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One of these approaches, probabilistic robotics, has led to fielded systems with unprecedented levels of autonomy and robustness. While the roots of this approach can be traced back to the early 1960s, in recent years the probabilistic approach has become the dominant paradigm in a wide array of robotic problems.

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Thrun is also known for his work on probabilistic algorithms for robotics with applications including robotic mapping. In recognition of his contributions, and at the age of 39, he was elected into the National Academy of Engineering and also into the Academy of Sciences Leopoldina in 2007.

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Probabilistic robotics leverages decades of research in probability theory, statistics, engineering and operations research. In recent years, probabilistic techniques have solved many outstanding robotics problems, and they have led to new theoretical insights into the structure of robotics

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