



**Trinity College Dublin**

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## 07 – Interrupts

**CS1022 – Introduction to Computing II**

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Want to write a program to take some action when the button is pressed

## Approach 1

suppose a memory location (e.g. 0xE1000000) is set to 1 when the button is pressed

keep reading 0xE1000000 until we read 0

do nothing between tests

## Approach 2

keep reading 0xE1000000 until we read 0

do useful things between tests

*Polling*

## Approach 3

do useful things

break out of F-D-E cycle when event occurs

*Interrupts*

Interrupt ReQuest (IRQs) } Exception  
Fast Interrupt reQuest (FIQs) } Classes

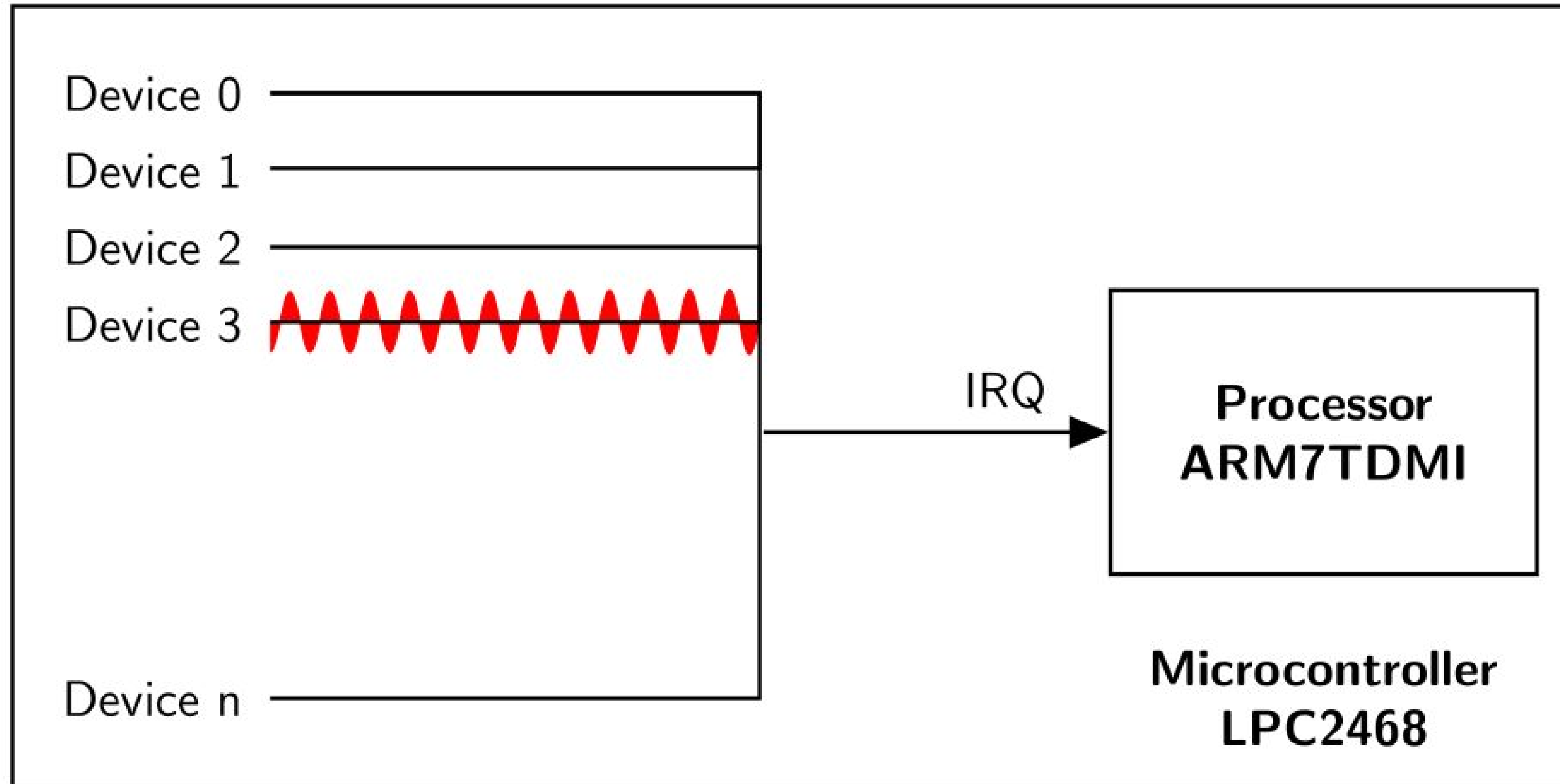
Interrupts are “raised” by devices external to the CPU when events of interest occur

e.g. mouse movement, key press, hardware timer expired

When an IRQ or FIQ occurs, the IRQ or FIQ exception handler is executed

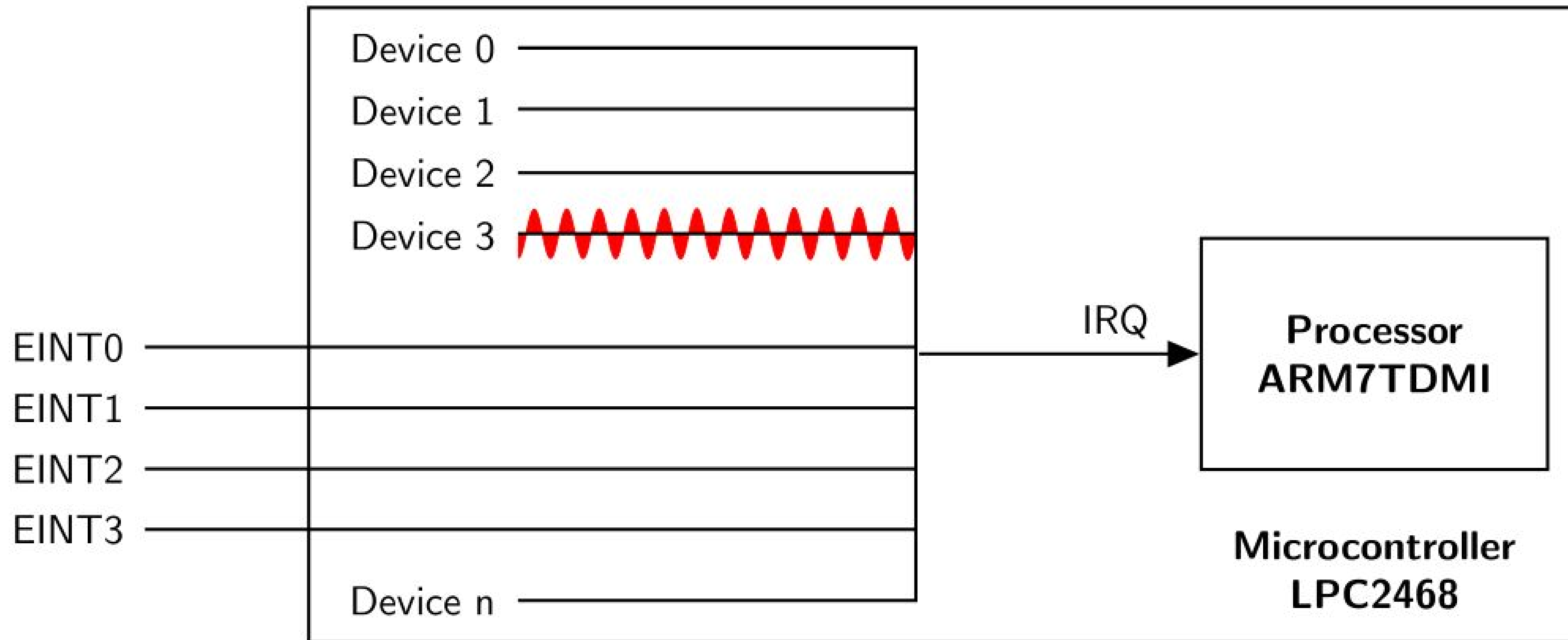
Interrupt could have been “raised” by any one of the devices connected to the CPU

Handler must determine which device raised the interrupt and execute a further handler for that device



# Raising an Interrupt

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How can we determine which device raised the interrupt?

“Ask” each device (e.g. read a memory-mapped status register) whether it has a pending interrupt

- Takes multiple cycles (multiple LDRs) to determine source of interrupt

- Too slow for IRQs

- Way too slow for FIQs

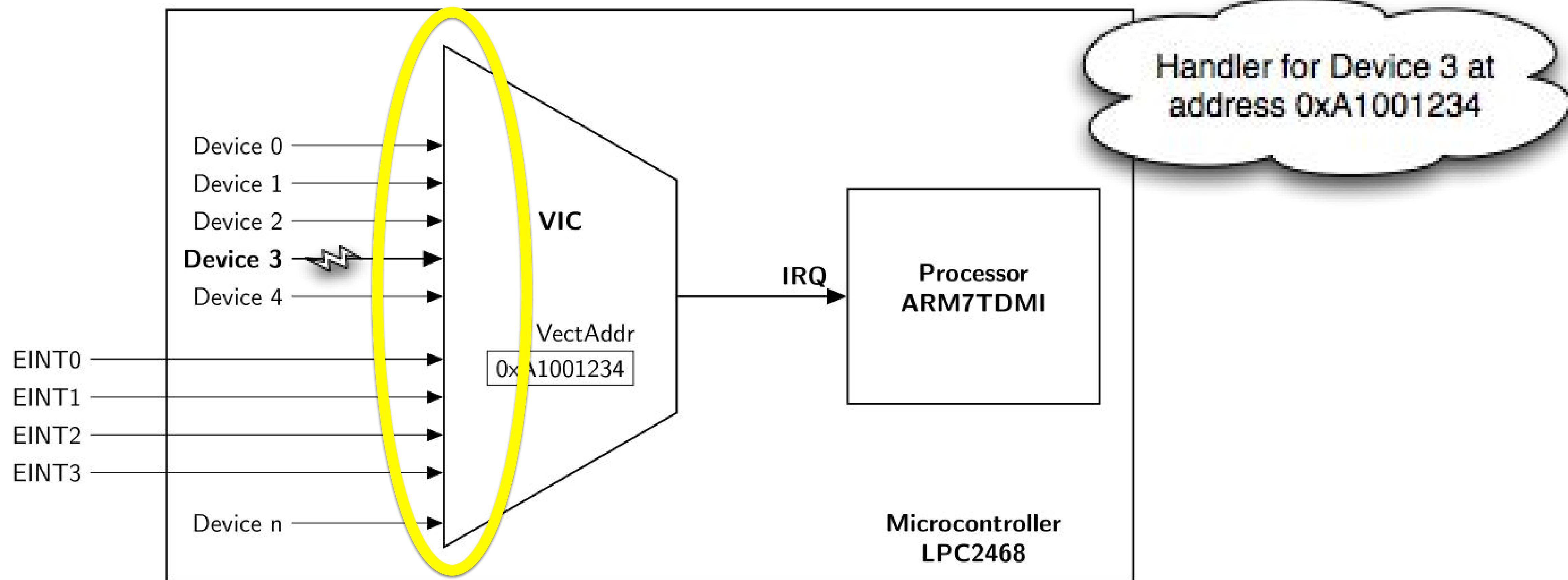
Get assistance from an external “helper” device

- Vectored Interrupt Controller (“VIC”)*



# Raising an Interrupt – Vectored Interrupt Controller

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```
LDR PC, [address of VIC VectAddr register]
```

```
LDR PC, [PC, #-0x0120]
```

Up to 32 interrupt sources

- Internal (e.g. TIMER, ADC)

- External (EINT0/1/2/3, e.g. P2.10 push-button)

Interrupt sources configured independently

When one of the sources raises an interrupt, the VIC ...

- loads address of a source-specific handler into VectAddr

- raises either the processor's IRQ line or FIQ line

Processor executes source-specific handler loading Program Counter with address in VectAddr register



Design and write a program that will cause an LED to blink with a period of 1s

Use LED connected to pin P2.10 of the LPC2468 (see IO example)

User TIMER0 integrated into LPC2468 to generate an interrupt every 1 second.



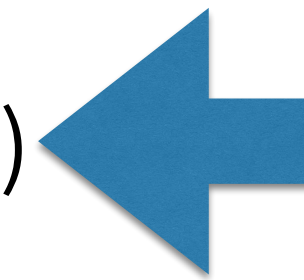
Four integrated timer/counters

Multipurpose

Count input signal transitions (examples?)

Capture time on input signal transition (examples?)

Measure time interval (counting input clock cycles) (examples?)



Optionally generate an interrupt when an event occurs (events?)

*See LPC2468 User Manual Chapter 24*

## When program starts ...

- Configure pin P2.10 for LED output (PINSEL4 – GPIO, FIO2DIR1 – output)

- Stop and Reset TIMER0

- Configure TIMER0 for periodic 1 second interrupts

- Configure VIC channel for TIMER0 (IRQs or FIQs, handler address, enable channel)

- Clear any previous TIMER0 interrupts (e.g. from last time program ran)

- Start TIMER0

## When an interrupt occurs ...

- Reset TIMER0 interrupt (so the device can raise further interrupts)

- Read and invert LED state (FIO2PIN1)

- Clear VIC interrupt source (so VIC can raise further interrupts, perhaps from other devices)

Reset and disable TIMER0 (it might already be enabled)

TOTCR [0xE0004004] – Set bit 1 = 1 (reset) and bit 0 = 0 (stop)

Clear any previous TIMER0 interrupt

TOIR [0xE0004000] – Write 0xFF to clear interrupts

Want timer mode, generating interrupts every second

TOCTCR [0xE0004070] – Set bits 1:0 to 00 for timer mode

Want to generate an interrupt (when the count register equals the match register) every 1 seconds

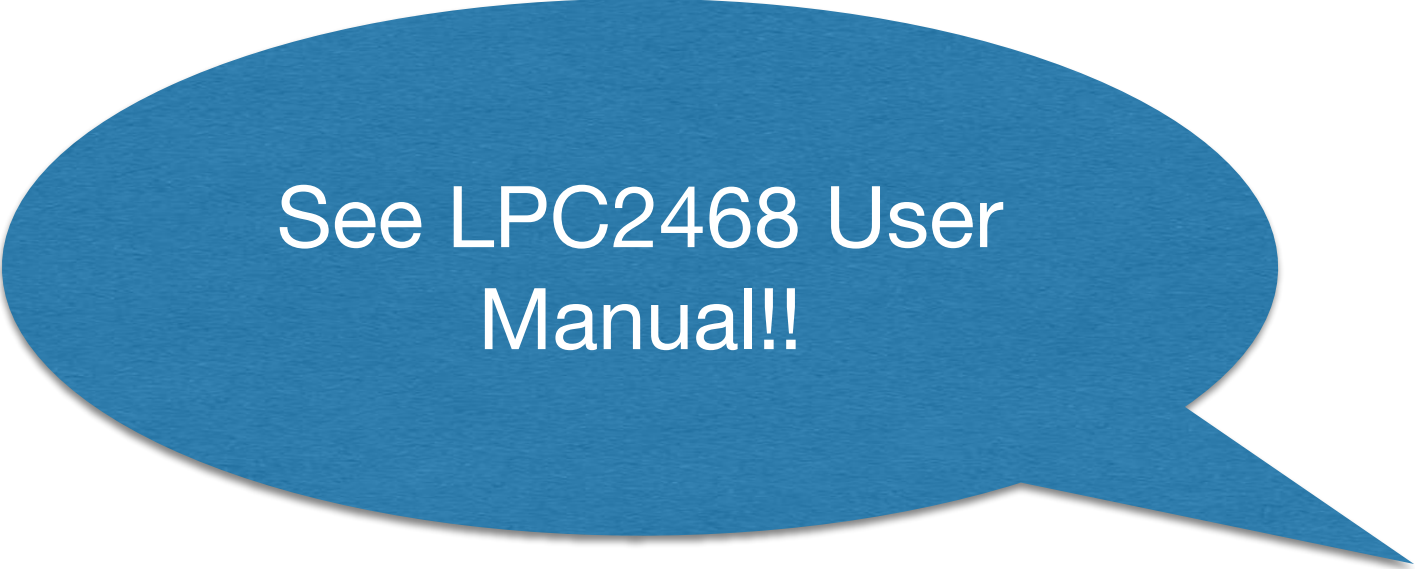
TOMR0 [0xE0004018] = 12,000,000 (assuming TIMER is “fed” with a 12MHz clock)

Want to generate an interrupt, reset and restart the timer when the count register equals the match register

TOMCR [0xE0004014] – Set bits 1:0 to 11

No pre-scaling required (period is sufficiently small)

TOPR [0xE000400C] – Set to 0 for prescale factor of 1



See LPC2468 User Manual!!

Identify the VIC vector number for TIMER0 ... 4

Corresponds to a bit mask 0x10 ( 0001 0000 ) – we will use this later ...

Set vector for IRQ (not FIQ)

VICIntSelect [0xFFFFF00C] – set bit 4 to 0 – BIC using our mask (0x10)

Set priority for vector 4 (e.g. to 15)

VICVectPriority0 (Base Address of VICVectPriority array) = 0xFFFFF200

VICVectPriority4 [0xFFFFF200 + (4 x 4)] – Set to 15

Set handler address

VICVectAddr0 (Base Address of VICVectAddr array) = 0xFFFFF100

VICVectAddr4 [0xFFFFF100 + (4 x 4) ] – Set to address of our TimerHandler routine

Enable vector 4

VICIntEnable [0xFFFFF010] – Write 1 to bit 4 (using our mask (0x10))



## Interrupt handler looks like a subroutine, with a few differences

Note the ^ in the LDMFD instruction to restore the SPSR as the CPSR when we return

Note the subtraction of 4 from the LINK register

Note: we save/restore all used registers, including R0-R3

No parameters passed to the subroutine

## Interrupt handler must

Clear TIMER0 interrupt – Set T0IR to 0xFF to clear TIMER0 interrupt

Perform action (e.g. inverting LED state)

Clear VIC (by writing 0 to VICVectAddr)

Return