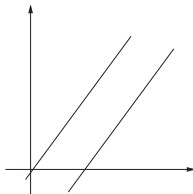
## Linear Systems in Two Unknowns I

- One equation:  $ax + by = c$  represents a line in  $\mathbb{R}^2$ . There are infinitely many solutions of this equation (one for each point on the line). (Here  $a$ ,  $b$  and  $c$  are real numbers, and  $a$  and  $b$  are not both zero).
- Two equations: Solutions of linear equations in two variables correspond to intersection points of lines.

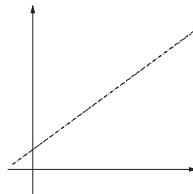
Three ways in which lines can intersect:



Intersect at unique point



Parallel lines - no intersection point



Lines coincide

A function from a set  $A$  to a set  $B$  written as  $f : A \rightarrow B$  is a relation or rule such that for each element,  $x$ , in  $A$  there is a most one result,  $f(x)$ , in  $B$ .

A function  $f : \mathbb{R} \rightarrow \mathbb{R}$  is **linear** if the variable in the expression for  $f$  has a first degree i.e. a power of 1. e.g.  $f : \mathbb{R} \rightarrow \mathbb{R}$  such that  $f(x) = 3 * x + 4$ .

A function,  $g : \mathbb{R} \rightarrow \mathbb{R}$  such that  $g(x) = x^2 - 4$  is not linear due to the power of 2 on the variable  $x$ .



## Root of a Function

A root of a function,  $f$ , is the value that makes the function result zero. For example, a root of the function  $f : \mathbb{R} \rightarrow \mathbb{R}$  such that  $f(x) = 3 * x + 4$  is  $-\frac{4}{3}$  as  $3 * (-\frac{4}{3}) + 4 = 0$ .

## Equation

A equation is an expression of the form  $f(x) = 0$ . e.g.

$$3 * x + 4 = 0 .$$

A solution to an equation is a value that makes the equation true.

Example:

The number  $-\frac{4}{3}$  is a solution to the equation  $3 * x + 4 = 0$ .

# Calculating Solution to Simultaneous Equations

From above we can solve the simultaneous equation:

$$a_1 * x + a_2 * y = k_1$$

$$b_1 * x + b_2 * y = k_2$$

by

$$x = \frac{k_1 * b_2 - k_2 * a_2}{a_1 * b_2 - b_1 * a_2} \quad y = \frac{a_1 * k_2 - b_1 * k_1}{a_1 * b_2 - b_1 * a_2}$$

# Calculating Solution to Simultaneous Equations Cont'd

Example: Solve

$$5 * x + 8 * y = 18$$

$$3 * x + 5 * y = 11$$

Using general form:

$$a_1 * x + a_2 * y = k_1$$

$$b_1 * x + b_2 * y = k_2$$

$$x = \frac{k_1 * b_2 - k_2 * a_2}{a_1 * b_2 - b_1 * a_2} \text{ i.e. } x = \frac{18 * 5 - 11 * 8}{5 * 5 - 3 * 8} = \frac{90 - 88}{25 - 24} = 2$$

$$y = \frac{a_1 * k_2 - b_1 * k_1}{a_1 * b_2 - b_1 * a_2} \text{ i.e. } y = \frac{5 * 11 - 3 * 18}{5 * 5 - 3 * 8} = \frac{55 - 54}{25 - 24} = 1$$

How would this calculating approach be extended to 3x3 Simultaneous Equations?

# New Improved Gaussian Approach

## Gaussian Elimination:

We consider a more algorithmic approach, named “Gaussian Elimination”, after the mathematician, Carl Friedrich Gauss. We can write

$$5 * x + 8 * y = 18$$

$$3 * x + 5 * y = 11$$

in an abbreviated ‘matrix’ way by regarding the variables as implicit.

$$\begin{array}{l} R1 \\ R2 \end{array} \quad \begin{array}{cc} 5 & 8 \\ 3 & 5 \end{array} \left| \begin{array}{c} 18 \\ 11 \end{array} \right.$$

$$\begin{array}{l} R1 := \frac{R1}{5} \\ R2 \end{array} \quad \begin{array}{cc} 1 & \frac{8}{5} \\ 3 & 5 \end{array} \left| \begin{array}{c} \frac{18}{5} \\ 11 \end{array} \right.$$

$$\begin{array}{l} R1 \\ R2 := R2 - 3 * R1 \end{array} \quad \begin{array}{c} 1 \\ 0 \end{array} \quad \begin{array}{c} \frac{8}{5} \\ 5 - \frac{24}{5} \end{array} \quad \left| \quad \begin{array}{c} \frac{18}{5} \\ 11 - \frac{54}{5} \end{array} \right.$$

Converting back to using the variables  $x$  and  $y$

$$\begin{aligned} x + \frac{8}{5} * y &= \frac{18}{5} \\ \frac{25 - 24}{5} * y &= \frac{55 - 54}{5} \end{aligned}$$

i.e.  $y = 1$

By back substitution, as above, we find  $x = 2$ .

# Avoiding Back Substitution

We can avoid back substitution by the following

From above:

$$\begin{array}{ccc|c} R1 & 1 & \frac{8}{5} & \frac{18}{5} \\ R2 & 0 & \frac{1}{5} & \frac{1}{5} \end{array}$$

$$\begin{array}{ccc|c} R1 & & 1 & \frac{8}{5} \\ R2 := R2 * 5 & & 0 & 1 \end{array}$$

$$\begin{array}{ccc|c} R1 := R1 - \frac{8}{5} * R2 & (1 - \frac{8}{5} * 0) & \frac{8}{5} - \frac{8}{5} & \frac{18}{5} - \frac{8}{5} \\ R2 & 0 & 1 & 1 \end{array}$$

# Simplification

Simplifying the above:

$$\begin{array}{l} R1 \\ R2 \end{array} \quad \begin{array}{cc|c} 1 & 0 & 2 \\ 0 & 1 & 1 \end{array}$$

Translating back to using variables  $x$  and  $y$

$$1 * x + 0 * y = 2$$

$$0 * x + 1 * y = 1$$

i.e.  $x = 2$  and  $y = 1$

# Allowed Operations on Rows

The follows operations on rows are allowed which do not change the solutions:

- Interchange rows  $R_i$  and  $R_j$
- Multiply row,  $R$ , by a number  $n$  to give  $R := n * R$
- Add a multiple of one row to another: for  $i \neq j$   
 $R_i := R_i + n * R_j$



# History of Gaussian Elimination

## Gauss-Jordan Elimination in Operation VIII

Historical context:

- The method of Gaussian elimination is mentioned in the Chinese mathematical text “Jiuzhang suanshu” or “The Nine Chapters on the Mathematical Art”. It dates to between 150BC and 179AD.
- In Europe it appears in the notes of Isaac Newton(1642 -1727) in 1670, where he commented that all the algebra books he knew of lacked a lesson for solving simultaneous equations – which he then supplied.
- Cambridge University published his notes as “Arithmetica Universalis” in 1707.
- By the end of the 18th century the method was a standard lesson in algebra textbooks.
- In 1810 Carl Friedrich Gauss devised a notation for symmetric elimination that was adopted in the 19th century by professional hand computers to solve the normal equations of least-squares problems (a methodology used for curve fitting to a set of points) .
- The algorithm we know was named after Gauss only in the 1950s as a result of confusion over the history of the subject

## Reading materials

### Linear algebra



Linear Algebra

J. Hefferon, Online textbook: <http://joshua.smcvt.edu/linearalgebra/>



Elementary Linear Algebra

K. R. Matthews, chapter 1, Online textbook: <http://www.numbertheory.org/book/>



Elementary Linear Algebra

Howard Anton, Chris Rorres, Wiley (any edition will do)

### Non-course specific reading material



How Not to Be Wrong: The Power of Mathematical Thinking Jordan Ellenberg, Penguin, 2014



How to Read and Do Proofs Daniel Solow, Wiley, 2010.



How to Solve It George Pólya, Penguin.