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This is a direct acting controller whose gain is negative $[p'(t) = K_c(r'(t) - h'(t))]$ 11-6 11.6 For proportional controller, $G_c(s) = K_c$ Assume that the level transmitter and the control valve have negligible dynamics.

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Therefore the process transfer function G cannot exhibit oscillations when the input is a step function. 5.7 Assume that at steady state the temperature indicated by the sensor T_m is equal to the actual temperature at the measurement point T .

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