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Robot Modeling and Control Mark W. Spong, S. Hutchinson, M. Vidyasagar John Wiley and Sons, Inc., 2005 Table of Contents 1. Introduction 2. Rigid Motions and Homogeneous Transformations 3. Forward and Inverse Kinematics 4. Velocity Kinematics-The Jacobian 5. Path and Trajectory Planning 6. Independent Joint Control

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1Spong, M., S. Hutchinson, and M. Vidyasagar, Robot Modeling and Control, John Wiley & Sons, 2006. ECE569 Problem Set 1 Solution November 14, 2017 2 2-39 Consider the diagram (Figure 2.14, p. 71). A robot is set up 1 meter from a table. ... Solution In this problem the block is left balancing on the edge of the table { half on and half o .

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