



אוניברסיטת בן-גוריון בנגב
Ben-Gurion University of the Negev

HUMAN ACTIVITY RECOGNITION

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MOTIVATION

HEALTH & SAFETY

- Detect falls
- Chronic-disease early warnings
- alerts to keep patients safe

MOVEMENT REMINDERS

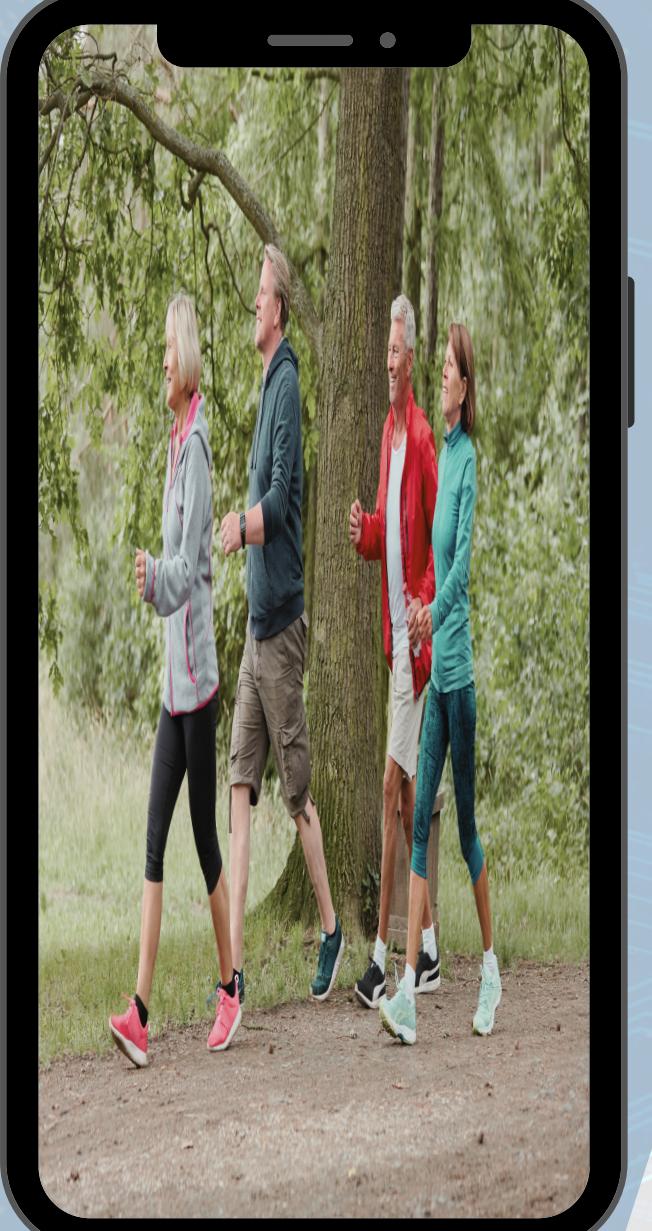
Track sitting time and send movement alerts

DYNAMIC UI ADAPTATION

Adjust the interface according to movement (e.g., pause music)

FITNESS & COACHING

- Record workouts
- offer simple form tips



DATA



PARTICIPANTS

30 volunteers (age 19–48) wearing a Samsung Galaxy S II on the waist

FEATURES

561 columns containing time and frequency (normalized to $[-1, 1]$)

ACTIVITIES LABELS:

Walking, Walking Upstairs, Walking Downstairs, Sitting, Standing, Laying



Challenges

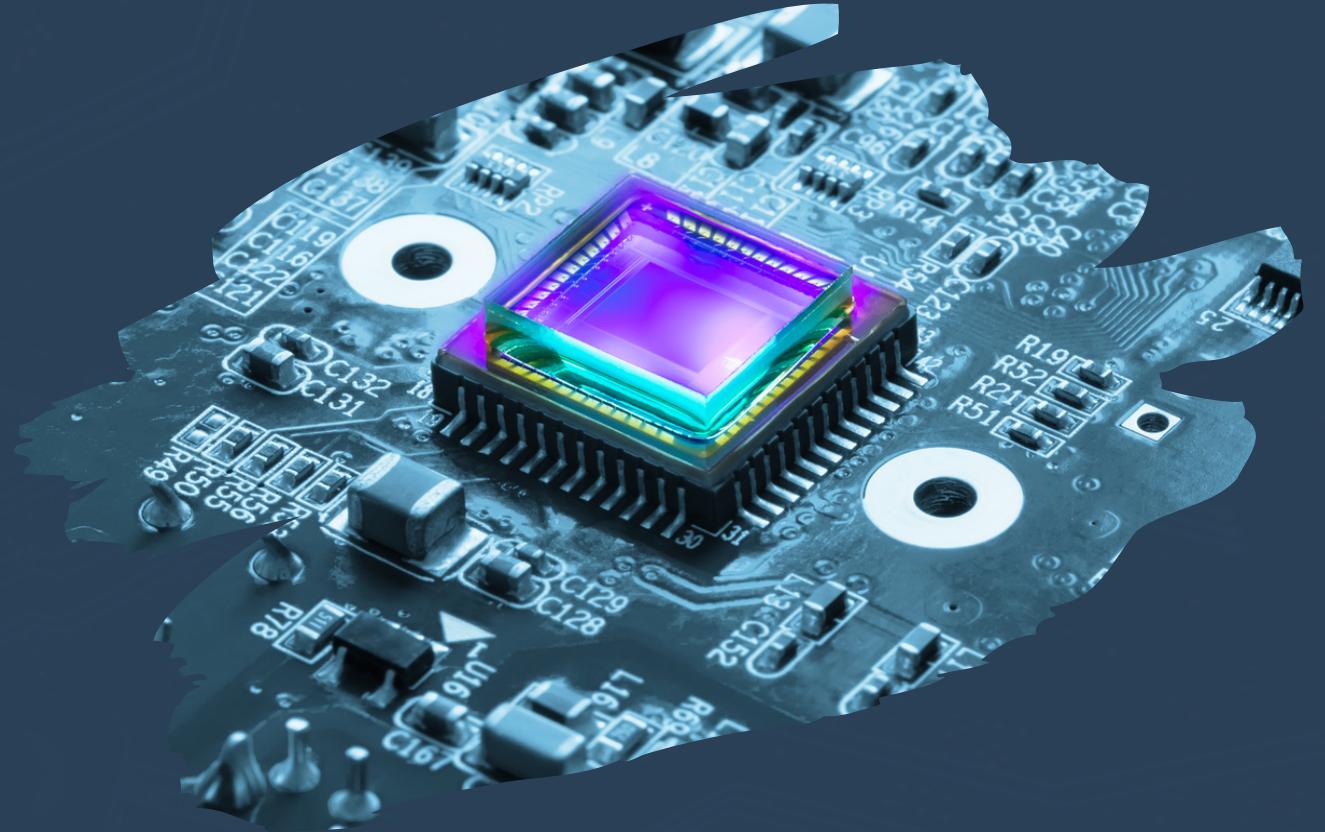
PRE-PROCESSED

First decode ~~DATA SET~~, then adapt it to our goals



561
~~FEATURES~~
High quality demands smart reduction

Preprocessing of Sensor Signals



Noise filtering

Apply noise filters to accelerometer and gyroscope readings to remove glitches.

Gravity vs. body-acceleration separation

Apply a 0.3 Hz filter to capture gravity, then subtract it to isolate body motion.

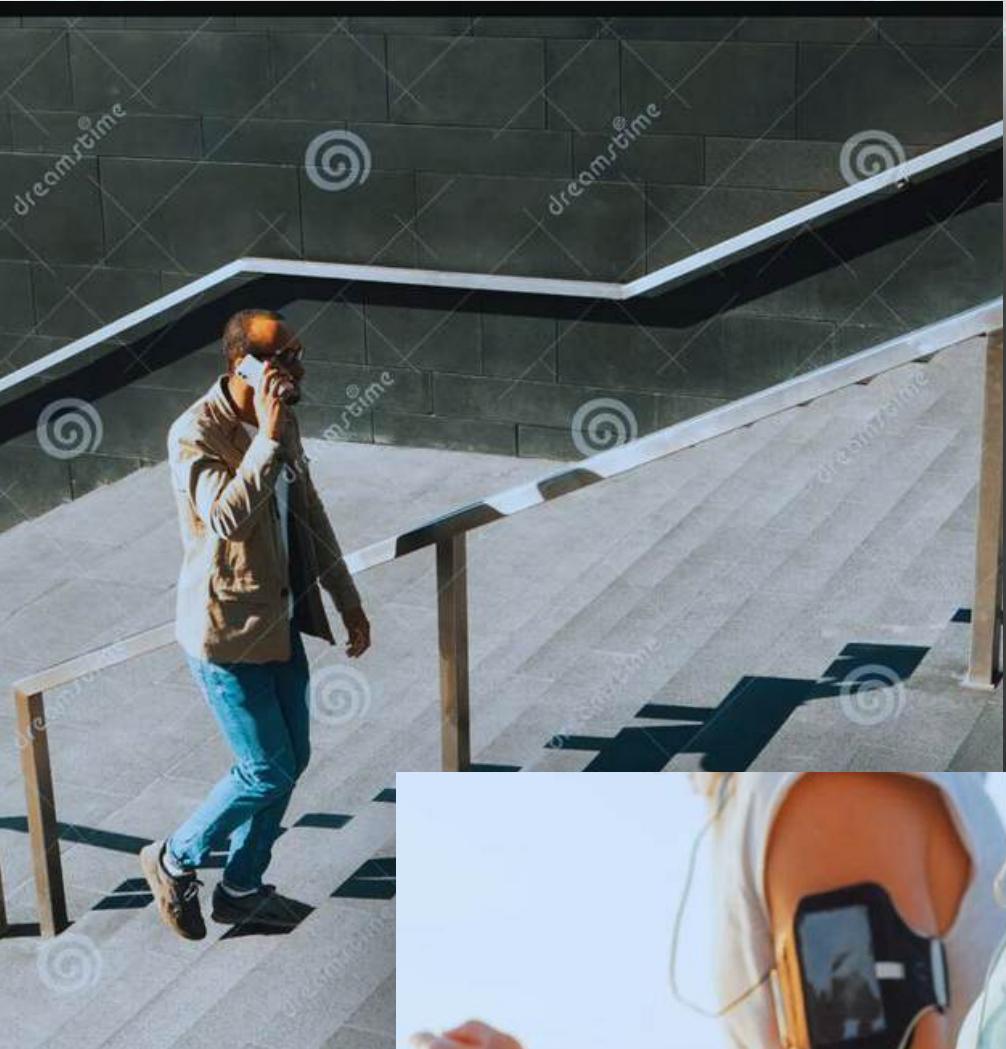
Sliding-window segmentation

Split the continuous signal into overlapping 2.56-(50%) second windows.

Feature extraction (time & frequency domains)

From each window compute summary stats and spectral measures or model input

Column Explanation



SubjectID

Volunteer identifier
(1–30)



ActivityLabel

Type of movement (6 classes)



FeatureVector (561 numbers)

Summary of each 2.56 s window of sensor data, combining:



Time-domain metrics

(e.g. average, variability, peaks)

Describe how acceleration and rotation change over time

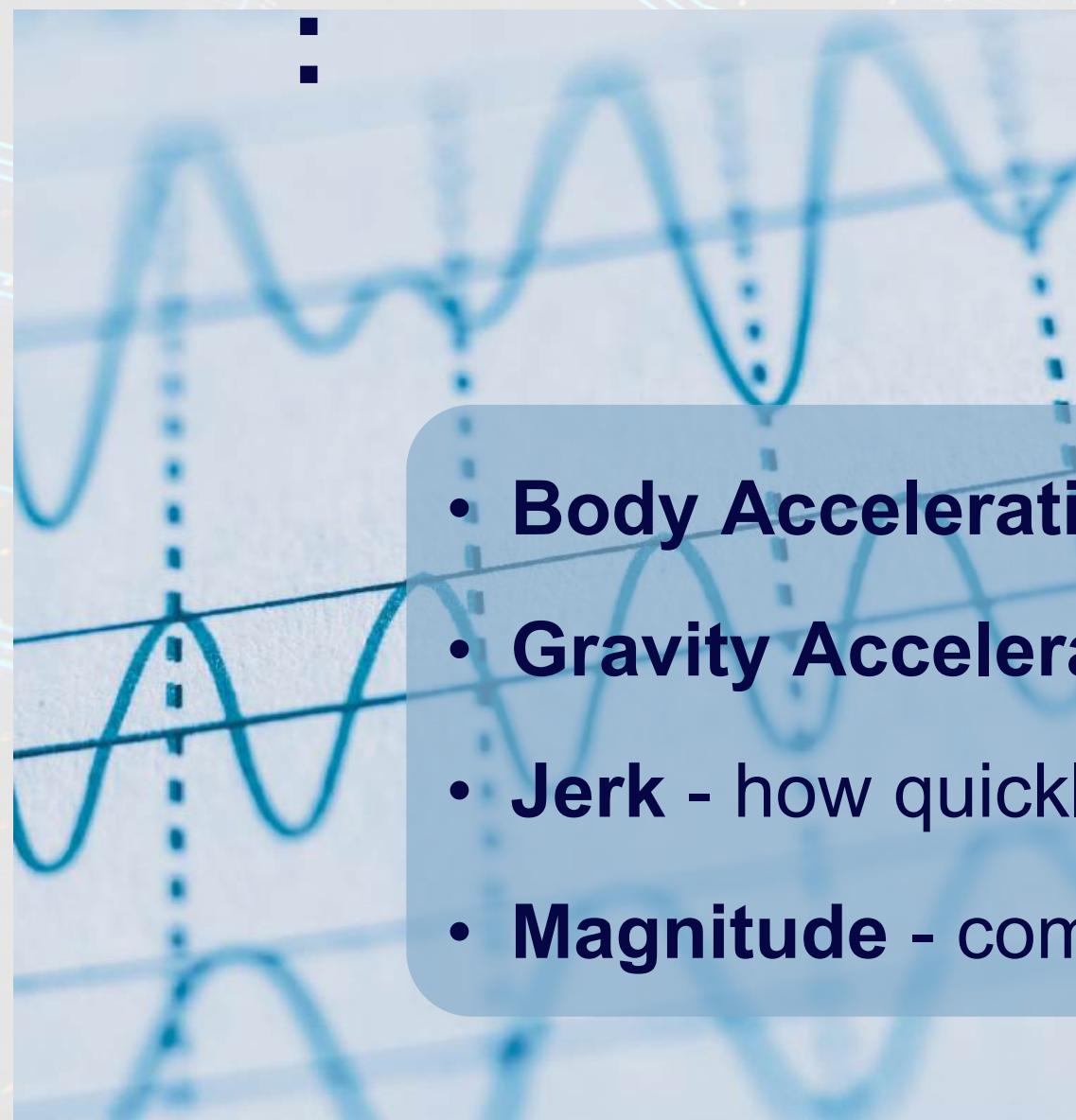


Frequency-domain metrics

Capture repeating patterns in the motion data

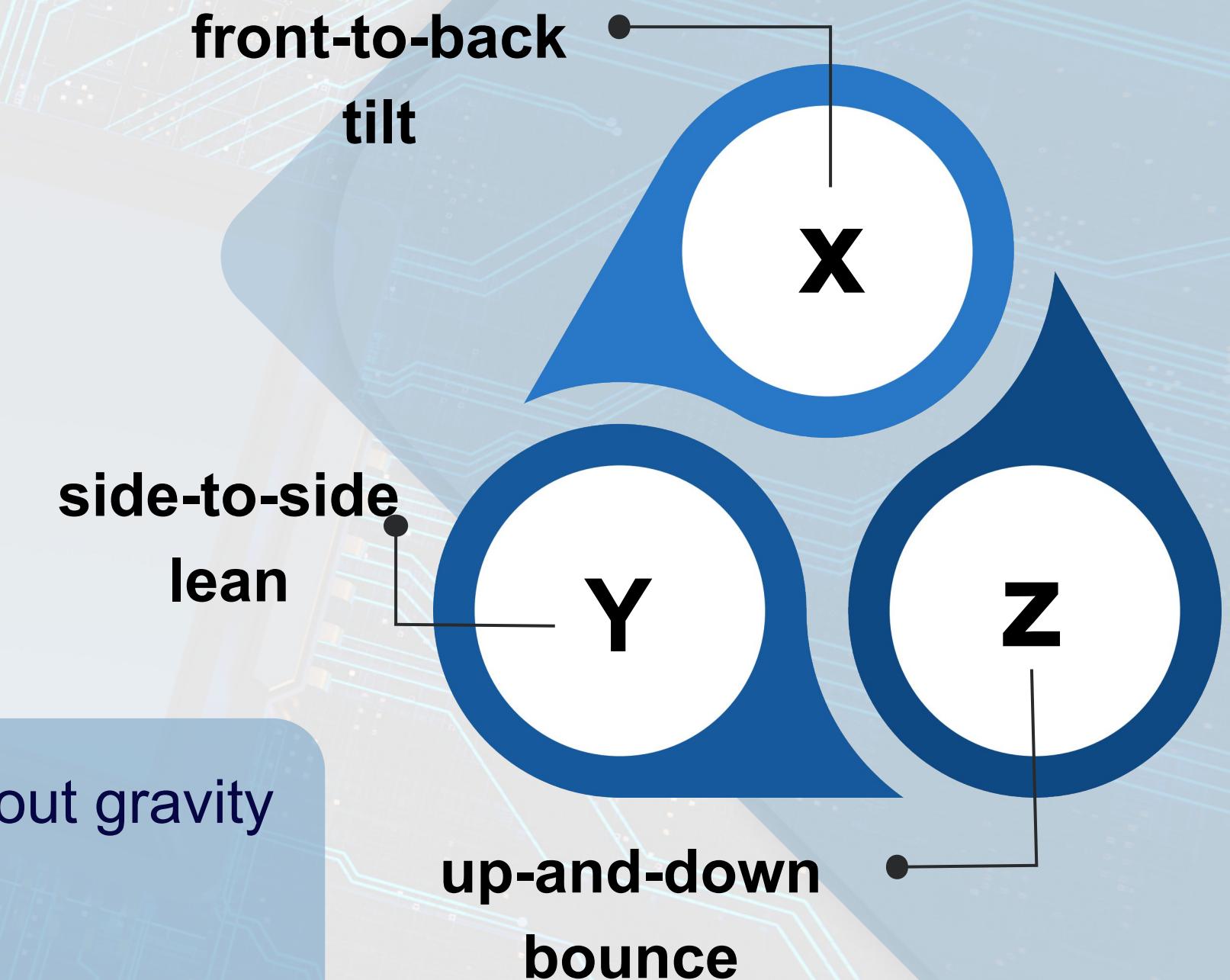
What's Inside Our Data?

Signals

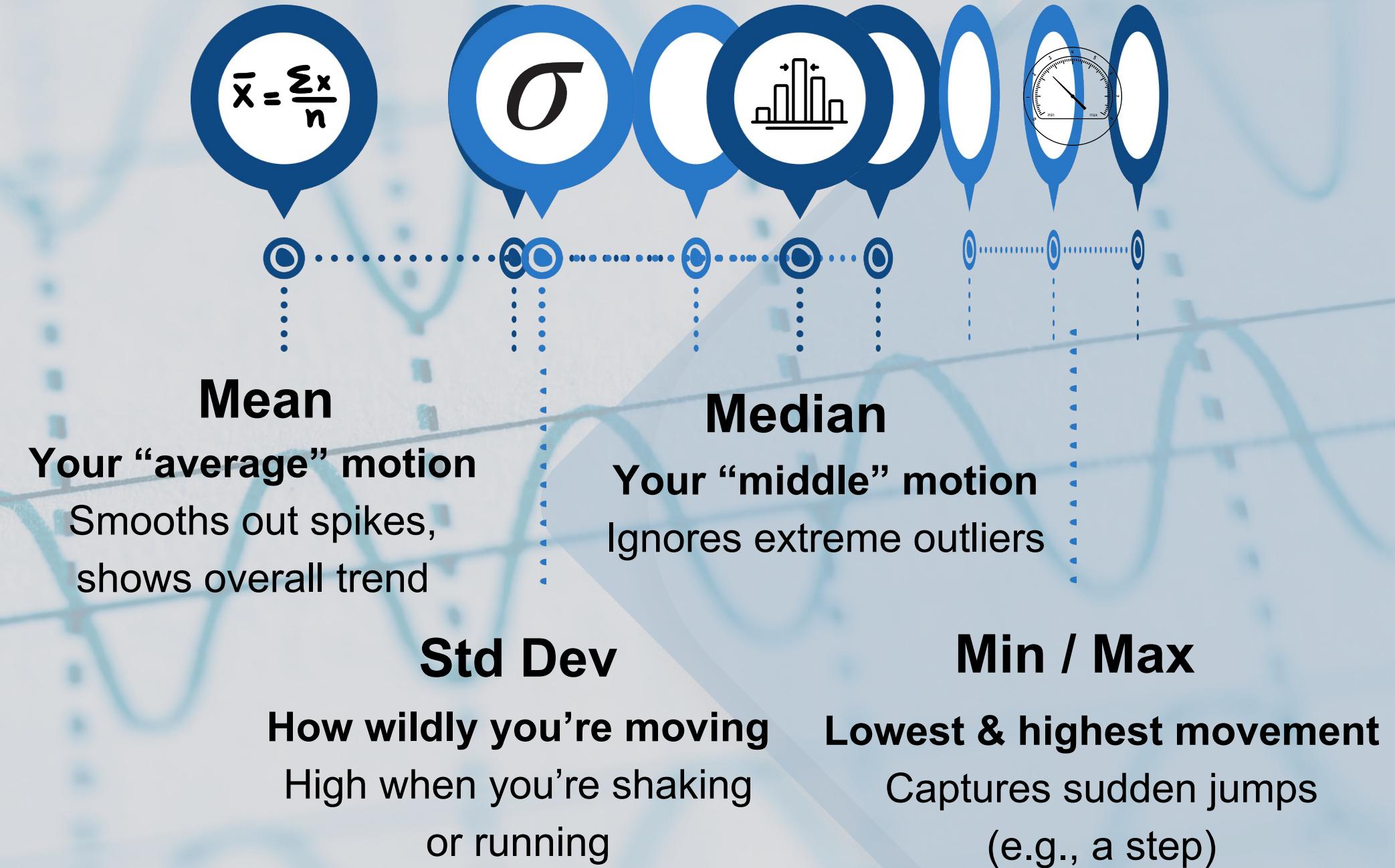


- **Body Acceleration** - raw motion without gravity
- **Gravity Acceleration** - stationary tilt
- **Jerk** - how quickly you start / stop
- **Magnitude** - combined strength of X + Y + Z

Measure - X, Y, Z axes :



How We Summarize Each 2.56 s Window:



Bottom Line

We turn every 2.5 seconds of X/Y/Z sensor readings into a handful of simple numbers so our model can “see” patterns like walking vs. sitting.



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Workflow



Raw Data

2.56-s window
into 561 features

Feature importance

into
434 features

PCA

into
50 PCs

t-SNE

2-D visual map
of 6 activities

1. Feature Selection

- Combined normalized Mutual-Information and RandomForest scores into one “average importance” per feature.
- Sorted features by the combined score

**Result - 434 out of 561 Features
(94.9% total importance)**

2. PCA on Selected Features

- Ran PCA on those 434 features.
- Selected Features captured 90% of the variance.

Result - A compact 50-dimensional representation,
removing low variance / noise directions.

T-SNE

What & Why

t-SNE is a visualization tool

Measures **similarity** of each pair of high-dimensional samples, then arranges the points in **2-D** so that close neighbors stay close and distant ones spread apart.

Result - A scatter plot where tight blobs mark clear clusters

Why we need it ?

- We can't "see" 561- dimensional sensor features
t-SNE turns them into an intuitive picture.
- Quickly shows whether the six activities naturally group into distinct clusters - before we train any model.



3. t-SNE

Projects the 50-dimensional PCA output down to 2D,
preserving local neighborhoods.

Result - Reveals tight clusters for each activity

Key Insights

- **Distinct regions:**
static (Sitting / Standing), stair (Up / Down),
and level Walking each form their own islands.
- **LAYING is alone:**
near-zero motion makes it uniquely
separable.
- **Up stairs vs. Down stairs:**
adjacent yet separate clusters - opposite vertical impulses.
- **Walking island:**
periodic stride pattern keeps it apart from both
static and stair groups.
- **Sitting ↔ Standing overlap:**
minimal movement → occasional mix-ups.



Bottom Line:
A 2-D map still cleanly splits the six activities,
confirming our features capture strong,
learnable patterns.

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Model Architecture



FFNN

with **ReLU** activations



Hidden Layer

Each uses **L2** regularization & **Dropout**,
(followed by Batch Normalization)



Final Layer

Final **softmax** layer -
6 neurons
(one per activity)



Optimizer

Optimized with **Adam** (decaying LR) and early stopping

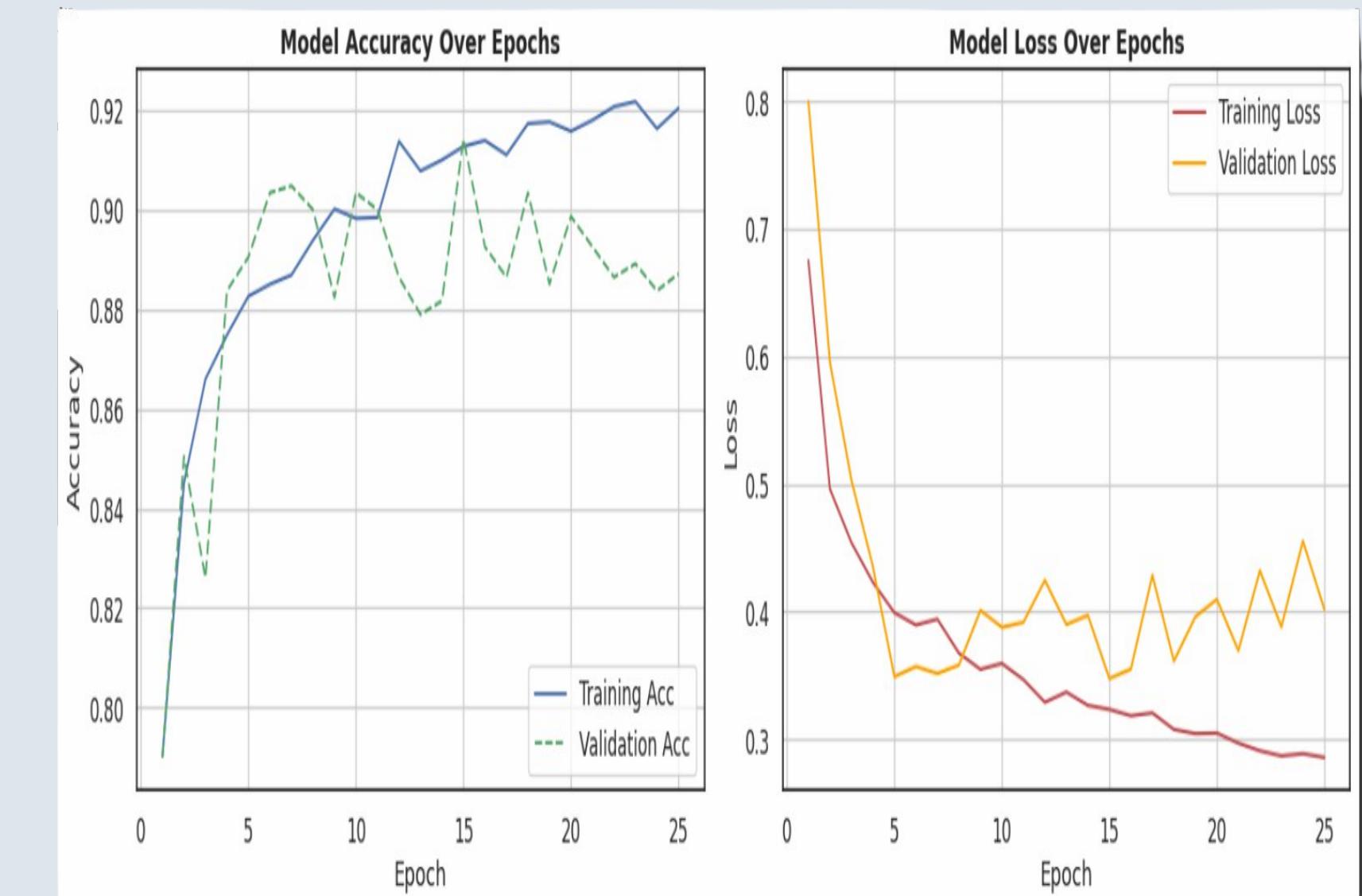
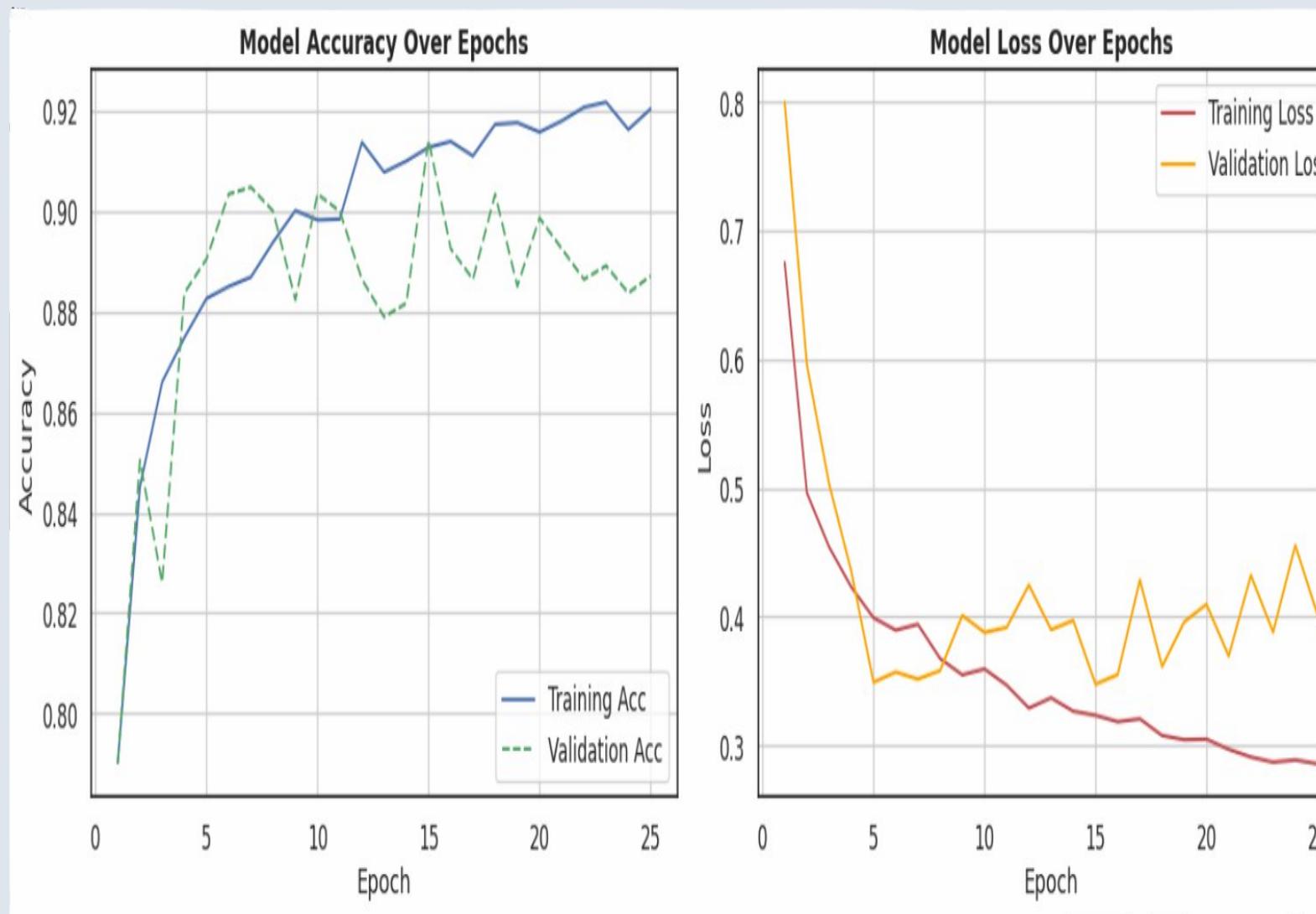
Evaluation & Results

(On the Test Set)



- **Accuracy - 0.88**
- **Macro Avg:**
 - **Precision - 0.879**
 - **Recall - 0.877**
 - **F1 - 0.877**
- **Weighted Avg:**
 - **Precision - 0.88**
 - **Recall - 0.88**
 - **F1 - 0.88**

Before Balancing...



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THANK YOU

FOR YOUR ATTENTION
AND PARTICIPATION

Any Questions ?

