

# OCELOT: TRACE OVERVIEWS BASED ON MULTIDIMENSIONAL DATA AND VISUAL AGGREGATION

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# INTRODUCTION

# TRACE VISUALIZATION PROBLEMATIC

## ► Trace contents:

- **SPACE** = application structure:

- **hardware** components: *clusters, machines, cores, etc.*
- **software** components: *processes, threads, etc.*

- **TIME** = timestamped events:

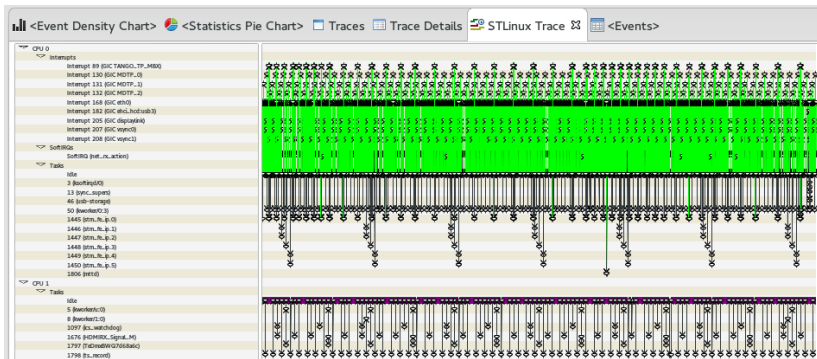
- *function calls, communications, CPU load, malloc, etc.*

## ► Traces can be **HUGE**

→ **scalability issues** of space-time representations



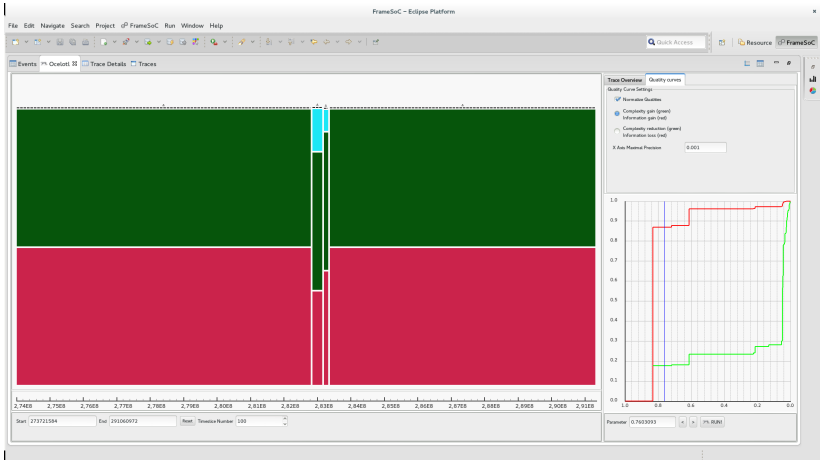
# PROBLEMATIC VISUALIZATION



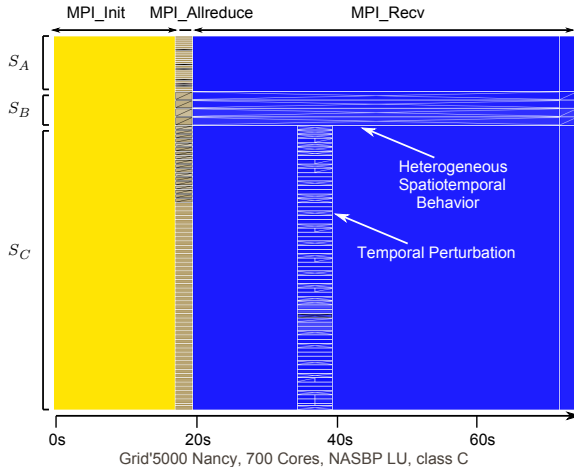
# OUR PROPOSAL MULTIDIMENSIONAL OVERVIEWS

- ▶ Several overviews generated thanks to **data aggregation**
  - Temporal
  - Spatiotemporal
- ▶ Showing **meaningful information** (phases, perturbations)
- ▶ Possibility to adjust dynamically the **level of details**

# EXAMPLE : TEMPORAL OVERVIEW



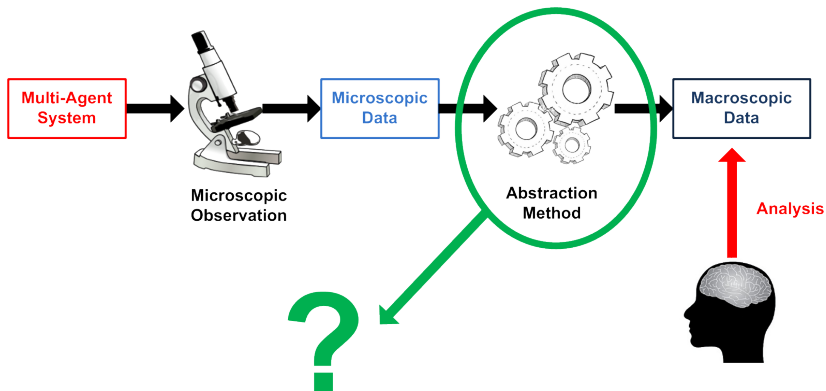
# EXAMPLE : SPATIOTEMPORAL OVERVIEW



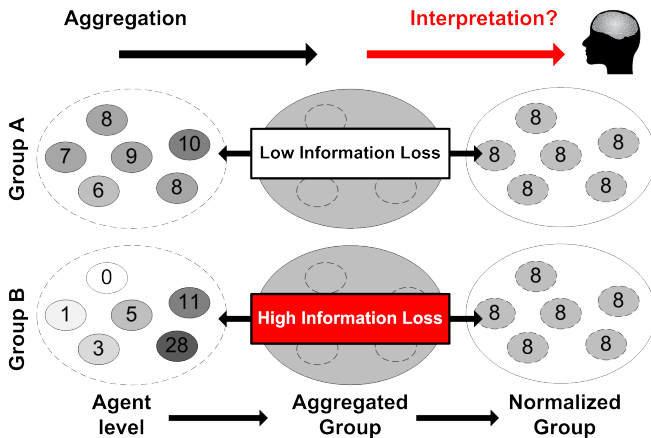
THEORETICAL BACKGROUND :  
LAMARCHE-PERRIN  
METHODOLOGY



# ADAPTING AN AGGREGATION METHODOLOGY

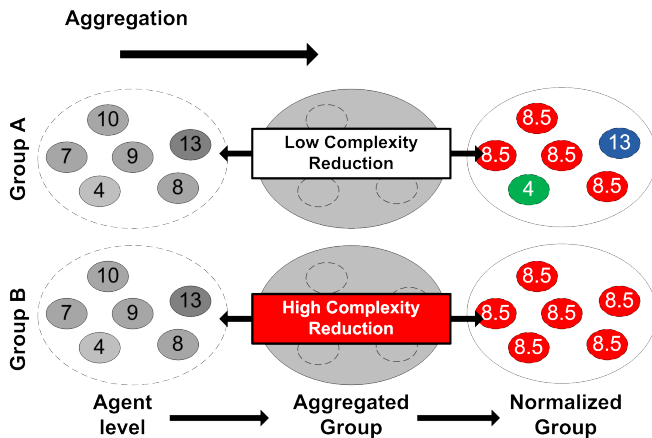


# INFORMATION LOSS: KL DIVERGENCE



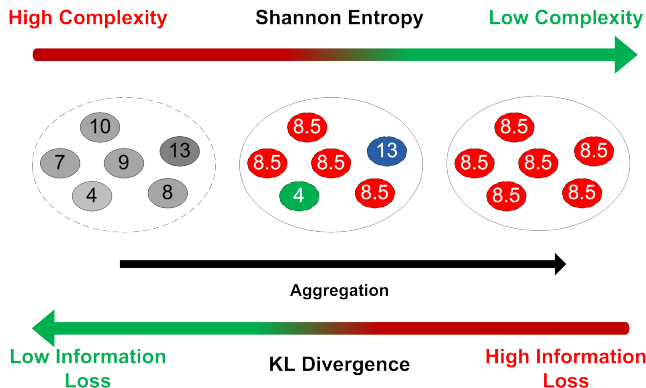
$$\text{loss}_E = \sum_{e \in E} \rho_e \log_2 \left( \frac{\rho_e}{\rho_E} \right)$$

# COMPLEXITY REDUCTION: SHANNON ENTROPY



$$\text{gain}_E = \rho_E \log_2 \rho_E - \sum_{e \in E} \rho_e \log_2 \rho_e$$

# TRADE-OFF: PIC



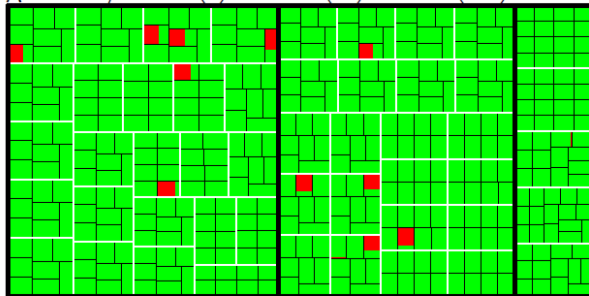
$$pIC_E = p \text{ gain}_E - (1-p) \text{ loss}_E$$

$$pIC_{\mathcal{P}} = \sum_{E \in \mathcal{P}} pIC_E$$

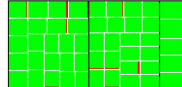
- For a given  $p$ : choose  $\mathcal{P}$  with the highest  $pIC$
- Aggregate in priority most homogeneous values

# VIVA: SPATIAL AGGREGATION (SCHNORR & LP)

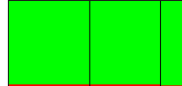
A Hierarchy: Cluster (3) - Machine (50) - Process (433)



A.1 Machine level



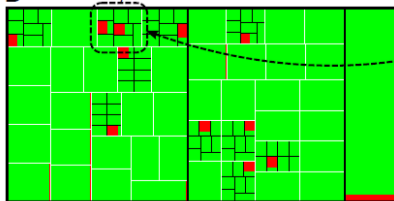
A.2 Cluster level



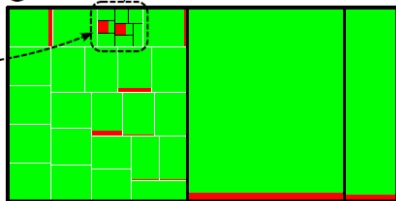
A.3 Full aggregation



B Ratio Gain/Loss with  $P = 10\%$



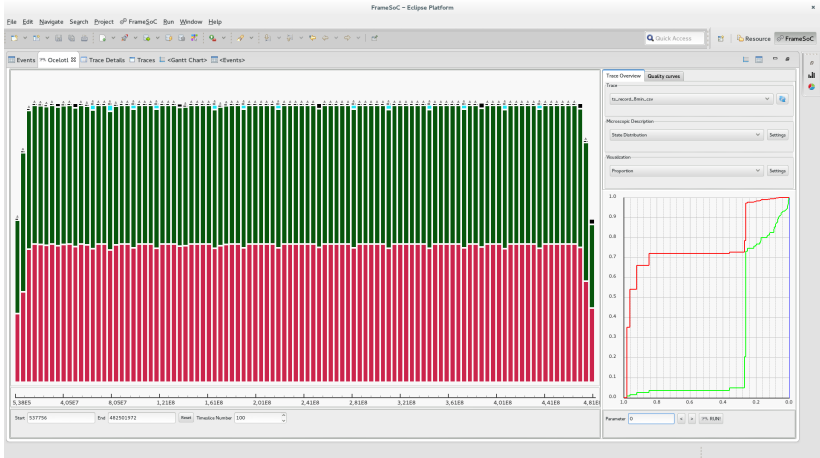
C Ratio Gain/Loss with  $P = 30\%$



# TEMPORAL OVERVIEW

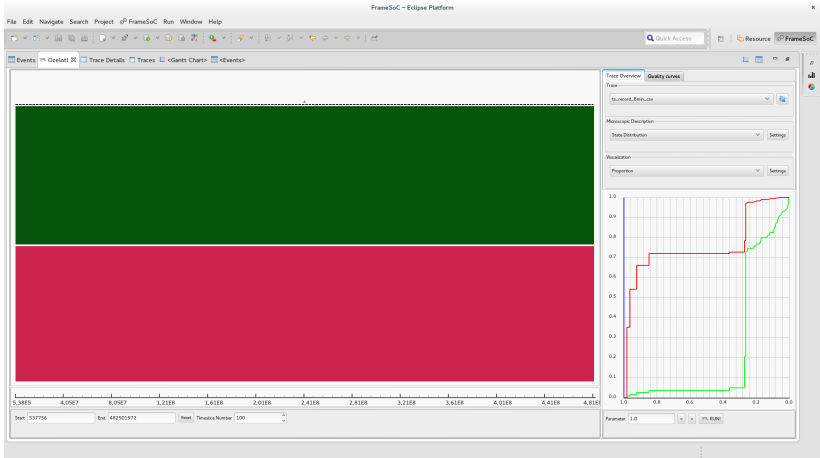


# MINIMUM INFORMATION LOSS: $P=0$

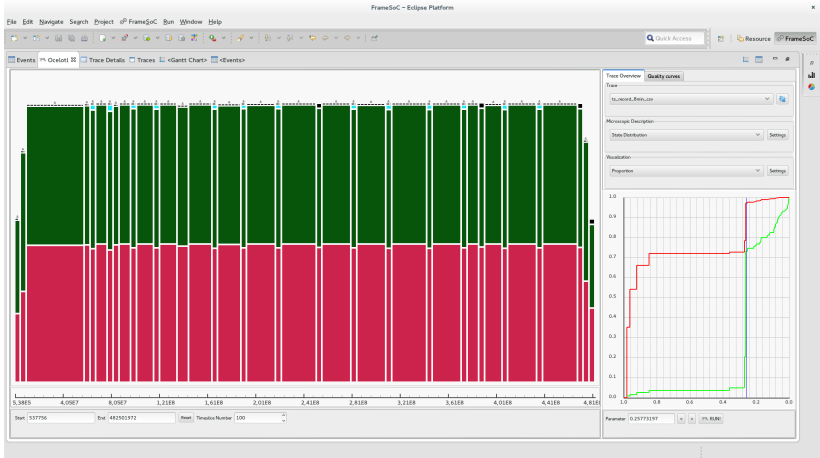




# MAXIMUM COMPLEXITY REDUCTION: $P=1$

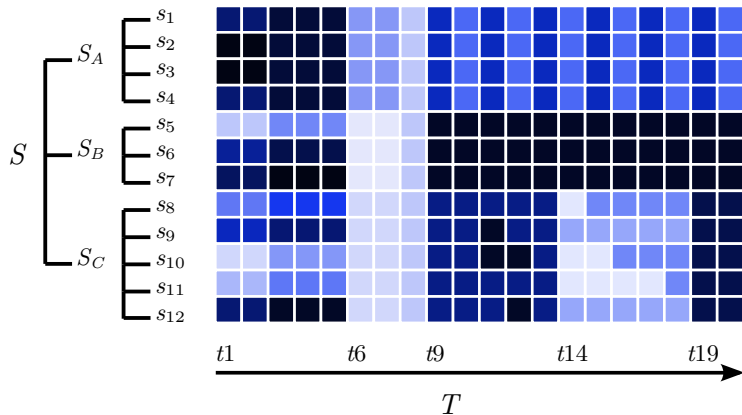


# INTERESTING TRADE-OFF



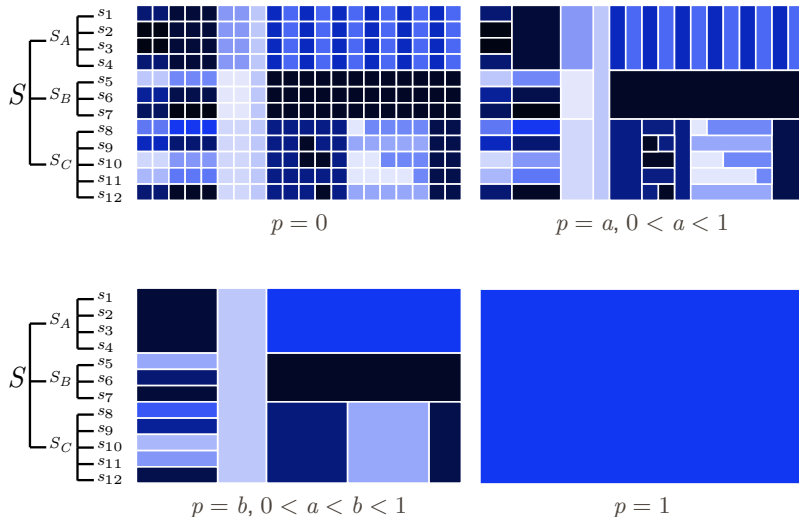
# SPATIOTEMPORAL OVERVIEW

# GENERATE A TRACE MICROSCOPIC MODEL



$$|X| = 2, \rho_x(s, t) = d_x(s, t)/d(t) \in [0, 1], \rho_1(s, t) = 1 - \rho_2(s, t)$$

# AGGREGATE THE MICROSCOPIC MODEL

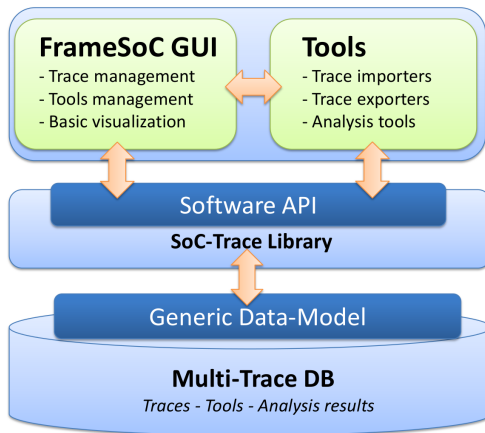


# IMPLEMENTATION AND FEATURES

# OCELOTL TOOL

- ▶ Implementation of the overview techniques
- ▶ Generic architecture. Add:
  - Your own **aggregation operator** (dimensions, metric)
  - Your own **visualization**
- ▶ Persistent caches to avoid long recomputations
- ▶ Integrated in **Framesoc**:
  - Trace and tools management
  - **Fast** trace reading (DB queries)
  - **Interaction** with other analysis tools
  - Also enable to **add you own tools**

# FRAMESOC

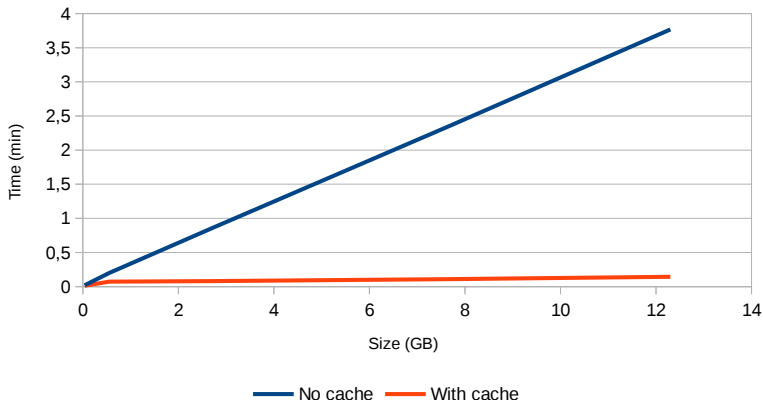


- Trace format compatibility : Pajé (Akypuera: tool to convert from OTF2, Tau), LTTng, KPTrace



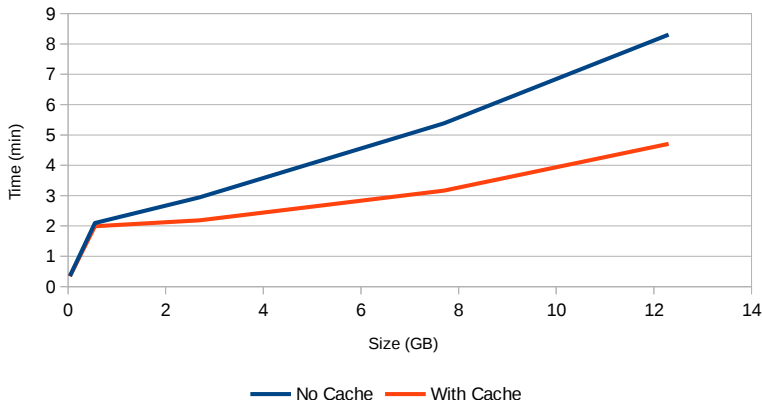
# PERFORMANCE: TEMPORAL ANALYSIS

Total analysis time as a function of trace size (100 time slices)



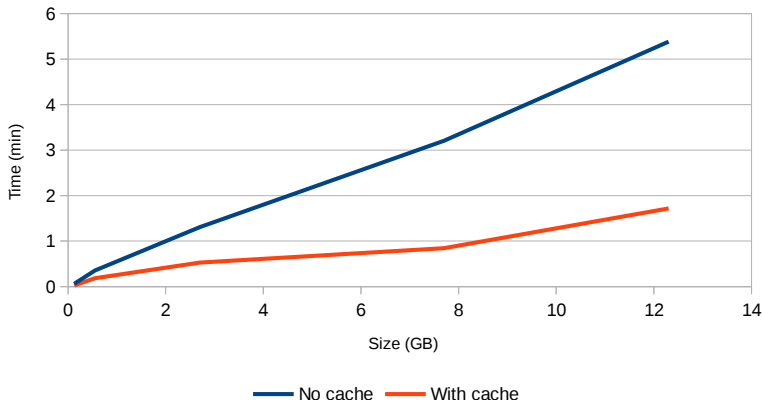
# PERFORMANCE: TEMPORAL ANALYSIS

Total analysis time as a function of trace size (1000 time slices)



# PERFORMANCE: SPATIOTEMPORAL ANALYSIS

Total analysis time as a function of trace size (30 time slices)



# DEMONSTRATION

# CONCLUSION

# CONCLUSION

- ▶ **Visualizations** based on spatiotemporal **data aggregation**
  - Solves screen, computing and analyst capability **limitations**
  - Gives **meaningful information** about homogeneity (phases, perturbations)
- ▶ **Implementation:**
  - **Interaction** (zoom, switch to other tools)
  - Helps to drastically **reduce computation times** (caches)
  - **Generic architecture:** add your own aggregation and visualization
- ▶ **Future work:**
  - **Extend methodology** and design new algorithms ( $\mathcal{H}(S) \times \mathcal{H}(S) \times \mathcal{I}(T)$ , surface, etc.)
  - **Improve visualization** and **interaction** to get more details
  - Framesoc: native compatibility with **OTF2** (soon)

# LINKS

## Ocelotl:

<http://soctrace-inria.github.io/ocelotl/>

## Framesoc:

<http://generoso.github.io/framesoc/>

## Tools:

<http://github.com/schnorr/>

# PROJECT

## ► **Current Project: SoC-Trace**

- **Academics:** Inria, Grenoble Univ., LIG
- **Industrials:** STMicroelectronics, ProbaYes, Magillem
- **Funding:** FUI (Ministry of Industry)
- **Topic:** Embedded System Analysis Infrastructure

## ► **After SoC-Trace?**

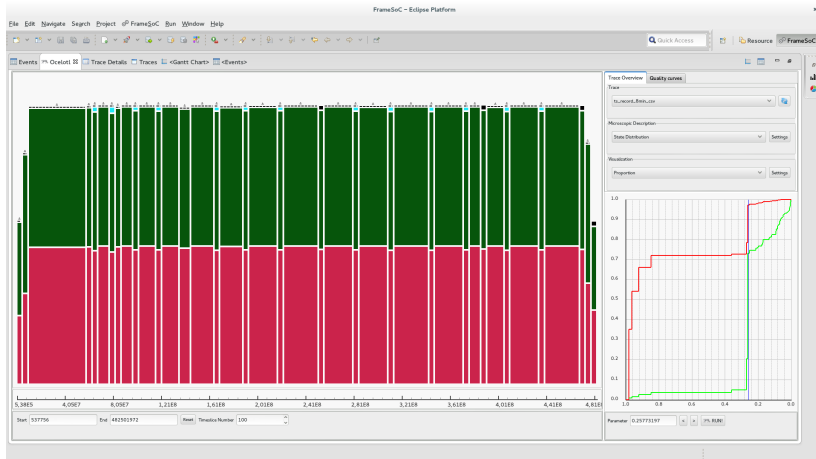
- European Project
- BSC?
- Contacts:
  - [guillaume.huard@imag.fr](mailto:guillaume.huard@imag.fr)
  - [arnaud.legrand@imag.fr](mailto:arnaud.legrand@imag.fr)



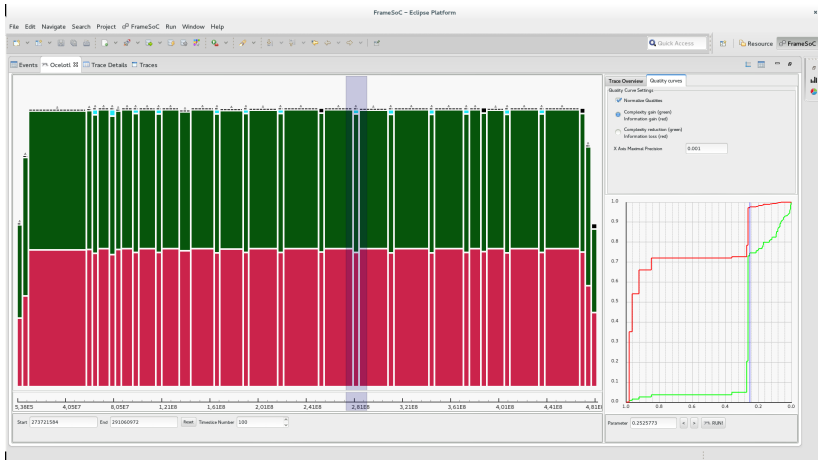
# THANK YOU FOR YOUR ATTENTION



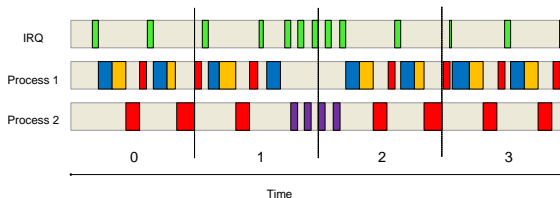
# OCELOT: TEMPORAL AGGREGATION (1)



# OCELOT: TEMPORAL AGGREGATION (2)



# GENERATE A TRACE MICROSCOPIC MODEL



IRQ	0	0	0	0
Process 1	1	2.1	1	3
Process 2	4.1	2	4.1	4

IRQ	2	4.9	3	2.4
Process 1	0	0	0	0
Process 2	0	0	0	0

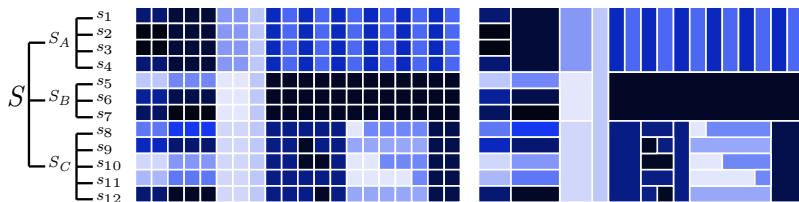
And so on...

# DATA AGGREGATION METHODOLOGY

- ▶ A1. Choose a **model** and a **metric**
- ▶ A2. Choose on **which dimension(s)** aggregate
- ▶ A3. Define the **operands**
- ▶ A4. **Constrain** the aggregation :  $\rightarrow$  partitions  $\mathcal{P}$  allowed
- ▶ A5. Define the **operator**
- ▶ A6. Define the **trigger** - the aggregation condition
- ▶ A7. Build the **algorithm** satisfying A1-A6

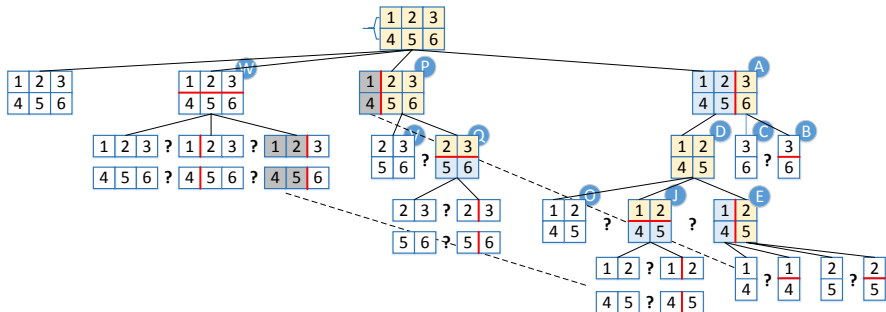
## A2-A5

- ▶ A2. We aggregate simultaneously on  $T$  and  $S$
- ▶ A3. Operands:  $(s, t) \in S \times T$
- ▶ A4. Constraint:  $\mathcal{A}(S \times T) = \mathcal{H}(S) \times \mathcal{I}(T)$   
Aggregation result is a partition  $\mathcal{P}(S \times T) \in \mathcal{A}(S \times T)$
- ▶ A5. Operator:  $+$
- ▶ A6. Trigger: maximize pIC of the partition  $\mathcal{P}(S \times T)$



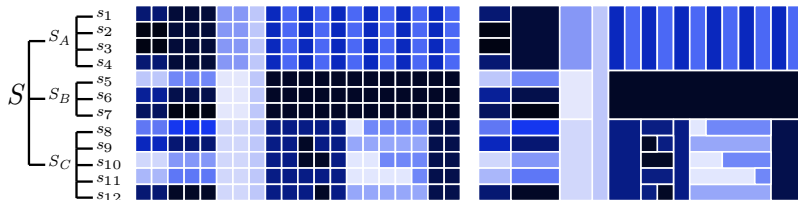
# BEST CUT ALGORITHM

- Compute the partition with the highest pIC :
  - Cut an area : time, space (or no cut)
  - Best cut: the partition  $\mathcal{P}$  where  $\sum_{E \in \mathcal{P}} \text{pIC}_E$  is max
  - Recursively cut and evaluate the partitions of  $E_1, E_2 \in \mathcal{P}$
  - Useless recomputation is avoided



## A6. TRIGGER THE AGGREGATION

- ▶ Quantification of data reduction and information loss
  - aggregate the homogeneous areas
  - preserve the microscopic information of the heterogeneous areas
- ▶ Each  $(S_k, T_{(i,j)}) \in \mathcal{A}(S \times T)$  has an associated gain and loss
- ▶ gain and loss of a partition  $\mathcal{P}(S \times T)$  is the sum of gain and loss of its content  $(S_k, T_{(i,j)}) \in \mathcal{P}(S \times T)$

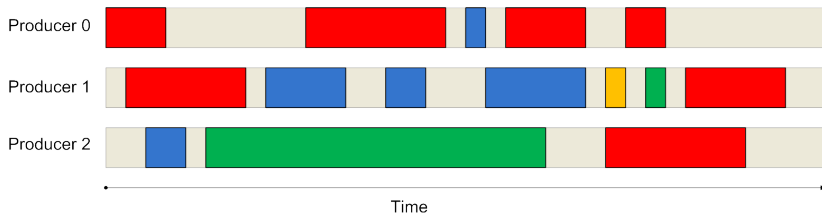




# ELMQVIST-FEKETE CRITERIA

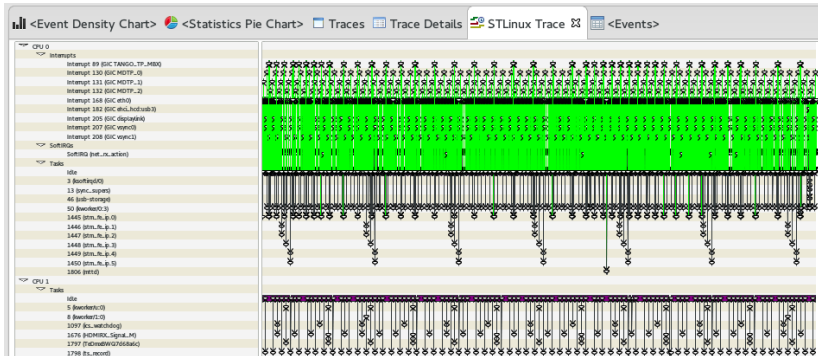
- ▶ **Shneiderman** : **overview**, zoom and filter, then get details on demand
- ▶ **Elmqvist & Fekete**: guidelines to design an **overview** visualization based on hierarchical aggregation
  - G1. Entity Budget
  - G2. Visual Summary
  - G3. Visual Simplicity
  - G4. *Discriminability*
  - G5. Fidelity
  - G6. *Interpretability*

# VISUALIZATIONS NOT FULFILLING THESE CRITERIA (1)



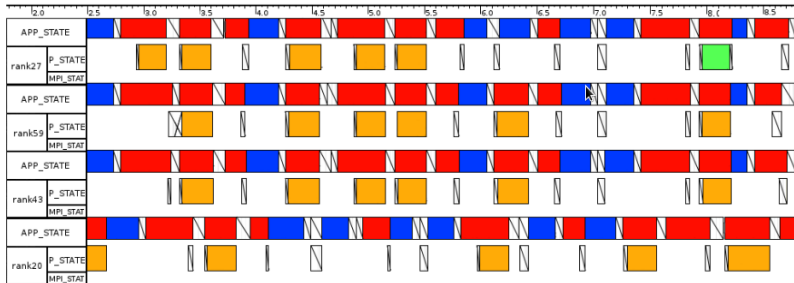
Example of Gantt chart - space-time diagram

# VISUALIZATIONS NOT FULFILLING THESE CRITERIA (2)



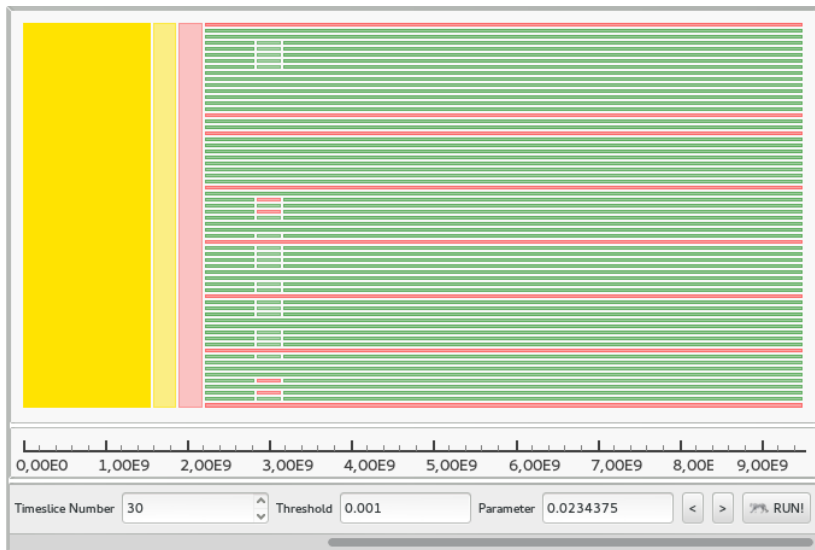
KPTrace:  $\overline{G1}$  (time),  $\overline{G2}$ ,  $\overline{G4}$ ,  $\overline{G5}$

## VISUALIZATIONS NOT FULFILLING THESE CRITERIA (2)

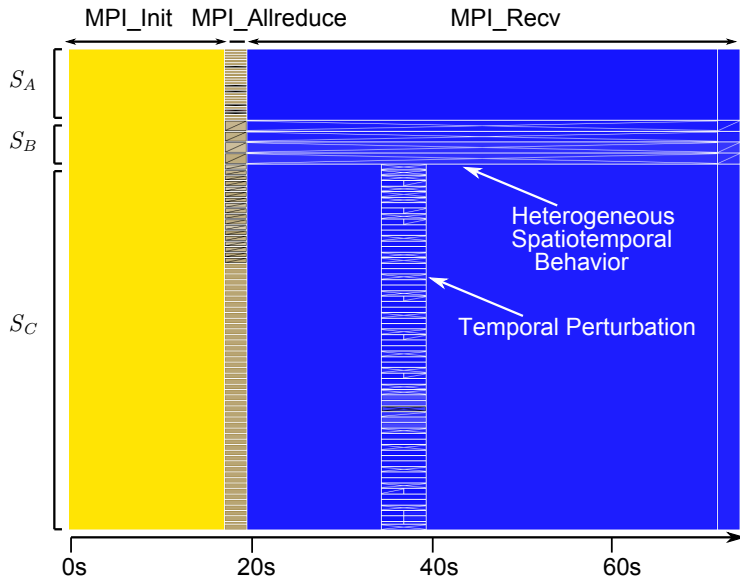


Pajé:  $\overline{G1}$  (space),  $\overline{G2}$

# CG CLASS C, 64 PROCESSES ON G5K RENNES



# LU CLASS C, 700 PROCESSES ON G5K NANCY



# PERFORMANCES (SPATIOTEMPORAL)

	Case A	Case B	Case C	Case D
<b>Application</b>	CG, class C	CG, class C	LU, class C	LU, class B
<b>Processes</b>	64	512	700	900
<b>Site</b>	Rennes	Grenoble	Nancy	Rennes
<b>Clusters (nodes)</b>	parapide(8)	adonis(9), edel(24), genepi(31)	graphene(26), graphite(4), griffon(67)	paradent(38), parapide(21), parapluie(18)
<b>Event number</b>	3,838,144	49,149,440	218,457,456	177,376,729
<b>Trace size</b>	136.9 MB	1.8 GB	8.3 GB	6.7 GB
<b>Ocelotl computation times (30 time slices)</b>				
<b>Trace reading + Microscopic description</b>	5 s	31 s	222 s	174 s
<b>Aggregation</b>	<1s	<1s	2s	2s