ASSIGNMENT -3

QUESTION:

Build wowki product, use ultrasonic sensor and detect the distance from the object.whenever distance is less than 100cms upload the value to the ibm cloud.in recent device events upload the data from wowki.

CODE: #include <WiFi.h>// library for WIFI #include < PubSubClient.h > // library for MQTT //----- credentials of IBM Accounts -----#define ORG "rwazv5" // IBM organisation id #define DEVICE TYPE "NodeRed" // Device type mentioned in ibm watson iot platform#define DEVICE ID "12345" // Device ID mentioned in ibm watson iot platform #define TOKEN "vC@S3TBre6(97jAOJ " // Token #define speed 0.034 #define led 14 String data3: int LED = 4;// customise above values char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name char publishTopic[] = "iot-2/evt/sreedhar/fmt/json"; // topic name and type of event perform and format in which data to be send char topic[] = "iot-2/cmd/led/fmt/String"; // cmd Represent type and command is test format of strings char authMethod[] = "use-token-auth"; authentication method chartoken[] = TOKEN; char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID; //Client id

WiFiClient wifiClient; // creating instance for wificlient PubSubClient client(server, 1883, wifiClient); // calling the predefined client id by passing parameter like server id, port and wifi credential

```
const int
trigpin=5; const
int echopin=18;
String
command;
String
data="";
long
duration;
float dist;
void setup()
Serial.begin(11520
0); pinMode(led,
OUTPUT);
pinMode(trigpin,
OUTPUT);
pinMode(echopin,
INPUT);
wifiConnect();
mqttConnect();
}
void loop() { bool isNearby
    dist <
    100;
digitalWrite(led,
isNearby);
publishD
ata();
delay(50
0);
```

```
}
void mqttConnect()
if (!client.connected())
Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
while (!client.connect(clientId, authMethod, token))
Serial.print(".");
delay(500);
initManagedDevice();
Serial.println();
void
initManagedDevice
() {if
(client.subscribe(to
pic))
Serial.println("IBM subscribe to cmd OK");
else
Serial.println("subscribe to cmd FAILED");
void publishData()
digitalWrite(trigpin,
LOW);
digitalWrite(trigpin,
HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
```

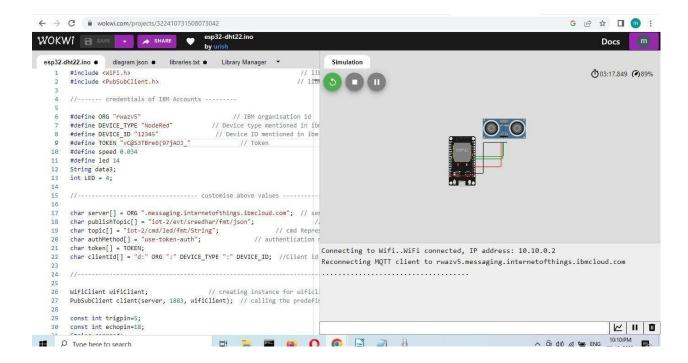
```
dist=duration*speed/2;
if(dist<100)
{
    digitalWrite(LED,HIG
H); String payload =
    "{\"Alert Distance\":";
    payload += dist;
    payload += "}";

Serial.print("\n");
Serial.print("Sending payload: "); Serial.println(payload); if
(client.publish(publishTopic, (char*) payload.c_str())) // if data is uploaded to cloud successfully,prints publish ok else prints publish failed</pre>
```

```
Serial.println("Publish OK");
if(dist>100)
digitalWrite(LED,HIGH);
String payload =
"{\"Distance\":";payload
+= dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending
payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
Serial.println("Publish OK");
else
digitalWrite(LED,LOW);
Serial.println("Publish FAILED");
```

OUTPUT:

Code simulation on wokwi



Data sent to IBM Cloud with distance

