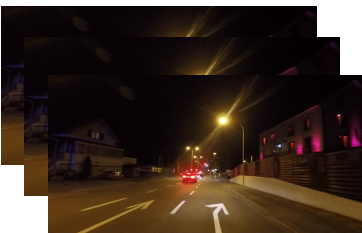
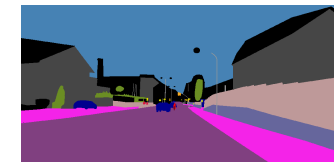




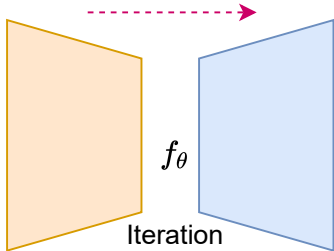
Image



Batch of images



Ground truth



Iteration

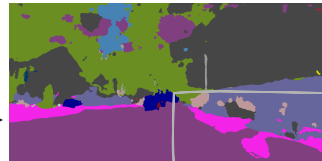
$$\frac{\partial L(S)}{\partial S_p}$$

S

$L(S)$



Initial prediction



Iteration 3



Iteration 5

