

# MULTIDIMENSIONAL DATA AGGREGATION AND VISUALIZATION FOR HUGE EXECUTION TRACE ANALYSIS

MOAIS seminary, 28th November 2014

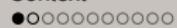
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Advisors: Guillaume Huard, Jean-Marc Vincent



# CONTEXT

Context



Data Aggregation



Temporal Overview



Spatiotemporal Overview



Demo

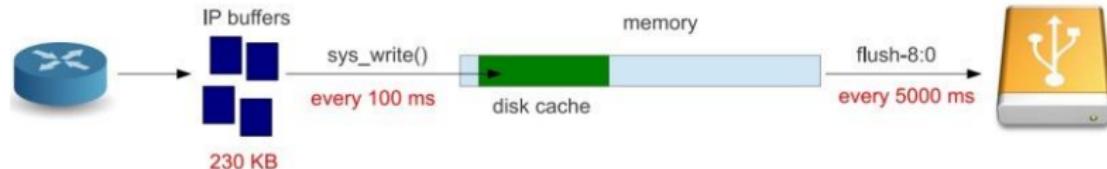
Conclusion



# EXAMPLE

Play

# ST MICROELECTRONICS' TS RECORD USE CASE



- ▶ HD video streaming : **big quantity of data** transmitted through the **network**
- ▶ Data stored in **IP buffers**, waiting to be sent to the disk
- ▶ **sys\_write()** function send the data to the disk every 100 ms
- ▶ The **kernel flushes** the disk cache every 5000 ms

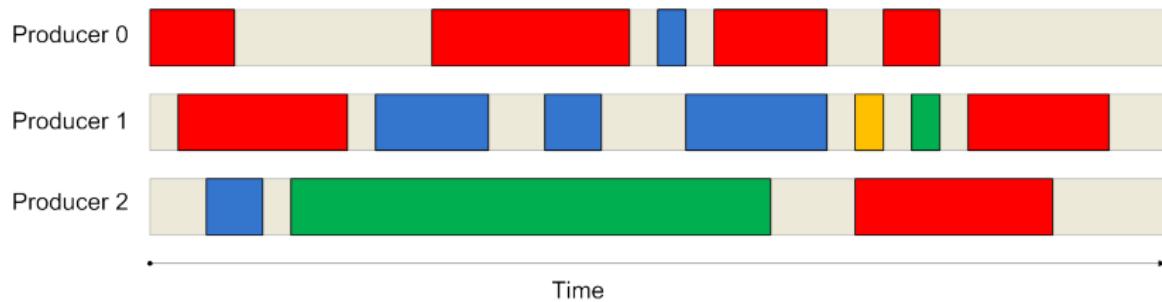
# SOC-TRACE PROJECT

- ▶ **Inria, UJF, STMicroelectronics, ProbaYes, Magillem**
- ▶ **Objective:** Analysis flow of execution traces of embedded multimedia applications
- ▶ **Main contributions:**
  - **Framesoc:** trace, tool and analysis result management infrastructure (MESCAL)
  - FrameMiner, MegaLog: data mining, pattern recognition, probabilistic analysis (HADAS, ProbaYes)
  - **Ocelotl: trace overviews based on data and visual aggregation (MOAIS)**

# PARALLEL AND DISTRIBUTED SYSTEM ANALYSIS

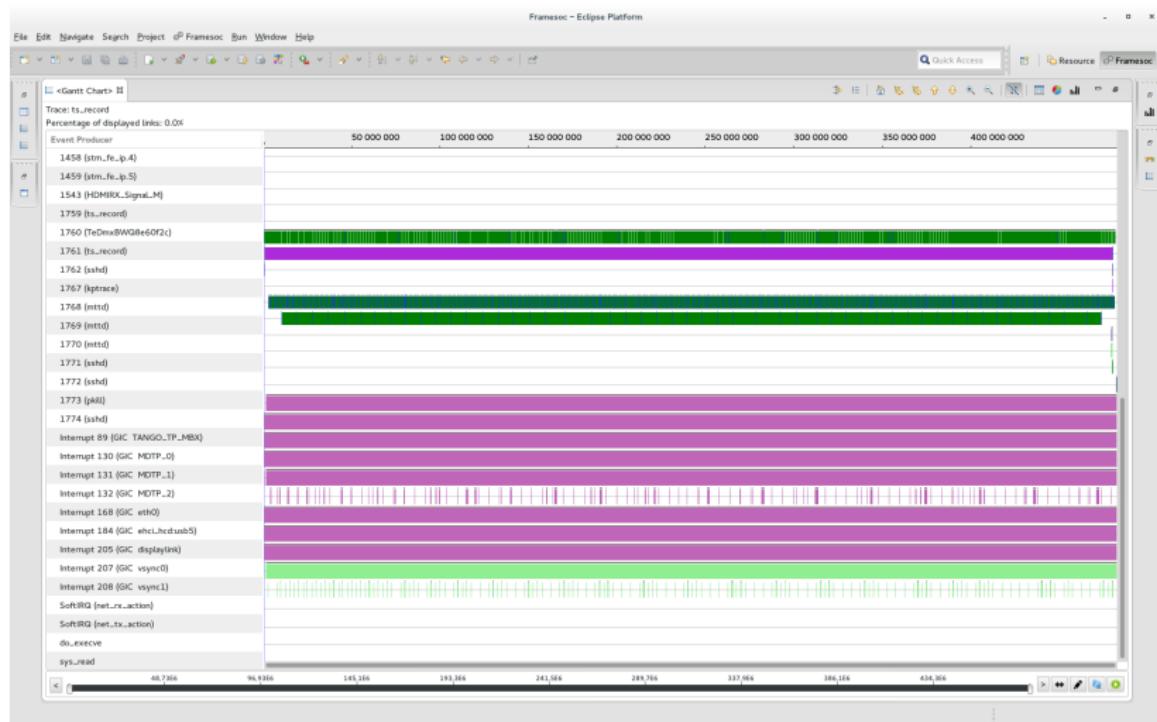


# SPACE-TIME REPRESENTATIONS PROBLEMATIC



- ▶ Structure can be composed of millions of resources
- ▶ Trace can contain billions of events (up to TB)

# LIMITED SCREEN SIZE ISSUES



# COMPUTATION - RENDERING - INTERACTIVITY ISSUES



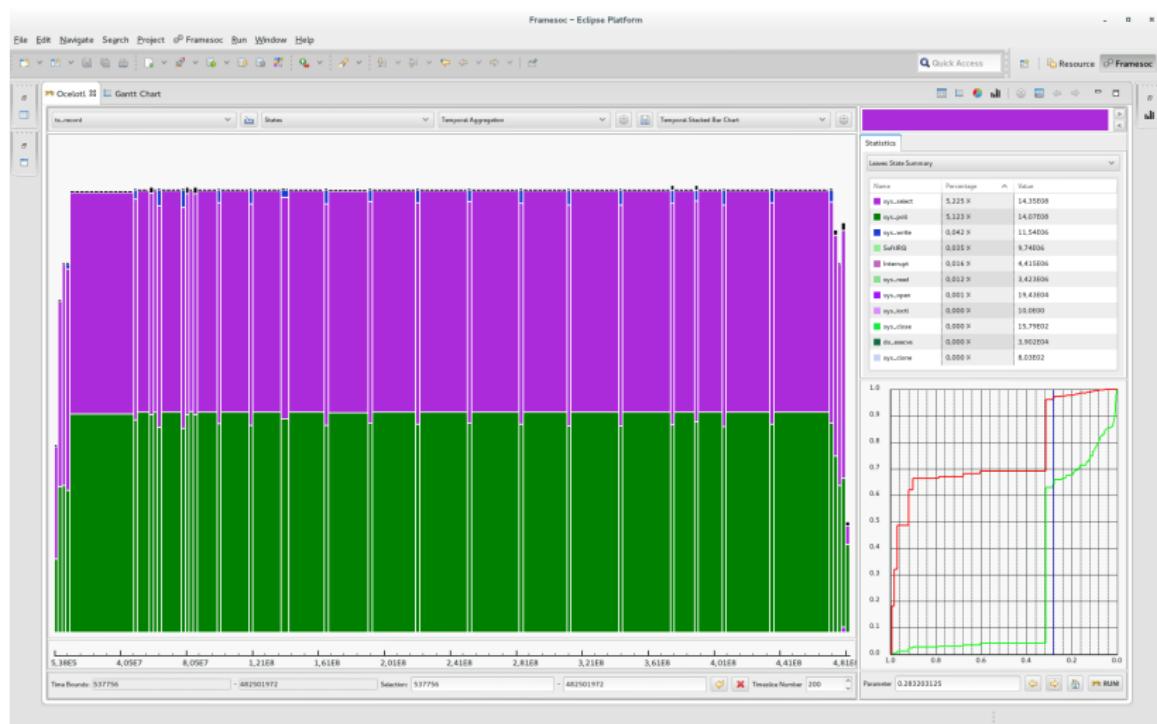
# ANALYST CAPABILITY LIMITS



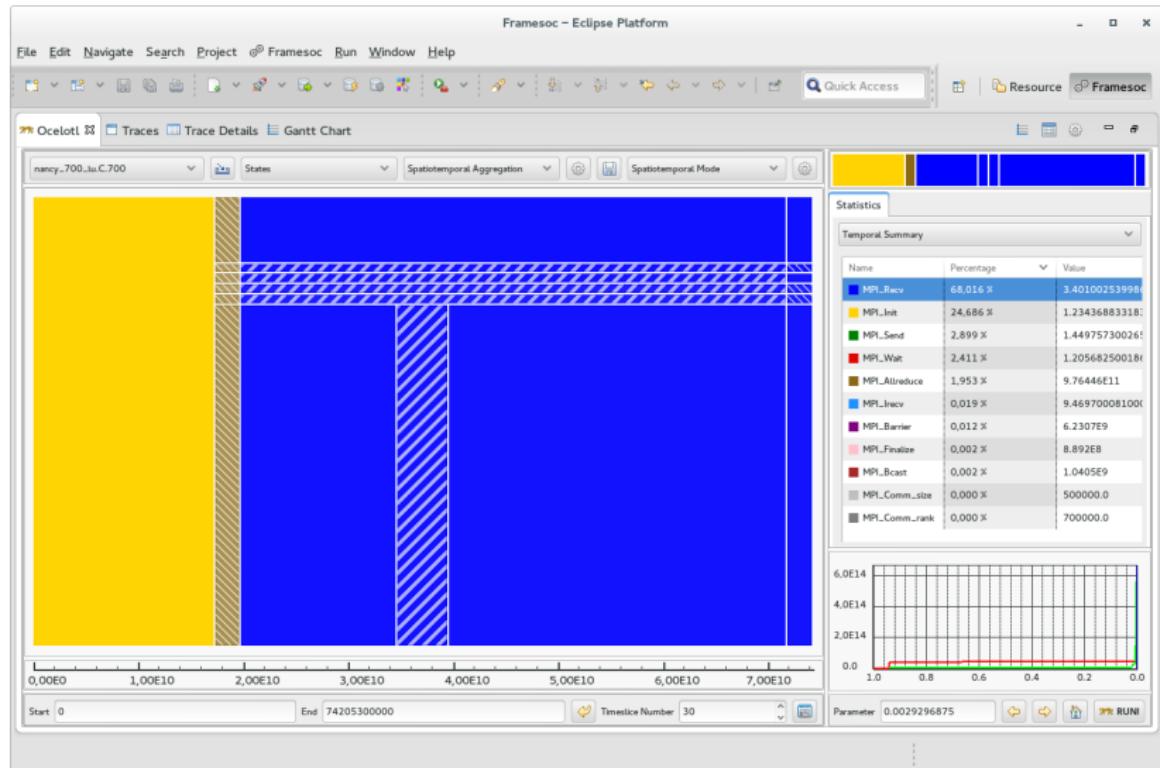
# OUR PROPOSAL: METHODOLOGY TO BUILD OVERVIEWS

- ▶ Overviews generated using **data and visual aggregation**
- ▶ Showing **meaningful information** (phases, perturbations)
- ▶ Enabling to adjust dynamically the **level of details**
- ▶ **Interaction:**
  - Zoom
  - Filtering
  - Synchronized statistics
  - Switch to other representations

# OCELOT: TEMPORAL AGGREGATION

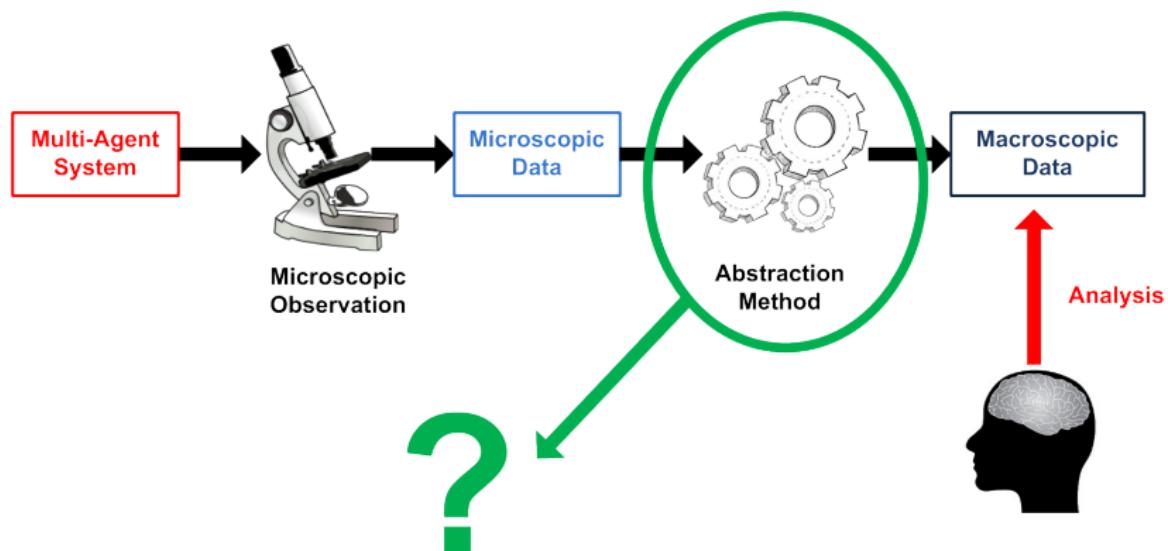


# OCELOT: SPATIOTEMPORAL AGGREGATION

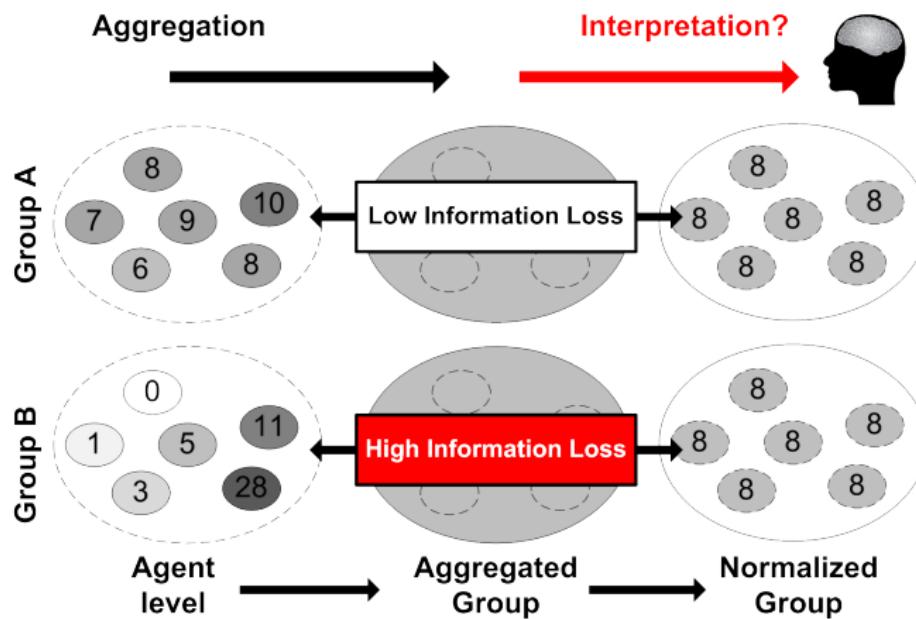


# DATA AGGREGATION METHODOLOGY

# ADAPTING AN AGGREGATION METHODOLOGY (R.LP)

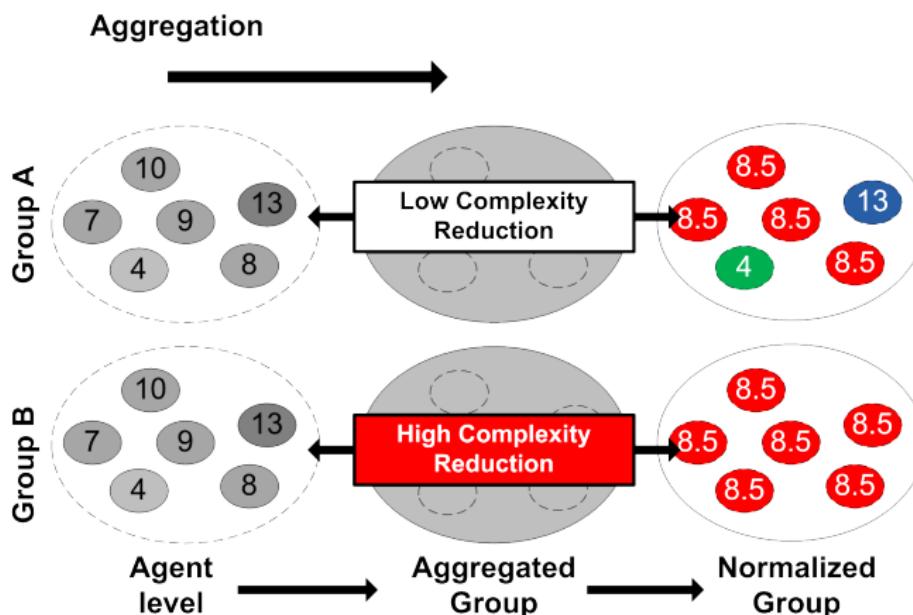


# INFORMATION LOSS: KL DIVERGENCE



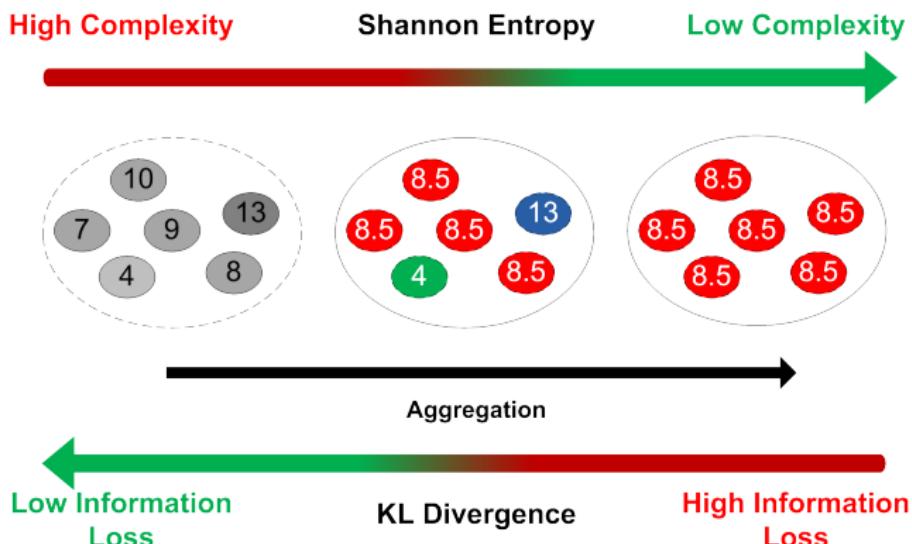
$$\text{loss}_E = \sum_{e \in E} \rho_e \log_2 \left( \frac{\rho_e}{\rho_E} \right)$$

# COMPLEXITY REDUCTION: SHANNON ENTROPY



$$\text{gain}_E = \rho_E \log_2 \rho_E - \sum_{e \in E} \rho_e \log_2 \rho_e$$

# TRADE-OFF: PIC



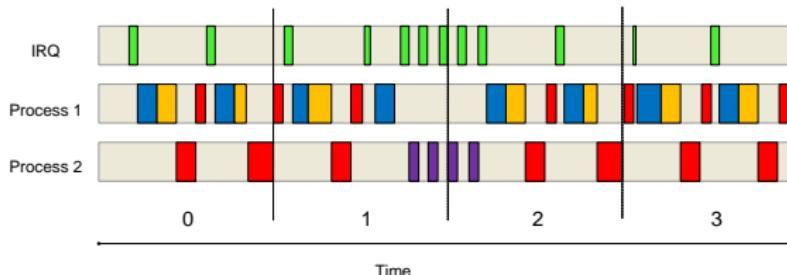
$$\text{pIC}_E = p \text{gain}_E - (1-p) \text{loss}_E$$

$$\text{pIC}_{\mathcal{P}} = \sum_{E \in \mathcal{P}} \text{pIC}_E$$

- ▶ For a given  $p$ : choose  $\mathcal{P}$  with the highest pIC
- ▶ Aggregate in priority most homogeneous values

# TEMPORAL OVERVIEW

# GENERATE A TRACE MICROSCOPIC MODEL

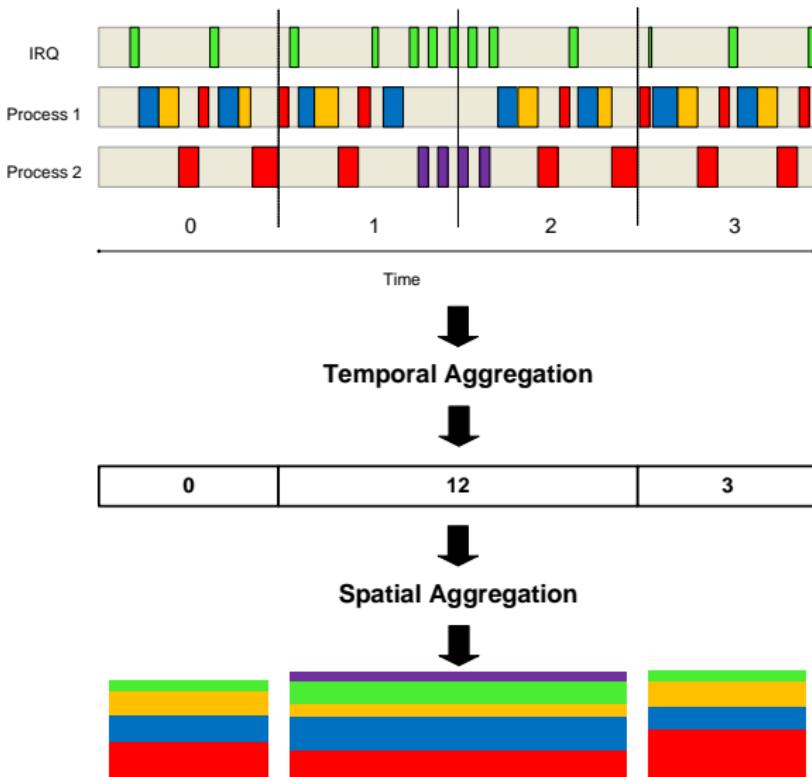


|           |     |     |     |   |
|-----------|-----|-----|-----|---|
| IRQ       | 0   | 0   | 0   | 0 |
| Process 1 | 1   | 2.1 | 1   | 3 |
| Process 2 | 4.1 | 2   | 4.1 | 4 |

|           |   |     |   |     |
|-----------|---|-----|---|-----|
| IRQ       | 2 | 4.9 | 3 | 2.4 |
| Process 1 | 0 | 0   | 0 | 0   |
| Process 2 | 0 | 0   | 0 | 0   |

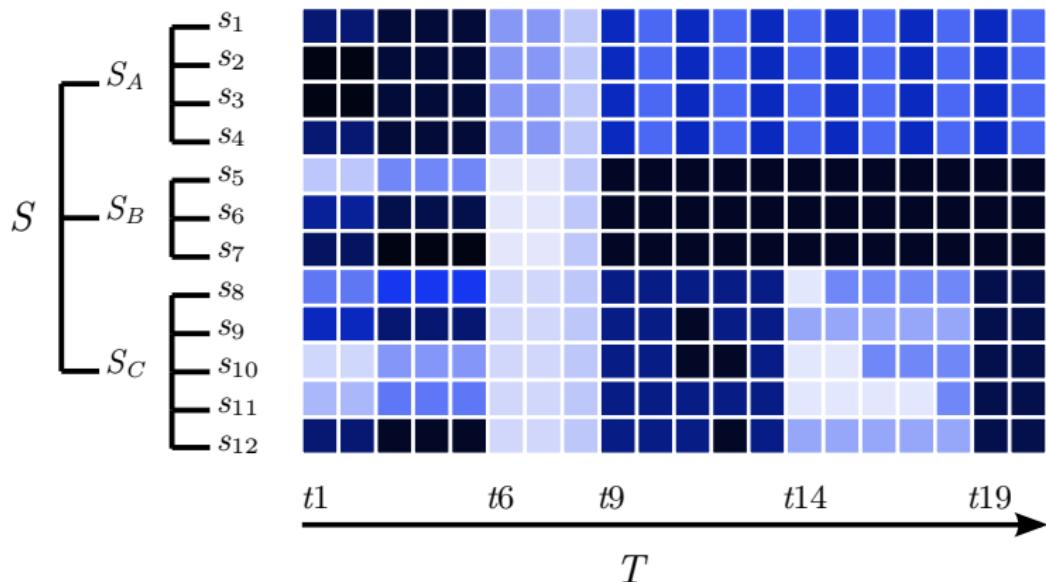
And so on...

# TEMPORAL AGGREGATION AND VISUALIZATION



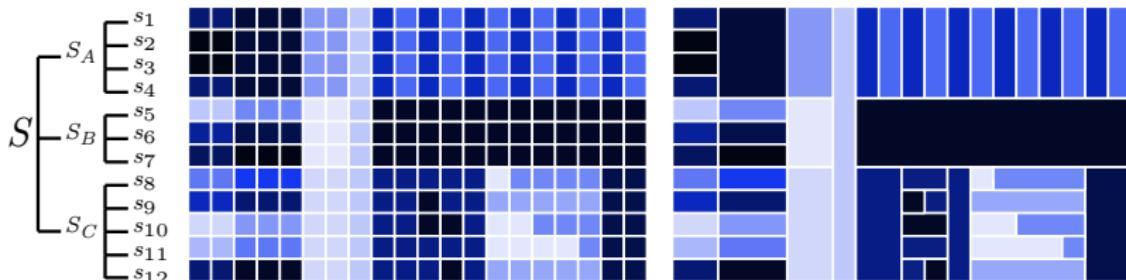
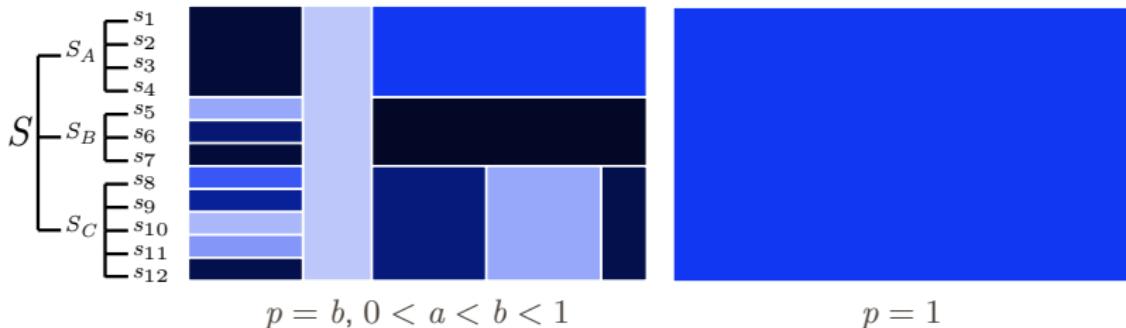
# SPATIOTEMPORAL OVERVIEW

# GENERATE A TRACE MICROSCOPIC MODEL



$$|X| = 2, \rho_x(s, t) = d_x(s, t)/d(t) \in [0, 1], \rho_1(s, t) = 1 - \rho_2(s, t)$$

# AGGREGATE THE MICROSCOPIC MODEL

 $p = 0$  $p = a, 0 < a < 1$  $p = b, 0 < a < b < 1$  $p = 1$

DEMO

# CONCLUSION

# CONCLUSION

- ▶ **Visualizations based on data and visual aggregation**
  - Solves screen, computing and analyst capability limitations
  - Gives meaningful information about homogeneity (phases, perturbations)
- ▶ **Implementation:**
  - Interaction (zoom, switch to other tools)
  - Performance 5 min for a 12 GB trace (220 millions of events), <1 min using a cache
- ▶ **Improvement axes:**
  - New aggregation algorithms
  - Visualization & interaction
  - Analysis of bigger and more complex applications

# LINKS

**Ocelotl:**

<http://soctrace-inria.github.io/ocelotl/>

# THANK YOU FOR YOUR ATTENTION

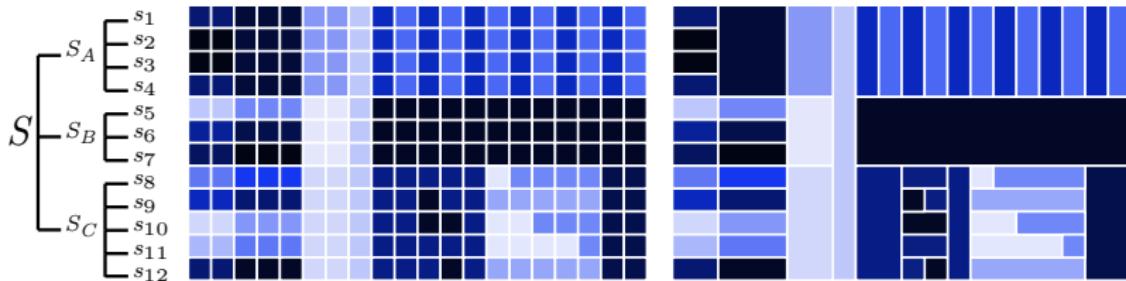


# DATA AGGREGATION METHODOLOGY

- ▶ A1. Choose a **model** and a **metric**
- ▶ A2. Choose on **which dimension(s)** aggregate
- ▶ A3. Define the **operands**
- ▶ A4. **Constrain** the aggregation : → partitions  $\mathcal{P}$  allowed
- ▶ A5. Define the **operator**
- ▶ A6. Define the **trigger** - the aggregation condition
- ▶ A7. Build the **algorithm** satisfying A1-A6

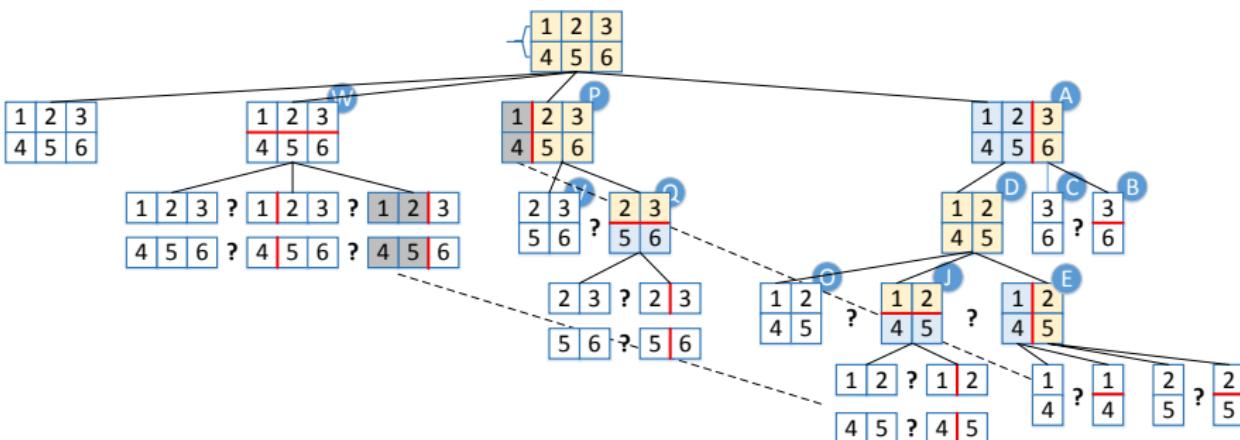
## A2-A5

- ▶ A2. We aggregate simultaneously on  $T$  and  $S$
- ▶ A3. Operands:  $(s, t) \in S \times T$
- ▶ A4. Constraint:  $\mathcal{A}(S \times T) = \mathcal{H}(S) \times \mathcal{I}(T)$   
Aggregation result is a partition  $\mathcal{P}(S \times T) \in \mathcal{A}(S \times T)$
- ▶ A5. Operator:  $+$
- ▶ A6. Trigger: maximize pIC of the partition  $\mathcal{P}(S \times T)$



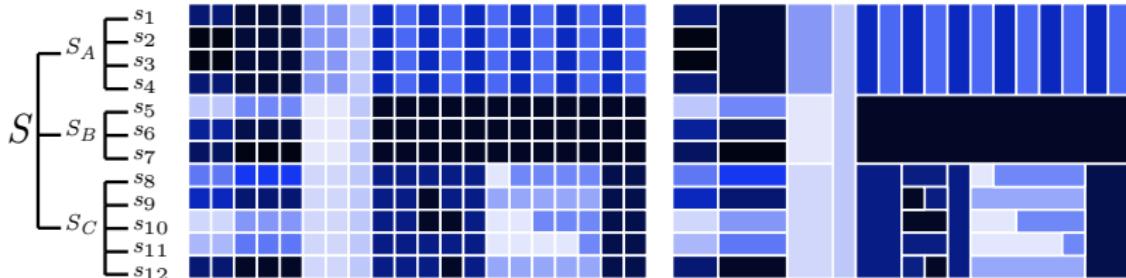
## BEST CUT ALGORITHM

- ▶ Compute the partition with the highest pIC :
    - Cut an area : time, space (or no cut)
    - Best cut: the partition  $\mathcal{P}$  where  $\sum_{E \in \mathcal{P}} \text{pIC}_E$  is max
    - Recursively cut and evaluate the partitions of  $E_1, E_2 \in \mathcal{P}$
    - Useless recomputation is avoided



## A6. TRIGGER THE AGGREGATION

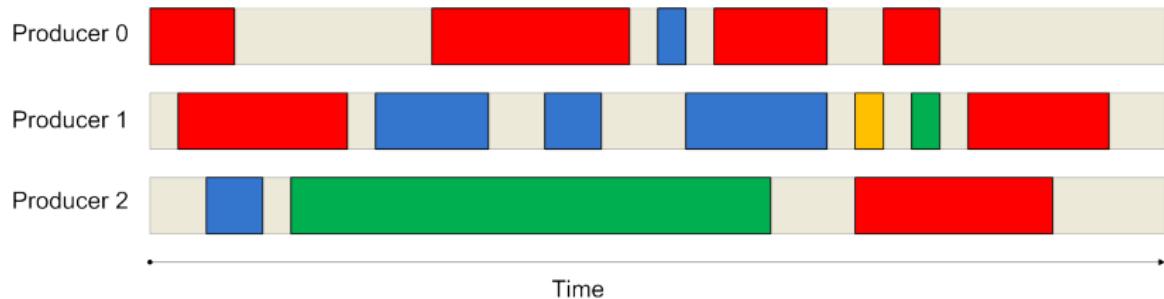
- ▶ Quantification of data reduction and information loss
  - aggregate the homogeneous areas
  - preserve the microscopic information of the heterogeneous areas
- ▶ Each  $(S_k, T_{(i,j)}) \in \mathcal{A}(S \times T)$  has an associated gain and loss
- ▶ gain and loss of a partition  $\mathcal{P}(S \times T)$  is the sum of gain and loss of its content  $(S_k, T_{(i,j)}) \in \mathcal{P}(S \times T)$



# ELMQVIST-FEKETE CRITERIA

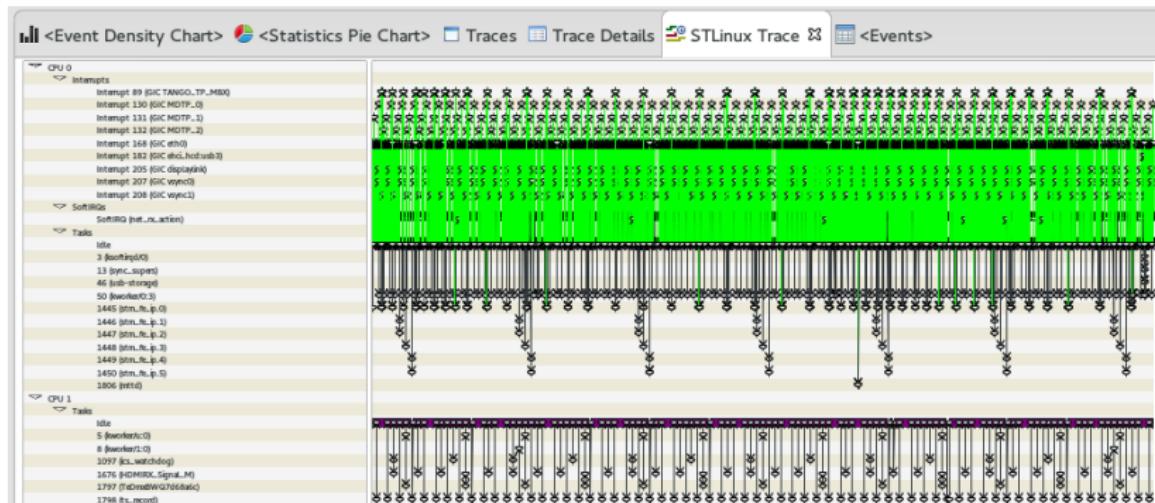
- ▶ **Shneiderman** : **overview**, zoom and filter, then get details on demand
- ▶ **Elmqvist & Fekete**: guidelines to design an **overview** visualization based on hierarchical aggregation
  - G1. Entity Budget
  - G2. Visual Summary
  - G3. Visual Simplicity
  - G4. *Discriminability*
  - G5. Fidelity
  - G6. *Interpretability*

# VISUALIZATIONS NOT FULFILLING THESE CRITERIA (1)



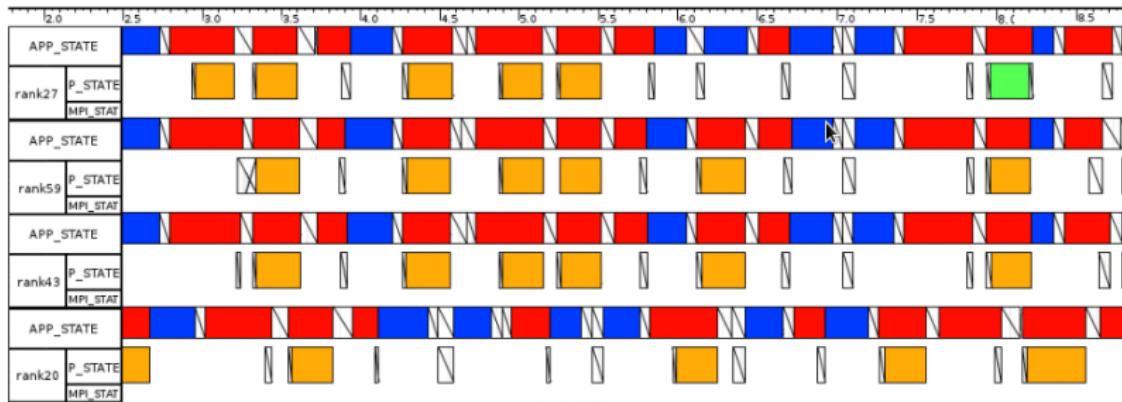
Example of Gantt chart - space-time diagram

# VISUALIZATIONS NOT FULFILLING THESE CRITERIA (2)



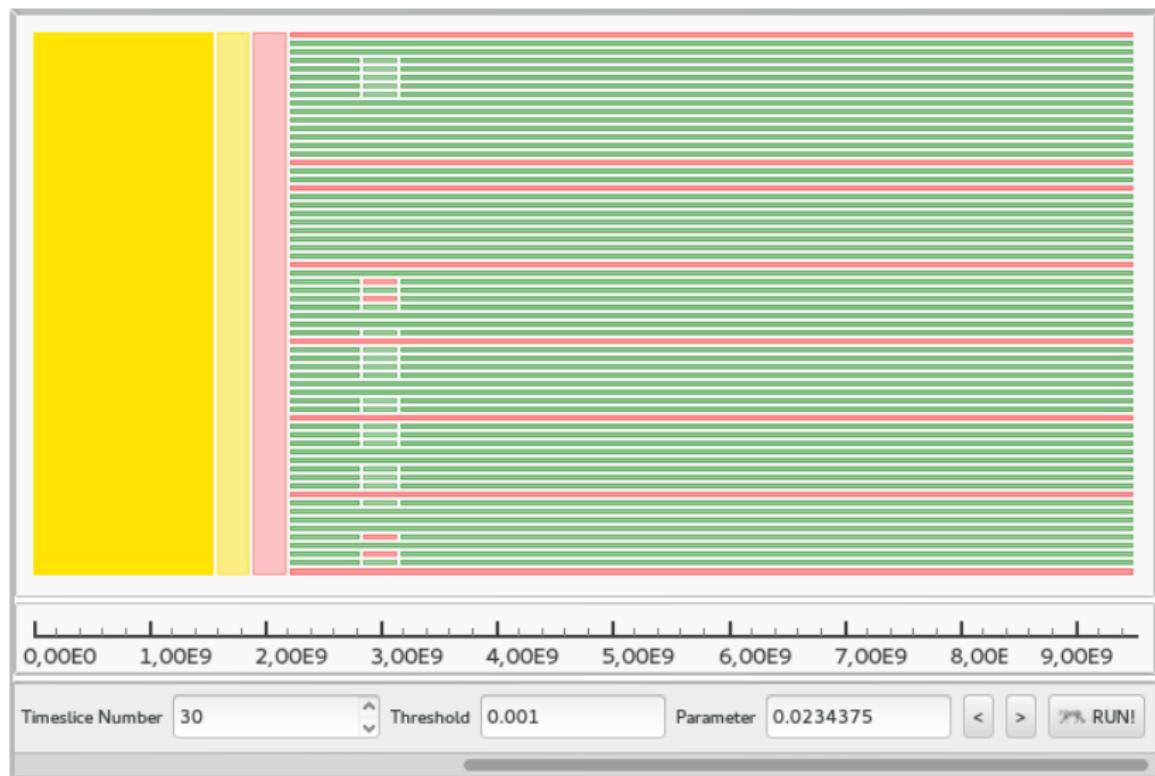
KPTTrace: G1 (time), G2, G4, G5

## VISUALIZATIONS NOT FULFILLING THESE CRITERIA (2)

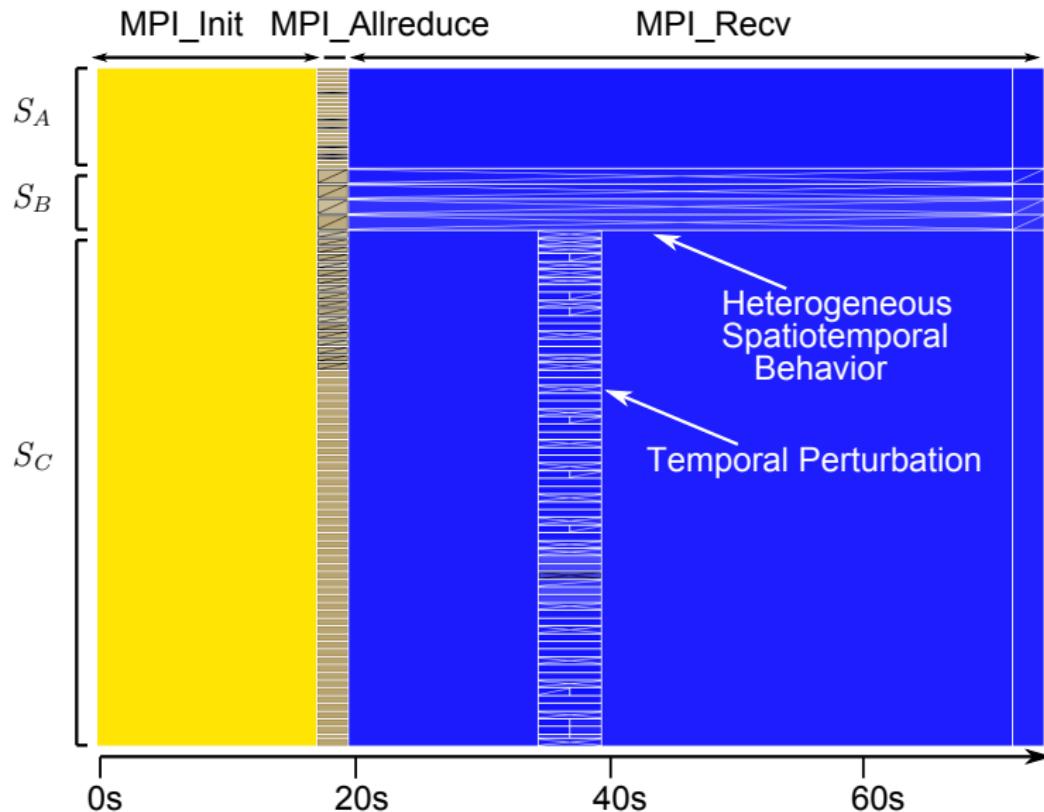


Pajé:  $\overline{G_1}$  (space),  $\overline{G_2}$

# CG CLASS C, 64 PROCESSES ON G5K RENNES



# LU CLASS C, 700 PROCESSES ON G5K NANCY



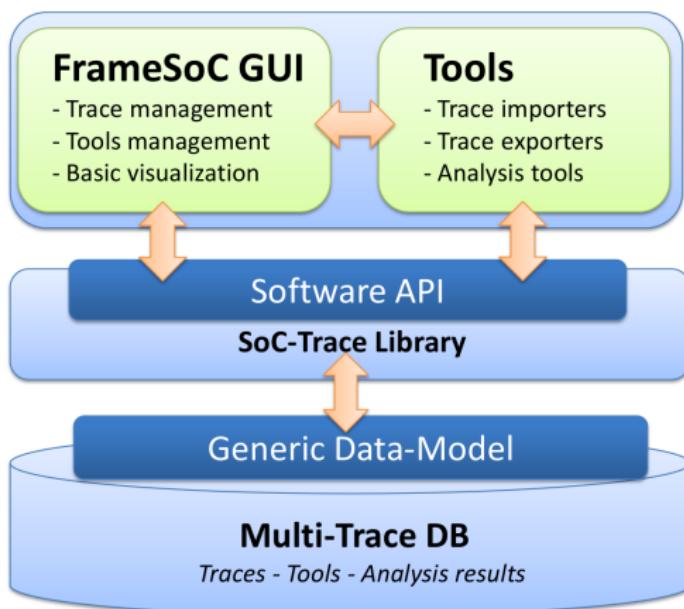
# PERFORMANCES (SPATIOTEMPORAL)

|  | <b>Case A</b> | <b>Case B</b>                         | <b>Case C</b>                                | <b>Case D</b>                                   |
|--|---------------|---------------------------------------|--|---|
| <b>Application</b>                                     | CG, class C   | CG, class C                           | LU, class C                                  | LU, class B                                     |
| <b>Processes</b>                                       | 64            | 512                                   | 700  | 900   |
| <b>Site</b>  | Rennes        | Grenoble                              | Nancy  | Rennes  |
| <b>Clusters<br/>(nodes)</b>                            | parapide(8)   | adonis(9),<br>edel(24),<br>genepi(31) | graphene(26),<br>graphite(4),<br>griffon(67) | paradent(38),<br>parapide(21),<br>parapluie(18) |
| <b>Event number</b>                                    | 3,838,144     | 49,149,440                            | 218,457,456                                  | 177,376,729                                     |
| <b>Trace size</b>                                      | 136.9 MB      | 1.8 GB                                | 8.3 GB                                       | 6.7 GB  |
| <hr/>  |               |                                       |  |   |
| <b>Ocelotl computation times (30 time slices)</b>      |               |                                       |  |   |
| <b>Trace reading<br/>+ Microscopic<br/>description</b> | 5 s           | 31 s                                  | 222 s  | 174 s   |
| <b>Aggregation</b>                                     | <1s           | <1s                                   | 2s   | 2s  |

# OCELOT TOOL

- ▶ Implementation of the overview techniques
- ▶ Generic architecture. Add:
  - Your own **aggregation operator** (dimensions, metric)
  - Your own **visualization**
- ▶ Persistent caches to avoid long recomputations
- ▶ Integrated in **Framesoc**:
  - Trace and tools management
  - **Fast** trace reading (DB queries)
  - **Interaction** with other analysis tools
  - Also enable to **add your own tools**

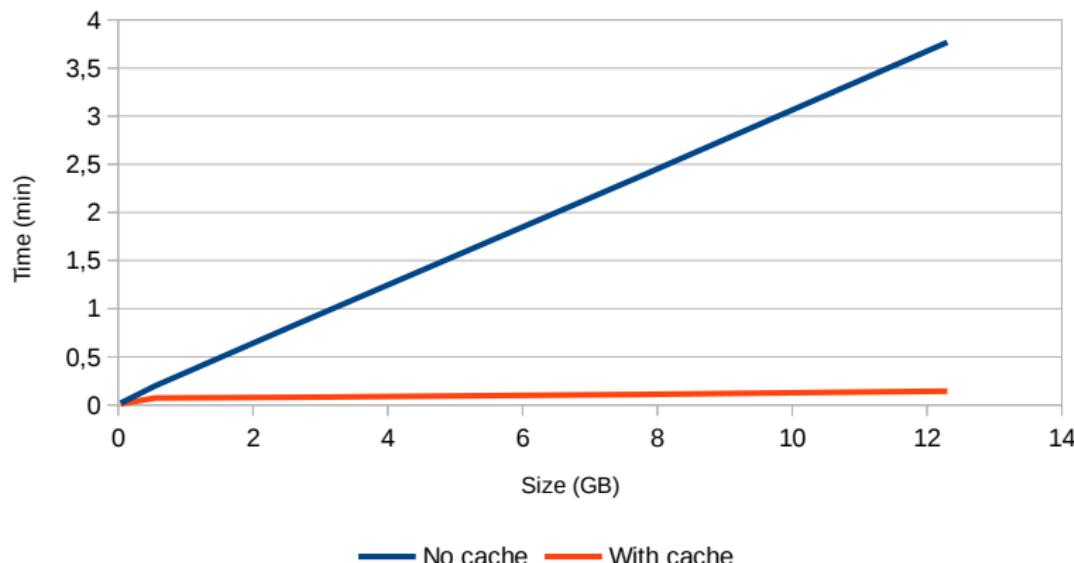
# FRAMESOC



- Trace format compatibility : Pajé (Akypuera: tool to convert from OTF2, Tau), LTTng, KPTrace

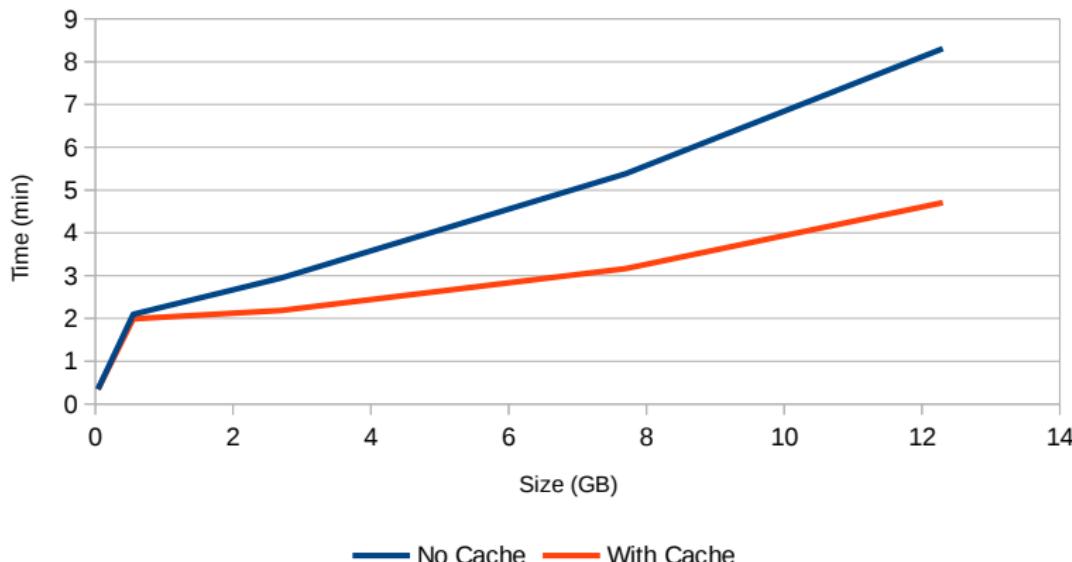
# PERFORMANCE: TEMPORAL ANALYSIS

Total analysis time as a function of trace size (100 time slices)



# PERFORMANCE: TEMPORAL ANALYSIS

Total analysis time as a function of trace size (1000 time slices)



# PERFORMANCE: SPATIOTEMPORAL ANALYSIS

Total analysis time as a function of trace size (30 time slices)

