

```
1 using System.Collections;
2 using System.Collections.Generic;
3 using UnityEngine;
4
5 public class MyTransform
6 {
7
8     public static Matrix4By4 YawRotate(float RotX)
9     {
10
11         Matrix4By4 YawMatrix = new Matrix4By4(new MyVector3(Mathf.Cos(RotX), ↗
12             0, -Mathf.Sin(RotX)),
13             new MyVector3(0, 1, 0),
14             new MyVector3(Mathf.Sin(RotX), ↗
15                 0, Mathf.Cos(RotX)),
16             MyVector3.Zero());
17
18         return YawMatrix;
19     }
20     public static Matrix4By4 PitchRotate(float RotY)
21     {
22         Matrix4By4 PitchMatrix = new Matrix4By4(new MyVector3(1, 0, 0),
23             new MyVector3(0, Mathf.Cos ↗
24                 (RotY), Mathf.Sin(RotY)),
25             new MyVector3(0, -Mathf.Sin ↗
26                 (RotY), Mathf.Cos(RotY)),
27             MyVector3.Zero());
28
29         return PitchMatrix;
30     }
31     public static Matrix4By4 RollRotate(float RotZ)
32     {
33         Matrix4By4 RollMatrix = new Matrix4By4(new MyVector3(Mathf.Cos(RotZ), ↗
34             Mathf.Sin(RotZ), 0),
35             new MyVector3(-Mathf.Sin(RotZ), ↗
36                 Mathf.Cos(RotZ), 0),
37             new MyVector3(0, 0, 1),
38             MyVector3.Zero());
39
40         return RollMatrix;
41     }
42     public static Matrix4By4 Rotation(float RotX, float RotY, float RotZ)
43     {
44         Matrix4By4 RotationMatrix = YawRotate(RotX) * (PitchRotate(RotY) * ↗
45             RollRotate(RotZ));
46
47         return RotationMatrix;
48     }
49     public static Matrix4By4 Scale(float ScaleX, float ScaleY, float ScaleZ)
50     {
51         Matrix4By4 ScaleMatrix = new Matrix4By4(new MyVector3(ScaleX, 0, 0) , ↗
52             new MyVector3(0, ScaleY, 0) , new MyVector3(0, 0, ScaleZ), ↗
53             MyVector3.Zero());
```

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45
46
47     return ScaleMatrix;
48 }
49 public static Matrix4By4 Translate(float TranslateX, float TranslateY, ↗
    float TranslateZ)
50 {
51     Matrix4By4 TranslateMatrix = new Matrix4By4(new MyVector3(1, 0, 0), ↗
        new MyVector3(0,1, 0), new MyVector3(0, 0, 1), new MyVector3 ↗
        (TranslateX, TranslateY, TranslateZ));
52     return TranslateMatrix;
53 }
54 public static Matrix4By4 TRS(Matrix4By4 Translate, Matrix4By4 Rotate, ↗
    Matrix4By4 Scale)
55 {
56
57     Matrix4By4 M = (Rotate * Scale)* Translate;
58
59     return M;
60 }
61 public static Matrix4By4 QuaternionToRotationMatrix(MyVector3 quat)
62 {
63     Matrix4By4 Rotation = MyTransform.Rotation(quat.x, quat.y, quat.z);
64
65
66     return Rotation;
67 }
68 //public static Matrix4By4 ScaleInverse(float ScaleX, float ScaleY, float ↗
    ScaleZ)
69 //{
70
71 //}
72 //public static Matrix4By4 RotationInverse()
73 //{
74 //    return new Matrix4By4(GetRow(),GetRow(1), GetRow(1), GetRow(1))
75 //}
76 //public static Matrix4By4 TranslateInverse(float TranslateX, float ↗
    TranslateY, float TranslateZ)
77 //{
78
79 //}
80 }
```